

# AEMPY: A Python Toolbox for Frequency- and Time-Domain Electromagnetic Data from the TELLUS Surveys



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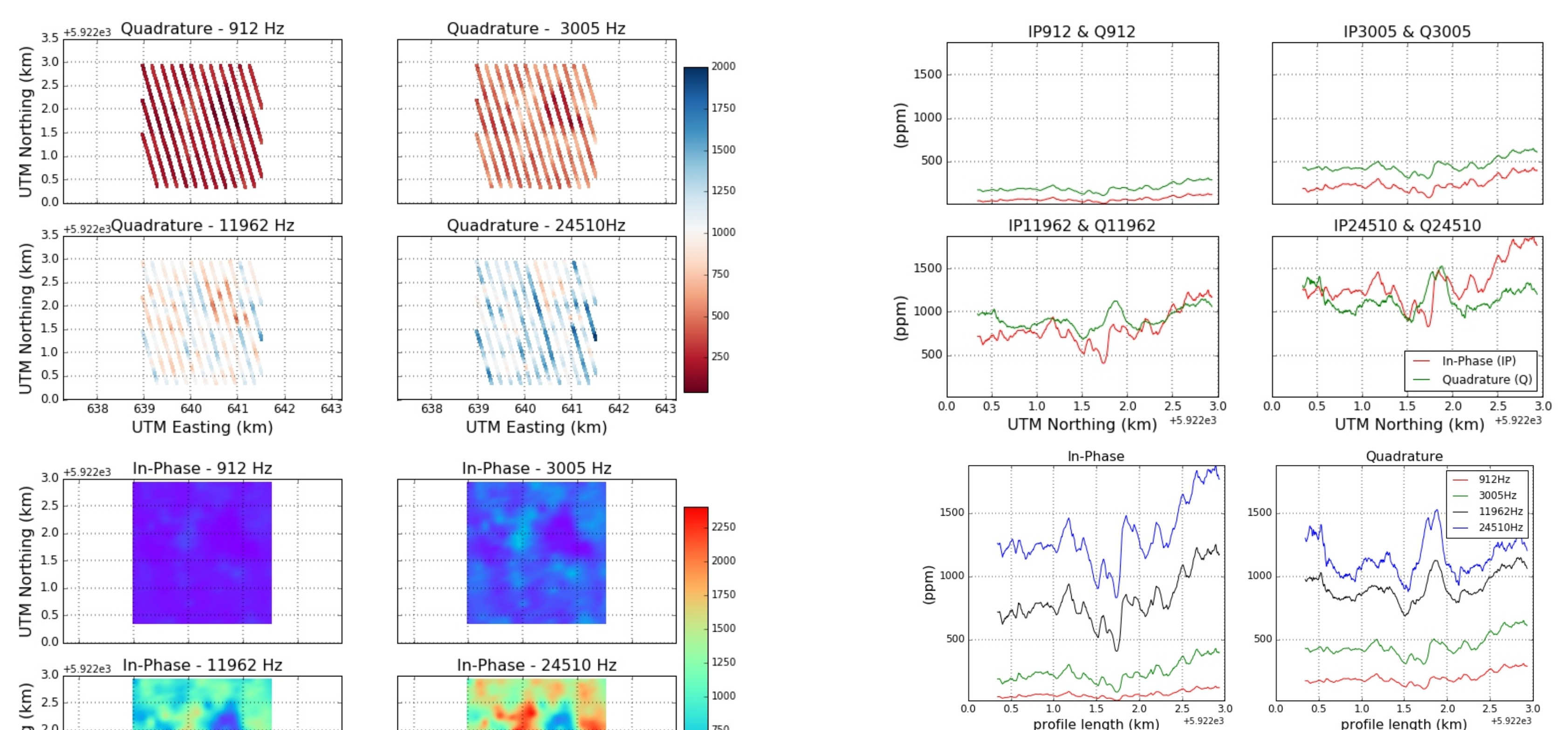


## ABSTRACT

The frequency- and time-domain Airborne ElectroMagnetic (AEM) data collected under the Tellus surveys of the Geological Survey of Ireland (GSI) represent a wealth of information on the multi-dimensional electrical structure of Ireland's near-surface. Our project, which was funded by the Short Call Research Programme of the GSI (sc2015-004), aims to develop and implement inverse techniques based on various Bayesian methods for the densely sampled Tellus data.

We have developed a highly flexible toolbox using Python language for the one-dimensional inversion of AEM data along the flight lines. The computational core is based on an adapted frequency- and time-domain forward modelling core derived from the well-tested open-source code AirBeo, which was developed by the CSIRO (Australia) and the AMIRA consortium. Three different methods have been implemented: (i) Tikhonov-type inversion including optimal regularisation methods (Aster et al., 2012; Zhdanov, 2015), (ii) Bayesian MAP inversion in parameter and data space (e.g. Tarantola, 2015), and (iii) Full Bayesian inversion with Markov Chain Monte Carlo (e.g. Sambridge and Mosegaard, 2002), all including different forms of spatial constraints. The methods have been tested on synthetic and field data. This contribution will introduce the toolbox and present case studies on the AEM data from the Tellus surveys.

## DATA VISUALISATION



## IMPLEMENTATION

Python  
Modules and Scripts  
Numpy, Scipy, Matplotlib

DIAS GIT Repository  
Free Access (Coming Soon!)



**Input File**  
Tellus  
FDEM & TDEM Data

### Conversion to Internal Data Format

#### FDEM Format

XUTM, YUTM, GPS, RADAR, IP912-24510Hz, Q912-24510Hz, PWLM

#### TDEM Format

XUTM, YUYM, GPS, RADAR, X1-X11, Z1-Z11

#### Define Dataset:

flightline, polygon, profile projection

## AEMPY

### Pre-processing

- Flag negative values & high fly areas
- Interpolate
- Average/Block data over a number of stations

### Bayesian Inversion along Flightline

#### Deterministic Approach

Tikhonov-type inversion  
MAP inversion  
Truncated SVD inversion

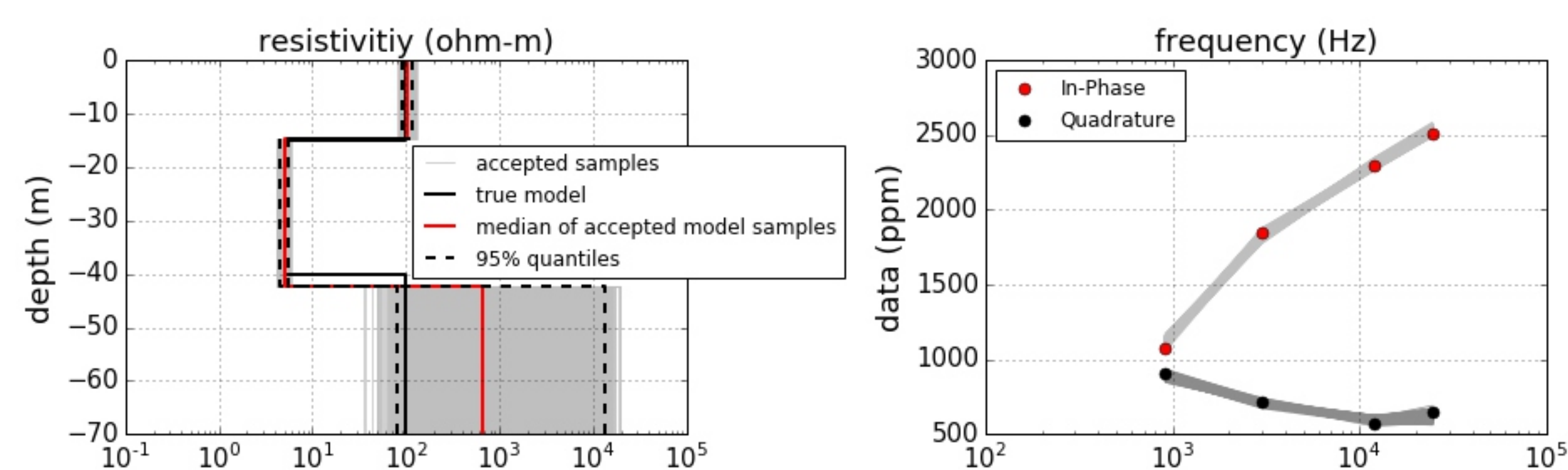
#### Stochastic Approach

Markov Chain Monte Carlo

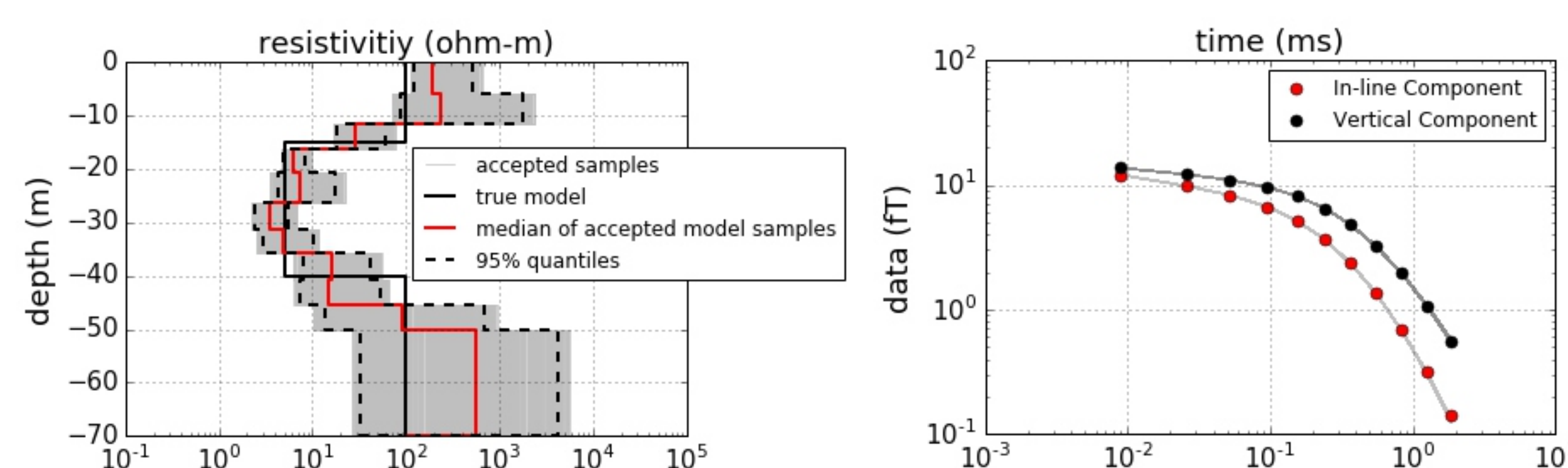
## DATA INVERSION

### THE METROPOLIS-HASTINGS ALGORITHM

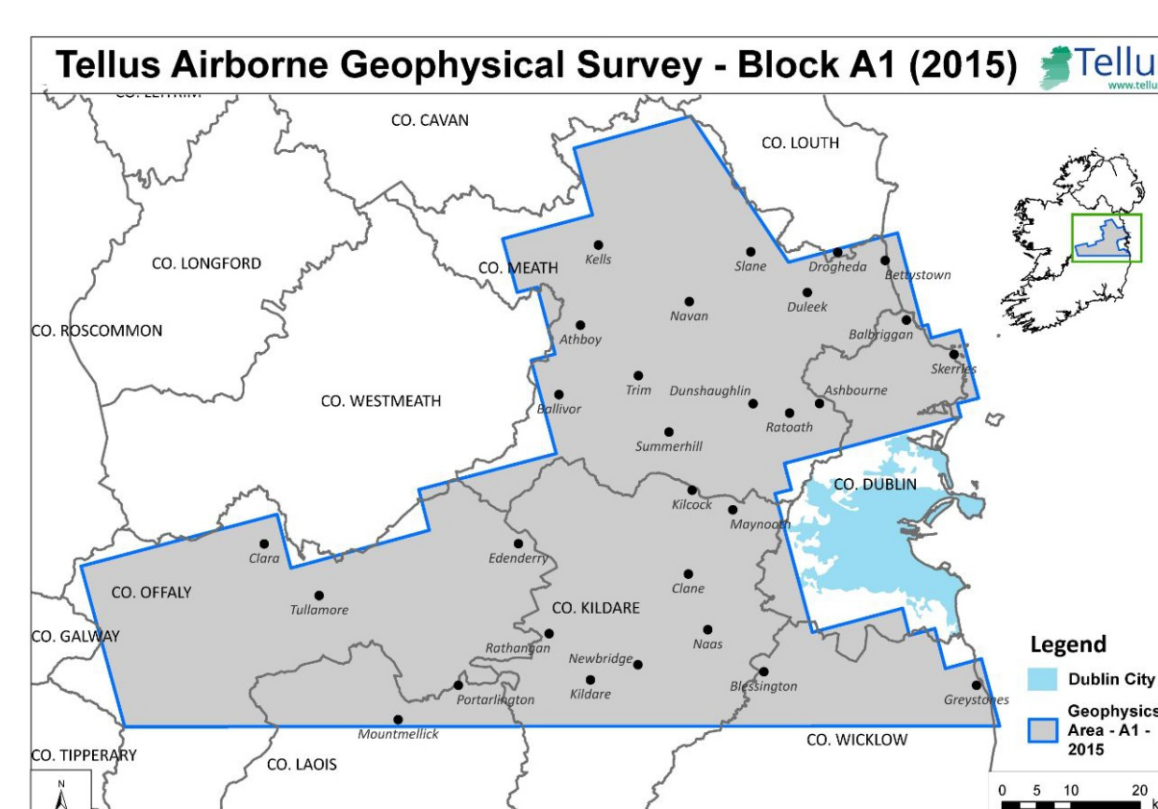
#### Synthetic Data - Frequency-Domain Results



#### Time-Domain Results

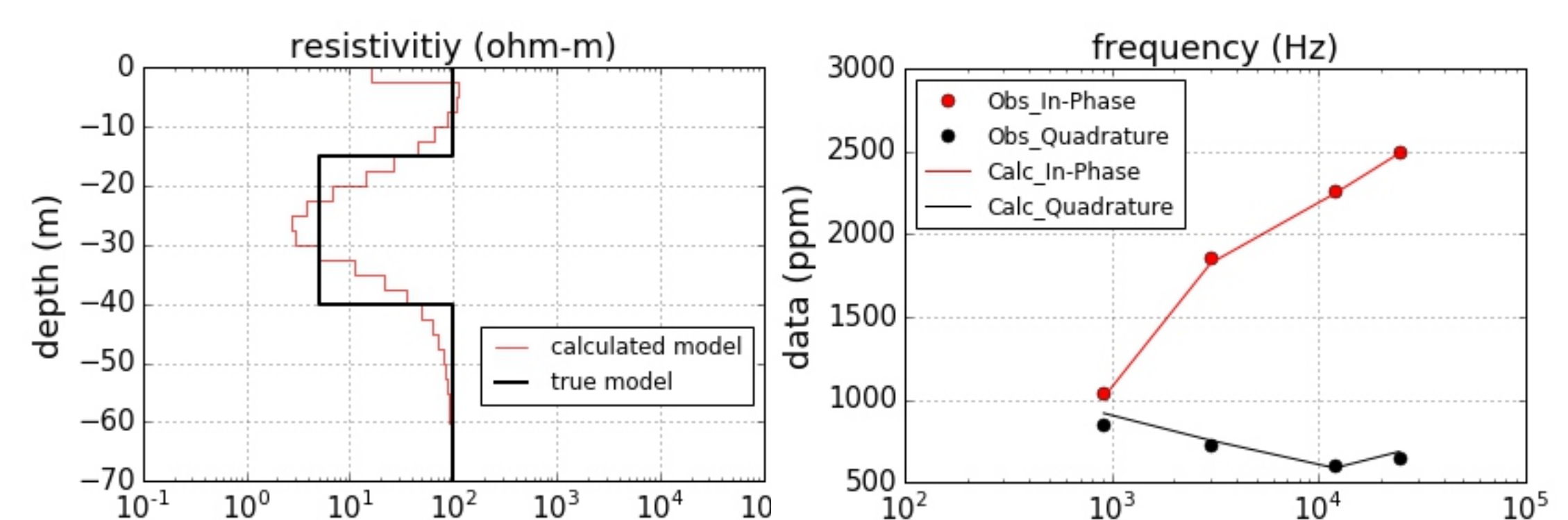


**Figure** shows a summary of the output from the Metropolis-Hastings (MH) simulation. The MH algorithm was run for 100,000 model samples and 1,000,000 model samples for frequency- and time-domain, respectively. **The left panel** shows every 50th and 500th of accepted sample models (light grey lines) for frequency- and time-domain, respectively. Superimposed are the true model (black line), bounds that contain 95 per cent of the accepted models (black dashed lines), and the median resistivity values (red line). **The right panel** illustrates the data fit in which the predicted data are represented with light and dark grey lines, and the observed data are represented with the solid circles.

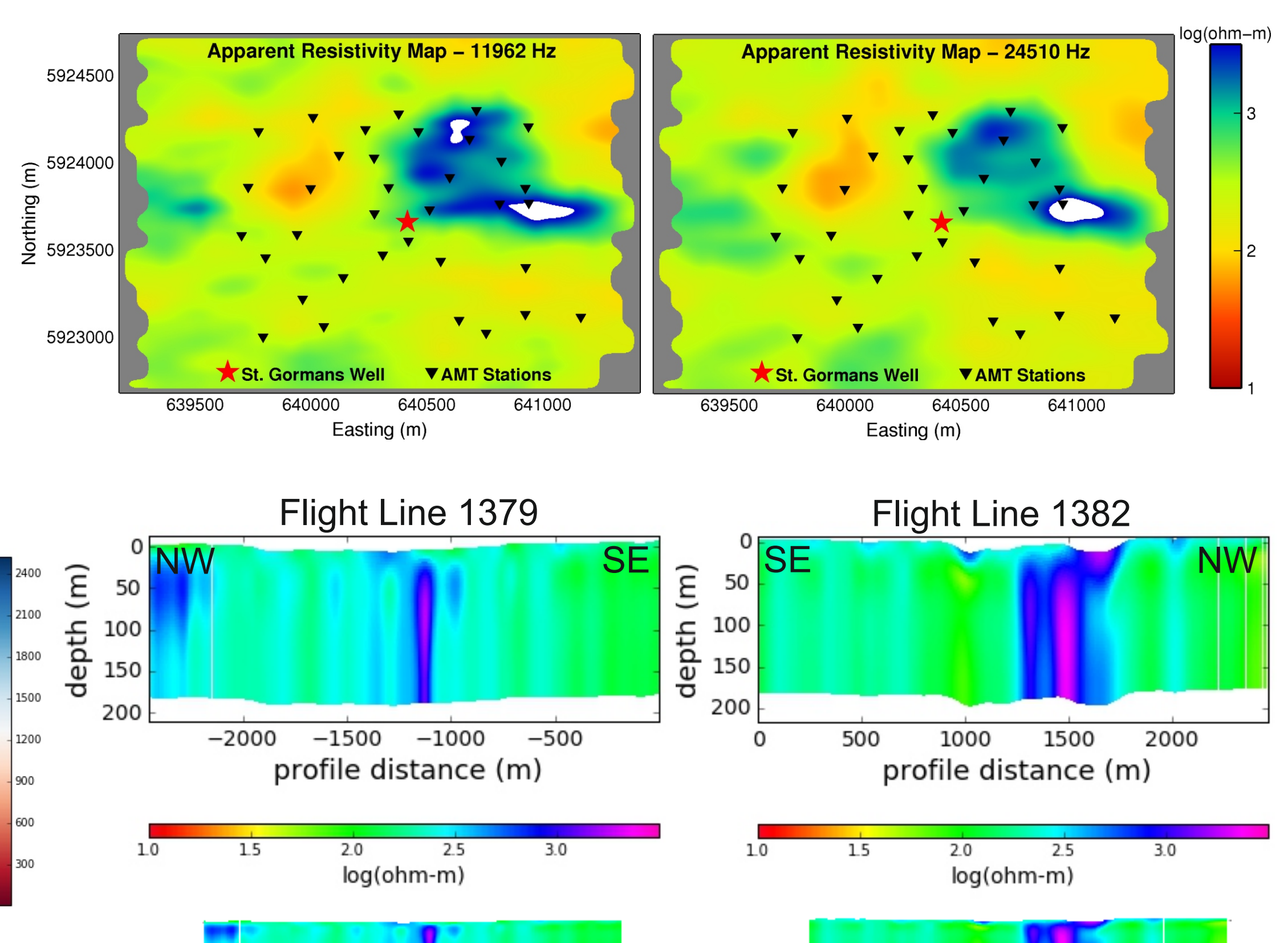


### DETERMINISTIC MAP INVERSION

#### Synthetic Data - Frequency-Domain Results



### TELLUS BLOCK A1 DATA



## CONCLUSIONS

Framework for the state of the art forward modelling for both frequency- and time-domain.

Inverse models of different types have been implemented as stochastic (e.g. MH sampling) or deterministic (Tikhonov, MAP, and TSVD).

Algorithms were tested with synthetic and field data from Tellus Block A1.

Visualisation tools for the evaluation of the results are available in the toolbox. Basic mapping capabilities have also been implemented in the toolbox.

## ACKNOWLEDGEMENTS

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