

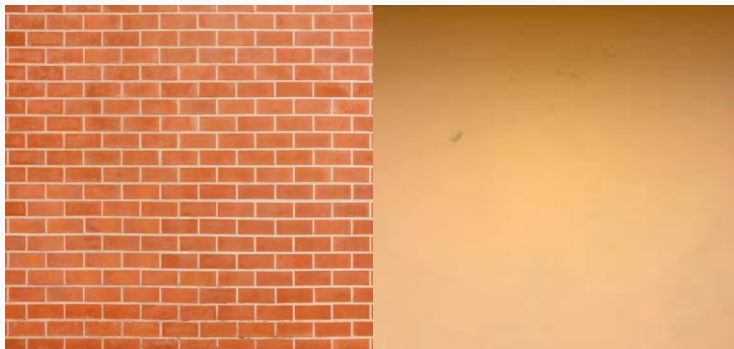
Gray Level Co- occurrence Matrix (GLCM)

CSE523 – Digital Image Processing

Gray Level Co-occurrence (GLCM)

Texture:

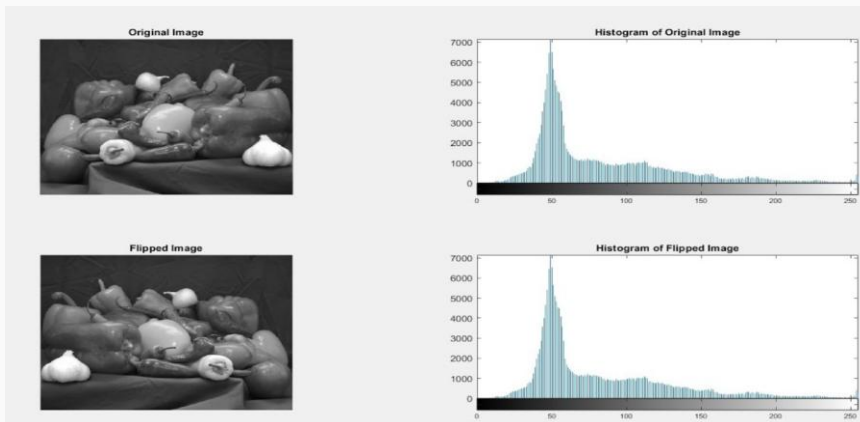
- ❑ Texture in an image means how a surface looks and feels visually – whether it appears smooth, rough, bumpy, or patterned.
- ❑ Texture comes from how pixel values change and repeat in a small area of the image.



Gray Level Co-occurrence (GLCM)

Background:

- ❑ An image histogram only counts how many times an intensity occurs, but not where it occurs.
- ❑ Many textures have similar histograms but different spatial patterns.



Keynote:

Texture is determined not only by intensities but by their relationship.

Gray Level Co-occurrence (GLCM)

Background :

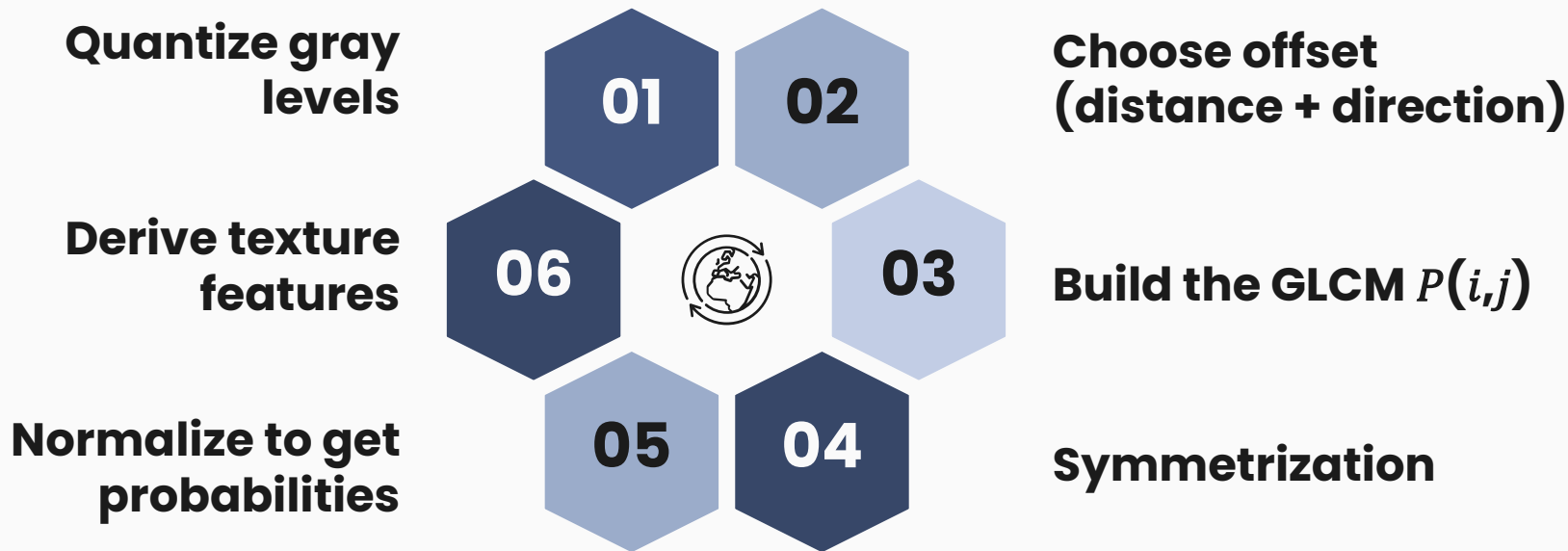
- ❑ By studying texture, a computer can understand what kind of surface is in an image.
- ❑ This helps in tasks like finding objects, separating regions, or identifying diseases in medical images.
- ❑ Methods like GLCM and LBP help computers measure these texture patterns automatically.

Gray Level Co-occurrence (GLCM)

GLCM:

- ❑ GLCM (Gray Level Co-occurrence Matrix) captures how often pairs of gray levels occur next to each other in a specific direction and distance.
- ❑ It encodes spatial relationships between pixels → good for texture analysis.
- ❑ It is simple and interpretable:
 - ❖ the matrix itself is just co-occurrence counts;
 - ❖ from it we derive well-known features (contrast, energy, homogeneity, correlation, etc.).

Main Mechanism of GLCM



Main mechanism of GLCM

Consider a grayscale image $I(x,y)$ with gray levels $0, 1, \dots, L - 1$.

Step 1: Quantize gray levels

- ❑ For an 8-bit image (0–255), we might reduce it to, say, $L = 16$ or $L = 8$ levels to keep the matrix size manageable.
- ❑ After quantization, every pixel has value in $\{0, 1, \dots, L - 1\}$.

- ❑ Quantization formula: $new_pixel = \frac{old_pixel}{Current\ range \div New\ range}$

$$I = \begin{bmatrix} 10 & 10 & 80 & 90 \\ 15 & 200 & 210 & 85 \\ 20 & 205 & 215 & 95 \\ 25 & 30 & 100 & 110 \end{bmatrix}$$

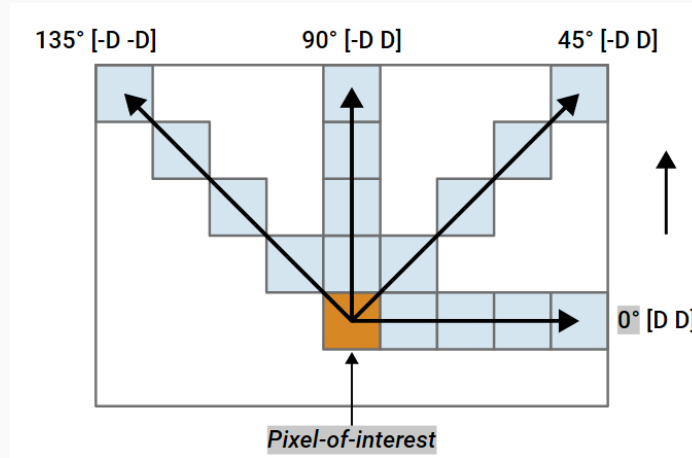
$$I_q = \begin{bmatrix} 0 & 0 & 1 & 1 \\ 0 & 3 & 3 & 1 \\ 0 & 3 & 3 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

$L = 8 \text{ bit to } L = 4 \text{ bit}$

Main mechanism of GLCM

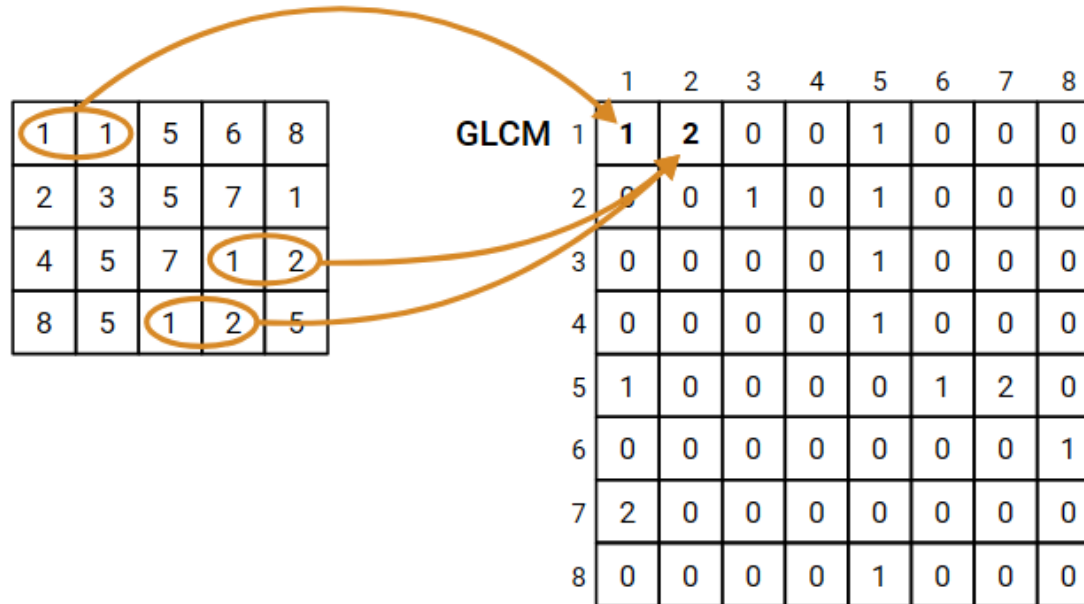
Step 2: Choose offset (distance + direction)

- ❑ Choose a distance d (e.g., 1 pixel, 2 pixels).
- ❑ Choose a direction θ :



Main mechanism of GLCM

Step 3: Build the GLCM $P(i,j)$



Main mechanism of GLCM

Step 4: Symmetrization

- ❑ Sometimes we count both directions:
- ❑ If we also count pairs (j, i) reverse direction, we might define a symmetric GLCM:

$$P_{sym}(i, j) = P(i, j) + P(j, i)$$

Step 5: Normalize to get probabilities

- ❑ To derive features, we often normalize:

$$p(i, j) = \frac{P(i, j)}{\sum_{i, j} P(i, j)}$$

- ❑ so that $\sum_{i, j} p(i, j) = 1$.

Main mechanism of GLCM

Step 6: Derive texture features

From the normalized GLCM $p(i, j)$, classic features include:

- ❑ **Contrast:** measures local intensity variation

$$\text{Contrast} = \sum (i - j)^2 p(i, j)$$

- ❑ **Energy** (Angular Second Moment):

$$\text{Energy} = \sum_{i,j} p(i, j)^2$$

- ❑ **Homogeneity** (Inverse Difference Moment):

$$\text{Homogeneity} = \sum_{i,j} \frac{p(i, j)}{1 + |i - j|}$$

- ❑ **Correlation:** measures how correlated neighboring gray levels are.

Example

We are given the 4×4 image,

- distance $d = 1$ pixel.
- Direction $\theta = 0^\circ$ (right side)

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3



P(i,j)	0	1	2	3
0	(0,0)	(0,1)	(0,2)	(0,3)
1	(1,0)	(1,1)	(1,2)	(1,3)
2	(2,0)	(2,1)	(2,2)	(2,3)
3	(3,0)	(3,1)	(3,2)	(3,3)

Example

Build the GLCM $P(i,j)$

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

For 0,0
→

$P(i,j)$	0	1	2	3
0	2			
1				
2				
3				

Example

Build the GLCM $P(i,j)$

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

For 0,1
→

$P(i,j)$	0	1	2	3
0	2	2		
1				
2				
3				

Example

Build the GLCM $P(i,j)$

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

For 0,2
→

$P(i,j)$	0	1	2	3
0	2	2	1	
1				
2				
3				

Example

Build the GLCM $P(i,j)$

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

For 0,3
→

$P(i,j)$	0	1	2	3
0	2	2	1	0
1				
2				
3				

Example

Build the GLCM $P(i,j)$

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

For 1,0
→

$P(i,j)$	0	1	2	3
0	2	2	1	0
1	0			
2				
3				

Example

Build the GLCM $P(i,j)$

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

For 1,1

$P(i,j)$	0	1	2	3
0	2	2	1	0
1	0	2		
2				
3				

Example

Build the GLCM $P(i,j)$

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

For 1,2
→

$P(i,j)$	0	1	2	3
0	2	2	1	0
1	0	2	0	
2				
3				

Example

Build the GLCM $P(i,j)$

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3

For 1,3
→

$P(i,j)$	0	1	2	3
0	2	2	1	0
1	0	2	0	0
2				
3				

Example

Build the GLCM $P(i,j)$

0	0	1	1
0	0	1	1
0	2	2	2
2	2	3	3



$P(i,j)$	0	1	2	3
0	2	2	1	0
1	0	2	0	0
2	0	0	3	1
3	0	0	0	1

Example

Symmetrization

2	2	1	0
0	2	0	0
0	0	3	1
0	0	0	1

CM of the image



2	0	0	0
2	2	0	0
1	0	3	0
0	0	1	1

Transpose CM of the
image



4	2	1	0
2	4	0	0
1	0	6	1
0	0	1	2

Symmetric GLCM

Example

Normalization

Sum of all elements = 24

4	2	1	0
2	4	0	0
1	0	6	1
0	0	1	2

Symmetric GLCM



0.167	0.083	0.0416	0
0.083	0.167	0	0
0.0416	0	0.25	0.0416
0	0	0.0416	0.083

Normalized GLCM

Example

Contrast

P(i,j)	0	1	2	3
0	0	1	4	9
1	1	0	1	4
2	4	1	0	1
3	9	4	1	0

$|I - J|^2$



0.167	0.083	0.0416	0
0.083	0.167	0	0
0.0416	0	0.25	0.0416
0	0	0.0416	0.083

Normalized GLCM p (i,j)



0	0.083	0.1664	0
0.083	0	0	0
0.1664	0	0	0.0416
0	0	0.0416	0

$|I - J|^2 \times p(i, j)$

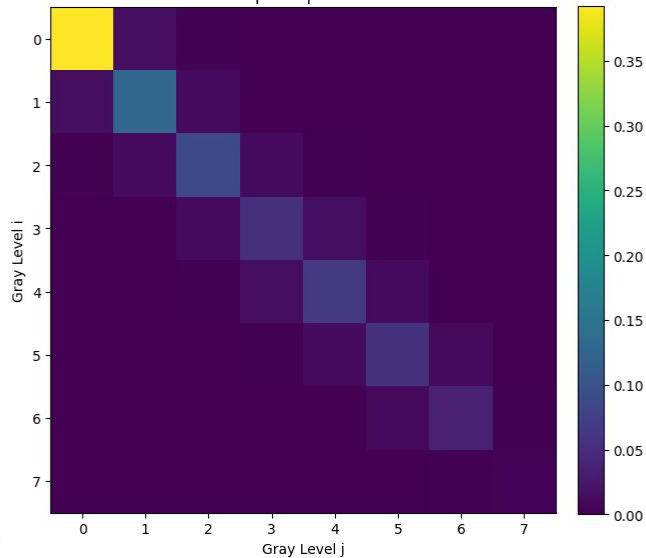
Contrast = 0.582

Example

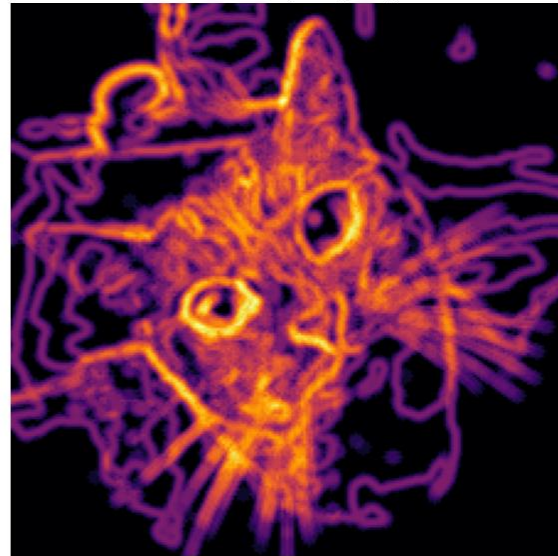
Original Image



GLCM Heatmap - 0° | Contrast = 0.2872



Local Texture (Entropy Map)



Advantages of GLCM

- ❑ **Captures texture, not just intensity**
 - ❖ Considers pairs of pixels → encodes spatial structure, helpful for distinguishing textures with similar histograms.
- ❑ **Flexible**
 - ❖ You can choose different directions and distances to capture anisotropic textures (e.g., vertical stripes vs horizontal stripes).
- ❑ **Interpretable features**
 - ❖ Features like contrast, energy, and homogeneity have intuitive meanings (rough vs smooth, homogeneous vs heterogeneous).

Limitations of GLCM

- ❑ **Parameter sensitivity**
 - ❑ Results depend on:
 - ❖ Number of gray levels L (quantization),
 - ❖ Choice of distance d ,
 - ❖ Choice of directions (0° , 45° , 90° , 135° , etc.).
- ❑ **High dimensionality for many gray levels**
 - ❖ For an 8-bit image with 256 gray levels, GLCM is $256 \times 256 \rightarrow 65,536$ entries per direction and distance \rightarrow heavy in memory and computation.
- ❑ **Not inherently rotation/scale invariant**
 - ❖ Changing the rotation of the image changes the GLCM unless you average over multiple directions.

Limitations of GLCM

- ❑ Sensitive to noise and illumination changes
 - ❖ Small changes in intensities (noise, illumination) can affect co-occurrence counts.
- ❑ Global unless localized
 - ❖ A single GLCM for the whole image may miss local variations; often people compute GLCM over moving windows, which increases computation.

Applications of GLCM

❑ Medical Imaging

- ❖ Tumor vs normal tissue classification in CT, MRI, ultrasound, histopathology, etc. GLCM features often help characterize tissue heterogeneity.

❑ Remote Sensing and Land Cover Classification

- ❖ Distinguish forests, urban areas, water bodies based on texture in satellite images.

❑ Industrial Inspection

- ❖ Detect surface defects (scratches, cracks, fabric defects, paper quality, etc.) from textures.

❑ Object Detection & Pattern Recognition

- ❖ Use GLCM features as inputs to machine learning models for object detection, texture classification, etc.

Local Binary Pattern (LBP)

CSE523 – Digital Image Processing

Local Binary Pattern (LBP)

LBP:

- ❑ Examine a pixel relative to its neighborhood:
 - ❖ Compare neighbor values to center pixel
 - ❖ Form binary pattern indicating structure
- ❑ It tells - are neighbors brighter or darker than the center?
- ❑ This effectively captures: Edges, Corners, Spots, Flat regions, Micro-texture.

Main mechanism of LBP

Consider a grayscale image $I(x,y)$

Step 1: Neighborhood (3×3 window)

P_0	P_1	P_2
P_7	P_c	P_3
P_6	P_5	P_4

Main mechanism of LBP

Step 2: $s(p_k - p_c)$

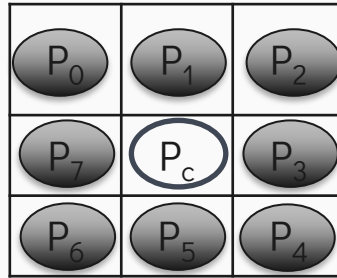
P_0	P_1	P_2
P_7	P_c	P_3
P_6	P_5	P_4

Step 3: Binary decision

$$s(x) = \begin{cases} 0, & x < 0 \\ 1, & x \geq 0 \end{cases}$$

Main mechanism of LBP

Step 2: $s(p_k - p_c)$

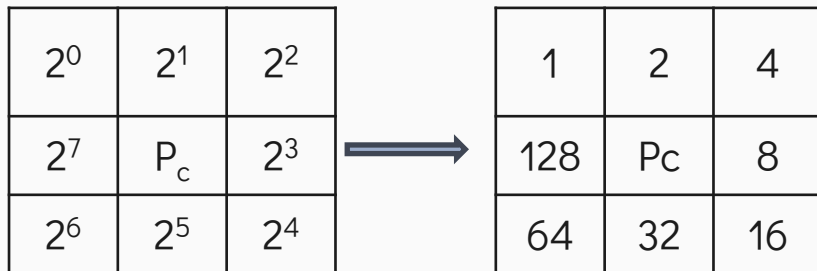


Step 3: Binary decision

$$s(x) = \begin{cases} 0, & x < 0 \\ 1, & x \geq 0 \end{cases}$$

Main mechanism of LBP

Step 4: 2^k matrix



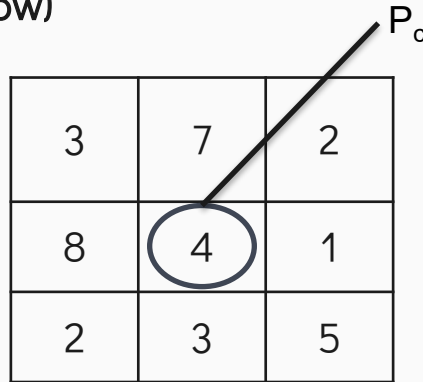
Step 5: LBP encoding

$$LBP(p_c) = \sum_{k=0}^{k=7} s(p_{kc} - p_c) \cdot 2^k$$

Example

Consider a grayscale image $I(x,y)$

Step 1: Neighborhood (3×3 window)

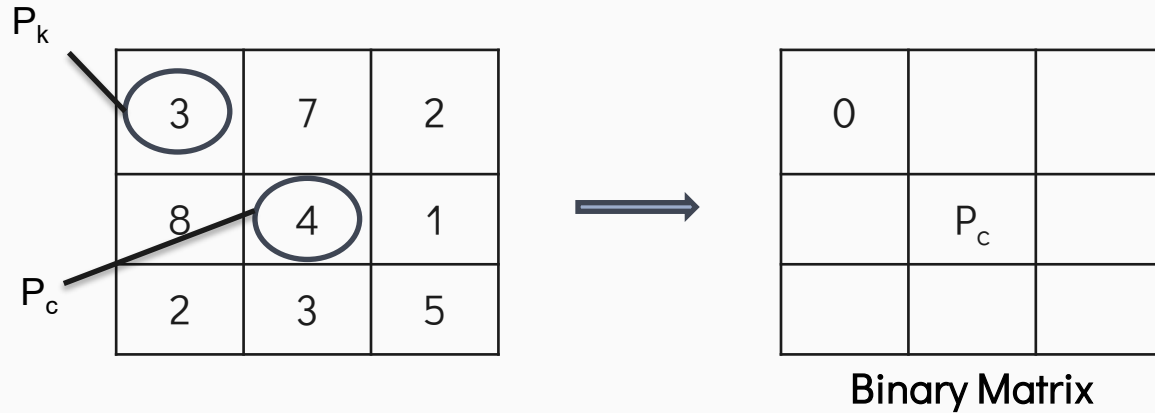


3	7	2
8	4	1
2	3	5

Example

Step 2: $s(p_k - p_c)$

$$s(x) = \begin{cases} 0, & x < 0 \\ 1, & x \geq 0 \end{cases}$$



Example

Step 2: $s(p_k - p_c)$

P_k

3	7	2
8	4	1
2	3	5

P_c



0	1	
	P_c	

Binary Matrix

$$s(x) = \begin{cases} 0, & x < 0 \\ 1, & x \geq 0 \end{cases}$$

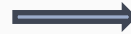
Example

Step 2: $s(p_k - p_c)$

P_k

3	7	2
8	4	1
2	3	5

P_c



0	1	0
	P_c	

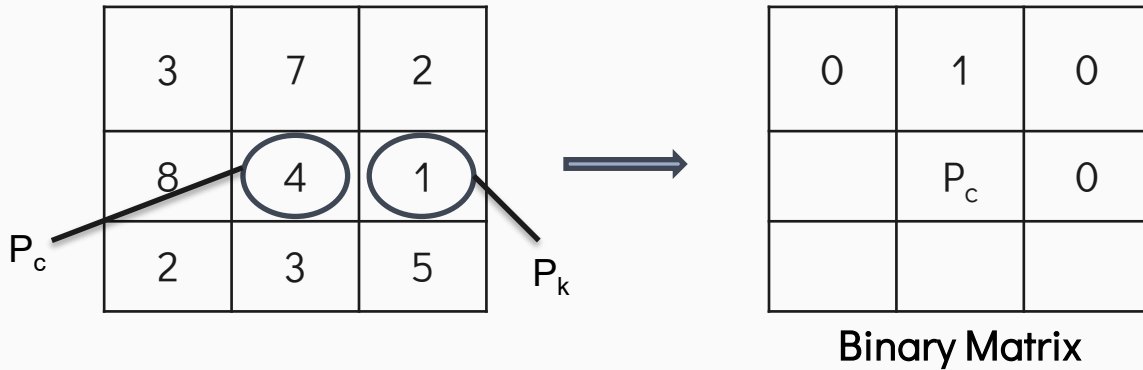
Binary Matrix

$$s(x) = \begin{cases} 0, & x < 0 \\ 1, & x \geq 0 \end{cases}$$

Example

Step 2: $s(p_k - p_c)$

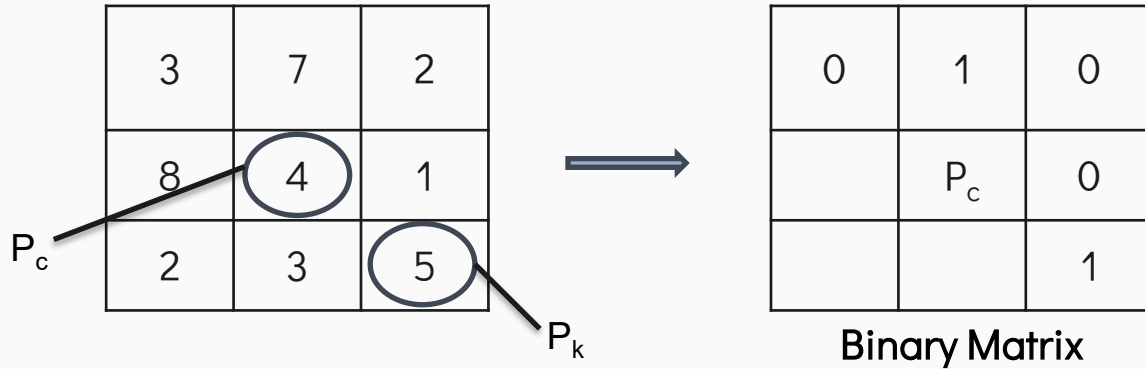
$$s(x) = \begin{cases} 0, & x < 0 \\ 1, & x \geq 0 \end{cases}$$



Example

Step 2: $s(p_k - p_c)$

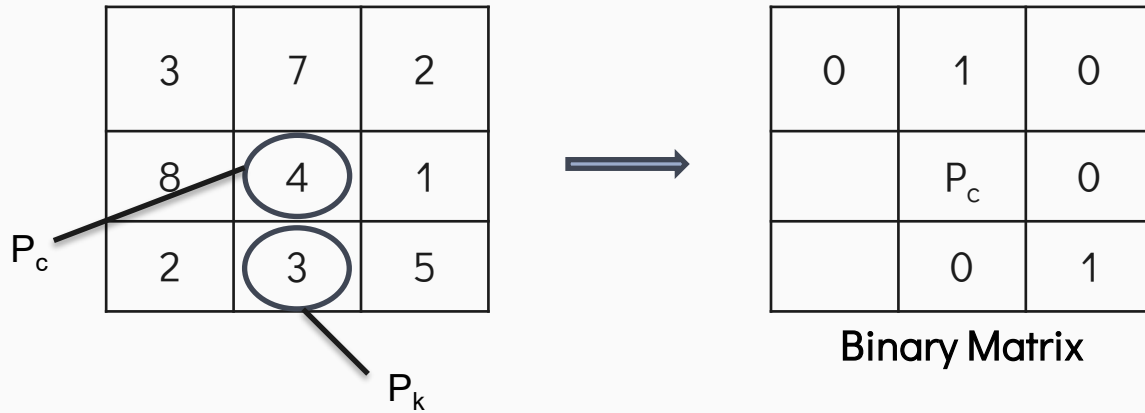
$$s(x) = \begin{cases} 0, & x < 0 \\ 1, & x \geq 0 \end{cases}$$



Example

Step 2: $s(p_k - p_c)$

$$s(x) = \begin{cases} 0, & x < 0 \\ 1, & x \geq 0 \end{cases}$$



Example

Step 2: $s(p_k - p_c)$

$$s(x) = \begin{cases} 0, & x < 0 \\ 1, & x \geq 0 \end{cases}$$

3	7	2
8	4	1
2	3	5

P_c points to the cell containing 2 (row 3, column 1).

P_k points to the cell containing 4 (row 2, column 2).



0	1	0
	P_c	0
0	0	1

Binary Matrix

Example

Step 2: $s(p_k - p_c)$

P_k

3	7	2
8	4	1
2	3	5

P_c

$$s(x) = \begin{cases} 0, & x < 0 \\ 1, & x \geq 0 \end{cases}$$



0	1	0
1	P_c	0
0	0	1

Binary Matrix

Example

Step 2: $s(p_k - p_c)$

3	7	2
8	4	1
2	3	5

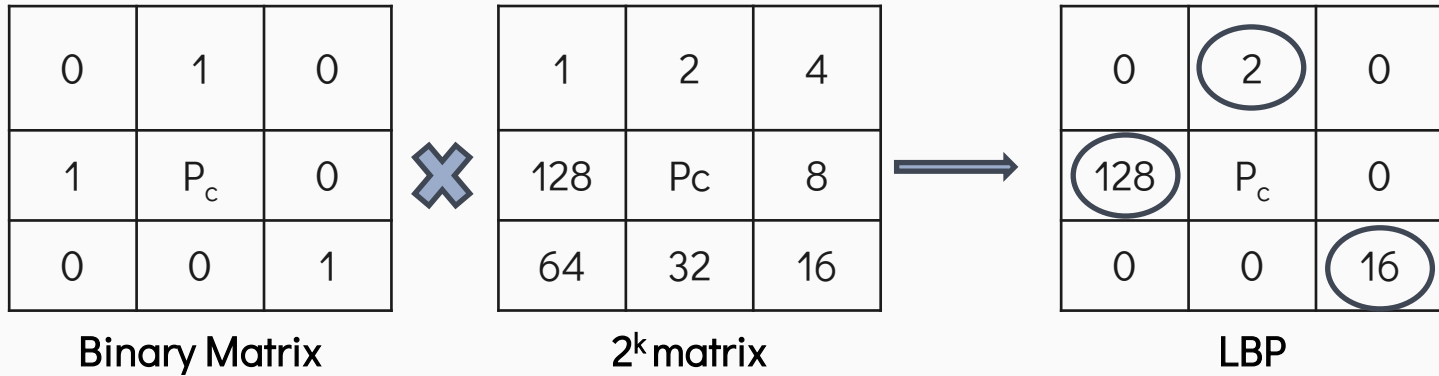


0	1	0
1	P_c	0
0	0	1

Binary Matrix

Example

Step 3: LBP encoding



Example

Step 3: LBP encoding

0	1	0
1	P_c	0
0	0	1

Binary Matrix



1	2	4
128	P_c	8
64	32	16

2^k matrix



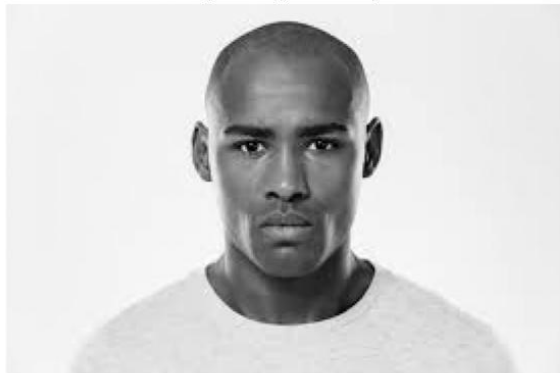
0	2	0
128	P_c	0
0	0	16

LBP

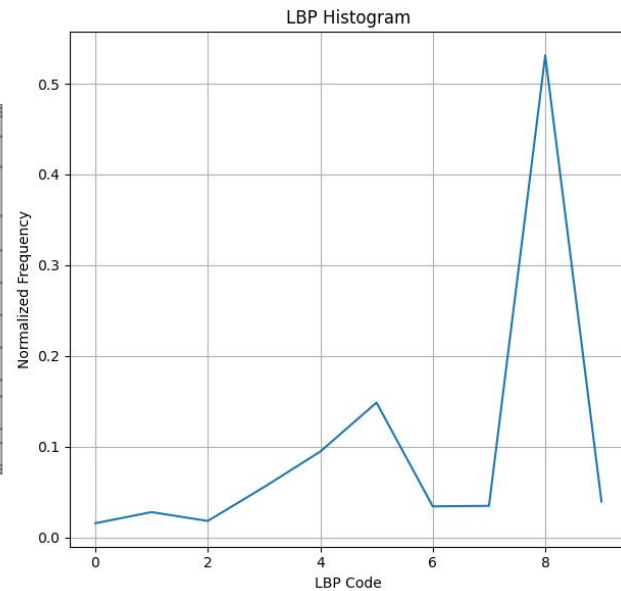
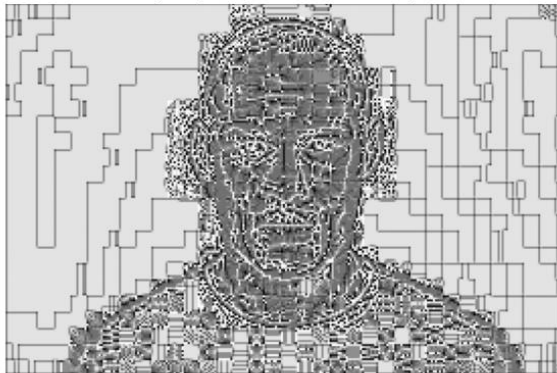
$$\sum_{i=0}^n 2 + 128 + 16 = 146$$

Example

Original Grayscale Image



LBP Image
(P=8, R=1, method='uniform')



Local Feature → Global Representation

- ❑ After computing LBP for every pixel, we obtain a texture map.
- ❑ We extract a histogram of LBP values
- ❑ Histogram becomes the final feature vector used for:
 - ❖ Classification
 - ❖ Segmentation
 - ❖ Recognition
 - ❖ Anomaly detection

Advantages of LBP

- ❑ Very fast and simple to compute.
- ❑ Works well even when lighting changes (brightness/contrast changes).
- ❑ Captures local texture patterns like edges, corners, and spots.
- ❑ Produces features that are easy to use in machine learning.
- ❑ Low memory usage → suitable for real-time systems

Limitations of LBP

- ❑ Sensitive to noise, especially in flat or low-contrast areas.
- ❑ Only captures local information → misses global or large-scale patterns.
- ❑ Standard LBP is not rotation-invariant unless improved versions are used.
- ❑ Binary thresholding (\geq or $<$) may lose fine intensity differences.
- ❑ Histogram features can become large if many neighborhoods are used

Applications of LBP

- ❑ Face recognition (LBPH algorithm).
- ❑ Medical image analysis – detecting tumors or abnormal tissue textures.
- ❑ Industrial inspection – detecting cracks, scratches, or surface defects.
- ❑ Surveillance – human and object detection.
- ❑ Remote sensing – land-use and vegetation texture classification.
- ❑ Document analysis – paper texture and print quality recognition.
- ❑ Agricultural imaging – plant disease texture detection

Comparison

❑ LBP vs GLCM Features

Feature Type	LBP	GLCM
Complexity	Low	Medium
Uses Local Info?	✓	✓
Histogram size	Small-medium	Depends on L, D, angles
Dataset size required	Small	Small
Explainability	High	Medium



Thanks!
