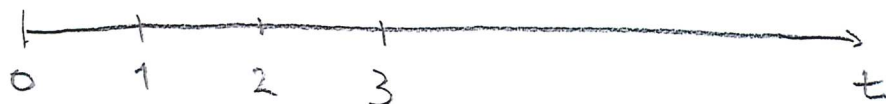


# Lecture 8

①

## 6. Portfolio dynamics

Let the time axis be discrete



### Def 6.1

$N$  = # of different assets

$S_n^i$  = the price of one unit of asset  $i$  at time  $n$

$h_n^i$  = # of units of asset  $i$  bought at time  $n$ .

$h_n = (h_n^1, h_n^2, \dots, h_n^N)$  is a portfolio

$V_n$  = the value of a portfolio  $h_n$  at time  $n$ .

$$= \sum_{i=1}^N h_n^i S_n^i = h_n \circ S_n \quad \text{vector mult.}$$

### Interpretation:

1. At time  $n$  - we have an old portfolio  $h_{n-1}$  from the previous period.
2. At time  $n$ ,  $S_n$  becomes observable
3. At time  $n$ , after observing  $S_n$ , we choose  $h_n$ .

### Budget equation:

$$h_n \circ S_{n+1} = h_{n+1} \circ S_{n+1}$$

Notation: If  $\{x_n\}_{n=0}^{\infty}$  is a sequence of real numbers, let  $\Delta x_n := x_{n+1} - x_n$ .

The budget equation becomes

(2)

$$S_{n+1} \cdot \Delta h_n = 0$$

← Backward increment!

Do not take limits

$\Delta t \rightarrow 0$  yet!

Recall  $V_n = h_n \cdot S_n$

$$\text{Since } \Delta V_n = h_{n+1} \cdot S_{n+1} - h_n \cdot S_n = h_{n+1} \cdot S_{n+1} - h_n \cdot S_{n+1} + h_n \cdot S_{n+1} - h_n \cdot S_n$$

$$\text{we have } = S_{n+1} \cdot \Delta h_n + h_n \cdot \Delta S_n$$

$\Delta V_n = h_n \cdot \Delta S_n$  if the budget equation is fulfilled.

Below we use this relation to define what is meant by a self-financing portfolio in continuous time.

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Def 6.10 Let  $\{S_t, t \geq 0\}$  be an  $N$ -dim price process. (3)

1. A portfolio  $h$  is an  $\mathcal{F}^S$ -adapted  $N$ -dim. process.
2.  $h$  is Markovian if  $h_t = h(t, S_t)$  for some function  $h$ .
3. The value process  $V^h$  of  $h$  is

$$V_t^h = \sum_{i=1}^N h_t^i S_t^i = h_t \cdot S_t$$

4. A portfolio  $h$  is self-financing if

$$dV_t^h = h_t \cdot dS_t$$

5. For a given portfolio  $h$ , the corresponding relative portfolio  $w$  is

$$w_t^i = \frac{h_t^i S_t^i}{V_t^h} \quad i = 1, \dots, N$$

Note that  $\sum_{i=1}^N w_t^i = 1$ .

Also,  $h$  is self-financing if and only if

$$dV_t^h = V_t^h \sum_{i=1}^N \frac{w_t^i}{S_t^i} dS_t^i.$$