HW04

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P15 = 0.003)

$$Q \mid F_{or} P_{1} = \frac{Q}{1+Q^{2}} \Rightarrow \frac{Q}{3Q} P_{1} = \frac{-1(1+Q^{2})-(-Q)(2Q)}{(1+Q^{2})^{2}}$$

$$\Rightarrow \frac{Q^{2}-1}{(1+Q^{2})^{2}} = 0 \Rightarrow \begin{cases} Q = -1 \\ Q = 1 \end{cases} \Rightarrow \max P_{1} = \frac{1}{2} = 0.5$$

$$\min P_{1} = \frac{-1}{2} = (-0.5)$$

Q2(a)  

$$\phi_1 = 1$$
  
 $\phi_2 = (-0.5)$   $\Rightarrow \rho_1 = \frac{1}{1-(-0.5)} = \frac{2}{3} \times \frac{1}{2}$ 

(b)
$$\rho_{0} = \frac{\rho_{2} - \phi_{1} \rho_{1}}{\phi_{2}} = \frac{(-\frac{1}{3}) - (1)^{\frac{2}{3}}}{(-0.5)} = 0$$

$$\rho_{10} = -0.021$$

$$\rho_{2} = \frac{\phi_{1}^{2}}{1 - \phi_{2}} + \phi_{2} = \frac{(-0.5)^{2}}{1 - (-0.5)} + (-0.5) = \frac{-1}{3} \rho_{11} = -0.01$$

$$\rho_{3} = (-0.17)$$

$$\rho_{6} = 0.083$$

$$\rho_{13} = 0.005$$

$$\rho_{14} = 0.005$$

Q3(1)

Q3(2)

 $\phi(\beta)=0$ 

$$\phi(\beta) = 0$$

7 B= 2.

7 stationary & invertible \*

Q3(3)

Q3(4)

Q4(a) (1-B) 4x = (1-05B) at 4x = (1+B+B2+B3+ ...)(1-0.5B)al Yt = (1+0.5B+0.5B+0.5B3+ ... +0.5B3) at - at + 05 at-1 + 0.5 at-2 + 0.5 at-3 => P1 = P2 = P3 = 0.5 Q4(b) (1-B) Yt = (1-05B) at Qt = (1-B)(1+0.5 B+0.25B2+0.125 B3+ ... + 05 Bn) 4t > (1-0.5B-0.25B2-0.125B3+ ... -0.5"B") YX => yt = Ot +05 yx-1 +0.25 yz-2 + ... \$ 05 yt. ] 7 Tu = 0.5, Tu = 0.05, Tu = 0.125. Q4(c) Var (yt) = Var [ (1+0.5 = B) ) at] = Var(at)+0.25 × n × Var(at) = 1+0.25h > n > 0

7 Var(yt)= 0 \*

Q5
$$\forall \text{Vor}(\forall y_t) = \forall \text{vr}(y_t - y_{t-1}) = \forall \text{vr}(y_t) + \forall \text{vor}(y_{t-1}) - 2 \text{Cov}(y_t, y_t)$$

$$\forall 2(1-P_1) \forall \text{var}(y_t) \neq \text{When } P_1 < \frac{1}{2} \neq 2(1-P_1) > 1$$

$$\forall \text{Still follows a stationary process}$$

$$26.$$

$$(a) \neq y_t = \forall y_{t-1} + e_t = \forall (\forall y_{t-2} + e_{t-1}) + e_t$$

(a) 
$$= 4t = 44t - 1 + e_{t} = 4(44t - 2 + e_{t-1}) + e_{t}$$
  
=  $4t = 4t - 1 + e_{t}$ 

Finally 
$$y_t = \phi^t y_0 + e_t + \phi e_{t-1} + \dots + \phi^{t-1} e_1$$

$$E(y_{t}) = E(\phi^{t}y_{0} + e_{t} + \phi e_{t-1} + \phi^{2}e_{t-2} + ... \phi^{t-1}e_{1})$$

$$= \phi^{t} E(y_{0}) = \phi^{t} \cdot M_{0} \times$$

$$Var(y_{t}) = Var(\phi^{t}y_{0} + e_{t} + \phi e_{t-1} + .... \phi^{t-1}e_{1})$$

$$= \phi^{2t} \delta_{0}^{2} + \delta_{e}^{2} + \delta_{e}^{2} + \delta_{e}^{2t} + \delta_{e$$

Q6(d).

if 
$$M_0 = 0$$
 and  $\phi = 1 \Rightarrow V(Y_t) = V(Y_{t-1}) + E_e^2$   
 $\Rightarrow Variance becomes larger and larger
 $\Rightarrow ids \text{ impossible}.$$ 

Resulting  $Q_{t}(e)$ Since  $y_{t}$  is stationary  $\Rightarrow V(y_{t}) = \frac{1-\phi^{2t}}{1-\phi^{2}} = \frac{3e^{2t}}{(1-\phi^{2t})}$