

# MicroBle Design Tips

MicroBle is an adapter interface tool for transfer from micro:bit to Unity via Windows PC using BLE (Bluetooth low energy). By connecting the sensor device (gyro, accelerometer, GPS, etc.) with micro:bit, you can input various sense data to Unity. You can also output various data from Unity by connecting the display device (LED, LCD panel, etc.) with micro:bit. This design tip explains how to modify for transfer data between Unity and micro:bit based on the purchased Unity script example and the purchased micro:bit code. MicroBle transfers array data up to 64 bytes from Unity to micro:bit and array data up to 64 bytes from micro:bit to Unity by changing the Unity script example and the micro:bit code.

## 1. How to transfer data from micro:bit to Unity

### 1.1 How to set up data to Unity in micro:bit

### 1.2 How to get data from micro:bit in Unity

## 2. How to transfer data from Unity to micro:bit

### 2.1 How to set up data to micro:bit in Unity

### 2.2 How to get data from Unity in micro:bit

## 1. How to transfer data from micro:bit to Unity

### 1.1 How to set up data to Unity in micro:bit

The micro:bit code 'microble-v2.ino' generates 3D Object 'glasses' tilt data 'x, y, z' using the 'accel.update' acceleration function and convert it to strings using the 'sprintf' function. The micro:bit code needs to change the strings to byte array data type using 'saccel.getBytes' function for sending data to Unity when micro:bit connects some sensors device.

```
...

void setAccelCharacteristicValue() {
    char acceldata[30];

    accel.update();
    float accelX = (float)accel.getX() * 0.0156;
    float accelY = (float)accel.getY() * 0.0156;
    float accelZ = (float)accel.getZ() * 0.0156;
```

```

    sprintf(acceldata, "accel - X: % 3.4f Y: % 3.4f Z: % 3.4f", accelX , accelY ,
    accelZ );
    Serial.println(acceldata);

    sprintf(acceldata, " % d, % d, % d", (int)(accelX * 100000), (int)(accelY * 100000),
    (int)(accelZ * 100000));
    Serial.println(acceldata);
    //accelCharacteristic.setValue(accel);

    String saccel = String(acceldata);
    //Serial.println(saccel);
    byte sbyte[saccel.length()];
    saccel.getBytes(sbyte, saccel.length() + 1);
    accelCharacteristic.setValue(sbyte, saccel.length());
};

...

```

The micro:bit code ‘microble-v2.ino’ calls the ‘setValue’ function in the following format for sending data to Unity.

```

void setValue(byte[] sbyte, int length);

```

## 1.2 How to get data from micro:bit in Unity

Unity script example ‘MicroBleSampleCode.cs’ receives BLE data from micro:bit as byte array data ‘data’ of return value of ‘m\_micro:bit BleLib.UpdateRead’ function. The byte array data ‘data’ encodes string code using ‘System.Text.Encoding.UTF8.GetString’ function and, using ‘text.Split’ function and ‘float.Parse’ function, the string code is converted to float position data.

```

...
// Update is called once per frame
void Update()
{
    byte[] readdata = new byte[] { };
    //UnityEngine.Debug.LogWarning("Update");
}

```

```

        if (!m_MicroBleLib.UpdateRead(ref readdata))
        {
            return;
        }
        UnityEngine.Debug.LogWarning(" Read1: " + readdata[0] + " " + readdata[1] +
        " " + readdata[2]);
        UnityEngine.Debug.LogWarning(" Read1: " + readdata.Length);

        string text = System.Text.Encoding.UTF8.GetString(readdata);
        UnityEngine.Debug.LogWarning(" Read: " + text);
        string[] arr = text.Split(',');
        float[] acceldata = new float[3];
        acceldata[0] = float.Parse(arr[0]) / 100000;
        acceldata[1] = float.Parse(arr[1]) / 100000;
        acceldata[2] = float.Parse(arr[2]) / 100000;

        UnityEngine.Debug.LogWarning(" Update: " + acceldata[0] + " " +
        acceldata[1] + " " + acceldata[2]);

        accelx = acceldata[0] * 400;
        accely = acceldata[1] * 400;
        accelz = acceldata[2] * 400;...
        ...

```

Unity script example 'MicroBleSampleCode.cs' calls the 'UpdateRead' function in the following format for reading data from mcro:bit.

```

bool UpdateRead(ref byte[] readdata)

```

## 2. How to transfer data from Unity to mcro:bit

### 2.1 How to set up data to mcro:bit in Unity

Unity script example 'MicroBleSampleCode.cs' call back 'ButtonClick' function at button 'On' clicked. 'ButtonClick' function inputs data from Inputfield 'Row' / Inputfield 'Col', then calls 'm\_MicroBleLib.Command' function with the parameter of

‘writedata’ byte array.

```
...
public void ButtonClick()
{
    UnityEngine.Debug.LogWarning("ButtonClick: ");

    byte[] writedata = new byte[2] { byte.Parse(inputFieldrow.text) ,
byte.Parse(inputFieldcol.text) };
    UnityEngine.Debug.LogWarning(writedata[0] + " " + writedata[1]);
    m_MicroBleLib.Command(writedata);
}
...
```

Unity script example ‘MicroBleSampleCode.cs’ calls the ‘Command’ function in the following format for sending byte array data to mcr0:bit.

```
void Command(byte[] writedata);
```

## 2.2 How to get data from Unity in mcr0:bit

The mcr0:bit code ‘microble-v2.ino’ calls ‘getContolCharacteristicValue’ function at received data from Unity. The ‘getContolCharacteristicValue’ function receives Inputfield ‘Row’ / Inputfield ‘Col’ of Unity as 2 bytes of data using the ‘controlCharacteristic.value’ function.

```
...
void getContolCharacteristicValue() {
    Serial.println("***** receive data! *****");
    if (controlCharacteristic.value()) {
        byte row = controlCharacteristic.value()[0];
        byte col = controlCharacteristic.value()[1];
        Serial.println(row);
        Serial.println(col);

        led_pset( col, row, HIGH);
    }
}
```

```
    delay(200);  
    led_pset( col, row, LOW);  
  }  
}  
...
```

The micro:bit code 'microble-v2.ino' calls the 'value' function for receiving byte array data in the following format from Unity.

```
byte value()[x];  
  
x: byte array index  
return: byte
```