

5. Stochastic Differential Equations

Let • a d -dimensional Brownian motion W

• $\mu : [0, \infty) \times \mathbb{R}^n \rightarrow \mathbb{R}^n$

• $\sigma : [0, \infty) \times \mathbb{R}^n \rightarrow \mathbb{R}^{n \times d}$

• $x_0 \in \mathbb{R}^n$

be given. A stochastic differential equation is an equation of the form

$$(*) \quad \begin{cases} dX_t = \mu(t, X_t) dt + \sigma(t, X_t) dW_t \\ X_0 = x_0 \end{cases}$$

or, equivalently,
$$X_t = x_0 + \int_0^t \mu(s, X_s) ds + \int_0^t \sigma(s, X_s) dW_s.$$

Prop 5.1 Assume $\|\mu(t, x) - \mu(t, y)\| + \|\sigma(t, x) - \sigma(t, y)\| \leq K\|x - y\|$
and $\|\mu(t, x)\| + \|\sigma(t, x)\| \leq K\|x\|$ for some K .

Then there exists a unique solution X_t to the SDE (*). Moreover,

i) X is \mathcal{F}^W -adapted

ii) X_t has continuous trajectories

iii) X is a Markov process.

Geometric Brownian motion ($n=1$)

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Consider $\begin{cases} dX_t = \alpha X_t dt + \sigma X_t dW_t \\ X_0 = x_0 \end{cases}$ $\xrightarrow{\text{constants}}$

Note: If $\sigma=0$, then $dX_t = \alpha X_t dt$ so $X_t = x_0 e^{\alpha t}$.

Let $Z_t = \ln X_t$. Then

$$\underset{\text{Ito}}{dZ_t} = \frac{1}{X_t} dX_t - \frac{1}{2} \frac{1}{X_t^2} (dX_t)^2 = \left(\alpha - \frac{\sigma^2}{2}\right) dt + \sigma dW_t$$

so

$$Z_t = \ln x_0 + \left(\alpha - \frac{\sigma^2}{2}\right)t + \sigma W_t$$

and $X_t = e^{Z_t} = x_0 e^{\left(\alpha - \frac{\sigma^2}{2}\right)t + \sigma W_t}$

Moreover,
$$\begin{aligned} E[X_t] &= x_0 + E\left[\int_0^t \alpha X_s ds\right] + \underbrace{E\left[\int_0^t \sigma X_s dW_s\right]}_0 \\ &= x_0 + \alpha \int_0^t E[X_s] ds \end{aligned}$$

so if $m(t) := E[X_t]$ we find that
$$\begin{cases} \dot{m}(t) = \alpha m(t) \\ m(0) = x_0 \end{cases}$$

Thus $m(t) = x_0 e^{\alpha t}$.

Result: The solution of $\begin{cases} dX_t = \alpha X_t dt + \sigma X_t dW_t \\ X_0 = x_0 \end{cases}$

is $X_t = x_0 \exp\left\{\left(\alpha - \frac{\sigma^2}{2}\right)t + \sigma W_t\right\}$.

Moreover, $E[X_t] = x_0 e^{\alpha t}$.

Ex: Consider the SDE $\begin{cases} dX_t = -X_t dt + dW_t \\ X_0 = x \end{cases}$ (3)

(this is a mean-reverting Ornstein-Uhlenbeck process).

Trick: Let $Y_t := e^t X_t$. Then

$$\begin{aligned} dY_t &= e^t X_t dt + e^t dX_t \\ &= e^t dW_t \end{aligned}$$

$$\text{so } Y_t = x + \int_0^t e^s dW_s.$$

$$\text{Thus } X_t = e^{-t} Y_t = x e^{-t} + e^{-t} \int_0^t e^s dW_s.$$

$$\text{Moreover, } E[X_t] = x e^{-t}.$$

Terminology: The solution X of an SDE

$$\begin{cases} dX_t = \mu(t, X_t) dt + \sigma(t, X_t) dW_t \\ X_0 = x_0 \end{cases}$$

is called a diffusion process.

μ is the drift and σ is the diffusion coefficient.

5.5 Partial Differential Equations

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Consider the following terminal value problem:

Given functions σ, μ, ϕ , find a function $F(t, x)$ such that

$$(*) \quad \begin{cases} \frac{\partial F}{\partial t}(t, x) + \frac{\sigma^2(t, x)}{2} \frac{\partial^2 F}{\partial x^2}(t, x) + \mu(t, x) \frac{\partial F}{\partial x}(t, x) = 0 & \text{for } (t, x) \in (0, \infty) \times \mathbb{R} \\ F(T, x) = \phi(x). \end{cases}$$

If $F(t, x)$ satisfies $(*)$, define X_s by

$$\begin{cases} dX_s = \mu(s, X_s) ds + \sigma(s, X_s) dW_s \\ X_t = x \end{cases}$$

and let $Z_s = F(s, X_s)$. Then

$$\begin{aligned} dZ_s &= \frac{\partial F}{\partial s} ds + \frac{\partial F}{\partial x} dX_s + \frac{1}{2} \frac{\partial^2 F}{\partial x^2} (dX_s)^2 \\ &\stackrel{It\ddot{o}}{=} \underbrace{\left(\frac{\partial F}{\partial s} + \mu \frac{\partial F}{\partial x} + \frac{\sigma^2}{2} \frac{\partial^2 F}{\partial x^2} \right)}_0 ds + \sigma \frac{\partial F}{\partial x} dW_s \\ &= \sigma \frac{\partial F}{\partial x} dW_s. \end{aligned}$$

$$\text{Integrate: } Z_T = Z_t + \int_t^T \sigma(s, X_s) \frac{\partial F}{\partial x}(s, X_s) dW_s$$

$$\text{Take expectation: } E[Z_T] = Z_t = F(t, x)$$

$$E[F(T, X_T)] = E[\phi(X_T)]$$

We write $F(t, x) = E_{t, x}[\phi(X_T)]$
to indicate that $X_t = x$

We have thus proved the following:

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Prop. 5.5 (Feynman-Kac)

$$\text{If } F(t, x) \text{ satisfies } \begin{cases} \frac{\partial F}{\partial t} + \frac{\sigma^2(t, x)}{2} \frac{\partial^2 F}{\partial x^2} + \mu(t, x) \frac{\partial F}{\partial x} = 0 & (t < T) \\ F(T, x) = \Phi(x) \end{cases}$$

$$\text{then } F(t, x) = E_{t, x}[\Phi(X_T)] \text{ where } \begin{cases} dX_s = \mu(s, X_s)ds + \sigma(s, X_s)dW_s \\ X_t = x \end{cases}$$

Ex 5.7 Solve the PDE
$$\begin{cases} \frac{\partial F}{\partial t} + \frac{\sigma^2}{2} \frac{\partial^2 F}{\partial x^2} = 0 \\ F(T, x) = x^2 \end{cases}$$

(σ constant).

Let X_s be the solution of
$$\begin{cases} dX_s = \sigma dW_s \\ X_t = x \end{cases}$$

i.e. $X_s = x + \sigma(W_s - W_t)$.

By Feynman-Kac,

$$\begin{aligned} F(t, x) &= E_{t, x}[X_T^2] = E[(x + \sigma(W_T - W_t))^2] = \\ &= x^2 + 2x\sigma E[W_T - W_t] + \sigma^2 E[(W_T - W_t)^2] \\ &= x^2 + \sigma^2(T - t). \end{aligned}$$

Answer: $F(t, x) = x^2 + \sigma^2(T - t)$