Hierarchical spatial modelling for applied population and community ecology

Jeffrey W. Doser, Marc Kéry, Gesa von Hirschheydt 24-27 June 2024



Single-species spatial occupancy models

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Recall the basic occupancy model

Occupancy (ecological) sub-model

$$z_j \sim \text{Bernoulli}(\psi_j)$$

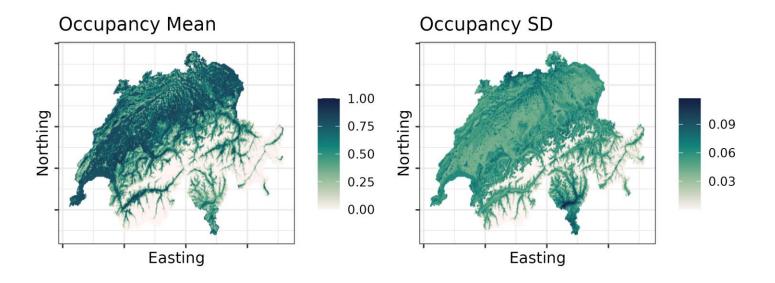
$$\text{logit}(\psi_j) = \beta_1 + \beta_2 \cdot X_{2,j} + \dots + \beta_r \cdot X_{r,j}$$

$$y_{j,k} \sim \text{Bernoulli}(p_{j,k} \cdot z_j)$$

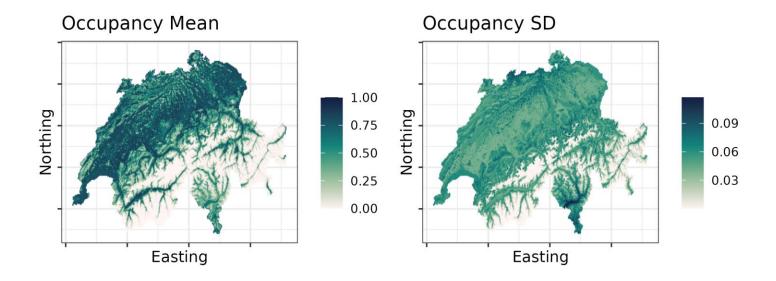
$$\text{logit}(p_{j,k}) = \alpha_1 + \alpha_2 \cdot V_{2,j,k} + \cdots + \alpha_r \cdot V_{r,j,k}$$

$$j = 1, ..., J$$
 (site)
 $k = 1, ..., K_j$ (replicate)

European Goldfinch example



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Does accounting for spatial autocorrelation improve our model and resulting species distribution map?

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- Accounting for spatial autocorrelation can often improve predictions.
- Maps of the predicted spatial effects can give insights on the underlying drivers.

Spatial occupancy model

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$$\mathbf{w} \sim \text{Normal}(\mathbf{0}, \mathbf{C}(d, \phi, \sigma^{2}))$$

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Spatial NNGP occupancy model

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Prior distributions (and spOccupancy defaults)

$$\beta_r \sim \text{Normal}(0, 2.72)$$
 $\alpha_r \sim \text{Normal}(0, 2.72)$
 $\sigma^2 \sim \text{Inverse-gamma}(2, 1)$
 $\phi \sim \text{Uniform}(\frac{3}{d_{\text{max}}}, \frac{3}{d_{\text{min}}})$

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See "2-intro-to-spatial-models.pdf" lecture

Prior distributions (and spOccupancy defaults)

Where does the 2.72 come from?

$$\beta_r \sim \text{Normal}(0, 2.72)$$

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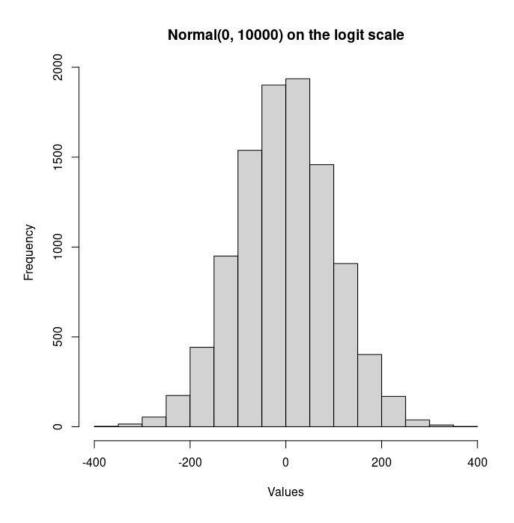
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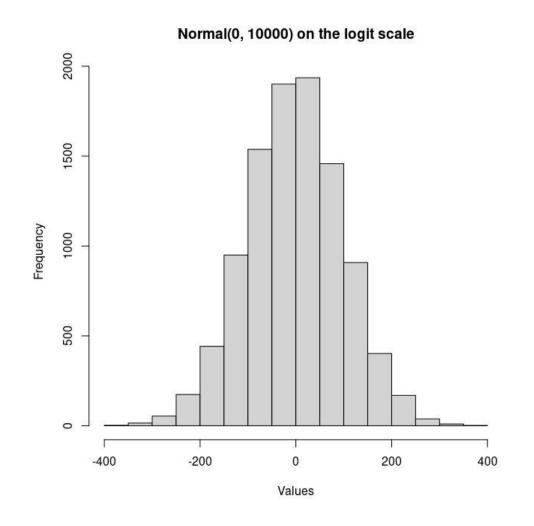
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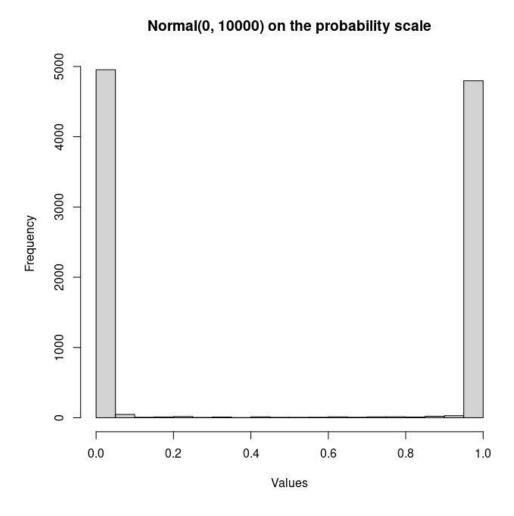
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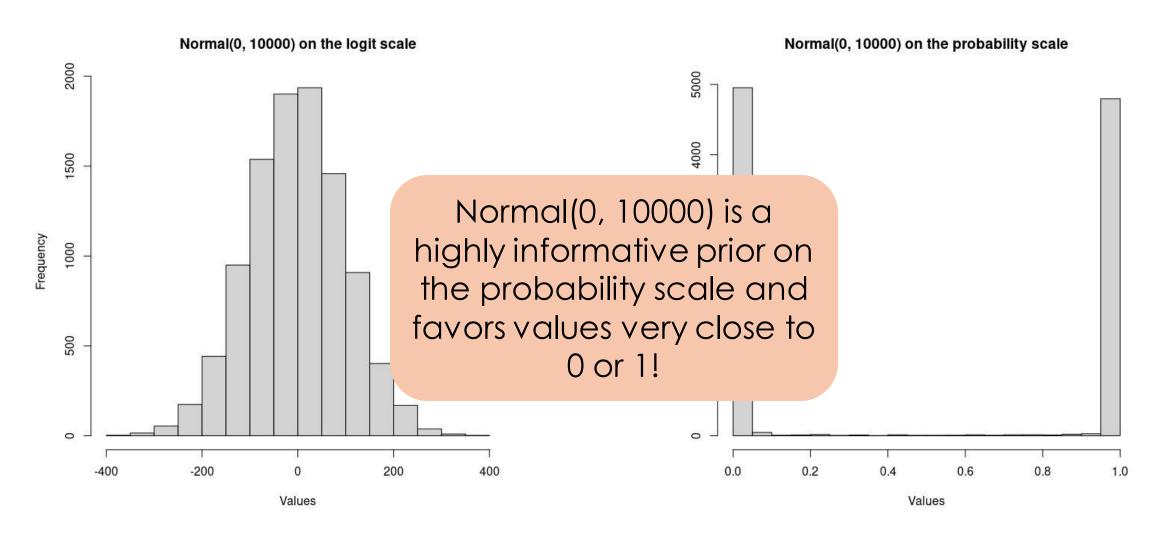
- A standard prior in regression models for the intercept and coefficients is a Normal prior with mean 0 and a very big variance (e.g., 1000).
- However, this actually becomes a very informative prior in occupancy models (and any type of binomial GLM)!!
- This is because the regression coefficients are on the logit scale.





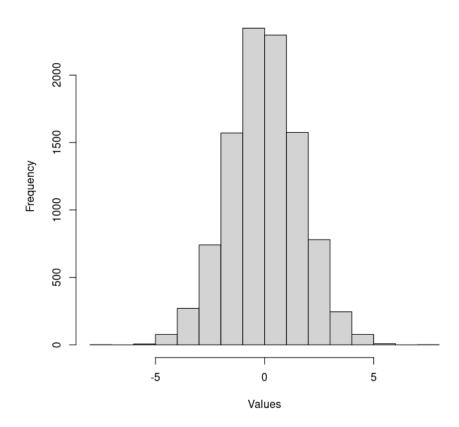




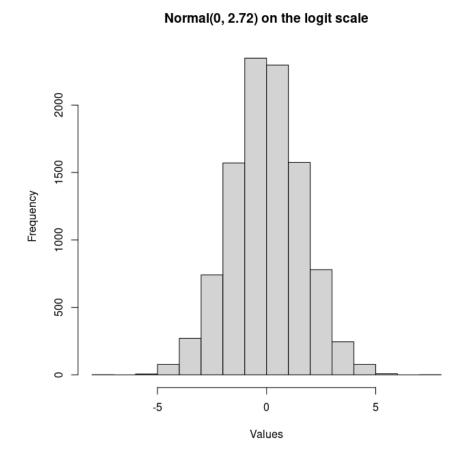


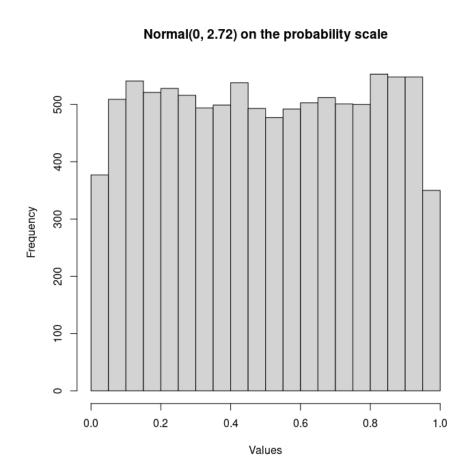
Instead, a good prior is Normal(0, 2.72)



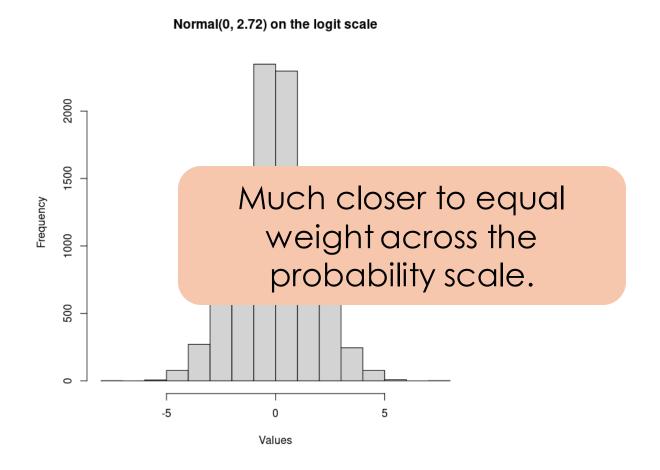


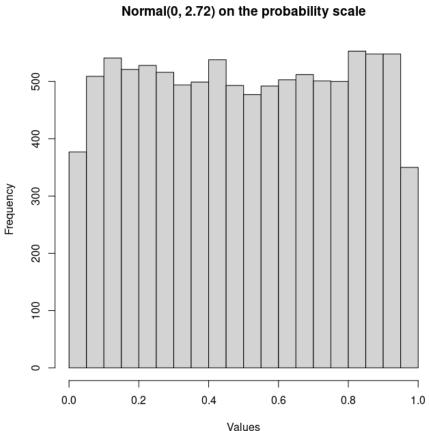
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Fitting spatial occupancy models in spOccupancy

- Function: spPGOcc (spatial Pólya-gamma occupancy model)
- Supports both full GP and NNGP models.
- The model is implemented using an algorithm called an Adaptive Metropolis sampler, which requires special considerations.

```
spPGOcc(occ.formula, det.formula, data, inits, priors,
    tuning, cov.model = "exponential", NNGP = TRUE,
    n.neighbors = 15, search.type = "cb", n.batch,
    batch.length, accept.rate = 0.43,
    n.omp.threads = 1, verbose = TRUE, n.report = 100,
    n.burn = round(.10 * n.batch * batch.length),
    n.thin = 1, n.chains = 1, k.fold, k.fold.threads = 1,
    k.fold.seed = 100, k.fold.only = FALSE, ...)
```

- Estimating the spatial decay parameter ϕ is difficult.
- At each step of the MCMC algorithm, we propose a new value for φ.
- The proposed value comes from a Normal distribution:
 - Mean: the current value of \$\phi\$
 - Variance: the Tuning Variance
- We use an algorithm to determine if we should keep the previous value, or accept the new one.
- Ideally, we want to accept the proposed value around 43% of the time.

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- To do this, the MCMC samples are split into a set of batches
- Each batch has a pre-specifed set of MCMC samples (e.g., 25)
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- Each batch has a pre-specifed set of MCMC samples (e.g., 25)
- After each batch, the tuning variance is adjusted to get closer to an acceptance rate of 0.43.
- This approach can greatly speed up the time to convergence for difficult to estimate parameters like φ.

What do you need to specify in spoccupancy?

- 1. The initial tuning variance (tuning).
- 2. The acceptance rate (accept.rate).
- 3. The number of MCMC batches to run (n.batch).
- 4. The number of MCMC samples in each batch (batch.length).

The total number of MCMC samples is n.batch * batch.length



4-spatial-european-goldfinch.R



