# **Matvey Panteleev**

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## Education \_\_\_\_\_

### St. Petersburg Polytechnic University (SPbPU)

St. Peterburg

BS IN ROBOTICS & MECHATRONICS GPA: 4.9/5.0

Sep 2018 - June 2022

# Experience \_\_\_\_

#### **Russian State Scientific Center for Robotics and Technical Cybernetics**

St.Petersburg

**ROBOTICS ENGINEER** 

November 2021 - Present

- Developed tools for automatic radio channel bandwidth testing.
- Participated in robotic system development in various roles.

## **Innopolis University**

INTERNSHIP August 2021

• Developed tools for automatic radio channel bandwidth testing.

## Skills \_\_\_\_

C/C++, Python, ROS, OpenCV, Matlab, Embedded Development CAD: Fusion 360, Altium Designer, Solidworks, Visual Components

English: C1 (IELTS 8.0)

## Projects \_

#### **Orthogonal Fisheye Stereo Vision System**

OpenCV, C++, Unity

A STEREO SYSTEM BASED ON ORTHOGONALLY PLACED FISHEYE CAMERAS. ALLOWS TO GET DEPTH DATA FOR A WIDE RANGE OF CAMERA CONFIGURATIONS.

https://github.com/QuOzer/fisheye\_stereo

**Manipulator** 

**VR Cobot Trainer** 

C, STM32, ROS https://github.com/QuoZer/Tertiarm\_ROS-STM

A ROS-CONTROLLED 5DOF MANIPULATOR BASED ON STM32 MCU

Python, Visual Components

A VISUAL COMPONENTS BASED APPLICATION FOR COBOT PROGRAMMING IN

VR. THE PROJECT IS BEING DEVELOPED INTO A STARTUP WITH A STATE GRANT

## **Quadruped Robot ROS integration**

C++, ROS

A ROS wrapper for Unitree A1 quadruped robot API. Tested with SLAM APPLICATION.

https://github.com/SailorTheMan/unitree\_slam

## Awards \_

May 2021

NTI Contest winner team, Assembled and lead a team that won an Intellectual Robotic Systems track of National Technical Initiative Contest.

Innopolis university