Analysis of Time Series, L6

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Today

3.5: Forecasting

- The best linear prediction
- The Durbin-Levinson algorithm
- ARMA processes



AR(p):

- We observe $x_t = \phi_1 x_{t-1} + \phi_2 x_{t-2} + ... + \phi_p x_{t-p} + w_t$ for t = 1, 2, ..., n.
- Assume that $\phi_1, \phi_2, ..., \phi_p$ are known.
- Predict x_{n+1} .
- A natural predictor is

$$\phi_1 x_n + \phi_2 x_{n-1} + \dots + \phi_p x_{n-p+1}$$
.

• Is it optimal in some sense?



- Assume that $\{x_t\}$ is stationary with known model parameters.
- We observe $x_1, x_2, ..., x_n$.
- Predict x_{n+m} by the linear predictor

$$x_{n+m}^{n} = \alpha_0 + \alpha_n x_n + \alpha_{n-1} x_{n-1} + \dots + \alpha_1 x_1$$

= $\alpha_0 + \sum_{k=1}^{n} \alpha_k x_k$.

• Mean square error $E\{(x_{n+m}-x_{n+m}^n)^2\}$.

Theorem (Property 3.3)

The linear predictor that minimizes the mean square error is found by solving

$$E\{(x_{n+m}-x_{n+m}^n)x_k\}=0, \quad k=0,1,...,n$$

where $x_0 = 1$, for $\alpha_0, \alpha_1, ..., \alpha_n$.

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- Assume WLOG that $E(x_t) = \mu = 0$, i.e. $\alpha_0 = 0$.
- Find the optimal one-step predictor

$$x_{n+1}^n = \phi_{n1}x_n + \phi_{n2}x_{n-1} + \dots + \phi_{nn}x_1.$$

Solve (why?)

$$\begin{pmatrix} \gamma(0) & \gamma(1) & \dots & \gamma(n-1) \\ \gamma(1) & \gamma(0) & \dots & \gamma(n-2) \\ \vdots & \vdots & \ddots & \vdots \\ \gamma(n-1) & \gamma(n-2) & \dots & \gamma(0) \end{pmatrix} \begin{pmatrix} \phi_{n1} \\ \phi_{n2} \\ \vdots \\ \phi_{nn} \end{pmatrix} = \begin{pmatrix} \gamma(1) \\ \gamma(2) \\ \vdots \\ \gamma(n) \end{pmatrix}$$

• i.e. $\Gamma_n \phi_n = \gamma_n$.



- $\Gamma_n \phi_n = \gamma_n$.
- For ARMA models, it can be shown that Γ_n is positive definite.
- Hence, $\phi_n = \Gamma_n^{-1} \gamma_n$, i.e.

$$\begin{pmatrix} \phi_{n1} \\ \phi_{n2} \\ \vdots \\ \phi_{nn} \end{pmatrix} = \begin{pmatrix} \gamma(0) & \gamma(1) & \dots & \gamma(n-1) \\ \gamma(1) & \gamma(0) & \dots & \gamma(n-2) \\ \vdots & \vdots & \ddots & \vdots \\ \gamma(n-1) & \gamma(n-2) & \dots & \gamma(0) \end{pmatrix}^{-1} \begin{pmatrix} \gamma(1) \\ \gamma(2) \\ \vdots \\ \gamma(n) \end{pmatrix}$$

• Derive the one-step predictors for zero mean causal AR(1) and AR(2) processes with one and two observations, respectively.

• Problem 3.45: For a zero mean causal AR(p),

$$x_{n+1}^n = \phi_1 x_n + \phi_2 x_{n-1} + \dots + \phi_p x_{n+1-p}.$$

• In general, for a zero mean causal process,

$$x_{n+1}^{n} = \phi_{n1}x_{n} + \phi_{n2}x_{n-1} + \dots + \phi_{nn}x_{1}$$

$$= \begin{pmatrix} \phi_{n1} & \phi_{n2} & \dots & \phi_{nn} \end{pmatrix} \begin{pmatrix} x_{n} \\ x_{n-1} \\ \vdots \\ x_{1} \end{pmatrix} = \phi'_{n}x.$$

Mean square prediction error (see the book, p.102)

$$P_{n+1}^n = E\{(x_{n+1} - x_{n+1}^n)^2\} = \gamma(0) - \gamma_n' \Gamma_n^{-1} \gamma_n.$$

The Durbin-Levinson algorithm

- We have derived $x_{n+1}^n = \phi_n' \mathbf{x} = \gamma_n' \Gamma_n^{-1} \mathbf{x}$.
- Is it possible to calculate x_{n+1}^n without inverting Γ_n ?

Theorem (Property 3.4, Problem 3.13)

 ϕ_n and P_{n+1}^n may be found iteratively as follows:

$$\phi_{00} = 0, \quad P_1^0 = \gamma_0.$$

For $n \geq 1$,

$$\phi_{nn} = \frac{\rho(n) - \sum_{k=1}^{n-1} \phi_{n-1,k} \rho(n-k)}{1 - \sum_{k=1}^{n-1} \phi_{n-1,k} \rho(k)}, \quad P_{n+1}^n = P_n^{n-1} (1 - \phi_{nn}^2),$$

where for $n \geq 2$,

$$\phi_{nk} = \phi_{n-1,k} - \phi_{nn}\phi_{n-1,n-k}, \quad k = 1, 2, ..., n-1.$$

The Durbin-Levinson algorithm

Theorem (Property 3.5, Problem 3.13)

The PACF of a stationary process $\{x_t\}$ is given by ϕ_{nn} .

Example 1:

Use the Durbin-Levinson algorithm to obtain the PACF of an AR(2) process!

The Durbin-Levinson algorithm

- Generalization to prediction more than one step is straightforward, see the book.
- For predicting MA processes it is easier to use *the innovations* algorithm (property 3.6).
- Read about it by yourself!

• Recall: For a zero mean causal AR(p), the optimal one-step predictor is

$$x_{n+1}^n = \phi_1 x_n + \phi_2 x_{n-1} + \dots + \phi_p x_{n+1-p}.$$

• Idea: For causal ARMA processes (including MA), why not just use the AR representation $x_t + \pi_1 x_{t-1} + \pi_2 x_{t-2} + ... = w_t$, i.e.

$$x_t = w_t - \pi_1 x_{t-1} - \pi_2 x_{t-2} - \dots$$

for prediction?

- Problem: This requires an infinite past!
- But for large samples, by truncation it can be used as an approximation.
- In particular, it can also be used as an approximation for pure MA processes.

One step ahead, forecast:

Replace the minimum mean square error predictor

$$x_{n+1}^n = E(x_{n+1}|x_n,...,x_1)$$

by

$$\tilde{x}_{n+1} = E(x_{n+1}|x_n,...,x_1,x_0,x_{-1},...).$$

The AR form

$$x_{n+1} = w_{n+1} - \pi_1 x_n - \pi_2 x_{n-1} - \dots = w_{n+1} - \sum_{j=1}^{\infty} \pi_j x_{n+1-j}$$

• implies (take $E(\cdot|x_n,...,x_1,x_0,x_{-1},...)$)

$$\tilde{x}_{n+1} = -\pi_1 x_n - \pi_2 x_{n-1} - \dots = -\sum_{j=1}^{\infty} \pi_j x_{n+1-j}.$$



One step ahead, prediction error:

• For invertible processes, the MA representation

$$x_{n+1} = w_{n+1} + \psi_1 w_n + \psi_2 w_{n-1} + \dots = w_{n+1} + \sum_{j=1}^{\infty} \psi_j w_{n+1-j}$$

• implies (take $E(\cdot|x_n,...,x_1,x_0,x_{-1},...)$)

$$\tilde{x}_{n+1} = \psi_1 w_n + \psi_2 w_{n-1} + \dots = \sum_{j=1}^{\infty} \psi_j w_{n+1-j}.$$

• Hence, $x_{n+1} - \tilde{x}_{n+1} = w_{n+1}$, and the mean square prediction error is

$$P_{n+1}^n = E\{(x_{n+1} - \tilde{x}_{n+1})^2\} = E(w_{n+1}^2) = \sigma_w^2.$$



 $m \ge 2$ steps ahead, forecast:

Calculate

$$\tilde{x}_{n+m} = E(x_{n+m}|x_n,...,x_1,x_0,x_{-1},...).$$

The AR form

$$x_{n+m} = w_{n+m} - \pi_1 x_{n+m-1} - \pi_2 x_{n+m-2} - \dots$$

$$= w_{n+m} - \sum_{j=1}^{m-1} \pi_j x_{n+m-j} - \sum_{j=m}^{\infty} \pi_j x_{n+m-j}$$

• implies (take $E(\cdot|x_n,...,x_1,x_0,x_{-1},...)$)

$$\tilde{x}_{n+m} = -\sum_{j=1}^{m-1} \pi_j \tilde{x}_{n+m-j} - \sum_{j=m}^{\infty} \pi_j x_{n+m-j}.$$



 $m \ge 2$ steps ahead, prediction error:

ullet For invertible processes, the MA representation $(\psi_0=1)$

$$x_{n+m} = w_{n+m} + \psi_1 w_{n+m-1} + \psi_2 w_{n+m-2} + \dots$$
$$= \sum_{j=0}^{m-1} \psi_j w_{n+m-j} + \sum_{j=m}^{\infty} \psi_j w_{n+m-j}$$

- $E(w_{n+m-j}|x_n,...,x_1,x_0,x_{-1},...)=0$ if m>j and w_{n+m-j} if $m\leq j$
- implies $\tilde{x}_{n+m} = \sum_{j=m}^{\infty} \psi_j w_{n+m-j}$.
- Hence, the mean square prediction error (MSPE) is

$$P_{n+m}^{n} = E\{(x_{n+m} - \tilde{x}_{n+m})^{2}\}\$$

$$= E\left\{\left(\sum_{j=0}^{m-1} \psi_{j} w_{n+m-j}\right)^{2}\right\} = \sigma_{w}^{2} \sum_{j=0}^{m-1} \psi_{j}^{2}.$$

To summarize:

Forecast

$$\tilde{x}_{n+m} = -\sum_{j=1}^{m-1} \pi_j \tilde{x}_{n+m-j} - \sum_{j=m}^{\infty} \pi_j x_{n+m-j}$$

MSPE

$$P_{n+m}^{n} = \sigma_{w}^{2} \sum_{i=0}^{m-1} \psi_{j}^{2}$$

Prediction interval

$$\tilde{x}_{n+m} \pm c_{\alpha/2} \sqrt{P^n_{n+m}}$$

ullet For normal (Gaussian) processes with lpha=0.05, $c_{lpha/2}=1.96$.



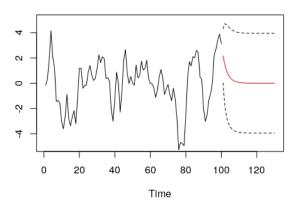
Example 2: Let

$$x_t = 0.8x_{t-1} + w_t + 0.4w_{t-1}$$
.

We observe $x_1, x_2, ..., x_n$, where n = 100, $x_{95} = 0.06$, $x_{96} = 2.21$, $x_{97} = 2.70$, $x_{98} = 3.40$, $x_{99} = 3.89$, $x_{100} = 3.15$.

- Calculate the forecast \tilde{x}_{n+m} for m=1,2,3.
- Calculate the MSPE.
- **3** Calculate the $1 \alpha = 0.95$ prediction interval assuming that $\{w_t\}$ is a normal process with $\sigma_w^2 = 1$.

Example 2: Plot of x_t with forecast horizon 30 and pointwise two standard deviations prediction intervals (obtained from estimated parameters).



In R:

```
> x=arima.sim(list(order=c(1,0,1),ar=0.8,ma=0.4),100)
> m=arima(x,order=c(1,0,1),include.mean=FALSE)
> m
Call:
arima(x = x, order = c(1, 0, 1), include.mean = FALSE)
Coefficients:
         ar1
                ma1
     0.6721 0.4730
s.e. 0.0838 0.0969
sigma^2 estimated as 1.148: log likelihood = -149.51, aic = 305.02
> fore=predict(m,n.ahead=30)
> ts.plot(x,fore$pred,col=1:2,ylim=c(-5,5))
> lines(fore$pred+2*fore$se,lty='dashed')
> lines(fore$pred-2*fore$se,lty='dashed')
```

News of today

- Optimal prediction of AR processes
 - by matrix inversion
 - by iteration
- Optimal prediction of ARMA processes with infinite past (useful as approximations even if not infinite past).
- Note that all of this required known parameters.