

# Inference 2, 2023, lecture 3

Rolf Larsson

November 7, 2023

# Outline of the course

Chap. 3.2 Fisher information (continued):

- More on the Fisher Information
- The multivariate case

# More on the Fisher Information

Recall: under regularity conditions, we have

## Definition (3.2)

For every  $\mathbf{x} \in \mathcal{A}$ , we define the **score function** as the derivative of the log-likelihood function, i.e.

$$V(\theta; \mathbf{x}) = l'(\theta; \mathbf{x}) = \frac{\partial}{\partial \theta} \log\{L(\theta; \mathbf{x})\}.$$

## Definition (3.3)

The **Fisher information** is defined by

$$I_{\mathbf{X}}(\theta) = \text{Var}_{\theta}\{V(\theta; \mathbf{X})\}.$$

$$I_{\mathbf{X}}(\theta) = -\text{E}_{\theta}\{l''(\theta; \mathbf{X})\} = -\text{E}_{\theta} \left[ \frac{\partial^2}{\partial \theta^2} \log\{p(\mathbf{X}; \theta)\} \right].$$

# More on the Fisher Information

## Theorem (3.3)

*Let  $X$  and  $Y$  be independent random variables. If  $I_X(\theta)$  and  $I_Y(\theta)$  are the Fisher informations contained in  $X$  and  $Y$ , respectively, then the Fisher information contained in  $(X, Y)$  is given by*

$$I_{(X,Y)}(\theta) = I_X(\theta) + I_Y(\theta).$$

# More on the Fisher Information

## Corollary (3.1)

Let  $\mathbf{X} = (X_1, \dots, X_n)$ , where  $X_1, \dots, X_n$  are independent and distributed as  $X$ , that has Fisher information  $i(\theta) = I_X(\theta)$ . Then,

$$I_{\mathbf{X}}(\theta) = nI_X(\theta).$$

Example 1:

- Let  $\mathbf{X} = (X_1, \dots, X_n)$ , where  $X_1, \dots, X_n$  are independent and distributed as  $X$ , which is exponential with intensity  $\beta$ .
- Verify by direct calculation that  $I_{\mathbf{X}}(\beta) = nI_X(\beta)$ .

# More on the Fisher Information

## Theorem (3.4)

*Let  $X$  be a random variable with distribution  $P_\theta$ . Suppose that another parametrization is given by  $\theta = h(\xi)$  where  $h$  is differentiable.*

*Then, the information contained in  $X$  about  $\xi$  is given by*

$$I_X^*(\xi) = I_X\{h(\xi)\}\{h'(\xi)\}^2.$$

*Here,  $I_X(\theta)$  is the information that  $X \sim P_\theta$  contains about  $\theta$  and  $I_X^*(\xi)$  is the information that  $X \sim P_{h(\xi)}$  contains about  $\xi$ .*

# More on the Fisher Information

Example 1':

- Let  $\mathbf{X} = (X_1, \dots, X_n)$ , where  $X_1, \dots, X_n$  are independent and distributed as  $X$ , which is exponential with intensity  $\beta$ .
- Let  $\beta = 1/\mu$ , where  $\mu = E(X)$ .
- Calculate the Fisher information in the  $\mu$  parametrization
  - 1 by direct calculation.
  - 2 by using the Fisher information in the  $\beta$  parametrization and theorem 3.4.

# More on the Fisher Information

## Theorem (3.5)

Let  $\mathbf{X}$  be a random variable with  $\mathbf{X} \sim P_\theta$ .

Let  $T(\mathbf{X})$  be any statistic. Suppose that regularity conditions 1-3 hold. Then,

$$I_{T(\mathbf{X})}(\theta) \leq I_{\mathbf{X}}(\theta),$$

where  $I_{T(\mathbf{X})}$  is computed with respect to the distribution of  $T(\mathbf{X})$



# The multivariate case

Recall the regularity conditions when the parameter  $\theta$  is a scalar:

- 1 The distributions  $\{P : \theta \in \Theta\}$  have common support, so that the set

$$\mathcal{A} = \{\mathbf{x} : p(\mathbf{x}; \theta) > 0\}$$

is independent of  $\theta$ .

- 2 The parameter space  $\Theta$  is an open interval (finite or infinite).
- 3 For any  $\mathbf{x} \in \mathcal{A}$  and all  $\theta \in \Theta$ , the derivative  $\partial p(\mathbf{x}; \theta) / \partial \theta$  exists and is finite.

Now, assume that  $\theta = (\theta_1, \dots, \theta_k)'$  is  $k$ -dimensional.

Modify conditions 2 and 3 as follows:

- 2'. The parameter space  $\theta \subseteq \mathcal{R}^k$  is an open set.
- 3'. For all  $\mathbf{x} \in \mathcal{A}$  the likelihood function has finite partial derivatives.

# The multivariate case

Under regularity conditions 1, 2', 3':

## Definition (3.5)

For all  $\mathbf{x} \in \mathcal{A}$ , the vector of partial derivatives (w.r.t. the parameters) of the log likelihood function

$$V(\theta; \mathbf{x}) = \left( \frac{\partial}{\partial \theta_1} l(\theta; \mathbf{x}), \dots, \frac{\partial}{\partial \theta_k} l(\theta; \mathbf{x}) \right)'$$

is called the **score function** or score vector.

# The multivariate case

## Definition (3.5)

The  $k \times k$  matrix

$$I_{\mathbf{X}}(\theta) = \text{Cov}_{\theta}\{V(\theta; \mathbf{X})\}$$

is called the **Fisher information matrix**. The element in row  $j$  and column  $r$  is given by

$$I_{\mathbf{X}}(\theta)_{jr} = \mathbb{E}_{\theta} \left\{ \frac{\partial}{\partial \theta_j} l(\theta; \mathbf{X}) \frac{\partial}{\partial \theta_r} l(\theta; \mathbf{X}) \right\}.$$

# The multivariate case

**Regularity condition 4'**: For all  $\mathbf{x} \in \mathcal{A}$  the likelihood function has second order partial derivatives and for all  $\theta \in \Theta$  and  $j, r = 1, \dots, k$ ,

$$\frac{\partial^2}{\partial \theta_j \partial \theta_r} \int_{\mathcal{A}} f(\mathbf{x}; \theta) d\mathbf{x} = \int_{\mathcal{A}} \frac{\partial^2}{\partial \theta_j \partial \theta_r} f(\mathbf{x}; \theta) d\mathbf{x}$$

in the continuous case, and similarly in the discrete case.

## Theorem (3.6)

*Suppose regularity conditions 1, 2', 3' and 4' hold.*

*Let  $J(\theta; \mathbf{X})$  (the observed Fisher information matrix) be a  $k \times k$  matrix with elements*

$$J(\theta; \mathbf{X})_{jr} = -\frac{\partial^2}{\partial \theta_j \partial \theta_r} l(\theta; \mathbf{X}), \quad j, r = 1, \dots, k.$$

*Then the Fisher information satisfies  $I_{\mathbf{X}}(\theta) = E_{\theta}\{J(\theta; \mathbf{X})\}$ .*

# The multivariate case

Example 2:

- Suppose  $\mathbf{X} = (X_1, \dots, X_n)$  where the  $X_i$  are independent and distributed as  $X$
- and that we have a sample  $\mathbf{x} = (x_1, \dots, x_n)$ .
- Calculate the Fisher information matrix of  $X \sim N(\mu, \sigma^2)$  (both parameters unknown).

# The multivariate case

Example 3:

- Suppose  $\mathbf{X} = (X_1, \dots, X_n)$  where the  $X_i$  are independent and distributed as  $X$
- and that we have a sample  $\mathbf{x} = (x_1, \dots, x_n)$ .
- Let  $X$  be multinomial such that the probability function is  $p(k) = p_k > 0$  for  $k = 1, 2, 3, 4$  and  $p(k) = 0$  otherwise.
- Calculate the Fisher information matrix of  $X$ .

# News of today

- For independent random variables, the Fisher information is additive.
- The Fisher information for a transformed parameter is given by a simple formula.
- A statistic does not contain more (Fisher) information than the original sample does.
- The multivariate case:
  - Score function
  - Fisher information