### **Concurrency Control**

# Hector Garcia-Molina and Mahmoud SAKR

#### **Invited Lectures**

#### Extensible Databases - 6/10/2021



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PostgreSQL major contributor & author of "The Art of PostgreSQL". Contributed extension facility & event triggers feature in Postgres. Maintains pg\_auto\_failover. Speaker at so many conferences.

#### Distributed Databases - 8/12/2021

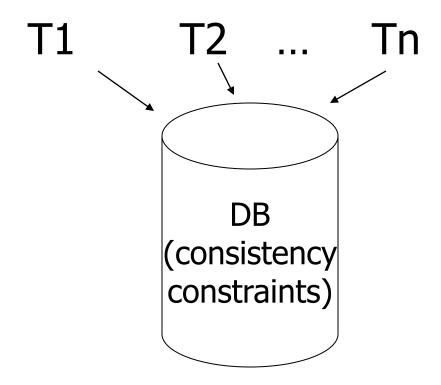


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Lead engineer on the Citus engine team at Microsoft. Speaker at Postgres Conf EU, PostgresOpen, pgDay Paris, Hello World, SIGMOD, & lots of meetups. PhD in distributed systems. Loves mountain hiking.

### Chapter 18 [18] Concurrency Control



### **Example:**

T1: Read(A)

 $A \leftarrow A+100$ 

Write(A)

Read(B)

 $B \leftarrow B+100$ 

Write(B)

Constraint: A=B

T2: Read(A)

 $A \leftarrow A \times 2$ 

Write(A)

Read(B)

 $B \leftarrow B \times 2$ 

Write(B)

#### Schedule A

```
T1
                                   T2
Read(A); A \leftarrow A+100
Write(A);
Read(B); B \leftarrow B+100;
Write(B);
                                   Read(A); A \leftarrow A \times 2;
                                   Write(A);
                                   Read(B);B \leftarrow B\times2;
                                   Write(B);
```

# Schedule A

		Α	В
T1	T2	25	25
Read(A); $A \leftarrow A+100$			
Write(A);		125	
Read(B); B $\leftarrow$ B+100;			
Write(B);			125
	Read(A);A $\leftarrow$ A $\times$ 2;		
	Write(A);	250	
	Read(B);B $\leftarrow$ B $\times$ 2;		
	Write(B);		250
·	vviice(D),	250	250

#### Schedule B

T1

T2

Read(A);  $A \leftarrow A \times 2$ ; Write(A); Read(B);  $B \leftarrow B \times 2$ ; Write(B);

```
Read(A); A \leftarrow A+100
Write(A);
Read(B); B \leftarrow B+100;
Write(B);
```

# Schedule B

		Α	В
T1	T2	25	25
	Read(A);A $\leftarrow$ A×2; Write(A); Read(B);B $\leftarrow$ B×2; Write(B);	50	50
Read(A); $A \leftarrow A+100$ Write(A); Read(B); $B \leftarrow B+100$ ;		150	150
Write(B);		150	150

### Schedule C

T1	T2
Read(A); $A \leftarrow A+100$	
Write(A);	
	Read(A);A $\leftarrow$ A $\times$ 2;
	Write(A);
Read(B); B $\leftarrow$ B+100;	
Write(B);	
	Read(B);B $\leftarrow$ B $\times$ 2;

Write(B);

# Schedule C

		Α	В
T1	T2	25	25
Read(A); $A \leftarrow A+100$			
Write(A);		125	
	Read(A);A $\leftarrow$ A×2;		
	Write(A);	250	
Read(B); B $\leftarrow$ B+100;			
Write(B);			125
	Read(B);B $\leftarrow$ B $\times$ 2;		
	Write(B);		250
		250	250

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#### Schedule D

```
T1
                                   T2
Read(A); A \leftarrow A+100
Write(A);
                                   Read(A); A \leftarrow A \times 2;
                                   Write(A);
                                   Read(B);B \leftarrow B\times2;
                                   Write(B);
Read(B); B \leftarrow B+100;
Write(B);
```

# Schedule D

		Α	В
_T1	T2	25	25
Read(A); $A \leftarrow A+100$			
Write(A);		125	
	Read(A);A $\leftarrow$ A $\times$ 2;		
	Write(A);	250	
	Read(B);B $\leftarrow$ B×2;		
	Write(B);		50
Read(B); B $\leftarrow$ B+100;			
Write(B);			150
		250	150

#### Schedule E

Same as Schedule D but with new T2'

T1

T2'

```
Read(A); A \leftarrow A+100
Write(A);
```

```
Read(A); A \leftarrow A \times 1;
Write(A);
Read(B); B \leftarrow B \times 1;
Write(B);
```

Read(B); B  $\leftarrow$  B+100; Write(B);

### Schedule E

Same as Schedule D but with new T2'

		А	В
_T1	T2'	25	25
Read(A); $A \leftarrow A+100$			
Write(A);		125	
	Read(A);A $\leftarrow$ A $\times$ 1;		
	Write(A);	125	
	Read(B);B $\leftarrow$ B $\times$ 1;		
	Write(B);		25
Read(B); B $\leftarrow$ B+100;			
Write(B);			125
		125	125

- Want schedules that are "good", regardless of
  - initial state and
  - transaction semantics
- Only look at order of read and writes

#### Example:

$$Sc=r_1(A)w_1(A)r_2(A)w_2(A)r_1(B)w_1(B)r_2(B)w_2(B)$$

#### Example:

$$Sc=r_1(A)w_1(A)r_2(A)w_2(A)r_1(B)w_1(B)r_2(B)w_2(B)$$

 $Sc'=r_1(A)w_1(A) r_1(B)w_1(B)r_2(A)w_2(A)r_2(B)w_2(B)$   $T_1$   $T_2$ 

### The Transaction Game

A				
В				
<b>T1</b>				
<b>T2</b>				

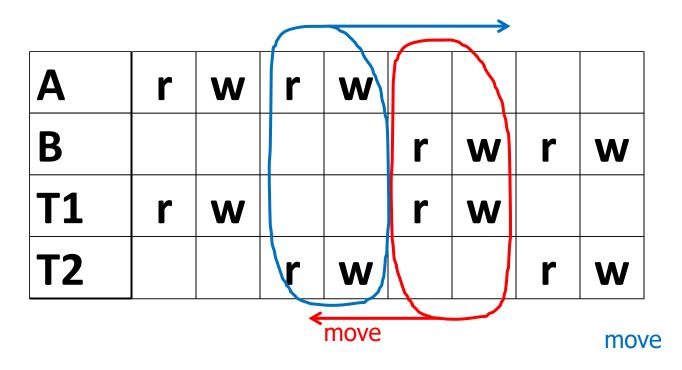
#### The Transaction Game

A	r	W	r	W				
В					r	W	r	W
<b>T1</b>	r	W			r	W		
<b>T2</b>			r	W			r	W

#### The Transaction Game

A	r	W	r	W	$\overline{\bigcap}$			
В			until	olumn	r	W	r	W
<b>T1</b>	r	W	hits sor	nething	r	W		
<b>T2</b>			r	W			r	W

can move column



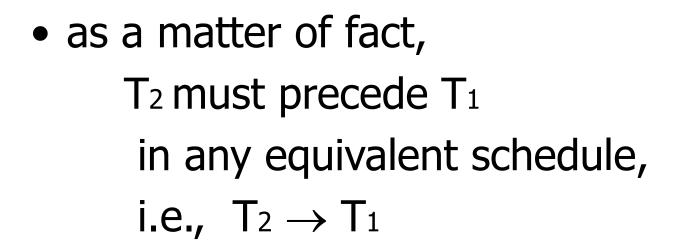
Α	r	W			r	W		
В			r	W			r	W
<b>T1</b>	r	W	r	W				
<b>T2</b>					r	W	r	W

# Schedule D

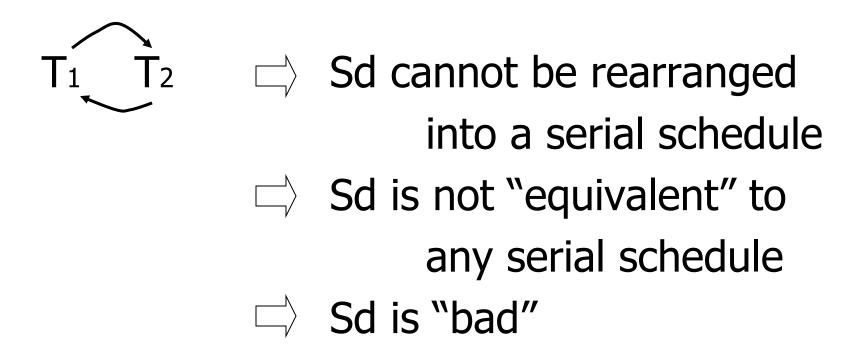
Α	r	W	r	W				
В					r	W	r	W
<b>T1</b>	r	W					r	W
<b>T2</b>			r	W	r	w		

#### However, for Sd:

 $Sd=r_1(A)w_1(A)r_2(A)w_2(A) r_2(B)w_2(B)r_1(B)w_1(B)$ 



- $T_2 \rightarrow T_1$
- Also,  $T_1 \rightarrow T_2$



#### Returning to Sc

Sc=r<sub>1</sub>(A)w<sub>1</sub>(A)r<sub>2</sub>(A)w<sub>2</sub>(A)r<sub>1</sub>(B)w<sub>1</sub>(B)r<sub>2</sub>(B)w<sub>2</sub>(B)  

$$T_1 \rightarrow T_2$$
  $T_1 \rightarrow T_2$ 

#### Returning to Sc

$$Sc=r_1(A)w_1(A)r_2(A)w_2(A)r_1(B)w_1(B)r_2(B)w_2(B)$$

$$T_1 \rightarrow T_2 \qquad T_1 \rightarrow T_2$$

• no cycles  $\Rightarrow$  Sc is "equivalent" to a serial schedule (in this case T<sub>1</sub>,T<sub>2</sub>)

#### **Concepts**

Transaction: sequence of ri(x), wi(x) actions Conflicting actions: ri(A) wi(X) wi(X) wi(X) actions wi(X) wi(X) wi(X) wi(X) actions wi(X) wi(X) wi(X) wi(X) actions wi(X) wi(X)

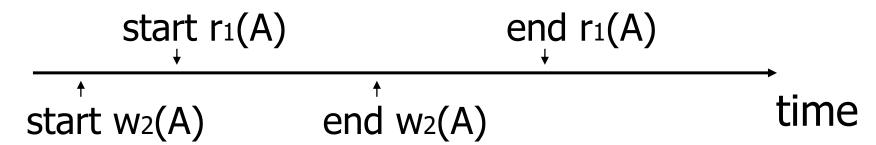
Schedule: represents chronological order in which actions are executed

Serial schedule: no interleaving of actions or transactions

# Is it OK to model reads & writes as occurring at a single point in time in a schedule?

• 
$$S = ... r_1(x) ... w_2(b) ...$$

# What about conflicting, concurrent actions on same object?



# What about conflicting, concurrent actions on same object?

- Assume equivalent to either r<sub>1</sub>(A) w<sub>2</sub>(A)
   or w<sub>2</sub>(A) r<sub>1</sub>(A)
- → low level synchronization mechanism
- Assumption called "atomic actions"

#### **Definition**

S<sub>1</sub>, S<sub>2</sub> are <u>conflict equivalent</u> schedules if S<sub>1</sub> can be transformed into S<sub>2</sub> by a series of swaps on non-conflicting actions.

#### **Definition**

A schedule is <u>conflict serializable</u> if it is conflict equivalent to some serial schedule.

### Precedence graph P(S) (S is schedule)

Nodes: transactions in S

Arcs:  $Ti \rightarrow Tj$  whenever

- p<sub>i</sub>(A), q<sub>j</sub>(A) are actions in S
- $p_i(A) <_S q_j(A)$
- at least one of p<sub>i</sub>, q<sub>j</sub> is a write

#### **Exercise:**

What is P(S) for
 S = w<sub>3</sub>(A) w<sub>2</sub>(C) r<sub>1</sub>(A) w<sub>1</sub>(B) r<sub>1</sub>(C) w<sub>2</sub>(A) r<sub>4</sub>(A) w<sub>4</sub>(D)

• Is S serializable?

#### **Another Exercise:**

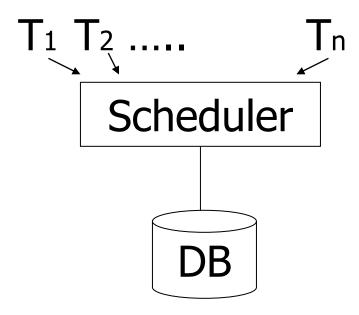
What is P(S) for
 S = w<sub>1</sub>(A) r<sub>2</sub>(A) r<sub>3</sub>(A) w<sub>4</sub>(A) ?

#### How to enforce serializable schedules?

Option 1: run system, recording P(S); at end of day, check for P(S) cycles and declare if execution was good

#### How to enforce serializable schedules?

# Option 2: prevent P(S) cycles from occurring

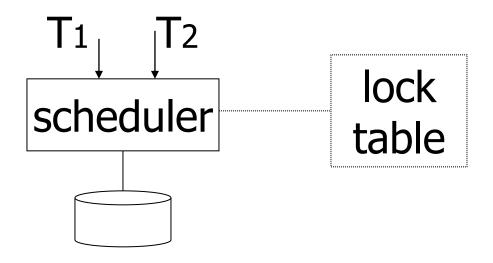


# A locking protocol

#### Two new actions:

lock (exclusive): li (A)

unlock: ui (A)



## Rule #1: Well-formed transactions

Ti: ... li(A) ... pi(A) ... ui(A) ...

# Rule #2 Legal scheduler

$$S = \dots I_i(A) \dots u_i(A) \dots no I_j(A)$$

## Exercise:

 What schedules are legal? What transactions are well-formed?  $S1 = I_1(A)I_1(B)r_1(A)w_1(B)I_2(B)u_1(A)u_1(B)$  $r_2(B)w_2(B)u_2(B)l_3(B)r_3(B)u_3(B)$  $S2 = I_1(A)r_1(A)w_1(B)u_1(A)u_1(B)$  $I_2(B)r_2(B)w_2(B)I_3(B)r_3(B)u_3(B)$  $S3 = I_1(A)r_1(A)u_1(A)I_1(B)w_1(B)u_1(B)$  $I_2(B)r_2(B)w_2(B)u_2(B)I_3(B)r_3(B)u_3(B)$ 

## Exercise:

What schedules are legal? What transactions are well-formed?  $S1 = I_1(A)I_1(B)r_1(A)w_1(B)I_2(B)u_1(A)u_1(B)$  $r_2(B)w_2(B)u_2(B)l_3(B)r_3(B)u_3(B)$  $S2 = I_1(A)r_1(A)w_1(B)u_1(A)u_1(B)$  $I_2(B)r_2(B)w_2(B)I_3(B)r_3(B)u_3(B)(u_2(B)?)$  $S3 = I_1(A)r_1(A)u_1(A)I_1(B)w_1(B)u_1(B)$  $I_2(B)r_2(B)w_2(B)u_2(B)I_3(B)r_3(B)u_3(B)$ 

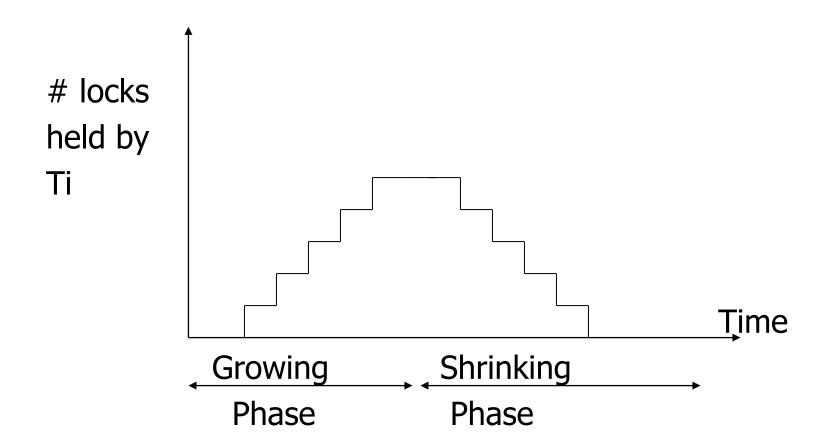
# Schedule F

T1	T2
I <sub>1</sub> (A);Read(A)	
$A \leftarrow A + 100; Write(A); u_1(A)$	
	I <sub>2</sub> (A);Read(A)
	A←Ax2;Write(A);u2(A)
	I <sub>2</sub> (B);Read(B)
	B←Bx2;Write(B);u <sub>2</sub> (B)
I <sub>1</sub> (B);Read(B)	
B←B+100;Write(B);u <sub>1</sub> (B)	

# Schedule F

		_A_	B
T1	T2	25	25
l <sub>1</sub> (A);Read(A)			
A←A+100;Write(A);u <sub>1</sub> (A)		125	
	I <sub>2</sub> (A);Read(A)		
	A←Ax2;Write(A);u <sub>2</sub> (A)	250	
	l <sub>2</sub> (B);Read(B)		
	B←Bx2;Write(B);u <sub>2</sub> (B)		50
l <sub>1</sub> (B);Read(B)			
B←B+100;Write(B);u <sub>1</sub> (B)			150
		250	150

# Rule #3 Two phase locking (2PL) for transactions



# Schedule G

T1	T2
I <sub>1</sub> (A);Read(A)	
A←A+100;Write(A)	
I1(B); u1(A)	ما حام ا
	I <sub>2</sub> (A);Read(A)
	<b>A←Ax2;Write(A)</b> (12(B))

# Schedule G

Γ	1
I	1

 $I_1(A);Read(A)$ 

 $A \leftarrow A + 100; Write(A)$ 

I<sub>1</sub>(B); u<sub>1</sub>(A)

Read(B);B ← B+100

Write(B); u<sub>1</sub>(B)

T2

l<sub>2</sub>(A);Read(A)

A ←Ax2; Write(A)

delayed

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# Schedule G

**T1** 

 $l_1(A);Read(A)$ 

 $A \leftarrow A + 100; Write(A)$ 

 $I_1(B); u_1(A)$ 

Read(B);  $B \leftarrow B+100$ 

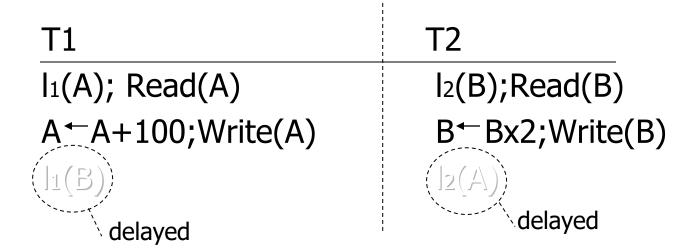
Write(B); u<sub>1</sub>(B)

T2

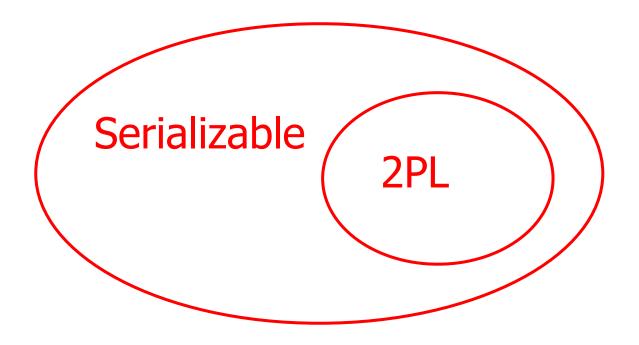
I<sub>2</sub>(A);Read(A) delayed A←Ax2;Write(A);I<sub>2</sub>(B)

l<sub>2</sub>(B); u<sub>2</sub>(A);Read(B)
B ← Bx2;Write(B);u<sub>2</sub>(B);

# Schedule H (T2 reversed)



# 2PL subset of Serializable





S1: w1(x) w3(x) w2(y) w1(y)

# S1: w1(x) w3(x) w2(y) w1(y)

- S1 cannot be achieved via 2PL:
   The lock by T1 for y must occur after w2(y), so the unlock by T1 for x must occur after this point (and before w1(x)). Thus, w3(x) cannot occur under 2PL where shown in S1 because T1 holds the x lock at that point.
- However, S1 is serializable (equivalent to T2, T1, T3).

If you need a bit more practice:

Are our schedules S<sub>C</sub> and S<sub>D</sub> 2PL schedules?

 $S_c$ : w1(A) w2(A) w1(B) w2(B)

 $S_D$ : w1(A) w2(A) w2(B) w1(B)

- Beyond this simple 2PL protocol, it is all a matter of improving performance and allowing more concurrency....
  - Shared locks
  - Multiple granularity
  - Inserts, deletes and phantoms
  - Other types of C.C. mechanisms

## **Shared locks**

So far:

$$S = ...l_1(A) r_1(A) u_1(A) ... l_2(A) r_2(A) u_2(A) ...$$

Do not conflict

## **Shared locks**

#### So far:

$$S = ...I_1(A) r_1(A) u_1(A) ... I_2(A) r_2(A) u_2(A) ...$$

Do not conflict

#### Instead:

$$S = ... Is_1(A) r_1(A) Is_2(A) r_2(A) .... us_1(A) us_2(A)$$

## Lock actions (Shared, Exclusive)

I-t<sub>i</sub>(A): lock A in t mode (t is S or X)

u-t<sub>i</sub>(A): unlock t mode (t is S or X)

#### **Shorthand:**

u<sub>i</sub>(A): unlock whatever modes
T<sub>i</sub> has locked A

### Rule #1 Well formed transactions

$$T_i = ... I-S_1(A) ... r_1(A) ... u_1(A) ...$$

$$T_i = ... I-X_1(A) ... w_1(A) ... u_1(A) ...$$

 What about transactions that read and write same object?

Option 1: Request exclusive lock  $T_i = ...l-X_1(A) ... r_1(A) ... w_1(A) ... u(A) ...$ 

 What about transactions that read and write same object?

# Option 2: Upgrade

(E.g., need to read, but don't know if will write...)

- Drop S, get X lock

# Rule #2 Legal scheduler

$$S = \dots I - S_i(A) \dots \dots u_i(A) \dots$$

$$no \ I - X_j(A)$$

$$S = \dots I - X_i(A) \dots \dots u_i(A) \dots$$

$$no \ I - X_j(A)$$

$$no \ I - X_j(A)$$

$$no \ I - S_j(A)$$

# A way to summarize Rule #2

#### Compatibility matrix

Comp

	S	X
S	true	false
X	false	false

## Rule # 3 2PL transactions

No change except for upgrades:

- (I) If upgrade gets more locks  $(e.g., S \rightarrow \{S, X\})$  then no change!
- (II) If upgrade releases read (shared) lock (e.g.,  $S \rightarrow X$ )
  - can be allowed in growing phase

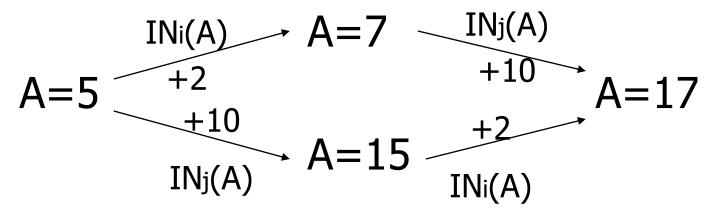
# Lock types beyond S/X

#### Examples:

- (1) increment lock
- (2) update lock

# Example (1): increment lock

- Atomic increment action: IN<sub>i</sub>(A)
   {Read(A); A ← A+k; Write(A)}
- IN<sub>i</sub>(A), IN<sub>j</sub>(A) do not conflict!



# Comp

	S	X	I
S			
X			
Ι			

# Comp

	S	X	I
S	Т	F	F
X	F	F	F
Ι	F	F	Т

# <u>Update locks</u>

A common deadlock problem with upgrades:

# **Solution**

If Ti wants to read A and knows it may later want to write A, it requests update lock (not shared)

## New request

Comp
S X U
S
Lock
already
held in

## New request

# Note: object A may be locked in different modes at the same time...

$$S_1=...I-S_1(A)...I-S_2(A)...I-U_3(A)...$$
  $I-S_4(A)...$ ?  $I-U_4(A)...$ ?

Note: object A may be locked in different modes at the same time...

$$S_1=...I-S_1(A)...I-S_2(A)...I-U_3(A)...$$
  $I-S_4(A)...$ ?  $I-U_4(A)...$ ?

 To grant a lock in mode t, mode t must be compatible with all currently held locks on object

#### How does locking work in practice?

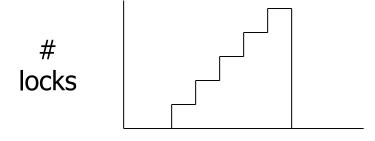
Every system is different

```
(E.g., may not even provide CONFLICT-SERIALIZABLE schedules)
```

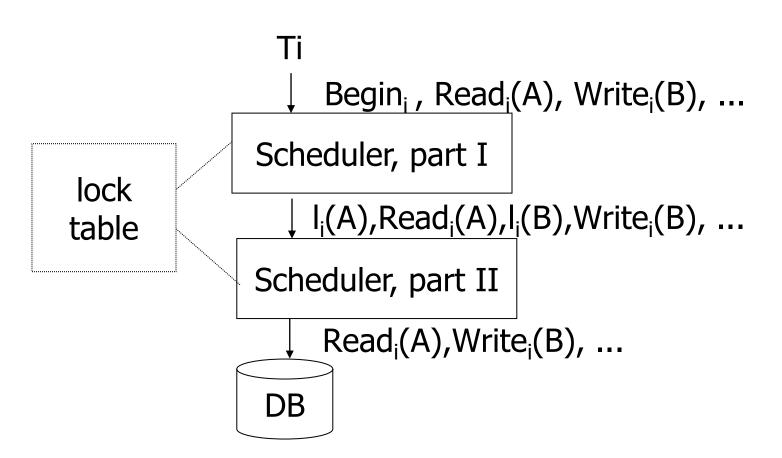
But here is one (simplified) way ...

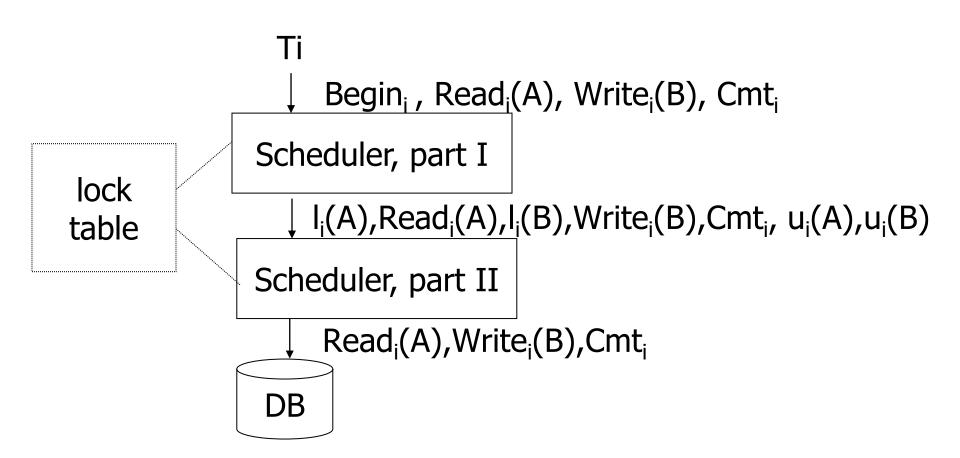
#### Sample Locking System:

- (1) Don't trust transactions to request/release locks
- (2) Hold all locks until transaction commits

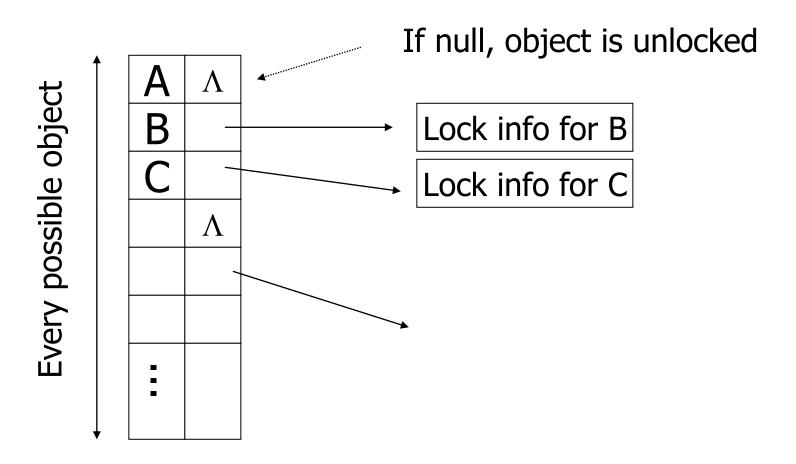


time

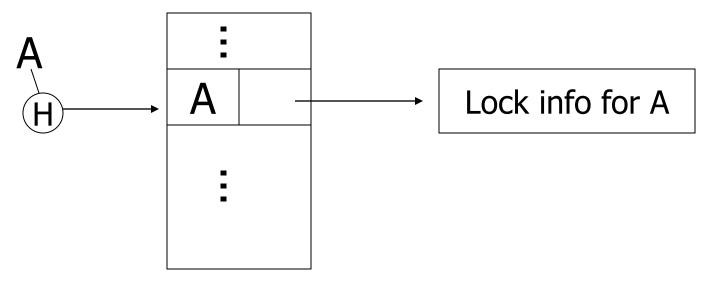




### Lock table Conceptually

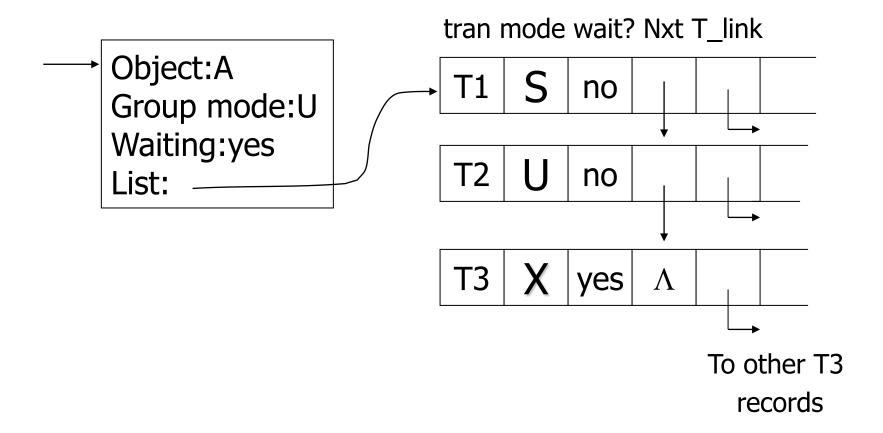


#### But use hash table:



If object not found in hash table, it is unlocked

### Lock info for A - example



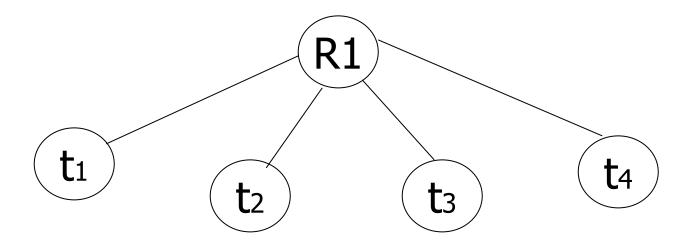
#### What are the objects we lock?

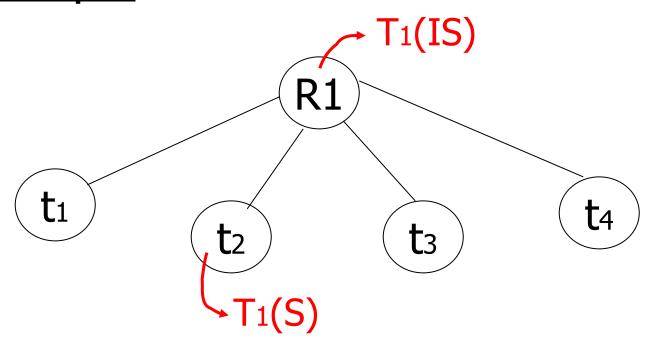
Tuple A Disk Relation A block Tuple B Α Tuple C Relation B Disk block В DB DB DB

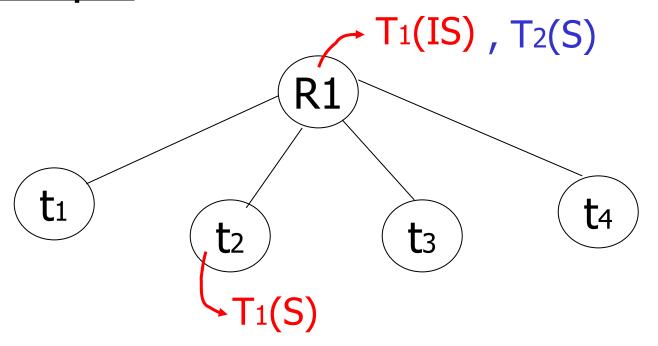
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 Locking works in any case, but should we choose <u>small</u> or <u>large objects?</u>  Locking works in any case, but should we choose <u>small</u> or <u>large objects?</u>

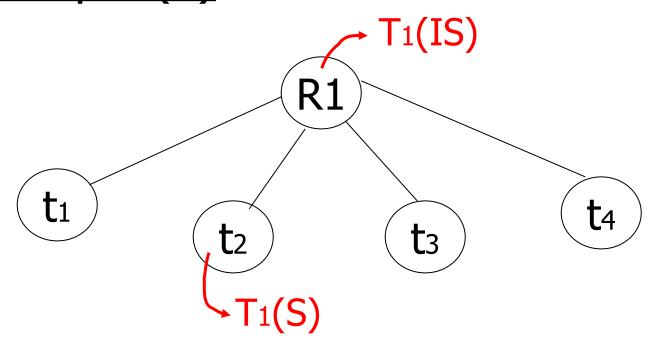
- If we lock <u>large</u> objects (e.g., Relations)
  - Need few locks
  - Low concurrency
- If we lock small objects (e.g., tuples, fields)
  - Need more locks
  - More concurrency

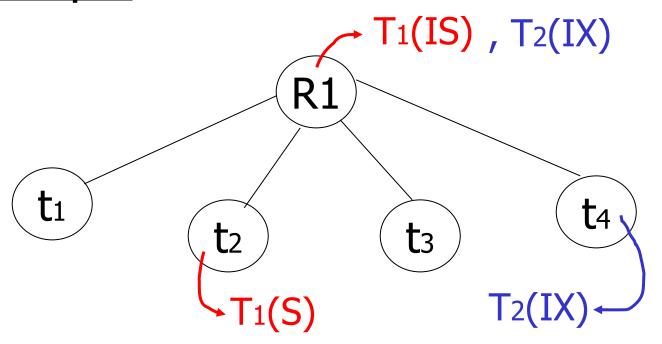






## Example (b)





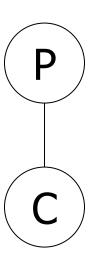
## Multiple granularity

Comp	Requestor					
		IS	IX	S	SIX	X
	IS					
Holder	IX					
	S					
•	SIX					
	X					

## Multiple granularity

Comp		Requestor				
		IS	IX	S	SIX	X
	IS	Т	Т	Т	T	F
Holder	IX	Т	Т	F	F	F
	S	Т	F	Т	F	F
	SIX	H	F	F	F	F
	X	F	F	F	F	F

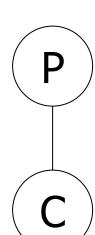
Parent locked in	Child can be locked in
IS	
IX	
S	
SIX	
X	



## Parent locked in

# Child can be locked by same transaction in

IS	IS, S
IX	IS, S, IX, X, SIX
S	none
SIX	X, IX, [SIX]
X	none

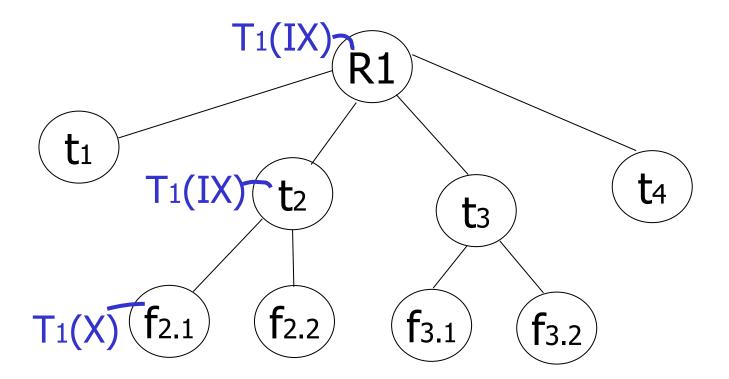


not necessary

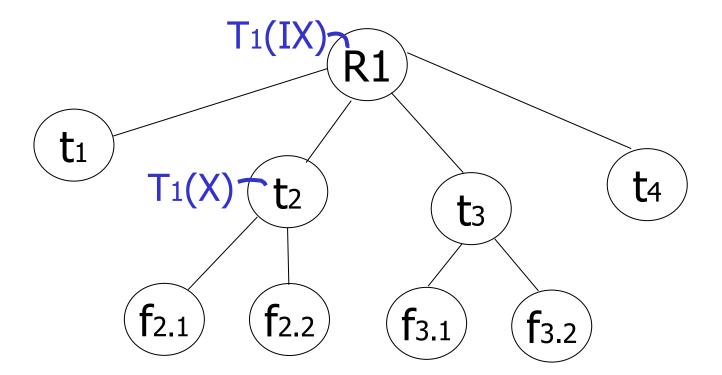
#### **Rules**

- (1) Follow multiple granularity comp function
- (2) Lock root of tree first, any mode
- (3) Node Q can be locked by Ti in S or IS only if parent(Q) locked by Ti in IX or IS
- (4) Node Q can be locked by Ti in X,SIX,IX only if parent(Q) locked by Ti in IX,SIX
- (5) Ti is two-phase
- (6) Ti can unlock node Q only if none of Q's children are locked by Ti

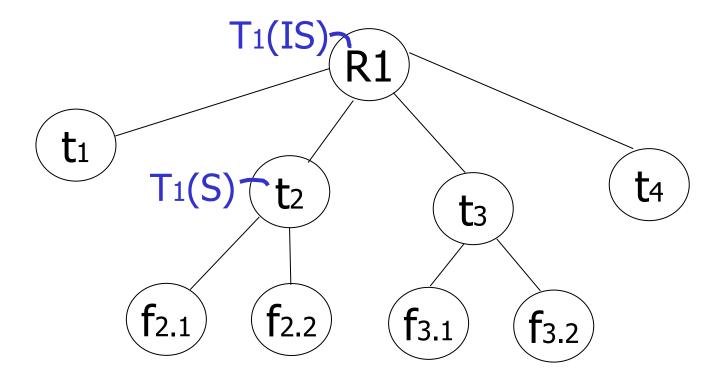
Can T<sub>2</sub> access object f<sub>2.2</sub> in X mode?
 What locks will T<sub>2</sub> get?



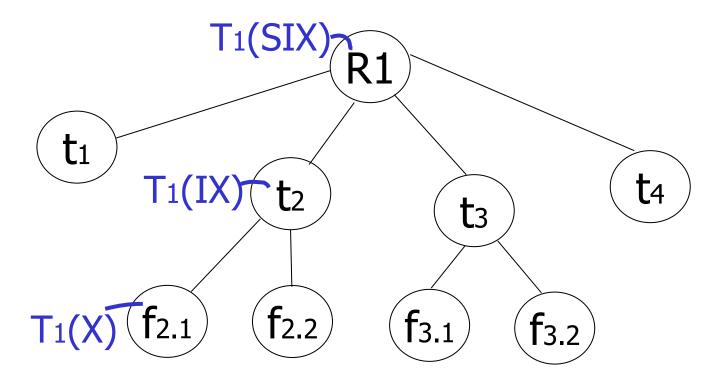
Can T<sub>2</sub> access object f<sub>2.2</sub> in X mode?
 What locks will T<sub>2</sub> get?



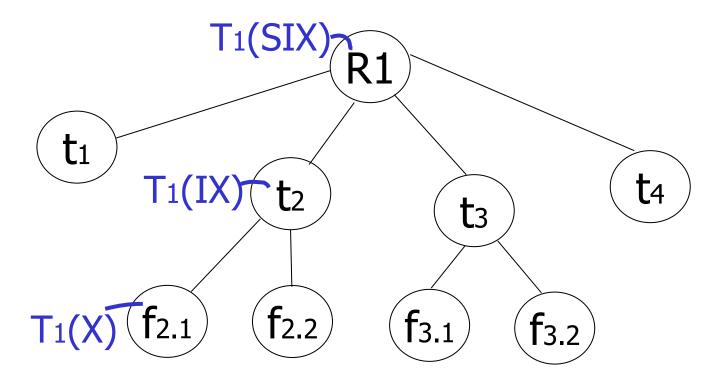
Can T<sub>2</sub> access object f<sub>3.1</sub> in X mode?
 What locks will T<sub>2</sub> get?



Can T2 access object f2.2 in S mode?
 What locks will T2 get?



Can T<sub>2</sub> access object f<sub>2.2</sub> in X mode?
 What locks will T<sub>2</sub> get?



## **Reading**

Ch18 Concurrency Control
Héctor García-Molina, Jeffrey Ullman, and
Jennifer Widom. Database Systems:
The Complete Book.