EXAM IN STATISTICAL MACHINE LEARNING STATISTISK MASKININLÄRNING

DATE AND TIME: March 10, 2022, 8.00–13.00

RESPONSIBLE TEACHER: Jens Sjölund

NUMBER OF PROBLEMS: 5

AIDING MATERIAL: Calculator, mathematical handbook

PRELIMINARY GRADES: grade 3 23 points

grade 4 33 points grade 5 43 points

Some general instructions and information:

- Your solutions should be given in English.
- Only write on one page of the paper.
- Write your exam code and a page number on all pages.
- Do not use a red pen.
- Use separate sheets of paper for the different problems (i.e. the numbered problems, 1–5).

With the exception of Problem 1, all your answers must be clearly motivated! A correct answer without a proper motivation will score zero points!

Good luck!

- 1. i. False. (See Figure 4.9 (a) in the draft (April 30, 2021) SML book. The bias is approximately constant as the number of training examples increases.)
 - ii. False. (Because the logistic loss is convex. Reference in the draft (April 30, 2021) SML book on page 96: "Examples of convex functions are the cost functions for logistic regression, linear regression and L^1 -regularized linear regression.")
 - iii. True. Reference in the draft (April 30, 2021) SML book on page 94: "Whereas L^2 regularization pushes all parameters towards small values (but not necessarily exactly zero), L^1 tends to favor so-called sparse solutions where only a few of the parameters are non-zero, and the rest are exactly zero."
 - iv. True (Because of the sparse interactions and parameter sharing in convolutional layers. Reference in the draft (April 30, 2021) SML book on page 126: "Furthermore, a convolutional layer uses significantly fewer parameters compared to the corresponding dense layer.")
 - v. False. (Reference in the draft (April 30, 2021) SML book on page 140: "It is important to understand that by the construction of bagging, more ensemble members does not make the resulting model more flexible, but only reduces the variance.")
 - vi. True. (Reference in the draft (April 30, 2021) SML book on page 141: "When using bagging, it turns out that there is a way to estimate the expected new data error E_{new} without using cross-validation.")
 - vii. False. (Reference in the draft (April 30, 2021) SML book on page 151: "Another unfortunate aspect of the sequential nature of boosting is that it is not possible to parallelize the learning.")
 - viii. True. (Reference in the draft (April 30, 2021) SML book on page 240: "For models that are trained iteratively we can reduce $E_{\rm train}$ by training longer.")
 - ix. False. (Reference in the draft (April 30, 2021) SML book on page 49: "linear regression is a model which is linear in its parameters")
 - x. True. (Reference in the draft (April 30, 2021) SML book on page 29)

- 2. (a) Liz is correct given a Gaussian noise assumption. Using the squared error loss is equivalent to assuming a Gaussian noise distribution in the maximum likelihood formulation.
 - (b) The decision boundary of a logistic regression classifier is given by $\Theta^T \tilde{\mathbf{x}} = 0$. This gives us the following decision boundary:

$$\Theta^T \tilde{\mathbf{x}} = -6.75 + 0.5m + v = 0 \iff v = 6.75 - 0.5m.$$

For each sample (m_*, v_*) in the test dataset, the expression for the decision boundary can be used to make a prediction according to:

$$\begin{cases} 1 & \text{for } -6.75 + 0.5m_* + v_* > 0 \\ -1 & \text{for } -6.75 + 0.5m_* + v_* < 0 \end{cases}$$

Comparing the predicted class to the true class for each sample in the test dataset gives a misclassification rate of $\frac{1}{6} \approx 17\%$.

(c) Liz is not correct. The material is a qualitative input feature that can be encoded using dummy variables. One suggestion is to use the dummy variables x_1 , x_2 and x_3 according to:

$$x_1 = \begin{cases} 1 & \text{if plastic} \\ 0 & \text{else} \end{cases}, \quad x_2 = \begin{cases} 1 & \text{if wood} \\ 0 & \text{else} \end{cases}, \quad x_3 = \begin{cases} 1 & \text{if metal} \\ 0 & \text{else} \end{cases}.$$

(d) The general criterion is that the data has to be (approximately) separable by a linear decision boundary in the space spanned by all inputs, including transformed inputs (1p).

Logistic regression can be used for all of the datasets depicted (1p per dataset; inputs x_1 , x_2 do not have to be mentioned explicitly):

- (i) The decision boundary already is linear, no transformed inputs are required.
- (ii) Use additional transformed input $x_3 = x_1^2$.
- (iii) Use transformed input $x_3 = r = \sqrt{x_1^2 + x_2^2}$.

3. a) **k-NN**

For the first missing point we have

$$||x_1 - x_A||_2 = \sqrt{(-2)^2 + (-8)^2} = \sqrt{68} = 2\sqrt{17} \approx 8.246$$

For the second missing point we have

$$||x_3 - x_A||_2 = \sqrt{(-7)^2 + (-7)^2} = \sqrt{98} = 7\sqrt{2} \approx 9.899$$

For our two cases we use the majority vote within the neighbor-

Runner id	X		y	$\left\ x-x_A\right\ _2$	
1	38	82	1	$\sqrt{68} \approx 8.246$	
2	32	85	1	9.4	
3	33	83	-1	$\sqrt{98} \approx 9.899$	
4	28	85	-1	13.0	
5	44	93	-1	5.0	
6	57	97	-1	18.4	

hood R, to assign x_A to class m with $\sum_{i \in R} 1\{y_i = m\}$. Using this we have:

i k = 1, we simply consider the class of the closest distance which is x_5 .

Hence, our prediction is y = -1.

ii k = 3, we take the three closest points x_5 , x_1 and x_2 . The sum of the classes for m = 1 is 2 and for m = -1 is 1. Hence our prediction is y = 1.

b) In a QDA model the prior/marginal probability p(y=1) is estimated by:

$$\hat{\pi}_1 = \frac{n_1}{n} = \frac{2}{6} = \frac{1}{3}$$

where n is the total number of data points in the dataset and n_1 the number of data points with label y = 1.

The likelihood p(x|y=1) is estimated as a normal distribution with the parameters $\hat{\mu}_1$ and $\hat{\Sigma}_1$ as following:

3

The mean of the distribution is given by:

$$\hat{\mu}_1 = \frac{1}{n_1} \sum_{i:y_i=1} x_i$$

$$= \frac{1}{2} (x_1 + x_2)$$

$$= 0.5([38 \ 82]^{\mathsf{T}} + [32 \ 85]^{\mathsf{T}})$$

$$= [35 \ 83.5]^{\mathsf{T}}$$

The estimation of the covariance matrix for the distribution in QDA is given by:

$$\hat{\Sigma}_{1} = \frac{1}{n_{1} - 1} \sum_{i:y_{i} = 1} (x_{i} - \hat{\mu}_{1})(x_{i} - \hat{\mu}_{1})^{\mathsf{T}}$$

$$= \frac{1}{2 - 1} [(x_{1} - \hat{\mu}_{1})(x_{1} - \hat{\mu}_{1})^{\mathsf{T}} + (x_{2} - \hat{\mu}_{1})(x_{2} - \hat{\mu}_{1})^{\mathsf{T}}]$$

$$= \begin{bmatrix} 9 & -4.5 \\ -4.5 & 2.25 \end{bmatrix} + \begin{bmatrix} 9 & -4.5 \\ -4.5 & 2.25 \end{bmatrix}$$

$$= \begin{bmatrix} 18 & -9 \\ -9 & 4.5 \end{bmatrix}$$

The likelihood is estimated by $p(x|y=1) = \mathcal{N}(x|\hat{\mu}_1, \hat{\Sigma}_1)$.

c) For runner A, we have that

$$p(y = 1|x_A) = \frac{\mathcal{N}(x_A|\hat{\mu}_1, \hat{\Sigma}) \cdot \hat{\pi}_1}{\mathcal{N}(x_A|\hat{\mu}_1, \hat{\Sigma}) \cdot \hat{\pi}_1 + \mathcal{N}(x_A|\hat{\mu}_{-1}, \hat{\Sigma}) \cdot \hat{\pi}_{-1}}$$
$$= \frac{0.0020 \cdot 0.31}{0.0020 \cdot 0.31 + 0.0030 \cdot 0.69}$$
$$= 0.23$$

Thus, we obtain $p(y = -1|x_A) = 1 - p(y = 1|x_A) = 1 - 0.23 = 0.77$.

For runner B, we obtain similarly

$$p(y = 1|x_B) = \frac{\mathcal{N}(x_B|\hat{\mu}_1, \hat{\Sigma}) \cdot \hat{\pi}_1}{\mathcal{N}(x_B|\hat{\mu}_1, \hat{\Sigma}) \cdot \hat{\pi}_1 + \mathcal{N}(x_B|\hat{\mu}_{-1}, \hat{\Sigma}) \cdot \hat{\pi}_{-1}}$$

$$= \frac{0.0014 \cdot 0.31}{0.0014 \cdot 0.31 + 0.00019 \cdot 0.69}$$

$$= 0.768$$

For the threshold r = 0.5, we predict $\hat{y}(x_A) = -1$ and $\hat{y}(x_B) = 1$. Thus, the average misclassification error is 0.5.

d) The figure can be drawn e.g. like the one in Figure 1. QDA

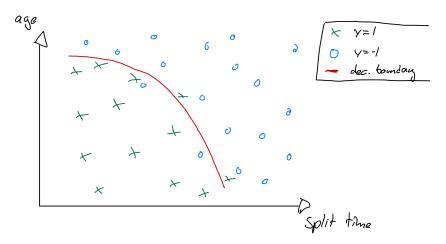


Figure 1: Possible solution for LDA/QDA scatter plot

would work better in this setting since the true decision boundary is quadratic. LDA would just define a linear decision boundary which would then have a higher error rate than a quadratic one.

- 4. (a) No, quite the opposite. A robust loss is insensitive to a limited amount of large errors (outliers), whereas the minimax loss picks out the largest errors.
 - (b) The prediction for each leaf is given by the average (the minimizer of the squared error). Based on this, we have to compute the minimax loss for each cutpoint $s \in \{2,4,6\}$ and select the one that minimizes the loss. As shown by the comparison in Table 1, s=2 minimizes the loss. The resulting prediction is plotted in Figure 2.

x	1	3	5	7	$L(\mathbf{y}, \hat{\mathbf{y}})$
\overline{y}	0	5	2	1	
$\hat{y}_{s=2}$	0	8/3	8/3	8/3	7/3
$\hat{y}_{s=4}$	5/2	5/2	3/2	3/2	5/2
$\hat{y}_{s=6}$	7/3	7/3	8/3 3/2 7/3	1	8/3

Table 1: Predictions of a stump with different cutpoints.

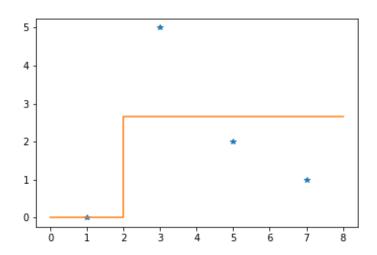


Figure 2: Prediction from stump.

(c) Following a similar procedure as in part (b), the models for each bootstrapped dataset can be found as shown in Tables 2 and 3:

The prediction of the bagged model is the average of the predictions from those two models (both of which happen to have the

Table 2: Stump trained on $\mathcal{T}^{(1)}$.

Table 3: Stump trained on $\mathcal{T}^{(2)}$.

Table 4: Predictions of the bagged model.

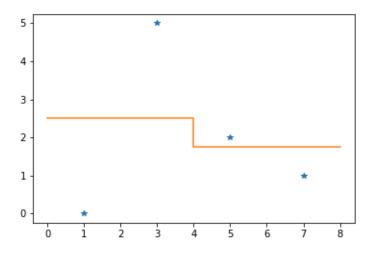


Figure 3: Prediction from bagged model.

same cutpoint, s=4), as shown in Table 4 and plotted in Figure 3.

(d) The leaf s < 2 has only one element, thus $\hat{y}_{\min}(1) = y(0) = 0$ attains the lower-bound on the loss: 0. The leaf $s \ge 2$ has three

elements, and the prediction is the solution to the optimization problem:

$$\hat{y}(x \ge 2)_{\min \max} = \underset{y}{\operatorname{arg\,min}} (\max(|5 - y|, |2 - y|, |1 - y|)) = 3.$$

This solution can be found, for instance, by plotting each component separately and finding the minimum of the pointwise max. Table 5 summarizes the predictions.

Table 5: Predictions of the minimax model.

(e) Bagging is a method for reducing variance, which can improve the performance of base models with low bias and high variance such as *deep* regression trees. In contrast, a shallow regression tree, such as a stump, has high bias and lower variance. Thus, bagging is not likely to improve the performance.

Boosting, on the other hand, is a method for reducing bias that is, in fact, often used with shallow regression trees.

$$1 - \sigma(z) = 1 - \frac{1}{1 + \exp(-z)} = \frac{1 + \exp(-z)}{1 + \exp(-z)} - \frac{1}{1 + \exp(-z)}$$
$$= \frac{1 + \exp(-z) - 1}{1 + \exp(-z)} = \frac{\exp(-z)}{1 + \exp(-z)}$$
$$= \frac{\frac{\exp(z)}{\exp(z)}}{\exp(z) + \frac{\exp(z)}{\exp(z)}} = \frac{1}{\exp(z) + 1} = \sigma(-z)$$

(2p)

- (b) i. We obtain $\begin{pmatrix} 13 & -16 & -1 \\ 20 & 28 & 22 \end{pmatrix}$, where for example $4 \cdot 2 + 3 \cdot 4 + 0 \cdot -1 = 20$. (2p)
 - ii. If the vectorization is done row-wise, i.e.,

$$\mathbf{x} = \operatorname{vec} \begin{bmatrix} \begin{pmatrix} x_1 & x_2 & x_3 \\ x_4 & x_5 & x_6 \\ x_7 & x_8 & x_9 \\ x_{10} & x_{11} & x_{12} \end{pmatrix} \end{bmatrix} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_{11} \\ x_{12} \end{pmatrix}$$

we obtain

$$\begin{pmatrix} f_1 & 0 & 0 & f_2 & 0 & 0 & f_3 & 0 & 0 & 0 & 0 & 0 \\ 0 & f_1 & 0 & 0 & f_2 & 0 & 0 & f_3 & 0 & 0 & 0 & 0 \\ 0 & 0 & f_1 & 0 & 0 & f_2 & 0 & 0 & f_3 & 0 & 0 & 0 \\ 0 & 0 & 0 & f_1 & 0 & 0 & f_2 & 0 & 0 & f_3 & 0 & 0 \\ 0 & 0 & 0 & 0 & f_1 & 0 & 0 & f_2 & 0 & 0 & f_3 & 0 \\ 0 & 0 & 0 & 0 & 0 & f_1 & 0 & 0 & f_2 & 0 & 0 & f_3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_{11} \\ x_{12} \end{pmatrix} = \begin{pmatrix} s_1 \\ s_2 \\ s_3 \\ s_4 \\ s_5 \\ s_6 \end{pmatrix}$$

In case of a column-wise vectorization, i.e.,

$$\mathbf{x} = \text{vec} \begin{bmatrix} \begin{pmatrix} x_1 & x_2 & x_3 \\ x_4 & x_5 & x_6 \\ x_7 & x_8 & x_9 \\ x_{10} & x_{11} & x_{12} \end{pmatrix} \end{bmatrix} = \begin{pmatrix} x_1 \\ x_4 \\ x_7 \\ x_{10} \\ \vdots \\ x_9 \\ x_{12} \end{pmatrix}$$

we get

$$\begin{pmatrix}
f_1 & f_2 & f_3 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & f_1 & f_2 & f_3 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & f_1 & f_2 & f_3 & 0 \\
0 & f_1 & f_2 & f_3 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & f_1 & f_2 & f_3 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & f_1 & f_2 & f_3
\end{pmatrix}
\begin{pmatrix}
x_1 \\ x_4 \\ x_7 \\ x_{10} \\ \vdots \\ x_9 \\ x_{12}
\end{pmatrix} = \begin{pmatrix}
s_1 \\ s_2 \\ s_3 \\ s_4 \\ s_5 \\ s_6
\end{pmatrix}$$
(3p)

(c) For i = j we have

$$\frac{\partial p_j}{\partial x_i} = \frac{\exp(x_j) \left(\sum_k \exp(x_k)\right) - \exp(x_j) \exp(x_i)}{\left(\sum_k \exp(x_k)\right)^2} \qquad \text{(derivative of a rational)}$$

$$= \frac{\exp(x_j)}{\sum_k \exp(x_k)} \cdot \frac{\left(\sum_k \exp(x_k)\right) - \exp(x_i)}{\sum_k \exp(x_k)} \qquad \text{(separate } \exp(x_j)\text{)}$$

$$= \frac{\exp(x_j)}{\sum_k \exp(x_k)} \cdot \left(\frac{\left(\sum_k \exp(x_k)\right)}{\sum_k \exp(x_k)} - \frac{\exp(x_i)}{\sum_k \exp(x_k)}\right)$$

$$= p_j \cdot (1 - p_i)$$

and for $i \neq j$ we get

$$\frac{\partial p_j}{\partial x_i} = \frac{0 - \exp(x_j) \exp(x_i)}{(\sum_k \exp(x_k))^2}$$
$$= \frac{\exp(x_j)}{\sum_k \exp(x_k)} \cdot \frac{- \exp(x_i)}{\sum_k \exp(x_k)}$$
$$= p_j \cdot (0 - p_i).$$

Combined, that yields

$$\frac{\partial p_j}{\partial x_i} = p_j(\delta_{ij} - p_i),$$

where δ_{ij} is 1 if i = j and 0 otherwise.

(3p)

 $\mathbf{w}\mathbf{x} = \mathbf{s}$