



Εθνικό Μετσόβιο Πολυτεχνείο
Σχολή Ηλεκτρολόγων Μηχανικών & Μηχανικών Υπολογιστών

6^ο Εξάμηνο
Συστήματα Μικροϋπολογιστών

4^η ΟΜΑΔΑ ΑΣΚΗΣΕΩΝ



Χατζή Ήβη

Άσκηση 1

```
.include "m16def.inc"
reset:
ldi r24,low(RAMEND) ; Initialize stack pointer
out SPL,r24
ldi r24,high(RAMEND) ;
out SPH,r24
ser r24 ; Initialize PORTA for output
out DDRA,r24
clr r24
out DDRB,r24 ; Initialize PORTB for input

main:
ldi r26,01 ; Start from LED0
rcall move_left
nop
rcall move_right
rjmp main

move_left:
in r24,PINB ; Input PB0
andi r24,01 ; Keep LSB
cpi r24,01 ; If PB0 = 1 don't move
breq move_left
out PORTA,r26
cpi r26,80 ; Check if reached MSB
brcc end_left ; If MSB return
lsl r26 ; Else shift left and continue
rjmp move_left

end_left: ret

move_right:
in r24,PINB ; Input PB0
andi r24,01 ; Keep LSB
cpi r24,01 ; If PB0 = 1 don't move
breq move_right
out PORTA,r26
cpi r26,01 ; Check if reached LSB
breq end_right ; If LSB return
lsr r26 ; Else shift right and continue
rjmp move_right

end_right: ret
```

Άσκηση 2

```
/*
 * ex2.c
 */

#include <avr/io.h>

int main(void)
{
    char input,A,B,C,D,F0,F1;
    DDRB=0xFF;           // initialise PORTB as output
    DDRA=0x00;           // initialise PORTA as input
    while(1)
    {
        input = PINA & 0x0F; //input bits 0-3 from PORTA
        A = input & 0x01;    // A is bit 0
        B = (input & 0x02) >> 1; // B is bit 1, shift once
        C = (input & 0x04) >> 2; // C is bit 2, shift twice
        D = (input & 0x08) >> 3; // D is bit 3, shift thrice

        F0 = ~((A & B & ~C)|(C & D)); // calculate F0
        F0 = F0 & 0x01; // isolate bit 0
        F1 = ((A | B) & (C | D)); // calculate F1
        F1 = (F1 << 1) & 0x02; // shift F1 once to the left and isolate bit 1

        PORTB = F1 | F0; // output at PORTB
    }
    return 0;
}
```

Άσκηση 3

```
/*
 *ex3.c
 */

#include<avr/io.h>

char x,input;

int main(void){

    DDRA = 0xFF;           // Initialise PORTA as output
    DDRC = 0x00;           // Initialise PORTC as input
    x = 1;                 // Initialise x for

    while(1){
        input=PINC;
        if(input == 1)     // SW0 is pressed
            if(x == 128) x = 1; // If 10000000 then 00000001 else
            else x = x << 1;    // Shift left once
        else if(input == 2) // SW1 is pressed
            if(x == 1) x = 128; // If 00000001 then 10000000 else
            else x = x >> 1;    // Shift right once
        else if(input == 4) // SW2 is pressed
            x=128;             // Led7 (MSB)
        else if(input == 8) // SW3 is pressed
            x = 1;            // Led0 (LSB)
        while(PINC != 0);     // Wait until push-button is unpressed
        PORTA = x;           // Apply the change of the output
    }
    return 0;
}
```