

Praktikum: P4 Gruppe: 22

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Zutreffendes bitte ausfüllen

WS20/21

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Versuch: MOKE

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Wird vom Betreuer ausgefüllt.

1. Abgabe am: _____

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2. Abgabe am: _____

Ergebnis: + / 0 / - Handzeichen: _____

Datum: _____ Kommentar:

Contents

1. Theory & Preparation

1.1 Aim of the Experiment

In the experiment, the magnetization curves of different magnetic materials are determined. The **magneto-optical Kerr effect (MOKE)** is used. In this effect, the linearly polarized light reflected from the magnetic material undergoes a rotation of the plane of polarization. The angle of rotation Φ_K can therefore be used to draw conclusions about the magnetization. For this purpose, different layer systems consisting of ferro-, anti-ferro- and ferrimagnetic components are used.

1.2 Polarisation

The polarization of an electromagnetic wave describes the direction of oscillation of the component of the electric field in relation to the direction of propagation. A distinction is made between linear, circular and elliptical polarization. By superposition of a right circular polarized \vec{E}^- - and a left circular polarized \vec{E}^+ -wave a linear polarized wave can be represented. For a circularly polarized wave, the magnitude of the electric field $|\vec{E}|$ is constant, but its direction rotates at a constant rate in the polarization plane.

$$\vec{E}_0 = \vec{E}^+ + \vec{E}^- \quad \text{with:} \quad E^\pm = \frac{E_0}{2} \begin{pmatrix} 1 \\ \pm i \\ 0 \end{pmatrix} \quad (1.1)$$

1.3 Magnetic field in matter

Due to atomic magnetic dipole moments, materials possess magnetic properties. The sum of all atomic magnetic moments \vec{m}_i divided by the volume gives the magnetization:

$$\vec{M} = \frac{\vec{m}}{V}. \quad (1.2)$$

Thus, the magnetic flux density can be determined to:

$$\vec{B} = \mu_0 \vec{H} + \mu_0 \vec{M} = \mu_0 \mu \vec{H} \quad \text{with:} \quad \mu = 1 + \chi_m. \quad (1.3)$$

Here χ_m is equal to the magnetic susceptibility.

1.4 Magneto-optical Kerr effect

The **MOKE** changes the direction of polarization and intensity of the light beam reflected from a magnetic layer system. The effect results from the side diagonal elements of the permittivity tensor ϵ . This results in an anisotropic permittivity and finally in a direction dependent phase velocity in the medium with:

$$v_p = \frac{c}{\sqrt{\epsilon_r \mu_r}}. \quad (1.4)$$

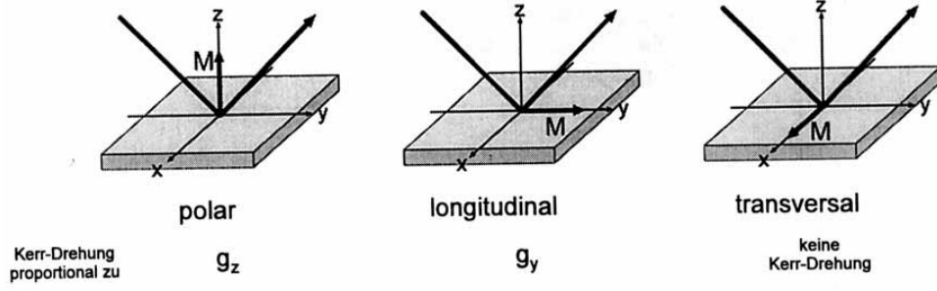


Figure 1.1: Illustration of MOKE with different geometries

Different geometries can now be distinguished, the magnitude of the effect typically decreases by one order in each case. The **polar** MOKE occurs when magnetization is perpendicular to the surface, this has the greatest influence. Furthermore, the **longitudinal** MOKE occurs when the magnetization is oriented parallel to the surface and to the plane of incidence of light. Lastly, the **transversal** MOKE occurs when the magnetization is parallel to the surface but perpendicular to the optical plane.

We consider for simplicity a perpendicular incident beam, the refractive index of a circularly polarized wave can thus be determined by:

$$\vec{n}^{\pm} \approx \vec{n}_0 \left(1 \pm \frac{\hat{n}_0 \cdot \vec{g}}{2} \right). \quad (1.5)$$

Where \hat{n}_0 is the unit vector parallel to the propagation direction (\hat{k}) and \vec{g} is the gyration vector with $Q = |\vec{g}|$ being the Voigt constant. It follows that with $\vec{g} \parallel \hat{n}_0$ for the reflection coefficient:

$$r^{\pm} = \frac{n_0 \cdot (1 \pm 0.5 \cdot Q) - 1}{n_0 \cdot (1 \pm 0.5 \cdot Q) + 1} \quad (1.6)$$

Choosing an incident EM wave parallel to the x-axis and the magnetization in the z-direction, i.e., the surface in the x-y plane, it follows:

$$\vec{E}^i = \frac{E_0}{2} \left[\begin{pmatrix} 1 \\ i \\ 0 \end{pmatrix} + \begin{pmatrix} 1 \\ -i \\ 0 \end{pmatrix} \right] \quad (1.7)$$

$$\vec{E}^r = r^+ \vec{E}^{i,+} + r^- \vec{E}^{i,-} = \left(E_0 \frac{n_0 - 1}{n_0 + 1} \cdot \vec{e}_x + \frac{n_0 \cdot Q}{(n_0 + 1)^2} \cdot i \vec{e}_y \right) \quad (1.8)$$

Here terms proportional to Q^2 were neglected. One recognizes a y-component of the reflected electric field as a result from the Kerr effect. The complex Kerr angle is then given by:

$$\Phi_K = \frac{E_y^r}{E_x^r} = in_0 Q \frac{1}{n_0^2 - 1} \quad (1.9)$$

Considering a purely real n_0 , there is no rotation of the plane of polarization. The Kerr angle corresponds to the phase shift of the two waves. The reflected wave is therefore elliptically polarized. For a complex n_0 one obtains a real Kerr angle and thus an additional change of the plane of polarization.

1.5 Magnetic anisotropy

Die magnetische Anisotropie beschreibt eine Vorzugsrichtung bei der Magnetisierung eines Materials. Sie wird beschrieben durch die magnetische Anisotropieenergie. Die Arbeit, die

benötigt wird, um die Magnetisierung \vec{M} in einem geschlossenen System ohne Teilchenaustausch aus der leichten Richtung herauszudrehen. Die leichte Richtung entspricht dabei der energetisch bevorzugten Richtung von spontaner magnetisierung. Als mikroskopische Ursache der magnetischen Anisotropie dient die Dipol-Dipol-Wechselwirkung und die Spin-Bahn-Kopplung.

Durch eine thermodynamische Betrachtung kann man die Gibbs'sche freie Energie bestimmen durch:

$$F = -J_S H \cos(\Theta - \Theta_H) + K_{eff} \sin^2(\Theta) \quad \text{with:} \quad J_S = \mu_0 M_S \quad (1.10)$$

Hierbei sind:

- M_S : magnetische Polarisierung
- M_S : Sättigungsmagnetisierung
- H : Betrag des angelegten Magnetfelds
- Θ_H : Winkel zwischen der Flächennormalen um dem Magnetfeld
- Θ : Winkel zwischen der Flächennormalen und der Magnetisierung
- K_{eff} : die effektive Anisotropiekonstante

Die Anisotropiekonstante ist dabei gegeben durch:

$$K_{eff} = -\frac{J_s^2}{2\mu_0} + K_1 + \frac{2k_s}{d}, \quad (1.11)$$

die Terme sind beschreiben dabei die Formanisotropie, magnetokristalline Anisotropie hexagonaler Symmetrie und die Grenzflächenanisotropie. K_{eff} entspricht dabei der Fläche unter der Magnetisierungskurve.

Die freie Energie ist ein thermodynamischen Potential und strebt im thermodynamischen Gleichgewicht ein Minimum an. Beim polaren MOKE gilt $\Theta_H = 0$, dadurch kann die Anisotropiekonstante beim Erreichen der Sättigung des Materials durch die Gleichgewichtsbedingung bestimmt werden.

$$\frac{dF}{d\Theta} = 0 \quad (1.12)$$

$$\Rightarrow K_{eff} = -\frac{1}{2}\mu_0 M_S H = -\frac{1}{2}J_S \quad (1.13)$$

Durch die Messung der Hysteresekurve muss noch die Koerzitivfeldstärke H_C von der Sättigungsfeldstärke H_S abgezogen werden. Außerdem ist der Kerrwinkel Φ_S im Sättigungsbereich proportional zur Sättigungsmagnetisierung.

$$J_S \propto \Phi_S \quad (1.14)$$

Damit können wir die effektive Anisotropiekonstante berechnen zu:

$$K_{eff} \propto -\frac{1}{2}\Phi_S(H_S - H_C) \quad (1.15)$$

Magnetic anisotropy describes a preferred direction in the magnetization of a material. It is described by the magnetic anisotropy energy, the work required to rotate the magnetization \vec{M} out of the easy direction in a closed system without particle exchange. The easy direction corresponds to the energetically preferred direction of spontaneous magnetization. The microscopic cause of the magnetic anisotropy is the dipole-dipole interaction and the spin-orbit coupling.

By a thermodynamic consideration, one can determine the Gibbs free energy by:

$$F = -J_S H \cos(\Theta - \Theta_H) + K_{eff} \sin^2(\Theta) \quad \text{with:} \quad J_S = \mu_0 M_S \quad (1.16)$$

Where:

- M_S : magnetic polarization
- M_S : Saturation magnetization
- H : magnitude of the applied magnetic field
- Θ_H : Angle between the surface normal and the magnetic field
- Θ : Angle between the surface normal and the magnetization
- K_{eff} : the effective anisotropy constant

Here, the anisotropy constant is given by:

$$K_{eff} = -\frac{J_s^2}{2\mu_0} + K_1 + \frac{2k_s}{d}, \quad (1.17)$$

the terms are describing the shape anisotropy, magnetocrystalline anisotropy of hexagonal symmetry and the interface anisotropy. K_{eff} corresponds to the area under the magnetization curve.

The free energy is a thermodynamic potential and tends to a minimum at thermodynamic equilibrium. In polar MOKE, $\Theta_H = 0$ holds, thus the anisotropy constant can be determined by the equilibrium condition when the material reaches saturation.

$$\frac{dF}{d\Theta} = 0 \quad (1.18)$$

$$\Rightarrow K_{eff} = -\frac{1}{2}\mu_0 M_S H = -\frac{1}{2}J_S \quad (1.19)$$

By measuring the hysteresis curve, the coercivity H_C must still be subtracted from the saturation field strength H_S . In addition, the kerr angle Φ_S in the saturation region is proportional to the saturation magnetization.

$$J_S \propto \Phi_S \quad (1.20)$$

Thus we can calculate the effective anisotropy constant to:

$$K_{eff} \propto -\frac{1}{2}\Phi_S(H_S - H_C) \quad (1.21)$$

1.6 Relevant types of magnetism

1.6.1 Ferromagnetism

1.6.2 Anti ferromagnetism

1.6.3 Ferrimagnetism

2. Experiment & Evaluation

2.1 Experimental setup

[Get setup picture, MOKE pdf p.15]

ToDo

As can be seen in ??, a sample can be placed inside of an electromagnet with controllable B -field. The measurement apparatus that will test the magneto-optic Kerr effect consists of a laser diode that shines polarised light onto the sample. Two polarisation filters and focusing lenses exist to tweak the properties of light beam and improve the overall signal strength. The light that gets reflected off the magnetic sample travels through a beam splitter into two photo diodes that in turn feed a differential amplifier. A Hall probe monitors the strength of the B -field in which the sample is placed.

2.2 Ferromagnets: Pd/Co/Pd sample

The first sample consists of two thin layers of Palladium (paramagnetic) and one layer of Cobalt (ferromagnetic) of variable thickness d . The crystal lattice of the trilayer system in total acts as a ferromagnet. The different magnetic properties of the sublattice however can cause strong changes in both magnitude and direction of magnetization in special cases. These effects will in part be analysed in this section.

Before the measurement data is evaluated the applied model is presented. The Kerr-angle that is measured as a function of external magnetic field is proportional to intrinsic magnetisation, we are effectively measuring a magnetic hysteresis modulo some numerical constants. Expanding on the work in [?] we can therefore impose a model to analytically describe the hysteresis curve traced out by the Kerr-angle Φ in the experiment. This model is presented in ??.

$$\Phi(H) = \Phi_s \tanh(B(H \pm H_c)) + \mu_0 H. \quad (2.1)$$

In the above ?? there are several parameters that influence the shape of the hysteresis curve. These are:

- Φ_s is the Kerr-angle at the saturation point.
- B^1 determines the magnetic hardness of the sample.
- $\pm H_c$ is the coercive field strength, on the up/downsweep of H .

¹for lack of more fitting nomenclature in the literature

Figure 2.1

Experimental setup of the MOKE lab

2.3 Antiferromagnets: Co/Pd/Co sample

2.4 Ferrimagnets: $\text{Fe}_{1-x}\text{Gd}_x$ samples

2.5 Conclusion