Rafay Lamir Bsee 19047 Control-Sys-Assignment 1

$$y = PV + dz$$

$$J = PK(Y+d_1-y)+d_2$$

$$J = PK(Y+di-y)+d2 \Rightarrow PKY+PKdi-PKY+d2$$

$$J(1+PK) = PK(Y+di) + d2$$

$$J = PK(Y+di) + d2$$

$$J = \frac{PK(r+di)}{(1+PK)} + d2$$

$$J = \frac{PK(r+di)}{(I+PK)} + \frac{d2}{(I+PK)} - , K = \frac{y-d2}{P(r+di-y)} - \frac{1}{P(r+di-y)}$$

(b) Yes we can, as the system is working under the feedback control loop so eventually output will become equals to the desired value, 
$$(y=r)$$

$$K = \frac{9.9 - 3}{5(10 - 9.9)}$$
 $K = \frac{13.8}{5}$ 

$$K = \frac{9.5 - 3}{5(1000 10 - 9.5)}$$
,  $K = 2.6$ 

## Rafay Lamir

Bsee 19047

Control systems Al

Q:-1



$$y = p(u+d_2)$$

$$y = p(Ke + dz)$$

$$y = P(K(y+d_1-y)+d_2)$$
 \_ 0

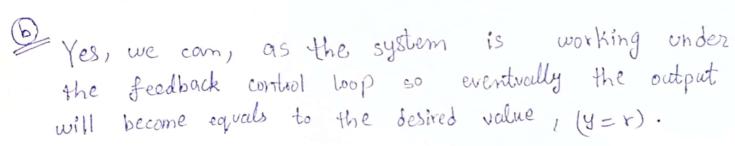
$$y + Pky = P(Kr + Kd_1 + d_2)$$

$$J = P(Kr + Kd_1 + d_2)$$

$$I + PK$$

$$J = \frac{P(Kr + Kd_1 + d_2)}{1+PK}, K = \frac{y - Pd_2}{P(r + d_1 - y)}$$

r. + 01 e K u + 02 P



$$0 K = ? , Y = 9.9$$

$$K = 9.9 - 5x3 = [-10.2]$$

$$5(10 - 9.9)$$

(ii) 
$$K=3$$
,  $Y=9.5$   
 $K=\frac{9.5-5\times3}{5(10-9.5)}=-2.2$ 

$$9' = 34$$

Solve

$$s^{3}y(s) = 3u(s)$$
  
 $\frac{y(s)}{u(s)} = \frac{3}{c^{3}}$ 

$$\bigcirc$$
  $2\ddot{y} = 5\dot{u} + 9u$ .

$$28^{2} y(s) = 58 u(s) + 9 u(s)$$

$$\frac{y(s)}{u(s)} = \frac{58 + 9}{28^{2}}$$

$$s y(s) = u(s) + \frac{1}{s}$$
  
 $\frac{y(s)}{u(s)} = \frac{(s+1)}{s^2}$ 

$$\frac{solve}{s(y(s))} = u(s) + 1u(s)$$

$$\frac{y(s)}{u(s)} = \frac{2}{s}$$

$$solve$$
 $sy(s) = u(s)$ 

$$\frac{y(s)}{u(s)} = \frac{1}{s}$$

$$\bigcirc G(S) = \frac{1}{(S+1)^2}$$

Solve By ILT

$$G(t) = teu(t)$$

(b) 
$$G(s) = \frac{s+1}{s^2 + 3s + 1}$$

$$= \frac{841}{84354541} \frac{8+1}{8^2+35+1}$$

$$= \frac{s + \frac{3}{2}}{\left(s + \frac{3}{2}\right)^2 - \frac{5}{4}} - \frac{\left(s + \frac{3}{2}\right)^2 - \frac{5}{4}}{\left(s + \frac{3}{2}\right)^2 - \frac{5}{4}}$$

Inverse Lapla ce:

$$= e^{\frac{3t}{2}} \cosh\left(\frac{15t}{2}\right) - \frac{1}{2} e^{\frac{3t}{2}} \sinh\left(\frac{15t}{2}\right)$$

$$G(t) = \begin{bmatrix} -\frac{3t}{2} \\ e^2 \cosh\left(\frac{15t}{2}\right) - \frac{1}{2} e^2 \sinh\left(\frac{15t}{2}\right) u(t) \end{bmatrix}$$

Impulse response graph:

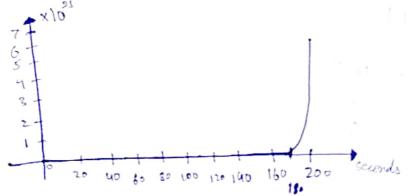
$$G(s) = \frac{1}{s^2 + 3s - 1}$$

$$G(s) = \frac{1}{(s+\frac{3}{2})^2 - \frac{13}{4}}$$

2 4 6 8 10 12 seconds

inverse laplace

$$G(t) = e^{\frac{3t}{2}} \sinh\left(\frac{\sqrt{13}t}{2}\right)u(t)$$



$$Q_{\circ}^{\circ} - 4$$
 $Q_{\circ}^{\circ} - 4$ 
 $Q_{\circ}^{\circ} -$ 

$$\ddot{y} + 3\ddot{y} + 2\dot{y} + y = 5u$$

Let 
$$x_1 = y$$
 ,  $x_2 = y$  ,  $x_3 = y$  ,  $x_4 = x_2 = y$  ,  $x_2 = x_3 = y$ 

and 
$$x_3 = y = 5u - 3x_3 - 2x_2 - x_1$$

$$\dot{x} = Ax + Bu$$
,  $\dot{y} = Cx + D$ 

$$\dot{\chi} = \begin{bmatrix} \dot{\chi}_1 \\ \dot{\chi}_2 \\ \dot{\chi}_3 \end{bmatrix} , \chi = \begin{bmatrix} \chi_1 \\ \chi_2 \\ \chi_3 \end{bmatrix}$$

$$\dot{\chi} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -1 & -2 & -3 \end{bmatrix} \begin{bmatrix} \chi_1 \\ \chi_2 \\ \chi_3 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 5 \end{bmatrix} \omega$$

$$J = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} \chi_1 \\ \chi_2 \\ \chi_3 \end{bmatrix} + 0$$

Now from the next questions and onwards i will be writing the SSR directly just to save time

(b) 
$$G(s) = \frac{w^2}{s^2 + 2 Sws + w^2}$$
solve

$$\dot{x} = \begin{bmatrix} 0 & 1 \\ -\omega^2 & -\omega^2 \end{bmatrix} \begin{bmatrix} \chi_1 \\ \chi_2 \end{bmatrix} + \begin{bmatrix} 0 \\ \omega^2 \end{bmatrix} u$$

$$y = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} \chi_1 \\ \chi_2 \end{bmatrix} + 0$$

© 
$$G(s) = \frac{s+1}{s^2 + 3s + 2}$$
  
 $G(s) = \frac{1}{s^2 + 3s + 2}$ 

$$G(s) = \frac{1}{s^2 + 3s + 2} (s+1)$$

$$\frac{1}{5^2 + 3s + 2} (s+1)$$

$$\frac{1}{5} + 3\frac{1}{5} + 2\frac{1}{5} = 4$$

$$x_1 = \overline{y}$$
,  $x_2 = \dot{\overline{y}}$ ,  $\dot{x}_1 = x_2 = \dot{\overline{y}}$ ,  $\dot{x}_2 = \ddot{\overline{y}} = u - 2\overline{y} - 3\dot{\overline{y}}$ 

$$y = 3\dot{y} + 2\ddot{y} = 3$$

$$y = \frac{1}{y} + 2\overline{y} = 2x_1 + x_2$$

$$\dot{x} = \begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} \begin{bmatrix} u \\ u \end{bmatrix}$$

$$y = \begin{bmatrix} 2 & 1 \end{bmatrix} \begin{bmatrix} \chi_1 \\ \chi_2 \end{bmatrix} + 0$$

$$\dot{\chi} = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} \begin{bmatrix} \chi_1 \\ \chi_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u$$

$$y = \left[2 \quad 1\right] \left[\frac{x_1}{x_2}\right]$$

 $\frac{U(3)}{s^2+3s+2}$   $\frac{1}{Y(3)}$   $\frac{1}{S+2}$ 

$$G(s) = \frac{1}{s^3 - 3s^2 - 17s + 49} \times \left[0 + 0 + 21s^2 - 126s + 231\right] + 9$$

$$G(s) = \frac{21s^2 - 126s + 231}{s^3 - 3s^2 - 17s + 49}$$

$$G(s) = \frac{9s^3 + -6s^2 - 297s + 672}{s^3 - 3s^2 - 17s + 49}$$