# Wired Wheel for Turrets

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## A mind map of it

Mind Map of two sides wired wheel



A:Go

Wired Wheel
Forward = 1
Reverse = -1

C

Add
Gate

A

Abs
Gate

Out:A

Out:D

ADV.
POD.
CON.
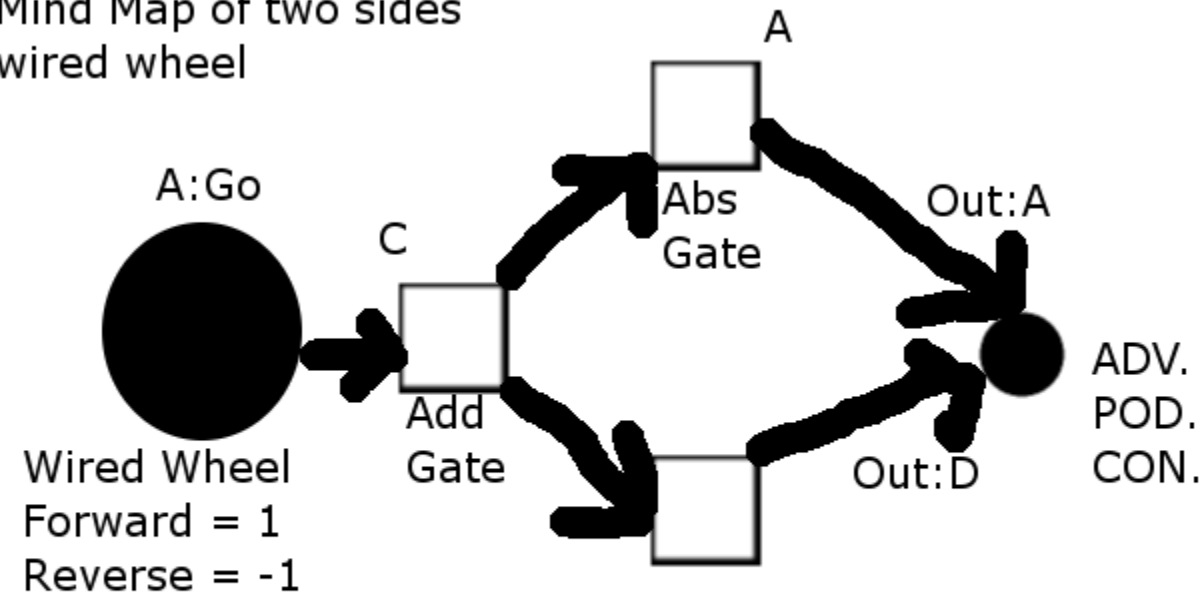
Caution! : All gates are Arythmetic!

Negative Gate is this at down

## Alternative method

Alternatively, you can subtract the output of A from the output of D on the advanced pod controller. Pressing neither gives you 0-0=0, Pressing A gives you 1-0=1, Pressing D gives you 0-1=-1. This is far simpler than the above method.

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