

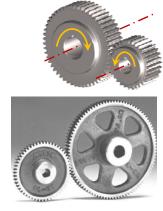
Gears

- ➤ Gears are toothed cylindrical or conical wheels used for power transmission with or without speed reduction
- > Types of gears
 - o Spur gears
 - o Helical gears
 - o Rack and pinion
 - o Bevel gears
 - Hypoid gears
 - o Worm and worm wheel
- > Internal and external

Spur gears

- Teeth are parallel to the axis of rotation
- Used for transmitting power between parallel shafts

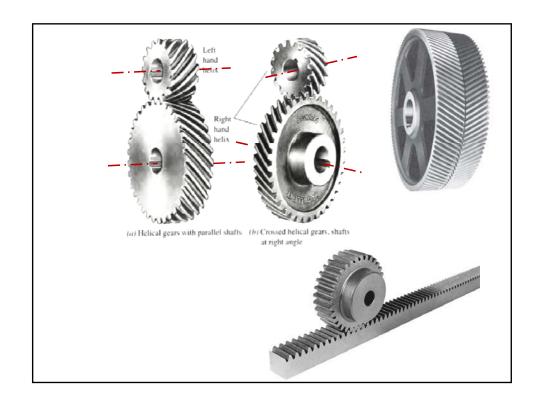




Helical gears

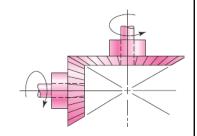
- Teeth are inclined to the axis of rotation
- Relatively quieter in operation
- Can be used for transmitting power between non-parallel shafts also

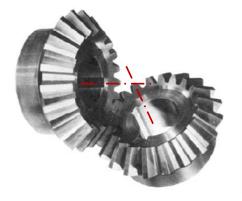


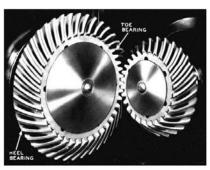


Bevel gears

- Teeth are formed on a conical surface
- Teeth can be straight or spiral
- Used for transmitting power between perpendicular intersecting shafts







Hypoid gears

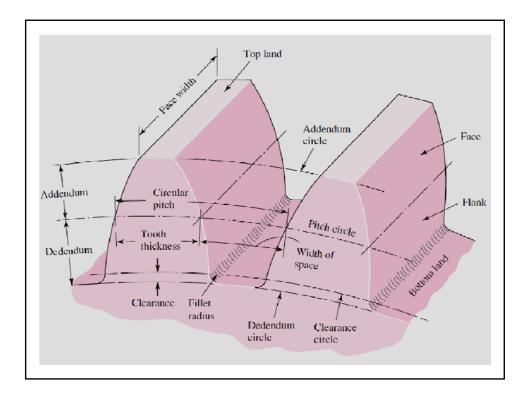
• Similar to bevel gear but shafts can be offset, perpendicular to each other



Worm and Worm wheel

- Shafts perpendicular, non intersecting
- Large speed reduction possible





Spur gear tooth geometry

Pitch circle

- Theoretical circle upon which all calculations are made
- Its diameter is called pitch circle diameter d
- Pitch circles of two mating gears are tangent to each other

Addendum, a

• Radial distance between top land and pitch circle

Circular pitch (p)

- Distance measured on the pitch circle from a point on the tooth to the corresponding point on an adjacent tooth
- p = tooth thickness + width of space (measured on PC)
- $p = \pi d/N$, N is number of teeth

Dedendum, b

Radial distance between bottom land and pitch circle

