

Computer Intensive Statistics and Applications Extension: SDE and Financial Applications

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Standard Brownian Motion

Definition

A stochastic process $\{W(t), 0 \leq t \leq T\}$ is a standard one-dimensional **Brownian motion** on $[0, T]$ if

- ① $W(0) = 0$,
- ② the mapping $t \rightarrow W(t)$ is a continuous function with probability 1,
- ③ the increments $W(t_1) - W(t_0)$, $W(t_2) - W(t_1)$, ..., $W(t_k) - W(t_{k-1})$ are independent for any k and for any $t_i \in [0, T]$,
- ④ $W(t) - W(s) \sim N(0, t - s)$ for any $0 \leq s < t \leq T$.

Black-Scholes Model

The Black-Scholes model is perhaps the first widely used mathematical model to model the asset price. Let $S(t)$ be the price of the asset at time t . Then,

$$\frac{dS(t)}{S(t)} = rdt + \sigma dW(t),$$

where r can be interpreted as a riskless interest rate, i.e., each unit invested at time 0 grows to a value of $\exp(rt)$ at time t , and σ is the volatility. This model implies that

$$S(T) = S(0) \exp \left\{ \left(r - \frac{1}{2}\sigma^2 \right) T + \sigma W(T) \right\}.$$

Call Option and Present Value

A **call option** gives you the right to buy the stock at a **strike price** K by the expiration date T . Then, the present value of the option is

$$e^{-rT} \mathbb{E} [\max (S(T) - K, 0)].$$

- For the standard Brownian motion, $W(t) \sim N(0, t)$. Hence, we can simulate $W(t)$ by $W(t) = \sqrt{t}Z$, where $Z \sim N(0, 1)$.
- It is also easy to see that, by taking the log of $S(T)$,

$$\log S(T) \sim N \left(\log S(0) + \left(r - \frac{1}{2}\sigma^2 \right) T, \sigma^2 T \right).$$

Monte Carlo Evaluation of Present Value

We can approximate the present value in this example by

Algorithm 1: Monte Carlo evaluation of stock price

```
1 for  $i = 1$  in  $1 : n$  do
2   Sample a candidate  $Z_i \sim N(0, 1)$  ;
3   Calculate  $S_i(T) = S(0) \exp \left\{ \left( r - \frac{1}{2}\sigma^2 \right) T + \sigma\sqrt{T}Z_i \right\}$  ;
4   Calculate  $C_i = \exp(-rT) \max(S_i(T) - K, 0)$  ;
5 end
6 The approximated value is  $n^{-1} \sum_{i=1}^n C_i$ .
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Variance Reduction: Importance Sampling

Let

$$Y = \log S(T) \sim N\left(\log S(0) + \left(r - \frac{1}{2}\sigma^2\right)T, \sigma^2\right).$$

We can rewrite $E[\max(S(T) - K, 0)]$ as

$$\begin{aligned} E[\max(S(T) - K, 0)] &= \int_{-\infty}^{\infty} [\exp(y) - K] \mathbf{1}(y > \log K) p(y) dy \\ &= \int_{\log K}^{\infty} [\exp(y) - K] \frac{p(y)}{g(y)} g(y) dy. \end{aligned}$$

We can use importance sampling and let $g(y)$ be a density with support on $\{y > \log K\}$, e.g., a shifted exponential distribution.

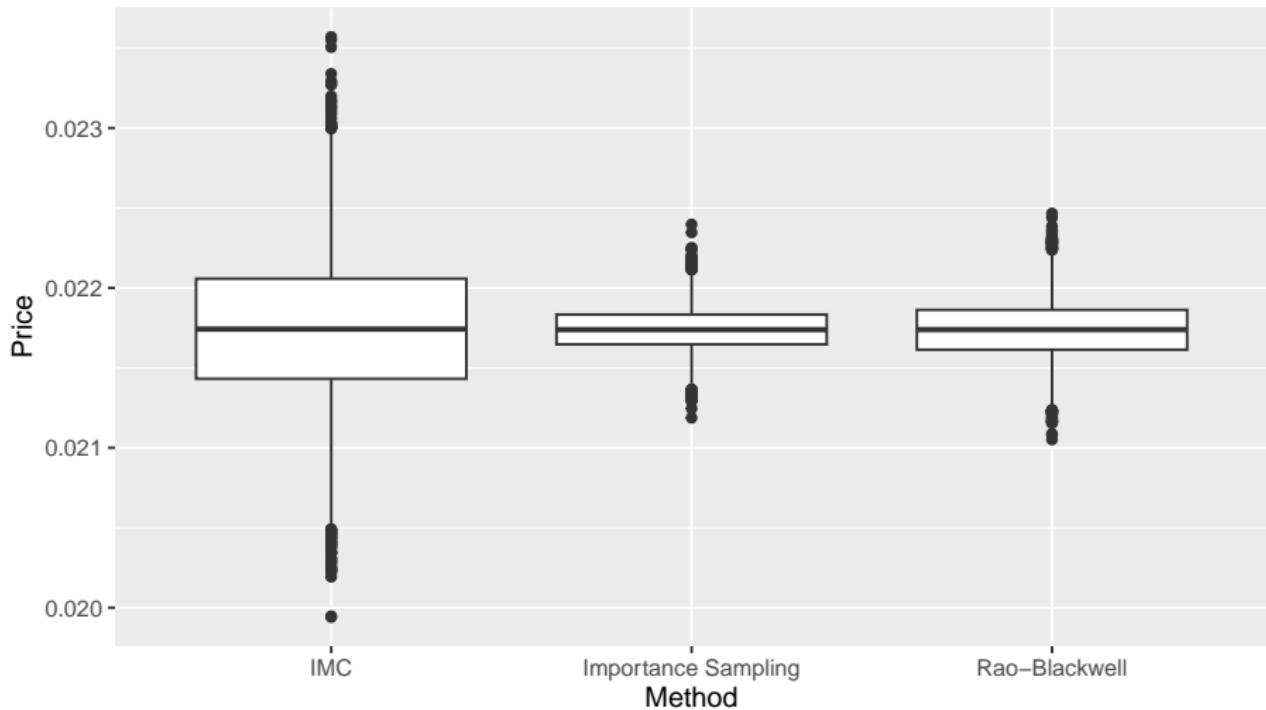
Variance Reduction: Rao-Blackwell

We can also condition $\max(S(T) - K, 0)$ on $S(T) > K$ as

$$\begin{aligned} \mathbb{E} [\max(S(T) - K, 0)] &= \mathbb{P} \{S(T) > K\} \mathbb{E} [S(T) - K \mid S(T) > K] \\ &= \mathbb{P}(Y > \log K) \mathbb{E} [\exp(Y) - K \mid Y > \log K]. \end{aligned}$$

- $\mathbb{P}(Y > \log K)$ is the normal probability.
- We can sample Y from the conditional distribution $Y \mid Y > \log K$ (a truncated normal distribution) to approximate $\mathbb{E} [\exp(Y) - K \mid Y > \log K]$.

Simulation: Present Value



Simulating Standard Brownian Motion

- Sometimes the asset value is path dependent.
- If we want to simulate W at multiple time points $0 < t_1 < \dots < t_k$, then

$$W(t_{i+1}) = W(t_i) + \sqrt{t_{i+1} - t_i} Z_{i+1},$$

where Z_1, \dots, Z_k are iid $N(0, 1)$.

- Because the increments $W(t_1) - W(t_0), W(t_2) - W(t_1), \dots, W(t_k) - W(t_{k-1})$ are independent.
- The simulation is exact (i.e., correct distribution) at the time points t_1, \dots, t_k .
- But any deterministic interpolation between t_i will introduce **discretization error**.

Brownian Motion

If $X(t) = \mu t + \sigma W(t)$, then $X(t)$ is a **Brownian motion** with **drift** μ and **diffusion coefficient** σ^2 .

- Since $W(t) \sim N(0, \sigma^2)$, we get $X(t) \sim N(\mu t, \sigma^2 t)$.
- Since $W(0) = 0$, we also have $X(0) = 0$.

Since $X(t) - X(s) = \mu(t-s) + \sigma[W(t) - W(s)]$, the increments are still normal and independent. Hence, we can simulate the Brownian motion by

$$X(t_{i+1}) = X(t_i) + \mu(t_{i+1} - t_i) + \sigma\sqrt{t_{i+1} - t_i}Z_{i+1}.$$

Geometric Brownian Motion

The stochastic process $S(t)$ is a **geometric Brownian motion** if $\log S(t)$ is a Brownian motion with initial value $\log S(0)$.

- The technical definition is that $S(t)$ is a geometric Brownian motion if

$$\frac{dS(t)}{S(t)} = \mu dt + \sigma dW(t).$$

- The solution is that

$$S(t) = S(0) \exp \left[\left(\mu - \frac{1}{2} \sigma^2 \right) t + \sigma W(t) \right],$$

where $S(0)$ is the initial value.

Simulate Geometric Brownian Motion

$$S(t) = S(0) \exp \left[\left(\mu - \frac{1}{2} \sigma^2 \right) t + \sigma W(t) \right].$$

For any $u < t$,

$$S(t) = S(u) \exp \left\{ \left(\mu - \frac{1}{2} \sigma^2 \right) (t-u) + \sigma [W(t) - W(u)] \right\}.$$

Hence, we can simulate the geometric Brownian motion as

$$S(t_{i+1}) = S(t_i) \exp \left\{ \left(\mu - \frac{1}{2} \sigma^2 \right) (t_{i+1} - t_i) + \sigma \sqrt{t_{i+1} - t_i} Z_{i+1} \right\}.$$

The simulation is still exact at the time points $\{t_i\}$.

Barrier Option: Discrete Monitoring

Consider a barrier option where the option is knocked out if $S(t) > B$, where B is the barrier level. The payoff such option is

$$\max \{S(T) - K, 0\} \prod_{m=1}^M 1 \{S(t_m) \leq B\}$$

if the monitoring times are $\{t_m\}$, for $m = 1, \dots, M$. The present value of the option is

$$E \left[\max \{S(T) - K, 0\} \prod_{m=1}^M 1 \{S(t_m) \leq B\} \right].$$

It can be easily approximated by

$$\frac{1}{N} \sum_{i=1}^n \left[\max \{S(T_i) - K, 0\} \prod_{m=1}^M 1 \{S(t_{m,i}) \leq B\} \right].$$

Barrier Option: Continuous Monitoring

Consider the previous barrier option but monitoring is continuous. The present value equals to

$$\mathbb{E} [\max \{S(T) - K, 0\} \mathbf{1}(S(t) \leq B, \forall t \leq T)].$$

We can use an idea similar to [Brownian bridge](#) to handle continuous monitoring. For a fixed $S(0)$,

$$\begin{aligned} & \mathbb{E} [\max \{S(T) - K, 0\} \mathbf{1}(S(t) \leq B, \forall t \leq T)] \\ = & \mathbb{E} \{\mathbb{E} [\max \{S(T) - K, 0\} \mathbf{1}(S(t) \leq B, \forall t \leq T) \mid S(T)]\} \\ = & \mathbb{E} \{\max \{S(T) - K, 0\} \mathbb{E} [\mathbf{1}(S(t) \leq B, \forall t \leq T) \mid S(T)]\} \\ = & \mathbb{E} \{\max \{S(T) - K, 0\} P[S(t) \leq B, \forall t \leq T \mid S(T)]\}. \end{aligned}$$

More General Stochastic Differential Equation

Now we consider a more general stochastic differential equation (SDE) of the form

$$dX(t) = a(X(t))dt + b(X(t))dW(t),$$

where $a()$ and $b()$ depend on the stochastic process $X(t)$.

The stochastic process $X(t)$ is a solution, if $X(t)$ solves the integral

$$X(t) - X(0) = \int_0^t a(X(s))ds + \int_0^t b(X(s))dW(s).$$

We can approximate the solution using discretization methods.

Euler-Maruyama Method

We discretize the time interval $[0, T]$ into a time grid of step size Δt . Then, the Euler-Maruyama approximation is

$$\hat{X}(t_{n+1}) = \hat{X}(t_n) + a(\hat{X}(t_n)) \Delta t + b(\hat{X}(t_n)) [W(t_{n+1}) - W(t_n)],$$

where $\Delta t = t_{n+1} - t_n$ for any n .

- Consider the approximation

$$\int_{t_n}^{t_{n+1}} a(X(s)) ds \approx a(X(t_n))(t_{n+1} - t_n) = a(X(t_n)) \Delta t,$$

$$\int_{t_n}^{t_{n+1}} b(X(s)) dW(s) \approx b(X(t_n)) [W(t_{n+1}) - W(t_n)].$$

- These approximations yield the Euler-Maruyama approximation.

Milstein Method

A refinement is the Milstein approximation:

$$\begin{aligned}\hat{X}(t_{n+1}) &= \hat{X}(t_n) + a\left(\hat{X}(t_n)\right)\Delta t + b\left(\hat{X}(t_n)\right)[W(t_{n+1}) - W(t_n)] \\ &\quad + \frac{1}{2}b\left(\hat{X}(t_n)\right)b'\left(\hat{X}(t_n)\right)\left\{[W(t_{n+1}) - W(t_n)]^2 - \Delta t\right\},\end{aligned}$$

where $b'(x) = \partial b(x) / \partial x$.

- The Euler-Maruyama approximation satisfies

$$\sup_{0 \leq t_n \leq T} E \left[|X(t_n) - \hat{X}(t_n)| \right] \leq O \left(\sqrt{\Delta t} \right).$$

- The Milstein approximation satisfies

$$\sup_{0 \leq t_n \leq T} E \left[|X(t_n) - \hat{X}(t_n)| \right] \leq O(\Delta t).$$

Example: Geometric Brownian Motion

Example

Consider a geometric Brownian motion

$$dS(t) = \mu S(t) dt + \sigma S(t) dW(t).$$

- ① The Euler-Maruyama approximation becomes

$$S(t_{n+1}) = S(t_n) + \mu S(t_n) \Delta t + \sigma S(t_n) [W(t_{n+1}) - W(t_n)].$$

- ② The Milstein approximation becomes

$$\begin{aligned} S(t_{n+1}) &= S(t_n) + \mu S(t_n) \Delta t + \sigma S(t_n) [W(t_{n+1}) - W(t_n)] \\ &\quad + \frac{1}{2} \sigma S(t_n) \cdot \sigma \cdot \left\{ [W(t_{n+1}) - W(t_n)]^2 - \Delta t \right\}. \end{aligned}$$

Example: Discretization Methods

Example

Consider the stochastic process

$$dX(t) = \theta(\mu - X(t))dt + \sigma dW(t).$$

- ① The Euler-Maruyama approximation becomes

$$X(t_{n+1}) = X(t_n) + \theta[\mu - X(t_n)]\Delta t + \sigma[W(t_{n+1}) - W(t_n)].$$

- ② The Milstein approximation becomes

$$\begin{aligned} X(t_{n+1}) &= X(t_n) + \theta[\mu - X(t_n)]\Delta t + \sigma[W(t_{n+1}) - W(t_n)] \\ &\quad + \frac{1}{2}b\left(\hat{X}(t_n)\right) \cdot 0 \cdot \left\{[W(t_{n+1}) - W(t_n)]^2 - \Delta t\right\}. \end{aligned}$$