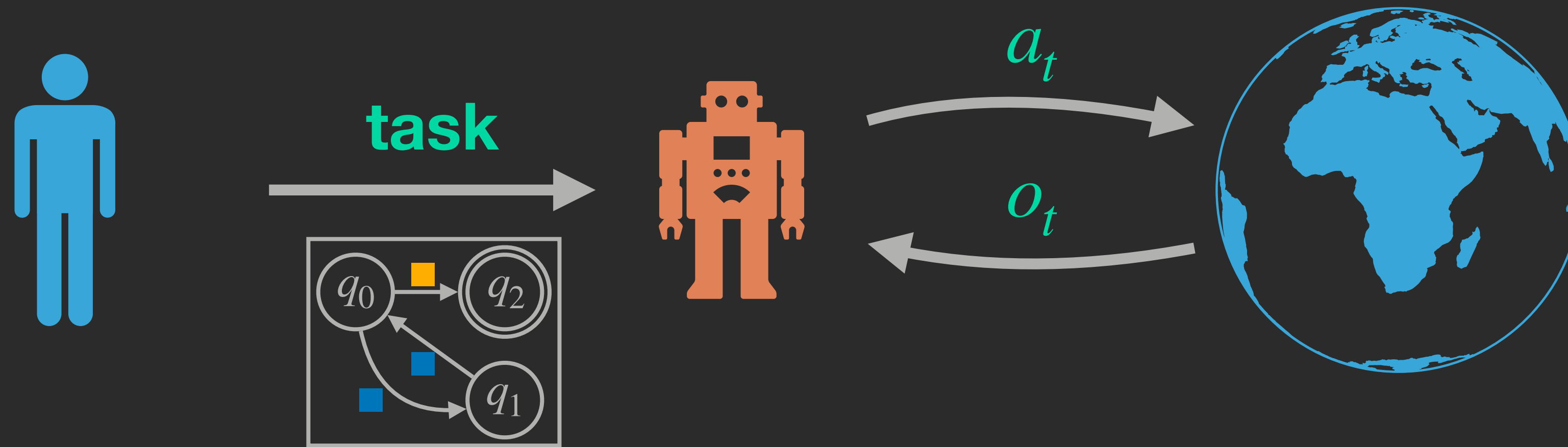# DFA-conditioned RL setting

DFA-conditioned RL setting

task

a_t

o_t

q_0 q_2

q_1

🟧 the robot picks up the coffee cup