ME361 – Manufacturing Science Technology

Rolling

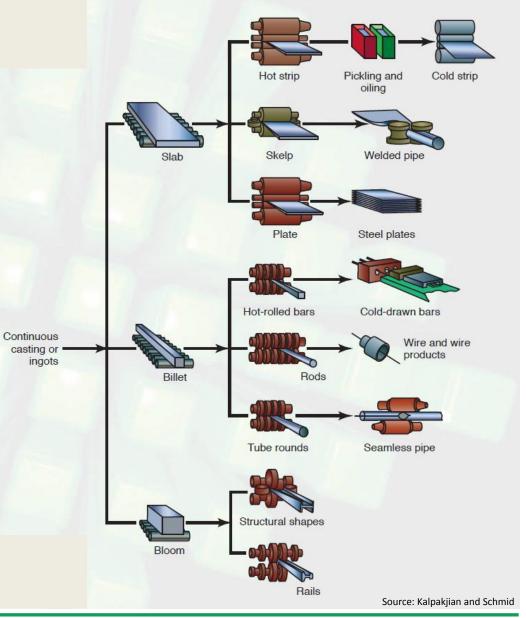
Dr. Mohit Law

mlaw@iitk.ac.in



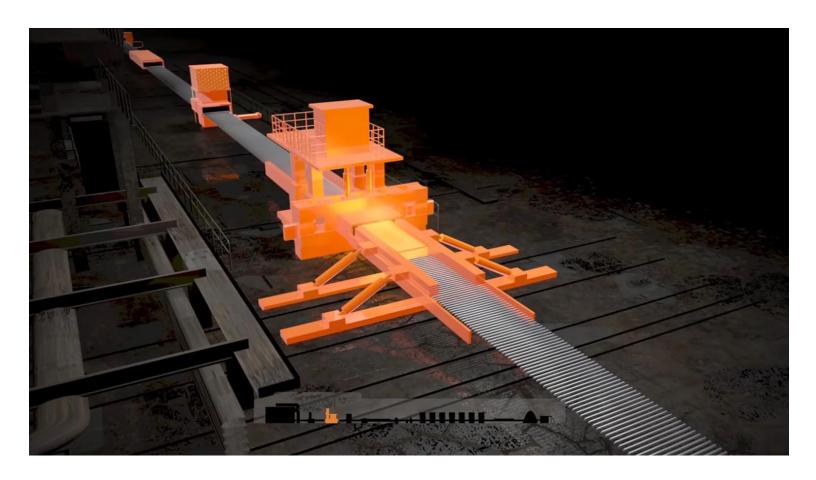
Rolling

- Accounts for ~90% of all metals produced by metal working processes
- Used to primarily make plates and sheets
 - Plates: thickness > 6 mm
 - Sheets: thickness < 6 mm





Rolling

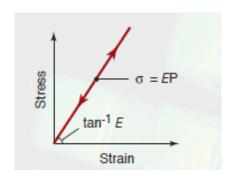


https://www.youtube.com/watch?v=LWM6b8P0r3E

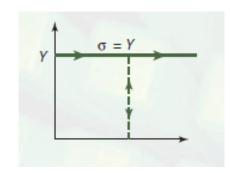


Preliminaries. Stress-strain behavior.

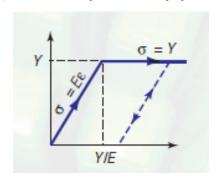
(a) Perfectly elastic



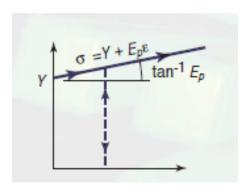
(b) Rigid, perfectly plastic



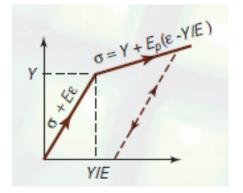
(c) Elastic, perfectly plastic



(d) Rigid, linearly strain hardening

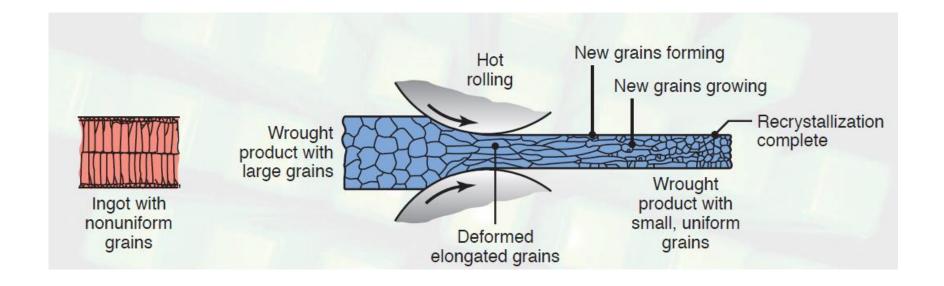


(e) Elastic, linearly strain hardening





Grain structure in rolling



Source: Kalpakjian and Schmid



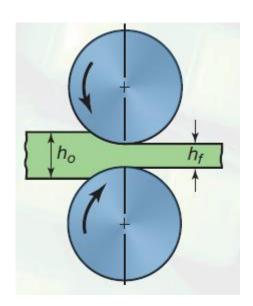
Rolling analysis: objectives and assumptions

Objectives:

- To determine roll separating forces
- To determine torque and power required to drive the rolls

Assumptions:

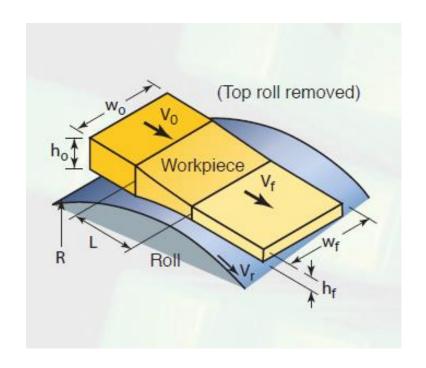
- Rolls are straight and rigid cylinders
- Width is larger than thickness and no significant
 widening takes place, i.e. problem is of plane strain type
- The coefficient of friction is low and constant over the entire roll-workpiece interface





Mechanics of flat rolling

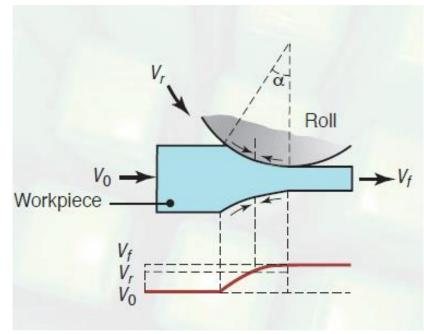
- Strip of thickness h_0 enters the roll gap and is reduced to thickness of h_f
- Surface speed of roll is V_r
- Entry speed of strip is V_o and exit speed is V_f
- Since volume rate is constant, velocity of strip must increase as it moves through the roll gap (similar to fluid flow through a converging channel).





Mechanics of flat rolling

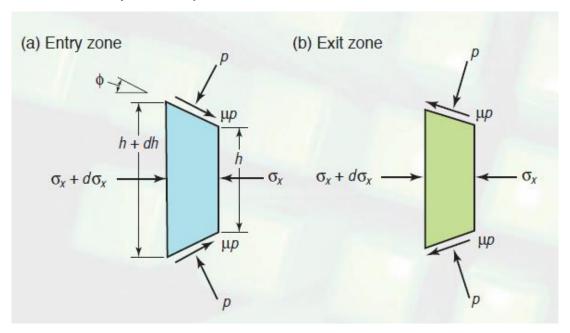
- In general, $V_f > V_r > V_o$
- However, because V_r is constant along the roll gap, sliding occurs between the roll and the strip
- At a point along the roll gap, $V_r = V_o = V_f$; this point is known as the neutral point, or no-slip point
- To the left of the neutral point, roll moves faster than the workpiece, and to the right the workpiece moves faster than the roll
- Frictional forces oppose each other at the neutral point, and these forces are greater on the left of the neutral point, than on the right, which pulls the strip into the gap



Forward slip =
$$\frac{V_f - V_r}{V_r}$$



Slab method of analysis for plane strain



Balance horizontal forces in this element:

$$(\sigma_x + d\sigma_x)(h + dh) - 2pRd\phi \sin\phi - \sigma_x h \pm 2\mu pRd\phi \cos\phi = 0$$

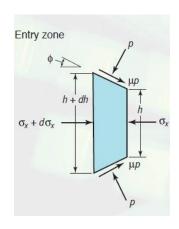


Balance horizontal forces in this element:

$$(\sigma_x + d\sigma_x)(h + dh) - 2pRd\phi \sin\phi - \sigma_x h \pm 2\mu pRd\phi \cos\phi = 0$$

Simplifying and neglecting 2nd order terms:

$$\frac{d(\sigma_x h)}{d\phi} = 2pR(\sin\phi \mp \mu\cos\phi)$$



Since α is usually only a few degrees, take: $\sin\phi=\phi$ and $\cos\phi=1$

$$\frac{d(\sigma_{x}h)}{d\phi} = 2pR(\phi \mp \mu) \tag{1}$$



Digression for plane strain

Recalling Hooke's law equations:

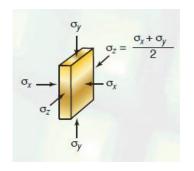
$$\varepsilon_{x} = \frac{1}{E} \left[\sigma_{x} - \nu (\sigma_{y} + \sigma_{z}) \right]$$

$$\varepsilon_{y} = \frac{1}{E} \left[\sigma_{y} - \nu (\sigma_{x} + \sigma_{z}) \right]$$

$$\varepsilon_{z} = \frac{1}{E} \left[\sigma_{z} - \nu (\sigma_{x} + \sigma_{y}) \right]$$

For plane strain, $\varepsilon_z = 0$; $\sigma_z = \frac{\sigma_x + \sigma_z}{2}$;

since $v = \frac{1}{2}$ in plastic deformation



Use a yield criterion (Distortion energy/von-Mises):

$$(\sigma_x - \sigma_y)^2 + (\sigma_y - \sigma_z)^2 + (\sigma_z - \sigma_x)^2 = 2Y^2$$

 σ_x , σ_y , σ_z — principle stresses; Y — the uniaxial yield stress

$$\sigma_y - \sigma_x = \frac{2}{\sqrt{3}}Y = Y'$$
 or $d\sigma_y = d\sigma_x$ (2)

 $^*\sigma_x$ and σ_y are assumed to be principle stresses, even though there is a shear component of $\mu\sigma_y$. However, since μ is usually small, this is reasonable



From the plane strain criterion:

$$\sigma_y - \sigma_x = \frac{2}{\sqrt{3}}Y = Y'$$
 Specifically for rolling $p - \sigma_x = Y'_f$ (2)

 Y'_f : flow stress for strain-hardened case

Recalling force balance equation:

$$\frac{d(\sigma_x h)}{d\phi} = 2pR(\phi \mp \mu) \quad \text{(1)} \quad \frac{\text{Substituting (2)}}{\text{into (1)}} \quad \frac{d[(p - Y'_f)h]}{d\phi} = 2pR(\phi \mp \mu)$$

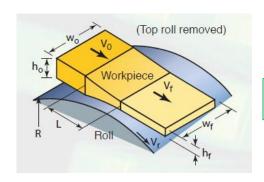
$$\frac{d}{d\phi} \left[Y'_f \left(\frac{p}{Y'_f} - 1 \right) h \right] = 2pR(\phi \mp \mu) \quad \text{(3)} \quad \text{Differentiating this...}$$



$$Y'_{f}h\frac{d}{d\phi}\left(\frac{p}{Y'_{f}}\right) + \left(\frac{p}{Y'_{f}} - 1\right)\frac{d}{d\phi}\left(Y'_{f}h\right) = 2pR(\phi \mp \mu) \tag{4}$$

Second term is usually very small, because as h decreases, Y'_f increases, thus making the product nearly a constant, and its derivate thus becomes zero, thus (4) becomes:

$$\frac{\frac{d}{d\phi} \left(\frac{p}{Y'_f}\right)}{\frac{p}{Y'_f}} = \frac{2R}{h} \left(\phi \mp \mu\right) \tag{5}$$



If h_f is the final thickness:

$$h = h_f + 2R(1 - \cos\phi) \quad \stackrel{\approx}{\longrightarrow} \quad h = h_f + R\phi^2 \quad (6)$$

Now, substitute (6) into (5)



Recalling again:

$$\frac{\frac{d}{d\phi} \left(\frac{p}{Y'_f}\right)}{\frac{p}{Y'_f}} = \frac{2R}{h} \left(\phi + \mu\right) \tag{5}$$

$$h = h_f + R\phi^2$$

Now, substitute (6) into (5), and integrating:

$$\ln \frac{p}{Y'_f} = \ln \frac{h}{R} + 2\mu \sqrt{\frac{R}{h_f}} \tan^{-1} \sqrt{\frac{R}{h_f}} \phi + \ln C$$

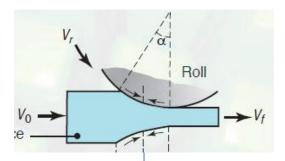
$$p = CY'_f \frac{h}{R} e^{\mp \mu H} \quad \text{wherein} \quad H = 2\sqrt{\frac{R}{h_f}} tan^{-1} \sqrt{\frac{R}{h_f}} \phi \quad (7)$$

- $p = f(h, \phi)$
- p increases with increasing material strength, increasing μ , and increasing R/h_f ratio



Roll pressure:
$$p = CY'_f \frac{h}{R} e^{\mp \mu H}$$

wherein
$$H = 2\sqrt{\frac{R}{h_f}}tan^{-1}\sqrt{\frac{R}{h_f}}\phi$$
 (7)



At entry:

$$\phi = \alpha; p = {Y'}_f; H = H_o$$

$$C = \frac{R}{h_0} e^{\mu H_0}$$

$$p = Y'_f \frac{h}{h_0} e^{\mu(H_0 - H)}$$
 (8)

At exit:

$$\phi = 0; p = Y'_f; H = H_f = 0$$

$$C = \frac{R}{h_f}$$

$$p = Y'_f \frac{h}{h_f} e^{\mu H}$$
 (9)



Determination of the neutral point

- All velocities at the neutral point are the same, i.e. $V_r = V_o = V_f$
- Pressures at the neutral point are also the same, hence the neutral point can be obtained by simply equating the pressure at the entry to that of the exit:

Pressure at entry
$$p = Y'_f \frac{h}{h_o} e^{\mu(H_o - H)} = p = Y'_f \frac{h}{h_f} e^{\mu H}$$
 Pressure at exit
$$\frac{h_0}{h_f} = \frac{e^{\mu H_o}}{e^{2\mu H_n}} = e^{\mu(H_o - 2H_n)} \longrightarrow H_n = \frac{1}{2} \left(H_0 - \frac{1}{\mu} \ln \frac{h_0}{h_f} \right)$$
 (10) Substituting (10) into (7)
$$H = 2 \sqrt{\frac{R}{h_f}} tan^{-1} \sqrt{\frac{R}{h_f}} \phi$$
 (7)
$$\phi_n = \sqrt{\frac{h_f}{R}} tan \left(\sqrt{\frac{h_f}{R}} \frac{H_n}{2} \right)$$



Roll pressure distribution: influence of friction

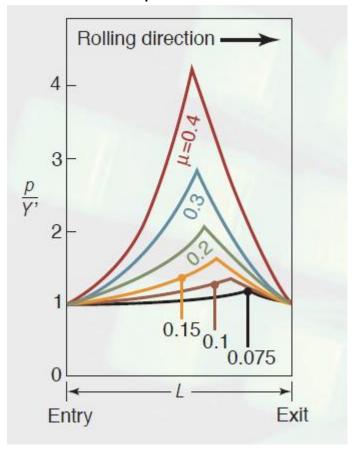
Recalling roll pressure:

$$p = CY'_f \frac{h}{R} e^{\frac{1}{\mu}H}$$

$$H = 2\sqrt{\frac{R}{h_f}} tan^{-1} \sqrt{\frac{R}{h_f}} \phi$$

- $p = f(h, \phi)$
- p increases with increasing material strength, increasing μ , and increasing R/h_f ratio
- Neutral point shifts to the exit as friction
 decreases, and without friction, the rolls slip, and
 the neutral point shifts completely to the exit

Dimensionless pressure distribution



Source: Kalpakjian and Schmid



Roll pressure distribution: influence of reduction

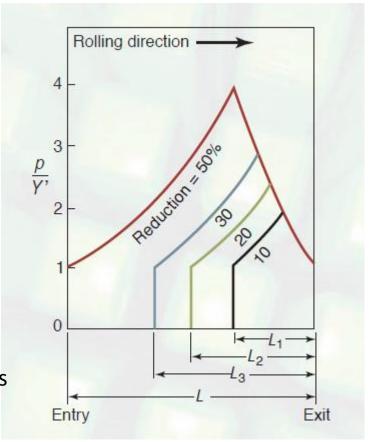
Recalling roll pressure:

$$p = CY'_f \frac{h}{R} e^{\mp \mu H}$$

$$H = 2\sqrt{\frac{R}{h_f}} tan^{-1} \sqrt{\frac{R}{h_f}} \phi$$

- $p = f(h, \phi)$
- p increases with increasing material strength, increasing μ , and increasing R/h_f ratio
- As thickness reduction increases, the length of contact in the roll gap increases, which increases the peak pressure

Dimensionless pressure distribution



Source: Kalpakjian and Schmid



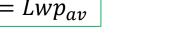
Rolling forces

- Given the pr. vs. contact-length curve, forces can be calculated from the area under the curve multiplied by the strip width, w
- Alternatively, roll-separating force is:

$$F = \int_0^{\phi_n} w \, pR d\phi + \int_{\phi_n}^{\alpha} w \, pR d\phi$$

Simpler method yet:

$$F = Lwp_{av}$$



 $L=\sqrt{R\Delta h};$

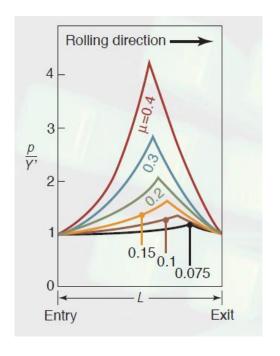
$$\Delta h = h_o - h_f$$

And the average pressure:

Wherein the arc of contact:

$$p_{av} = \overline{Y'} \left(1 + \frac{\mu L}{2h_{av}} \right)$$

wherein Y' is the average flow stress in plane strain in the roll gap





Roll torque and power

• Roll force:
$$F = \int_0^{\phi_n} w \, pR d\phi + \int_{\phi_n}^{\alpha} w \, pR d\phi$$

Roll torque, T, for each roll can be calculated as:

$$T = \int_{\phi_n}^{\alpha} w \, \mu p R^2 d\phi - \int_0^{\phi_n} w \, \mu p R^2 d\phi$$

Minus sign indicates a change in direction of friction force at the neutral point.

If frictional forces are equal, the torque will be zero

• Roll torque, T, can also be estimated by assuming roll force acts in the middle of the arc of contact, i.e. a moment arm of 0.5L, and that F is \bot to the plane of the strip:

$$T = \frac{FL}{2}$$
 \longrightarrow $Power = T\omega$ $\omega = 2\pi N$ $Power = \frac{\pi FLN}{60000} \text{kW}$



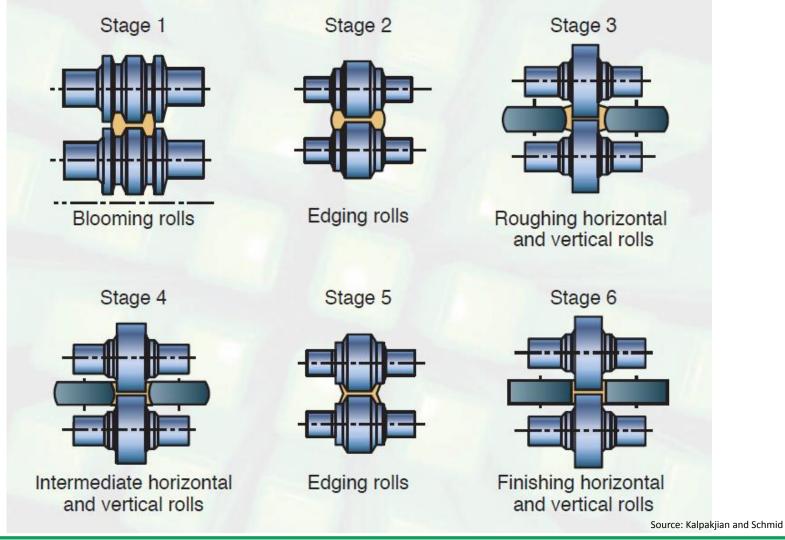
Other rolling operations:

- Rolling of special sections and shapes
- Thread rolling
- Skew rolling

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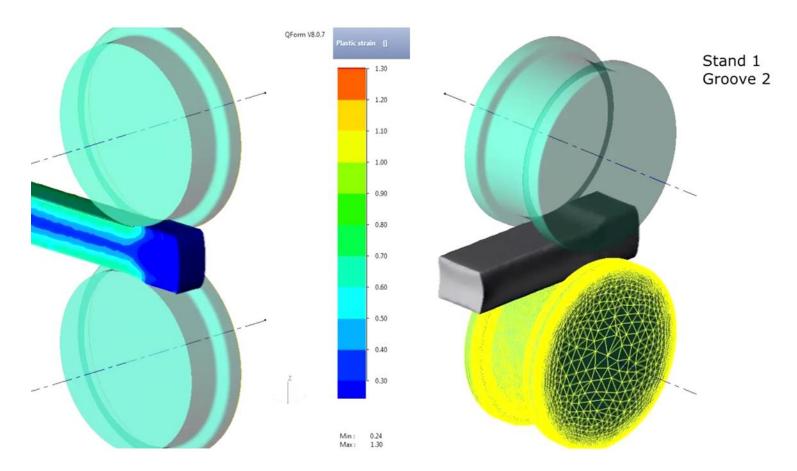


Rolling of different sections and shapes





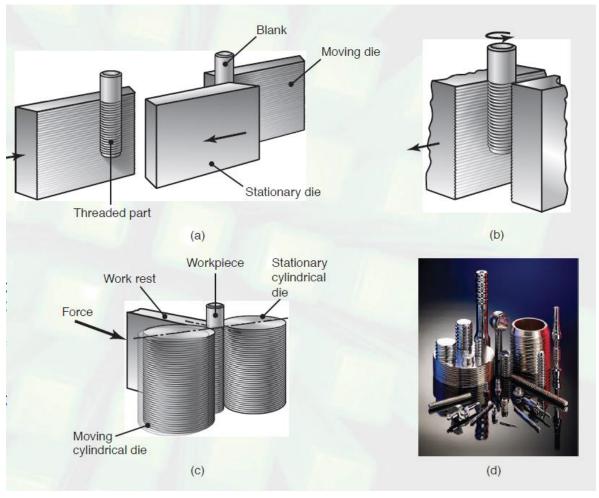
Rolling of sections: Numerical analysis



https://www.youtube.com/watch?v=aJnJjUSgmwI&t=13s



Thread rolling



Source: Kalpakjian and Schmid



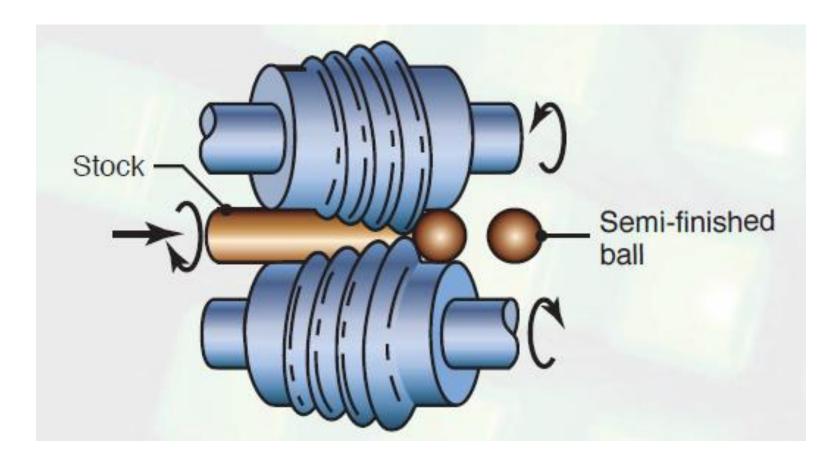
Thread rolling



https://www.youtube.com/watch?v=bclnb Cp4sE



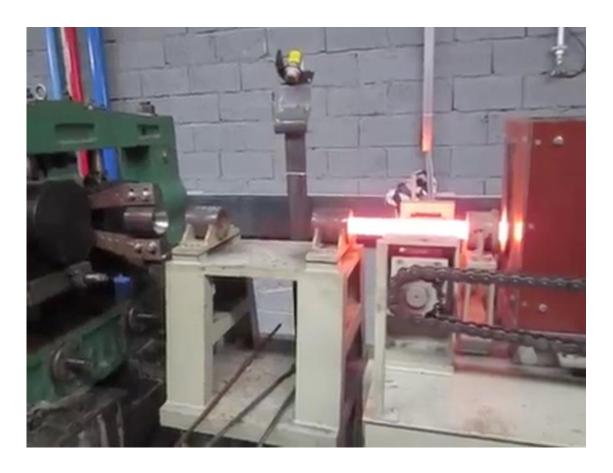
Skew rolling



Source: Kalpakjian and Schmid



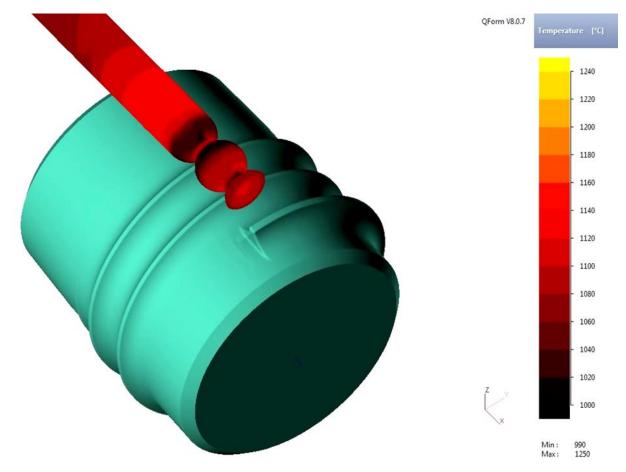
Skew rolling



https://www.youtube.com/watch?v=BazQnUg0k2Q



Skew rolling: numerical analysis



https://www.youtube.com/watch?v=67F GrfZTzM

