Recorded at time: 114.751 odom Broadcaster: /gazebo Average rate: 50.201 Buffer length: 4.98 Most recent transform: 114.746 Oldest transform: 109.766 base link Broadcaster: /robot state publisher Average rate: $1000\overline{0}.0$ Average rate: 25.202 Average rate: $25.\overline{202}$ Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 4.96 Buffer length: 4.96 Buffer length: 0.0 Most recent transform: 114.726 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 114.726 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 109.766 Oldest transform: 109.766 link_aruco_left_base laser link_left_wheel link_right_wheel link mast link_aruco_right_base caster_link Broadcaster: /robot state publisher Broadcaster: /robot state publisher | Broadcaster: /robot state publisher Average rate: $25.\overline{202}$ Average rate: $1000\overline{0}.0$ Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Buffer length: 4.96 Buffer length: 0.0 Most recent transform: 114.726 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 109.766 Oldest transform: 0.0 respeaker_base link_lift link head Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $1000\overline{0}.0$ Average rate: $1000\overline{0}.0$ Average rate: $1000\overline{0}.0$ Average rate: 25.202 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 4.96 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 114.726 Oldest transform: 0.0 Oldest transform: 109.766 Oldest transform: 0.0 Oldest transform: 0.0 __link_head_pan link_head_teleop_mount link_arm_l4 link_aruco_shoulder Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $25.\overline{202}$ Average rate: $25.2\overline{02}$ Average rate: $1000\overline{0}.0$ Buffer length: 4.96 Buffer length: 4.96 Buffer length: 0.0 Most recent transform: 114.726 Most recent transform: 114.726 Most recent transform: 0.0 Oldest transform: 109.766 Oldest transform: 109.766 Oldest transform: 0.0 link_head_teleop_camera link_head_tilt link_arm_l3 Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $25.\overline{202}$ Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Buffer length: 4.96 Most recent transform: 114.726 Most recent transform: 0.0 Oldest transform: 109.766 Oldest transform: 0.0 link_arm_l2 camera_bottom_screw_frame Broadcaster: /robot_state_publisher Broadcaster: /robot state publisher Average rate: 10000.0 Average rate: $25.\overline{202}$ Buffer length: 4.96 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 114.726 Oldest transform: 109.766 Oldest transform: 0.0 link_arm_l1 camera link Broadcaster: 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Average rate: 10000.0 Average rate: $1000\overline{0}.0$ Average rate: $1000\overline{0}.0$ Average rate: $1000\overline{0}.0$ Average rate: 10000.0 Average rate: $25.\overline{202}$ Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Buffer length: 4.96 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 114.726 Most recent transform: 0.0 Oldest transform: 109.766 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 _link_wrist_yaw camera_infra2_optical_frame link_aruco_top_wrist link_aruco_inner_wrist camera_accel_optical_frame camera_color_optical_frame camera_depth_optical_frame camera_infra1_optical_frame camera gyro optical frame Broadcaster: /robot state publisher Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 link_gripper Broadcaster: /robot_state_publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 10000.0 Average rate: $1000\overline{0}.0$ Average rate: 25.202 Average rate: 25.202 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 4.96 Buffer length: 4.96 Most recent transform: 0.0 Most recent transform: 114.726 Most recent transform: 114.726 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 109.766 Oldest transform: 109.766 Oldest transform: 0.0 link_grasp_center link_gripper_finger_left link_gripper_finger_right link_gripper_teleop_mount Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 10000.0 Average rate: $1000\overline{0}.0$ Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0

link_gripper_fingertip_left

link_gripper_fingertip_right

link_gripper_teleop_camera

view frames Result