

Electric field intensity (\vec{E}):

It is defined as the ratio of electrostatic force to the electric charge.

$$\vec{E} = \frac{\vec{F}}{q}$$

Unit: newton / coulomb

Electric Displacement vector (\vec{D}):

It is defined as the electric flux (Q) per unit area. It is also known as electric flux density.

$$\vec{D} = \frac{Q}{4\pi r^2} \rightarrow (1)$$

W.K.T Electric field intensity,

$$\vec{E} = \frac{Q}{4\pi \epsilon r^2} \rightarrow (2)$$

comparing (1) & (2) $\Rightarrow \boxed{\vec{D} = \epsilon \vec{E}}$

Electrical permittivity (ϵ):

It is defined as the ratio of displacement current (\vec{D}) to the electric field intensity (\vec{E}).

$$\epsilon = \frac{\vec{D}}{\vec{E}}$$

Unit: $C^2 N^{-1} m^{-2}$

Dielectric constant (or) Relative permittivity (ϵ_r):

It is defined the ratio of permittivity of the medium (ϵ) to the permittivity of free space (or) vacuum (ϵ_0).

$$\boxed{\epsilon_r = \frac{\epsilon}{\epsilon_0}} \quad (\text{or}) \quad \boxed{\epsilon = \epsilon_0 \epsilon_r}$$

Where $\epsilon_0 \rightarrow$ permittivity in free space or vacuum.

$$\epsilon_0 = 8.854 \times 10^{-12} \text{ C}^2 \text{ N}^{-1} \text{ m}^{-2}$$

Magnetic flux density (\vec{B}):

It is defined as the number of magnetic flux lines of force (ϕ_m) passing normally through unit area of cross section at that point.

$$\boxed{\vec{B} = \frac{\phi_m}{A}}$$

Magnetic field intensity (\vec{H}):

It is defined as the force experienced by a unit north pole placed at the given point in a magnetic field.

$$\boxed{\vec{H} = \frac{\vec{F}}{m}}$$

Magnetic permeability (μ):

It is defined as ratio of magnetic flux density (\vec{B}) to the magnetic field intensity (\vec{H})

$$\boxed{\mu = \mu_0 \mu_r = \frac{\vec{B}}{\vec{H}}}$$

Unit: $\text{N s}^2 \text{ C}^{-2}$

Relative permeability (μ_r):

It is defined as the ratio of permeability of the medium (μ) to the permeability of free space (or) vacuum (μ_0).

$$\mu_r = \frac{\mu}{\mu_0}$$

$$\text{or } \mu = \mu_0 \mu_r$$

where $\mu_0 \rightarrow$ permeability in free space or vacuum

$$\mu_0 = 4\pi \times 10^{-7} \text{ N s}^2 \text{ C}^{-2}$$

Gauss law for electric field:

It states that, the total flux through any closed surface is equal to $\frac{1}{\epsilon_0}$ times of the total charge (Q) enclosed in the surface.

$$\oint_S \vec{E} \cdot d\vec{s} = \frac{Q}{\epsilon_0}$$

Faraday's law:

It states that, the induced electromotive force (\mathcal{E}) in a coil is equal to the rate of change of the magnetic flux (ϕ) linking the coil.

$$\mathcal{E} = - \frac{d\phi}{dt}$$

The negative sign implies the decrease in magnetic flux.

Ampere's circuit law:

It states that, the line integral of magnetic field (\vec{B})

surrounding any closed path is equal to μ times of net current (I) passing through that path.

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I$$

$$\oint \frac{\vec{B}}{\mu_0} \cdot d\vec{l} = I$$

$$\therefore \vec{H} = \frac{\vec{B}}{\mu_0}$$

$$\oint \vec{H} \cdot d\vec{l} = I$$

Gauss law for magnetic field:

Gauss law for magnetic field states that the magnetic flux (\vec{B}) passing through the closed surface is equal to zero.

$$\oint \vec{B} \cdot d\vec{s} = 0$$

Derivations of Maxwell's equations

Maxwell's first equation from electric gauss law:

$S \rightarrow$ dielectric medium of surface

$V \rightarrow$ volume

$Q \rightarrow$ Total charge

$P \rightarrow$ charge density

According to gauss law, for electric field,

$$\oint_S \vec{E} \cdot d\vec{s} = \frac{Q}{\epsilon_0}$$

$$\oint_S \epsilon_0 \vec{E} \cdot d\vec{s} = Q \rightarrow (1)$$

W.K.T $\Rightarrow \vec{D} = \epsilon \vec{E}$

Since, $\epsilon = \epsilon_0 \epsilon_r$

$$\Rightarrow \vec{D} = \epsilon_0 \epsilon_r \vec{E}$$

Since, $\epsilon_r = 1$ (For Air)

$$\vec{D} = \epsilon_0 \vec{E} \rightarrow (2)$$

Sub (2) in (1) \Rightarrow

$$\oint_S \vec{D} \cdot d\vec{s} = Q \rightarrow (3)$$

Since, $Q = \int_V \rho \, dv \rightarrow (4)$

comparing (3) & (4) \Rightarrow

$$\oint_S \vec{D} \cdot d\vec{s} = \oint_V \rho dV \rightarrow \textcircled{5}$$

Eqn ⑤ is called Maxwell's first equation in integral form.

Differential form:

From eqn ⑤, Applying gauss divergence theorem on L.H.S \Rightarrow

$$\oint_S \vec{D} \cdot d\vec{s} = \oint_V \vec{\nabla} \cdot \vec{D} \cdot dV \rightarrow \textcircled{6}$$

From ⑤ & ⑥, we can write,

$$\oint_V \vec{\nabla} \cdot \vec{D} dV = \oint_V \rho dV \rightarrow \textcircled{7}$$

$$\boxed{\vec{\nabla} \cdot \vec{D} = \rho} \rightarrow \textcircled{8}$$

Eqn ⑧ \Rightarrow Maxwell's first equation in differential form.

Maxwell's ~~first~~ ^{1st} equation from magnetic gauss law:

According to gauss law for magnetic field,

$$\boxed{\phi = 0} \rightarrow \textcircled{9}$$

$$\text{W.K.T} \Rightarrow \boxed{\phi = \oint_S \vec{B} \cdot d\vec{s}} \rightarrow \textcircled{10}$$

comparing ⑨ and ⑩ \Rightarrow

$$\oint_S \vec{B} \cdot d\vec{s} = 0 \rightarrow \textcircled{11}$$

Eqn ⑪ \Rightarrow Maxwell's second equation in integral form

Differential form:

From eqn (1), using Gauss divergence theorem,

$$\oint_S \vec{B} \cdot d\vec{s} = \oint_V \vec{\nabla} \cdot \vec{B} dv = 0 \rightarrow (2)$$

$$\boxed{\vec{\nabla} \cdot \vec{B} = 0} \rightarrow (3)$$

Eqn (3) represents Maxwell's 2nd equation in differential form.

Maxwell's third equation from Faraday's law:

According to Faraday's law,

$$\boxed{\mathcal{E} = - \frac{d\phi}{dt}} \rightarrow (4)$$

$\mathcal{E} \rightarrow$ Electromotive force

$\phi \rightarrow$ Magnetic flux

W.K.T $\Rightarrow \boxed{\mathcal{E} = \oint_L \vec{E} \cdot d\vec{l}} \rightarrow (5)$

$$\boxed{\phi = \oint_S \vec{B} \cdot d\vec{s}} \rightarrow (6)$$

Sub (5) & (6) in (4) \Rightarrow

$$\oint_L \vec{E} \cdot d\vec{l} = - \frac{d \left[\oint_S \vec{B} \cdot d\vec{s} \right]}{dt}$$

$$\oint_L \vec{E} \cdot d\vec{l} = - \oint_S \frac{d\vec{B}}{dt} \cdot d\vec{s} \rightarrow (7)$$

Eqn (7) represents Maxwell's 3rd eqn in integral form.

Differential form :

From eqn (7), Applying Stoke's theorem on R.H.S.,

$$\oint \vec{E} \cdot d\vec{l} = - \oint_S \vec{\nabla} \times \vec{E} \cdot d\vec{S} \rightarrow (18)$$

Comparing (7) & (18) \Rightarrow

$$- \oint_S \vec{\nabla} \times \vec{E} \cdot d\vec{S} = \oint_S \frac{\partial \vec{B}}{\partial t} \cdot d\vec{S} \rightarrow (19)$$

Eqn (19) becomes,

$$\vec{\nabla} \times \vec{E} = - \frac{\partial \vec{B}}{\partial t} \rightarrow (20)$$

Eqn (20), represents Maxwell's 3rd eqn in differential form

Maxwell's Fourth equation from Ampere's law :

From ampere's law,

$$\oint \vec{H} \cdot d\vec{l} = I \rightarrow (21)$$

$$\text{W.K.T } \Rightarrow I = \oint_S \vec{J} \cdot d\vec{S} \rightarrow (22)$$

Sub (22) in (21) \Rightarrow

$$\oint \vec{H} \cdot d\vec{l} = \oint_S \vec{J} \cdot d\vec{S} \rightarrow (23)$$

From Stoke's theorem,

$$\oint \vec{H} \cdot d\vec{l} = \oint_S \vec{\nabla} \times \vec{H} \cdot d\vec{S} \rightarrow (24)$$

Comparing (23) & (24) \Rightarrow

$$\oint_S \vec{\nabla} \times \vec{H} \cdot d\vec{S} = \oint_S \vec{J} \cdot d\vec{S} \rightarrow (25)$$

Eqn (25) becomes,

$$\vec{\nabla} \times \vec{H} = \vec{J} \rightarrow (26)$$

Applying gauss divergence theorem on both sides,

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{H}) = \vec{\nabla} \cdot \vec{J} \rightarrow (27)$$

From vector identity, $\boxed{\vec{\nabla} \cdot (\vec{\nabla} \times \vec{H}) = 0}$

Eqn (27) becomes,

$$\vec{\nabla} \cdot \vec{J} = 0 \rightarrow (28)$$

According to eqn of continuity,

$$\boxed{\vec{\nabla} \cdot \vec{J} + \frac{\partial \rho}{\partial t} = 0}$$

$$\vec{\nabla} \cdot \vec{J} = -\frac{\partial \rho}{\partial t}$$

$$\vec{\nabla} \cdot \vec{J} = 0 \text{ only if } \frac{\partial \rho}{\partial t} = 0 \rightarrow (29)$$

$$\boxed{\vec{\nabla} \times \vec{H} = \vec{J} + \vec{J}_d} \rightarrow (30)$$

Taking divergence on both sides \Rightarrow

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{H}) = \vec{\nabla} \cdot (\vec{J} + \vec{J}_d) \rightarrow (31)$$

Using vector identity, $\vec{\nabla} \cdot (\vec{\nabla} \times \vec{H}) = 0$

Eqn (31) becomes, $\vec{\nabla} \cdot \vec{J} + \vec{\nabla} \cdot \vec{J}_d = 0$

$$\vec{\nabla} \cdot \vec{J} + \vec{\nabla} \cdot \vec{J}_d = 0$$

Since, $\boxed{\vec{\nabla} \cdot \vec{J} = - \frac{\partial \rho}{\partial t}}$

$$- \frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot \vec{J}_d = 0$$

$$\vec{\nabla} \cdot \vec{J}_d = \frac{\partial \rho}{\partial t}$$

From Maxwell 1st eqn, w.k.t $\boxed{\vec{\nabla} \cdot \vec{D} = \rho}$ ✓

$$\Rightarrow \vec{\nabla} \cdot \vec{J}_d = \frac{\partial (\vec{\nabla} \cdot \vec{D})}{\partial t}$$

$$\vec{\nabla} \cdot \vec{J}_d = \vec{\nabla} \cdot \frac{\partial \vec{D}}{\partial t}$$

$$\vec{J}_d = \frac{\partial \vec{D}}{\partial t} \rightarrow (32)$$

Sub eqn (32) in (30) \Rightarrow

$$\boxed{\vec{\nabla} \times \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t}} \rightarrow (33)$$

Eqn (33) \Rightarrow Maxwell's 4th eqn in differential form