# Module 7: Models with changing variance and frequency models

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#### Learning outcomes

- Understand how to fit ARCH, GARCH and SVM models in JAGS
- Know how to check assumptions for these methods
- Understand the basis of seasonal models
- Know the difference between time and frequency domain models and be able to implement a Fourier model

#### Relevant JAGS file:

```
jags_ARCH.R
jags_GARCH.R
jags_SVM.R
jags_Fourier.R
```

#### General principles of models for changing variance

► So far we have looked at models where the mean changes but the variance is constant:

$$y_t \sim N(\mu_t, \sigma^2)$$

▶ In this module we look at methods where instead:

$$y_t \sim N(\alpha, \sigma_t^2)$$

- These are:
- Autoregressive Conditional Heteroskedasticity (ARCH)
- Generalised Autoregressive Conditional Heteroskedasticity (ARCH)
- Stochastic Volatility Models (SVM)

#### Extension 1: ARCH

An ARCH(1) Model has the form:

$$\sigma_t^2 = \gamma_0 + \gamma_1 \epsilon_{t-1}^2$$

where  $\epsilon_t$  is the residual, just like an MA model

Note that  $\epsilon_t = y_t - \alpha$  so the above can be re-written as:

$$\sigma_t^2 = \gamma_0 + \gamma_1 (y_{t-1} - \alpha)^2$$

- ► The variance at time *t* thus depends on the previous value of the series (hence the autoregressive in the name)
- ▶ The residual needs to be squared to keep the variance positive.
- ▶ The parameters  $\gamma_0$  and  $\gamma_1$  also need to be positive, and usually  $\gamma_1 \sim U(0,1)$

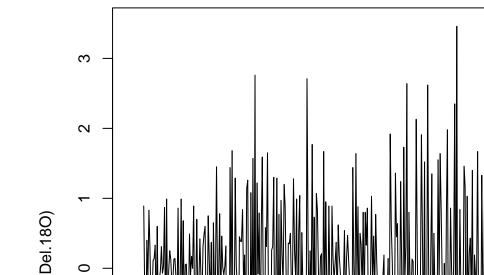
#### JAGS code for ARCH models

gamma\_1 ~ dunif(0, 10)  $gamma 2 \sim dunif(0, 1)$ 

```
model code = '
model
  # Likelihood
  for (t in 1:T) {
    y[t] ~ dnorm(alpha, tau[t])
    tau[t] \leftarrow 1/pow(sigma[t], 2)
  sigma[1] ~ dunif(0, 10)
  for(t in 2:T) {
    sigma[t] <- sqrt( gamma_1 + gamma_2 * pow(y[t-1] - alp)</pre>
  }
  # Priors
  alpha \sim dnorm(0.0, 0.01)
```

## Example: ice core data

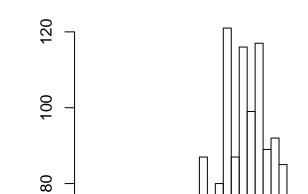
with(ice2,plot(Age[-1],diff(Del.180),type='l'))



#### Example: ice core output

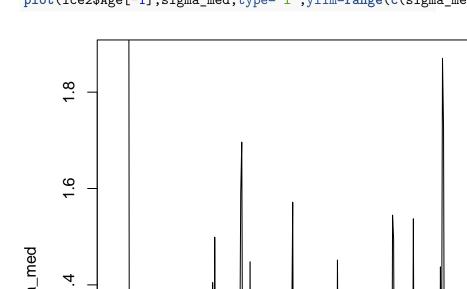
```
par(mfrow=c(1,2))
hist(real_data_run_1$BUGSoutput$sims.list$gamma_1, breaks=3
hist(real_data_run_1$BUGSoutput$sims.list$gamma_2, breaks=3
```

## stogram of real\_data\_run\_1\$BUGSoutput\$sims.list



## Example: posterior standard deviations

sigma\_med = apply(real\_data\_run\_1\$BUGSoutput\$sims.list\$sign
plot(ice2\$Age[-1],sigma\_med,type='l',ylim=range(c(sigma\_med))



#### From ARCH to GARCH

- ► The Generalised ARCH model works by simply adding the previous value of the variance, as well as the previous value of the observation
- ► The GARCH(1,1) model thus has:

$$\sigma_t^2 = \gamma_1 + \gamma_2 (y_{t-1} - \alpha)^2 + \gamma_3 \sigma_{t-1}^2$$

- ightharpoonup Strictly speaking  $\gamma_1+\gamma_2<1$  though like the stationarity conditions in ARIMA models we can relax this assumption and see if the data support it
- ▶ It's conceptually easy to extend to general GARCH(p,q) models which add in extra previous lags

## Example of using the GARCH(1,1) model

}

# Priors

alpha  $\sim$  dnorm(0.0, 0.01) gamma\_1 ~ dunif(0, 10)  $gamma 2 \sim dunif(0, 1)$ 

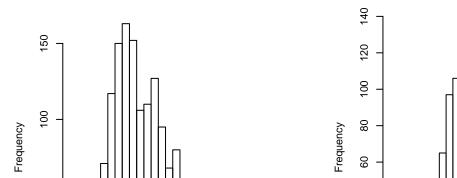
```
model code = '
model
  # Likelihood
  for (t in 1:T) {
    y[t] ~ dnorm(alpha, tau[t])
    tau[t] \leftarrow 1/pow(sigma[t], 2)
  sigma[1] ~ dunif(0,10)
  for(t in 2:T) {
    sigma[t] <- sqrt( gamma_1 + gamma_2 * pow(y[t-1] - alp)</pre>
```

#### Using the ice core data again

Have a look at the ARCH parameters;

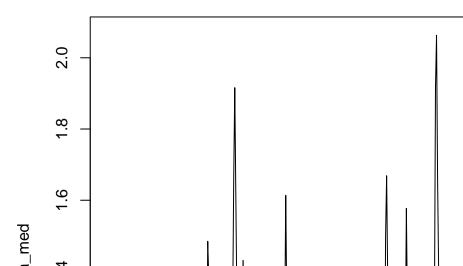
```
par(mfrow=c(1,3))
hist(real_data_run_2$BUGSoutput$sims.list$gamma_1, breaks=;
hist(real_data_run_2$BUGSoutput$sims.list$gamma_2, breaks=;
hist(real_data_run_2$BUGSoutput$sims.list$gamma_3, breaks=;
```

pgram of real\_data\_run\_2\$BUGSoutput\$sims.list\$@gram of real\_data\_r



#### Posterior median standard deviation

sigma\_med = apply(real\_data\_run\_2\$BUGSoutput\$sims.list\$sign
plot(ice2\$Age[-1], sigma\_med, type='l', ylim=range(c(sigma\_



#### Compare with DIC

```
with(r_1, print(c(DIC, pD)))
## [1] 2152.979029 3.713786

with(r_2, print(c(DIC, pD)))
## [1] 2141.418813 7.090526
```

 Suggests full GARCH model is best, despite the extra parameters

#### Stochastic Volatility Modelling

- ▶ Both ARCH and GARCH propose a deterministic relationship for the current variance parameter
- By contrast a Stochastic Volatility Model (SVM) models the variance as its own stochastic process
- SVMs, ARCH and GARCH are all closely linked if you go into the bowels of the theory
- ▶ The general model structure is often written as:

$$y_t \sim N(\alpha, \exp(h_t))$$

$$h_t \sim N(\mu + \phi(h_{t-1} - \mu), \sigma^2)$$

You can think of an SVM being like a GLM but with a log link on the variance parameter

#### JAGS code for the SVM model

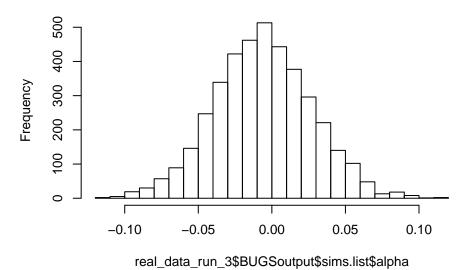
```
model code = '
model
  # Likelihood
  for (t in 1:T) {
    v[t] ~ dnorm(alpha, tau h[t])
    tau h[t] \leftarrow 1/exp(h[t])
  h[1] <- mu
  for(t in 2:T) {
    h[t] \sim dnorm(mu + phi * (h[t-1] - mu), tau)
  }
  # Priors
  alpha \sim dnorm(0, 0.01)
```

phi  $\sim$  dunif(-1, 1) +211 < -1/port(airms 2)

 $mu \sim dnorm(0, 0.01)$ 

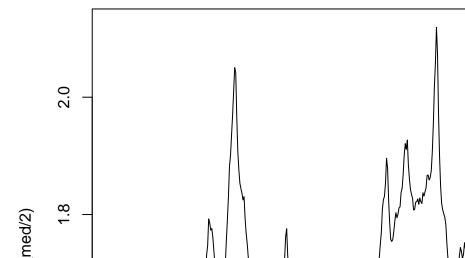
#### Example of SVMs and comparison of DIC

### Histogram of real\_data\_run\_3\$BUGSoutput\$sims.list\$a



#### Plot of h

h\_med = exp(apply(real\_data\_run\_3\$BUGSoutput\$sims.list\$h,2
plot(ice2\$Age[-1],exp(h\_med/2),type='l',ylim=range(c(exp(h\_med/2)))



#### Comparison with previous models

```
with(r_1, print(c(DIC, pD)))
## [1] 2152.979029 3.713786
with(r_2, print(c(DIC, pD)))
## [1] 2141.418813 7.090526
with(r_3, print(c(DIC, pD)))
## [1] 2239.756 164.230
```

Note quite as good, and many extra parameters due to h!

#### Seasonal time series

- So far we haven't covered how to deal with data that are seasonal in nature
- These data generally fall into two categories:
  - 1. Data where we know the frequency or frequencies (e.g. monthly data on a yearly cycle, frequency = 12)
  - Data where we want to estimate the frequencies (e.g. climate time series, animal populations, etc)
- The former are much simpler, as we can e.g. use month as a covariate in an ARIMAX model, perform a seasonal difference with an ARIMA, or fit a full seasonal ARIMA model (though the JAGS code for this gets complicated)
- ► The latter are much more interesting. The ACF and PACF can help, but we can usually do much better by creating a power spectrum

#### Methods for estimating frequencies

- ► The most common way to estimate the frequencies in a time series is to decompose it in a *Fourier Series*
- We write:

$$y_t = \alpha + \sum_{k=1}^K \left[ \beta_k \sin(2\pi t f_k) + \gamma_k \cos(2\pi t f_k) \right] + \epsilon_t$$

- ► Each one of the terms inside the sum is called a *harmonic*. We decompose the series into a sum of sine and cosine waves rather than with AR and MA components
- ▶ Each sine/cosine pair has its own frequency  $f_k$ . If the corresponding coefficients  $\beta_k$  and  $\gamma_k$  are large we might believe this frequency is important

#### Estimating frequencies via a Fourier model

- ▶ It's certainly possible to fit the model in the previous slide in JAGS, as it's just a linear regression model with clever explanatory variables
- However, it can be quite slow to fit and, if the number of frequencies K is high, or the frequencies are close together, it can struggle to converge
- ▶ More commonly, people repeatedly fit the simpler model:

$$y_t = \alpha + \beta \sin(2\pi t f_k) + \gamma \cos(2\pi t f_k) + \epsilon_t$$

for lots of different values of  $f_k$ . Then calculate the *power spectrum* as  $P(f_k) = \frac{\beta^2 + \gamma^2}{2}$ . Large values of the power spectrum indicate important frequencies

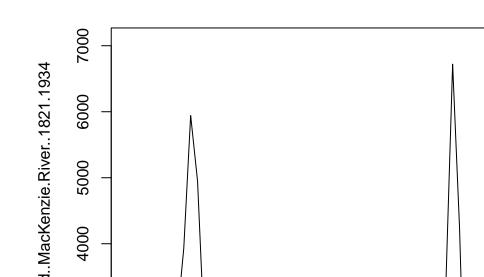
It's much faster to do this outside of JAGS, using other methods, but we will stick to JAGS

#### JAGS code for a Fourier model

```
model code = '
model
  # Likelihood
  for (t in 1:T) {
    y[t] ~ dnorm(mu[t], tau)
    mu[t] <- alpha + beta * cos( 2 * pi * t * f_k ) + gamma
  P = (pow(beta, 2) + pow(gamma, 2)) / 2
  # Priors
  alpha \sim dnorm(0.0,0.01)
  beta \sim dnorm(0.0, 0.01)
  gamma \sim dnorm(0.0,0.01)
  tau <- 1/pow(sigma,2) # Turn precision into standard dev:
  sigma \sim dunif(0.0,100.0)
```

#### Example: the Lynx data

```
lynx = as.ts(dmseries('http://data.is/Ky69xY'))
plot(lynx)
```

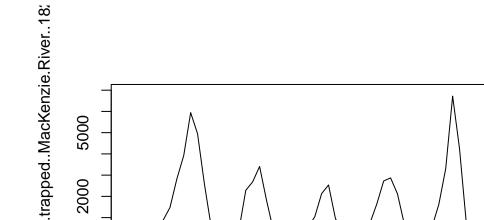


## Code to run the JAGS model repeatedly

```
periods = 5:40
K = length(periods)
f = 1/periods
Power = rep(NA,K)
model parameters = c("P")
for (k in 1:K) {
  curr model data = list(y = as.vector(lynx[,1]),
                         T = length(lynx),
                         f k = f[k],
                         pi = pi)
  model_run = jags(data = curr_model_data,
                   parameters.to.save = model_parameters,
                   model.file=textConnection(model_code),
                   n.chains=4.
                   n.iter=1000.
                   n hurnin-200
```

## Plotting the periodogram

```
par(mfrow = c(2, 1))
plot(lynx)
plot(f, Power, type='l')
axis(side = 3, at = f, labels = periods)
```



#### Bayesian vs traditional frequency analysis

- ► For quick and dirty analysis, there is no need to run the full Bayesian model, the R function periodogram in the TSA package will do the job
- However, the big advantage (as always with Bayes) is that we can also plot the uncertainty in the periodogram, or combine the Fourier model with other modelling ideas (e.g. ARIMA)
- There are much fancier versions of frequency models out there (e.g. Wavelets, or frequency selection models) which can also be fitted in JAGS but require a bit more time and effort
- ▶ These Fourier models work for continuous time series too

#### Summary

- We now know how to fit models with changing variance using a variety of techniques
- We can combine these new models with all the techniques we have previously learnt
- With known periodicity we can use seasonal differencing (or seasonal AR terms, not covered here but can be upon request)
- We've seen a basic Fourier model for estimating frequencies via the Bayesian periodogram