

# Non-Convex Shredded Signal Reconstruction via Sparsity Enhancement

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CS531, Detection and Estimation Theory  
Class presentation

# Outline

Introduction

Preliminaries

Optimization

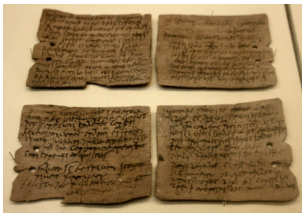
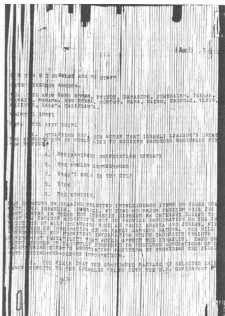
Sparsity

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# Problem at hand - Shredded Signal(document)

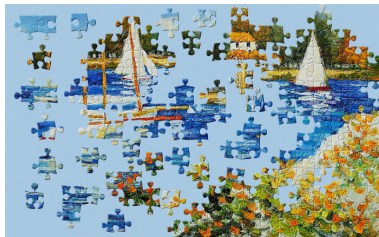
## reconstruction



- The documents are shredded.
- No piece is lost or missing.
- The pieces are of same size and identical in shape.

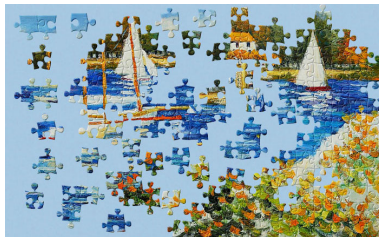
# Past work

- Optimum matching pieces with respect to their contents, color or texture appearance
- Apictorial jigsaw puzzle



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How to frame this as a mathematical problem

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# Optimization Problem

- Maximizing or minimizing some function  $f(x)$  over the variable  $x$ , when the function is subject to some constraints.

## Formal definition of an optimization problem

$$\begin{aligned} & \min_x f(x) \\ & \text{subject to } g_i(x) \leq c \\ & \quad h_j(x) = d, \text{ where } i = 1, \dots, m; j = 1, \dots, n \end{aligned}$$

- $f(x)$  is called the *Objective* - The main problem specification
- $g, h$  are called constraints - Additional details that define the problem
- $x$  is called the optimization variable

# Convexity

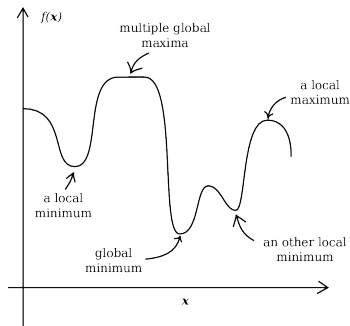
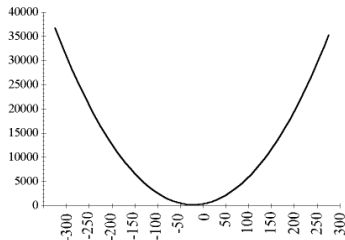


Figure: Figure on the left *Convex* and figure on the right *Non-convex*.

- **Convexity** :  $f(x)$ ,  $g(x)$  &  $h(x)$  are Convex. Else Non-convex
- Convex functions guarantee *Global minima*



# Sparsity

- A signal is sparse if that can be compactly expressed as a linear combination of a few small number of basis vectors.
- In other words , it is a matrix in which most of the elements are zero.
- Why is sparsity interesting ?

$$\begin{bmatrix} 0 & 0 & 0 & 0 \\ 5 & 8 & 0 & 0 \\ 0 & 0 & 3 & 0 \\ 0 & 6 & 0 & 0 \end{bmatrix}$$

can be simply stored as value = [5,8,3,6]; row = [2,2,3,4]; column = [1,2,2,3]

- Storing sparse matrix and computing are easier
- Natural signals are sparse !

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# Key Ideas

- Formulate the problem as a non-convex optimization problem
- Solve the optimization problem using alternate minimization technique.
- Simultaneously force sparsity of the recovered signal

# Formulate the problem as optimization problem

- What do we observe?  
Shredded signals, each signal of length  $N$  and  $M$  shreds.

$$\mathbf{y}_{MN \times 1} = [\mathbf{y}_1^T \mathbf{y}_2^T \dots \mathbf{y}_M^T]^T$$

- The original signal(document) to be recovered is  $\mathbf{x}_{MN \times 1}$
- If  $\mathbf{y}$  is arranged in right order, we can retrieve  $\mathbf{x}$ . This ordering is given by permutation matrix  $\mathbf{P}_{M \times M}$ .

$$\mathbf{x}_{MN \times 1} = (\mathbf{P}_{M \times M} \otimes \mathbf{I}_{N \times N})_{MN \times MN} \mathbf{y}_{MN \times 1} \quad (1)$$

- We also know that the signals are sparse in frequency domain. How do I access that?

$$\mathbf{x}_{MN \times 1} = \psi_{MN \times MN}^H \mathbf{v}_{MN \times 1} \quad (2)$$

# Formulate the problem as optimization problem

- Given optimal  $\mathbf{P}$  and  $\mathbf{v}$  the error between the functions 1 and 2 should be minimum. That is exactly our objective function.

$$\begin{aligned} \min_{\mathbf{P}, \mathbf{v}} \quad & \|(\mathbf{P} \otimes \mathbf{I})\mathbf{y} - (\psi^H \mathbf{v})\|_2 \\ \text{subject to} \quad & \|\mathbf{v}\|_2 = \|\mathbf{y}\|_2 \end{aligned}$$

## Specifying sparsity

- Let  $s$  be the sparsity order of  $\mathbf{v}$ . The number of non-zero values in  $\mathbf{v}$  is  $s$ . How do I represent this mathematically?

$$\mathbf{v} \in \mathcal{X}_s$$

where  $\mathcal{X}_s$  is a set of all vectors with at most  $s$  non-zero values. Add this as a constraint and now the problem becomes

$$\min_{\mathbf{P}, \mathbf{v}} \quad \|(\mathbf{P} \otimes \mathbf{I})\mathbf{y} - (\psi^H \mathbf{v})\|_2 \tag{3}$$

$$\text{subject to } \|\mathbf{v}\|_2 = \|\mathbf{y}\|_2 \tag{4}$$

$$\mathbf{v} \in \mathcal{X}_s \tag{5}$$

# Solving the optimization problem

We have three optimization variables  $\mathbf{P}$  and  $\mathbf{v}$  and  $s$

## Optimization Strategy

- Fix a sparsity order  $s$
- Alternatively optimize  $\mathbf{P}$ ,  $\mathbf{v}$
- Called *Cyclic minimisation* or *Alternate minimisation*

# Solving the optimization problem

## Step I : Solving $\mathbf{v}$

- Fix  $s$  and  $\mathbf{P}$

### Optimization problem in $\mathbf{v}$

$$\min_{\mathbf{v}} \quad \|\mathbf{v} - \psi(\mathbf{P} \otimes \mathbf{I})\mathbf{y}\|_2 \quad (6)$$

$$\text{subject to } \|\mathbf{v}\|_2 = \|\mathbf{y}\|_2 \quad (7)$$

$$\mathbf{v} \in \mathcal{X}_s \quad (8)$$

- Let  $\tilde{\mathbf{v}} = \psi(\mathbf{P} \otimes \mathbf{I})\mathbf{y}$
- Observe that

$$\|\mathbf{v} - \tilde{\mathbf{v}}\|_2^2 = c - 2\mathbf{v}^T \tilde{\mathbf{v}}$$

$$\text{where, } c = \|\mathbf{v}\|_2^2 + \|\tilde{\mathbf{v}}\|_2^2 = 2\|\mathbf{y}\|_2^2 \text{ is constant}$$

- Now the problem becomes maximizing  $\mathbf{v}^T \tilde{\mathbf{v}}$

# Solving the optimization problem

## Finding the optimal $\mathbf{v}$

- Note that  $\mathbf{v}$  has a sparsity constraint (defined by  $s$ )
- Idea : Pick the maximal  $s$  components of  $\tilde{\mathbf{v}}$
- Define  $\mu \in \{0, 1\}^{MN \times 1}$  as indices of the chosen components

## Optimal $\mathbf{v}$

$$\mathbf{v}_{\text{opt}} = \|\mathbf{y}\|_2 \left( \frac{\tilde{\mathbf{v}} \circ \mu}{\|\tilde{\mathbf{v}} \circ \mu\|_2} \right) \quad (9)$$

$\mathbf{v}_{\text{opt}}$  aligns maximally with  $\tilde{\mathbf{v}}$  and has the same norm as  $\mathbf{y}$



# Solving the optimization problem

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# Solving the optimization problem

## Step 2 : Solving $\mathbf{P}$

Fix  $\mathbf{v}$  and solve for  $\mathbf{P}$

- Let  $\hat{\mathbf{x}} = \psi^H \mathbf{v}_{opt}$  - a sparse estimate of the  $\mathbf{x}$  signals, from Step 1.
- We also have the  $\mathbf{y}$  - the observed shreds.
- Now, define  $\mathbf{U} \in \mathbb{C}^{M \times M}$ ; called cost matrix as

$$\mathbf{U}_{k,l} = \|\mathbf{y}_k - \hat{\mathbf{x}}_l\|_2^2$$

New objective for solving  $\mathbf{P}$

$$\mathbf{P}_{opt} = \arg \min_{\mathbf{P}} [\mathbb{1}_M^T (\mathbf{P} \circ \mathbf{U}) \mathbb{1}]$$

- The above problem is called the *Assignment problem* or the *Matching problem*
- Can be solved using *Hungarian Algorithm*

# Overall algorithm

## Final algorithm

Step 0: Set  $s = 1$ .

Step 1: Monotonically decrease the objective of equation 5 via cyclic minimization until convergence using equations 9 and equation 16.

Step 2: Set  $s \leftarrow s + 1$

Step 3: Repeat Step 1 until the decrease in the objective of 5 is negligible.

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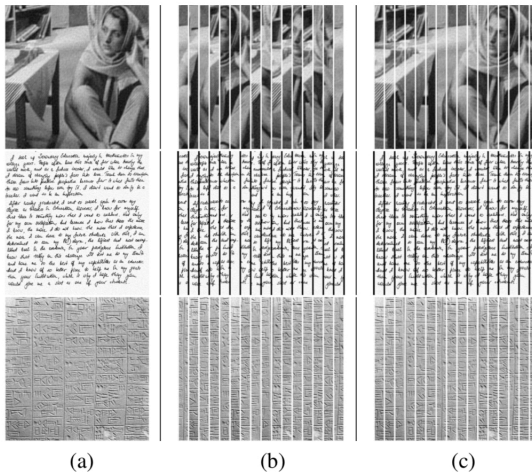
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**Fig. 2.** Reconstruction results: (a) original images, (b) scrambled shredded strips, (c) reconstructed images.

# Thank You!