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**Algorithm 1** Find

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**Input:** Point**Output:** Node

```
1: curr  $\leftarrow$  root
2: while !curr.isLeaf do
3:   next  $\leftarrow$  0
4:   if Point.x  $\geq$  curr.center.x then
5:     next  $\leftarrow$  next + 4
6:   if Point.y  $\geq$  curr.center.y then
7:     next  $\leftarrow$  next + 2
8:   if Point.z  $\geq$  curr.center.z then
9:     next  $\leftarrow$  next + 1
10:  curr  $\leftarrow$  curr.children[next]
11: return curr
```

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**Algorithm 2** Insert

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**Input:** Point**Output:** Boolean

```
1: node  $\leftarrow$  find(Point)
2: if node.contains(Point) then
3:   return False
4: node.points.add(Point)
5: if node.points.size  $\geq$  limit then
6:   node.subdivide
7: return True
```

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**Algorithm 3** Node Subdivision

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```
1: isLeaf  $\leftarrow$  False
2: newHalfSize  $\leftarrow$  halfSize  $\div$  2
3: for  $i \in \{0, 1\}$  do
4:   for  $j \in \{0, 1\}$  do
5:     for  $k \in \{0, 1\}$  do
6:        $X \leftarrow$  center.x - newHalfSize +  $i \times$  halfSize
7:        $Y \leftarrow$  center.y - newHalfSize +  $j \times$  halfSize
8:        $Z \leftarrow$  center.z - newHalfSize +  $k \times$  halfSize
9:       children[ $i \times 4 + j \times 2 + k$ ]  $\leftarrow$  Node( $\{X, Y, Z\}$ , newHalfSize)
10: for all Points in Node do
11:   remove(Point)
12:   next  $\leftarrow$  0
13:   if Point.x  $\geq$  center.x then
14:     next  $\leftarrow$  next + 4
15:   if Point.y  $\geq$  center.y then
16:     next  $\leftarrow$  next + 2
17:   if Point.z  $\geq$  center.z then
18:     next  $\leftarrow$  next + 1
19:   children[next].points.add(Point)
```

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**Algorithm 4** Resize

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**Input:** Point

```
1: while Point is out of bounds do
2:   if Point.x < root.center.x then
3:     direction.x  $\leftarrow$  -1
4:   if Point.y < root.center.x then
5:     direction.y  $\leftarrow$  -1
6:   if Point.z < root.center.x then
7:     direction.z  $\leftarrow$  -1
8:   newHalfSize  $\leftarrow$  root.halfSize  $\times$  2;
9:   newCenter.x  $\leftarrow$  root.center.x + direction.x  $\times$  root.halfsize
10:  newCenter.y  $\leftarrow$  root.center.y + direction.y  $\times$  root.halfsize
11:  newCenter.z  $\leftarrow$  root.center.z + direction.z  $\times$  root.halfsize
12:  newRoot  $\leftarrow$  Node(NULL, newCenter, newHalfSize)
13:  newRoot.subdivide
14:  rootCode  $\leftarrow$  (direction.x + 1)  $\times$  2
15:  rootCode  $\leftarrow$  rootCode + (direction.y + 1)
16:  rootCode  $\leftarrow$  rootCode + (direction.z + 1)  $\div$  2
17:  newRoot.children[rootCode]  $\leftarrow$  root
18:  root  $\leftarrow$  newRoot
```

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