

# Tc and Sc Understanding

Great question! Let me break down the time and space complexity analysis step by step.

## Time Complexity Analysis

Let's analyze each part of the code:

### 1. Building the array (Lines 4-7)

```
arr = []
for i in range(N):
    val = [S[i], F[i], i+1]
    arr.append(val)
```

- **Operation:** Loop N times, each iteration does  $O(1)$  work
- **Time:**  $O(N)$

### 2. Sorting the array (Line 12)

```
arr.sort(key = lambda x: x[1])
```

- **Operation:** Sorting N elements
- **Time:**  $O(N \log N)$

### 3. Finding maximum meetings (Lines 14-26)

```
for i in range(1, N):
    start_time, end_time, idx = arr[i]

    if prev_meeting_end_time >= start_time:
        continue
```

```
prev_meeting_end_time = end_time
count += 1
indexes.append(idx)
```

- **Operation:** Single loop through N elements, each iteration is  $O(1)$
- **Time:**  $O(N)$

## 4. Sorting the result (Line 28)

```
return sorted(indexes)
```

- **Operation:** Sorting the selected meeting indices
- **Key insight:** `indexes` can have at most N elements (worst case: all meetings are selected)
- **Time:**  $O(N \log N)$  in worst case

## Total Time Complexity

$$O(N) + O(N \log N) + O(N) + O(N \log N) = O(N \log N)$$

The sorting operations dominate, so **Time Complexity =  $O(N \log N)$**

## Space Complexity Analysis

### 1. The `arr` array

```
arr = []
for i in range(N):
    val = [S[i], F[i], i+1]
    arr.append(val)
```

- **Space:** Stores N meetings, each with 3 elements
- **Memory:**  $O(N)$

## 2. The **indexes** array

```
indexes = [arr[0][2]]  
# ... later additions in the loop
```

- **Space:** Stores selected meeting indices
- **Worst case:** All meetings are selected  $\rightarrow O(N)$
- **Best case:** Only 1 meeting selected  $\rightarrow O(1)$
- **Average/Worst case:**  $O(N)$

## 3. Other variables

```
prev_meeting_end_time = arr[0][1]  
count = 1  
start_time, end_time, idx = arr[i] # loop variables
```

- **Space:**  $O(1)$  for all auxiliary variables

## 4. Sorting space overhead

```
arr.sort(key = lambda x: x[1])  
sorted(indexes)
```

- **Space:** Most sorting algorithms use  $O(\log N)$  extra space for recursion stack
- **Memory:**  $O(\log N)$

## Total Space Complexity

$$O(N) + O(N) + O(1) + O(\log N) = O(N)$$

**Space Complexity =  $O(N)$**

## Summary

Aspect	Complexity	Explanation
<b>Time</b>	<b><math>O(N \log N)</math></b>	Dominated by sorting operations
<b>Space</b>	<b><math>O(N)</math></b>	Dominated by storing meeting data and results

## Visual Breakdown

```
def maxMeetings(self, N, S, F):
    #  $O(N)$  time,  $O(N)$  space
    arr = []
    for i in range(N):
        arr.append([S[i], F[i], i+1])

    #  $O(N \log N)$  time,  $O(\log N)$  space
    arr.sort(key = lambda x: x[1])

    #  $O(N)$  time,  $O(N)$  space (worst case)
    prev_meeting_end_time = arr[0][1]
    count = 1
    indexes = [arr[0][2]]

    for i in range(1, N):
        start_time, end_time, idx = arr[i]
        if prev_meeting_end_time >= start_time:
            continue
        prev_meeting_end_time = end_time
        count += 1
        indexes.append(idx)

    #  $O(N \log N)$  time,  $O(\log N)$  space
    return sorted(indexes)
```

## Key Insights

1. **Why  $O(N \log N)$  time?** The algorithm must sort meetings by end time to apply the greedy strategy effectively.
2. **Why  $O(N)$  space?** We need to store all meeting information and potentially all meeting indices in the result.
3. **Can we optimize?** The time complexity is optimal for this problem since we need sorting. Space could theoretically be optimized by sorting indices in-place, but it would complicate the code significantly.
4. **Greedy vs DP:** This greedy approach is much more efficient than a DP solution, which would typically be  $O(2^N)$  time for this problem.