

Joint Deconvolution and Blind Source Separation on the Sphere with an Application in Radio- Astronomy

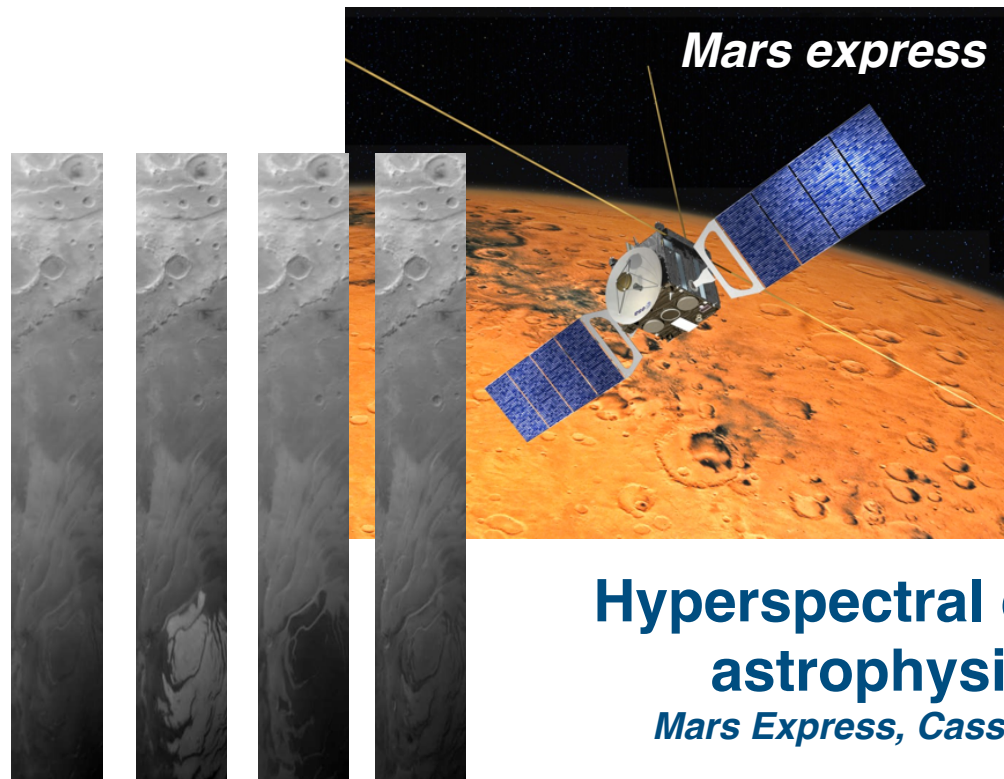
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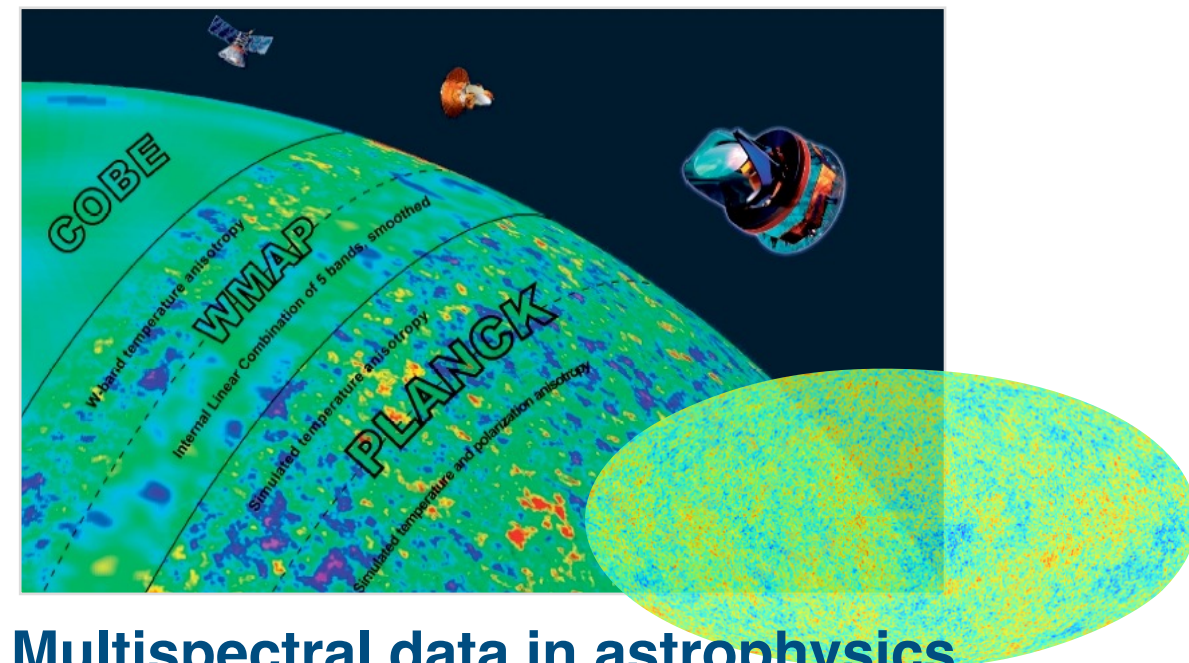
iTwist 2020

Blind source separation

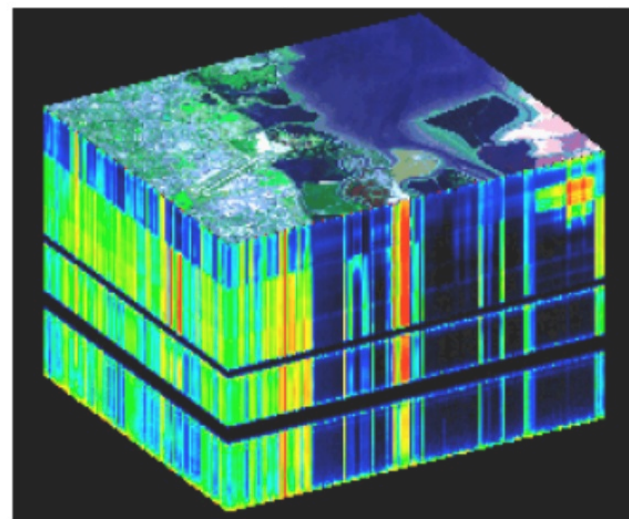
- Blind source separation (BSS) methods are employed to **decompose multi-spectral data in elementary components**



Hyperspectral data in astrophysics
Mars Express, Cassini, etc.



Multispectral data in astrophysics
Planck, Fermi, radio-interferometry (Lofar/SKA/...), etc.



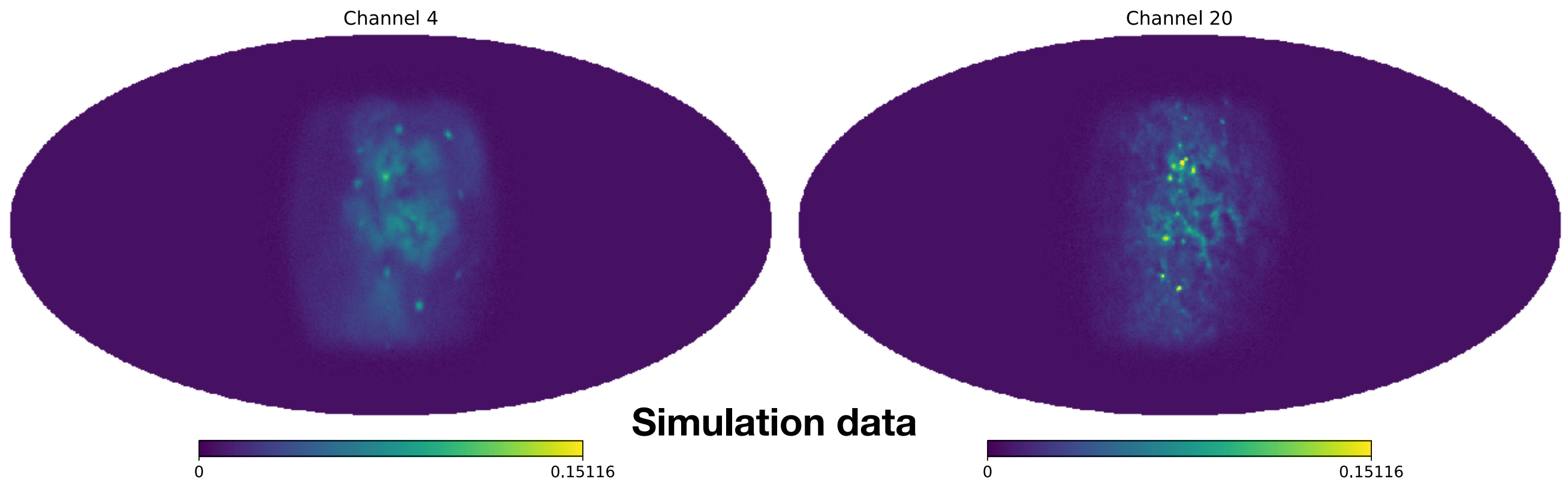
Courtesy of M. Lennon

Hyperspectral data
remote sensing, aerial data, etc.

Context

Forthcoming large-scale radio-telescopes (e.g. SKA) will produce:

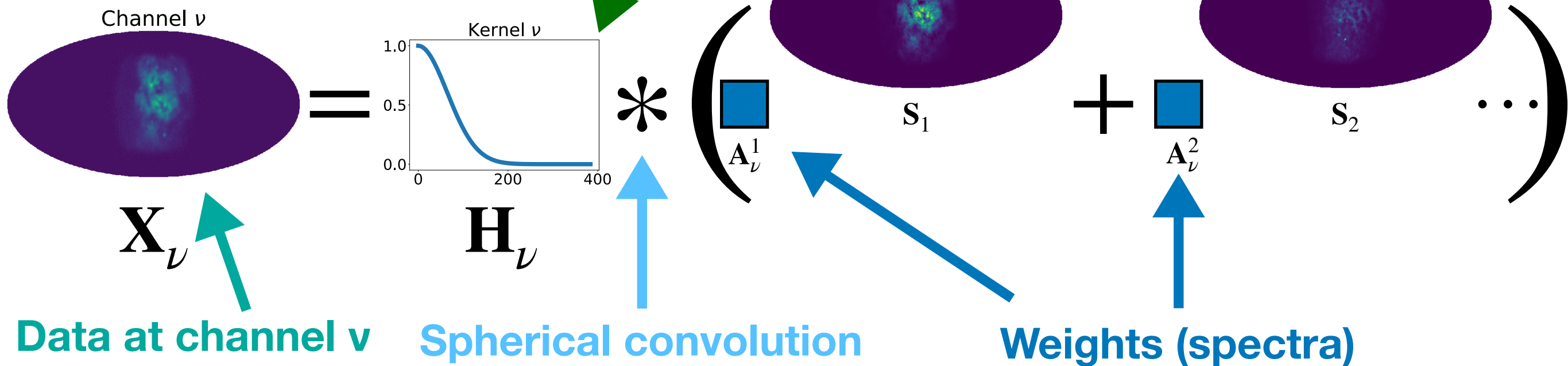
1. **Spherical** data
2. Multi-wavelength data with **diverse resolutions**



Need to develop joint **spherical deconvolution** and **blind source separation** methods

Modelling

- Forward-model:



$$\mathbf{X}_v = \mathbf{H}_v * (\mathbf{A}_v \mathbf{S}) + \mathbf{N}_v$$

Simplified in the spherical harmonic domain:

$$\hat{\mathbf{X}}^{l,m} = \text{diag}(\hat{\mathbf{H}}^l) \mathbf{A} \hat{\mathbf{S}}^{l,m} + \hat{\mathbf{N}}^{l,m}$$

Harmonic
multipole
(frequency)

Toward SDecGMCA

- Cost function: Data-fidelity term Sparse penalization

$$\operatorname{argmin}_{\mathbf{A}, \mathbf{S}} \frac{1}{2} \sum_{l,m} ||\hat{\mathbf{X}}^{l,m} - \operatorname{diag}(\hat{\mathbf{H}}^l) \mathbf{A} \hat{\mathbf{S}}^{l,m}||_2^2 + ||\mathbf{\Lambda} \odot (\mathbf{S} \mathbf{\Phi}^T)||_1$$

- Based on a **Projected Alternate Least-Square** (fast, robust and automatic choice of $\mathbf{\Lambda}$, GMCA *Bobin et al. 2007*)

- Update \mathbf{S} with \mathbf{A} fixed:

- Least-square: $\hat{\mathbf{S}}^{l,m} \leftarrow (\mathbf{A}^T \operatorname{diag}(\hat{\mathbf{H}}^l)^2 \mathbf{A})^{-1} \mathbf{A}^T \operatorname{diag}(\hat{\mathbf{H}}^l) \hat{\mathbf{X}}^{l,m}$

- Sparsity constraint

Ill-conditioned!
To be regularized

- Update \mathbf{A} with \mathbf{S} fixed:

- Least-square: $\mathbf{A}_\nu \leftarrow (\sum_{l,m} \hat{\mathbf{X}}_\nu^{l,m} \hat{\mathbf{H}}_\nu^l \hat{\mathbf{S}}^{l,m \dagger}) (\sum_{l,m} \hat{\mathbf{H}}_\nu^l \hat{\mathbf{S}}^{l,m} \hat{\mathbf{S}}^{l,m \dagger})^{-1}$

Source regularization

- Extra **Tikhonov regularization** (*Jiang et al. 2017*):

$$\hat{\mathbf{S}}^{l,m} \leftarrow (\mathbf{A}^T \text{diag}(\hat{\mathbf{H}}^l)^2 \mathbf{A} + \text{diag}_n(\varepsilon_{n,l}))^{-1} \mathbf{A}^T \text{diag}(\hat{\mathbf{H}}^l) \hat{\mathbf{Y}}^{l,m}$$

- Choice of $\{\varepsilon_{n,l}\}$? We propose **2 strategies**:

Mixing-matrix based:

Smallest eigenvalue

$$\varepsilon_{n,l} = \max \left(0, c - \frac{\lambda_{\min}(\mathbf{A}^T \text{diag}(\hat{\mathbf{H}}^l)^2 \mathbf{A})}{\lambda_{\min}(\mathbf{A}^T \mathbf{A})} \right)$$

Regularization hyperparameter

Gist: limit noise amplification

Robust

Source based:

Angular power spectra

$$\varepsilon_{n,l} = c \frac{\mathbf{c}_N[l]}{\mathbf{c}_{S_n}[l]}$$

Regularization hyperparameter

Gist: ~ Wiener filter

Precise, not robust

SDecGMCA

- Two-step procedure, starting from a PCA-based estimation:

1. Warm-up: while has not converged

**First guess, robustness
to initial point**

- Update \mathbf{S} with \mathbf{A} fixed
(**mixing-matrix-based** regularization strategy)
- Update \mathbf{A} with \mathbf{S} fixed

2. Refinement: while has not converged

Refines the results

- Update \mathbf{S} with \mathbf{A} fixed
(**source-based** regularization strategy)
- Update \mathbf{A} with \mathbf{S} fixed



**Use the angular power spectra of the
sources estimated at last iteration**

Numerical experiments

- Objectives:

1. **Characterize** SDecGMCA under various observation scenarios (SNR, nb. channels, resolution range, mix. mat. condition nb.)
2. **Compare** SDecGMCA with other BSS methods

- Separation performance metrics:

Asterisk denotes ground truth

The larger, the better

$$\text{NMSE} = -10\log_{10} \left(\frac{||\mathbf{S}^* - \mathbf{S}||_{\ell_2}^2}{||\mathbf{S}^*||_{\ell_2}^2} \right)$$

$$C_A = -10\log_{10} \left(\text{mean}(|\mathbf{A}^+ \mathbf{A}^* - \mathbf{I}|) \right)$$

- Oracle: estimate using ground truth mixing-matrix \mathbf{A}^*
➡ Provides an upper-bound for the NMSE

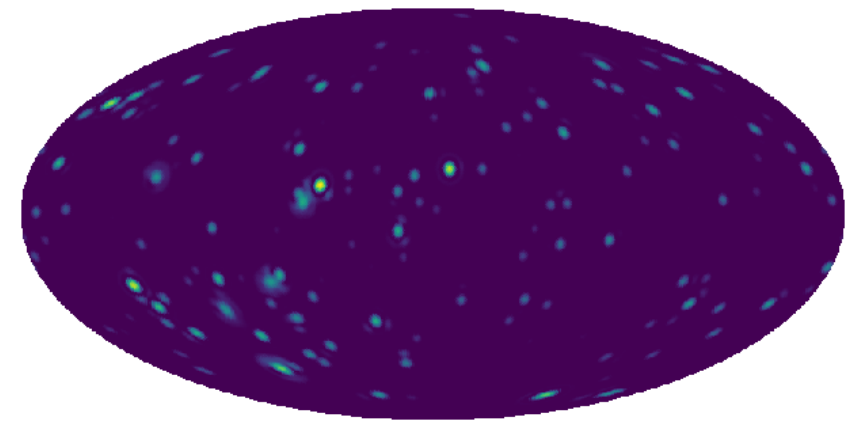
Synthetic data

Objective 1: characterize SDecGMCA

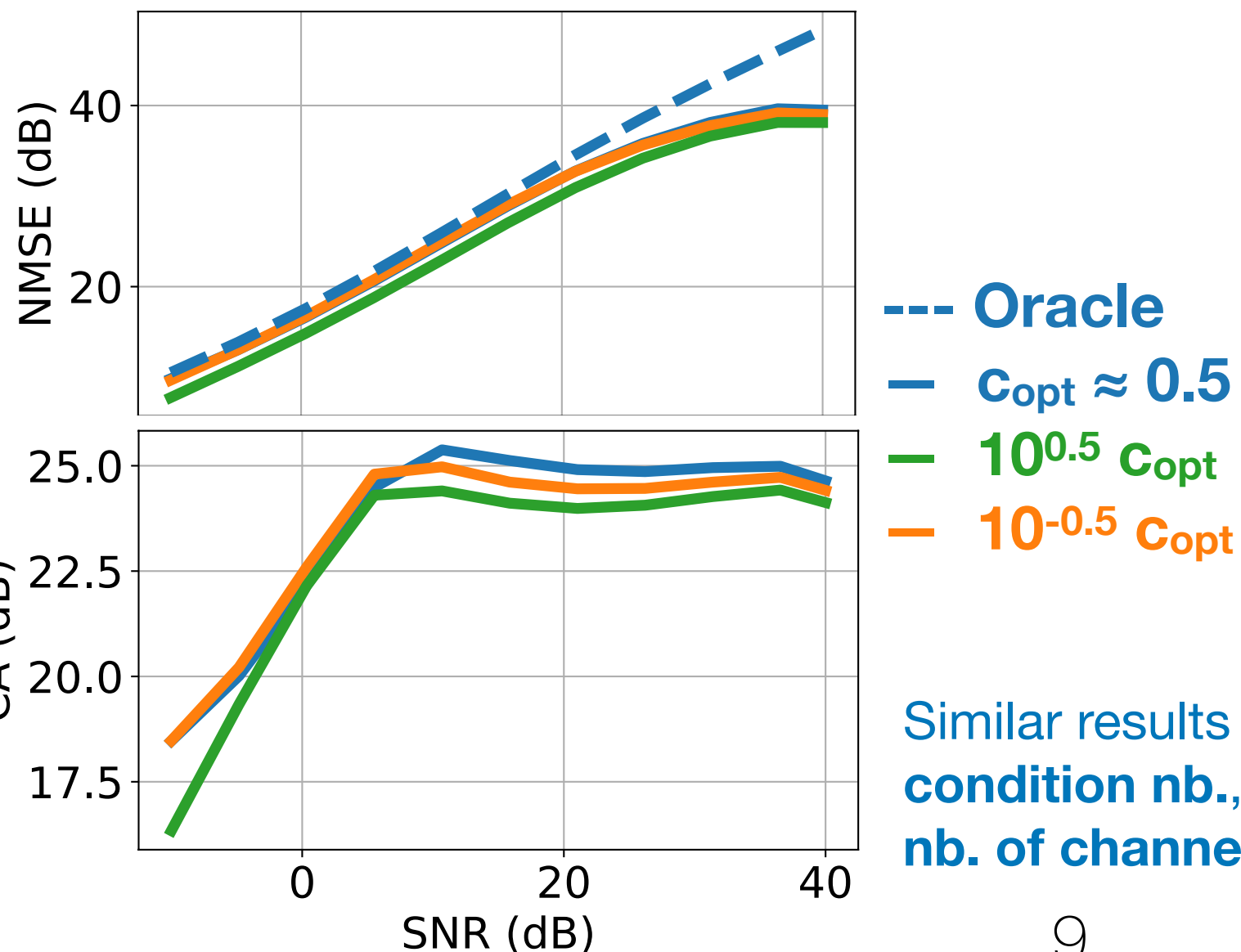
i. Regularization hyperparameter c ?

$$c_{\text{opt}} \approx 0.5$$

ii. Performances ? Sensibility of c ?



Source example (among 4)

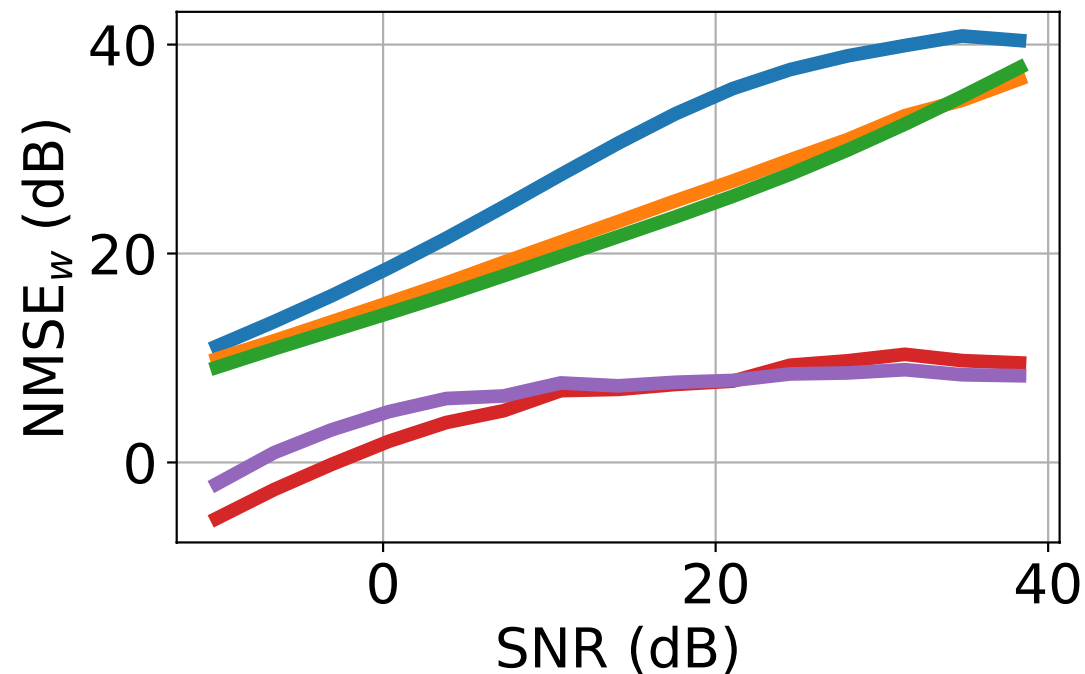


→ Sources close to oracle

→ Quite insensitive to c

Synthetic data

Objective 2: compare SDecGMCA



DBSS methods:

— **SDecGMCA**

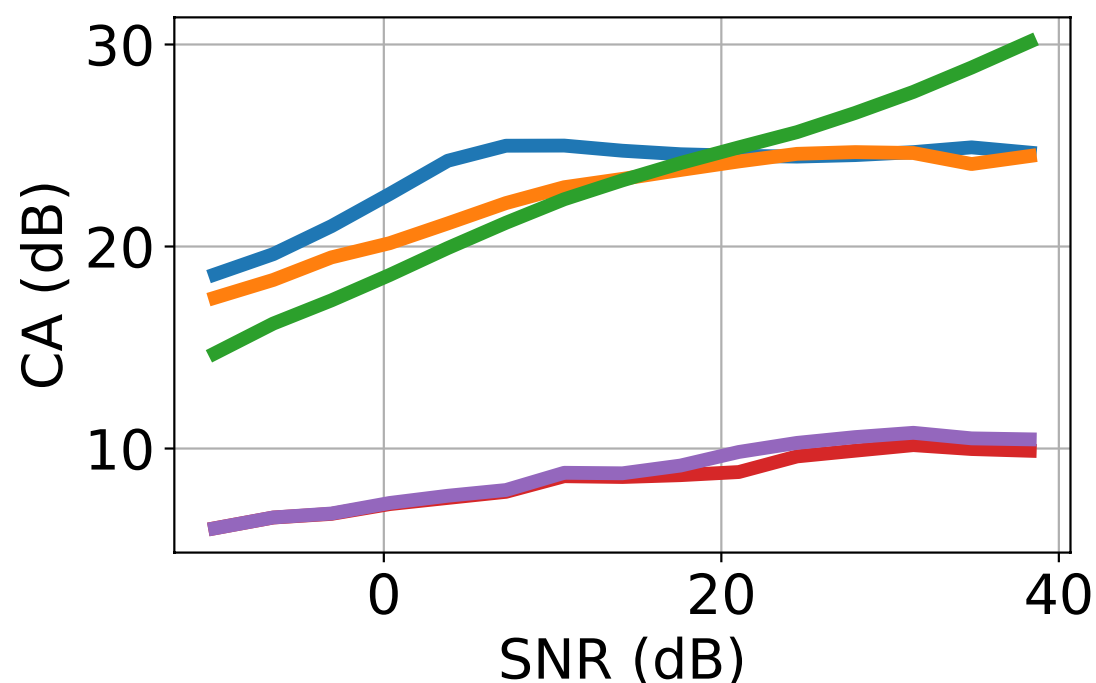
— ***Jiang et al. 2017***

BSS/NMF methods:

— **GMCA, *Bobin et al. 2007***

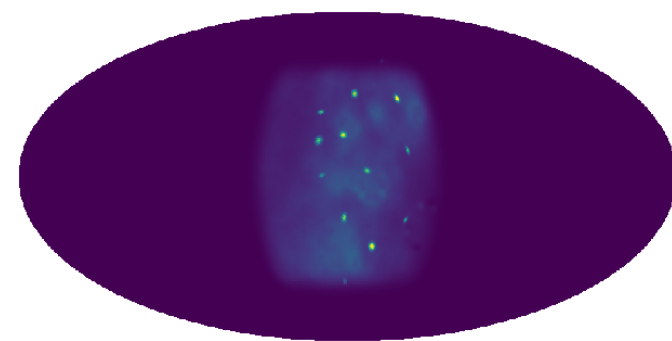
— **HALS, *Cichocki et al. 2007***

— **β -NMF S, *Cherni et al. 2020***

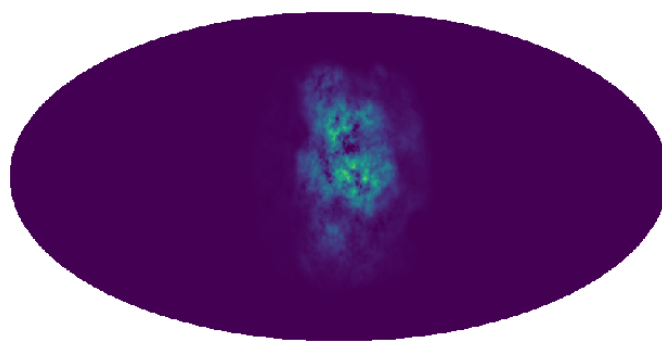


Similar results when varying the **mix. mat. condition nb.**, the **resolution range** & the **nb. of channels**

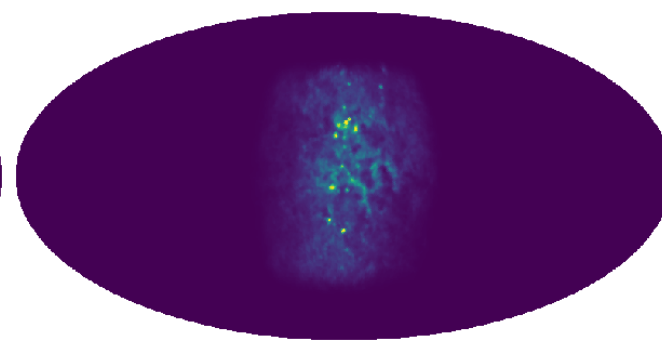
Realistic data



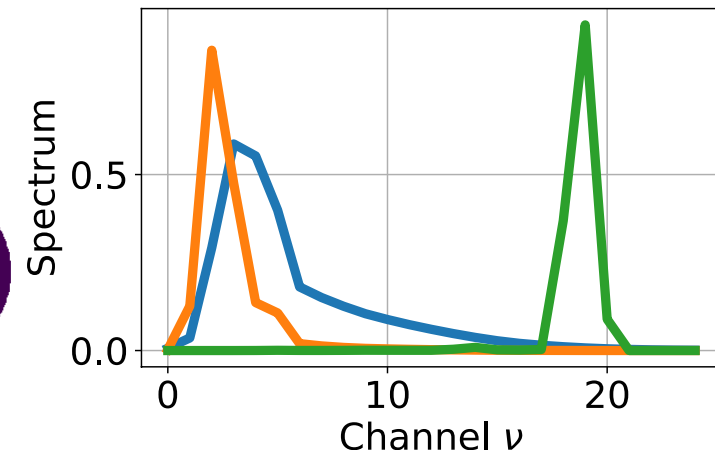
Synchrotron source



Thermal source

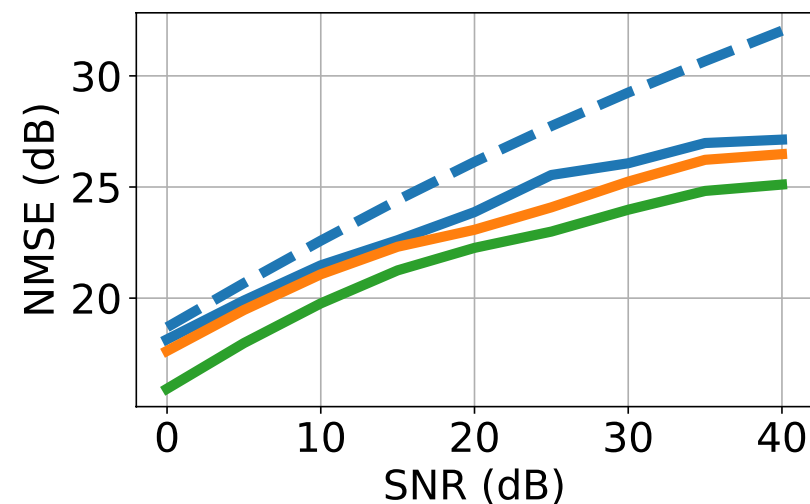


Emission line source

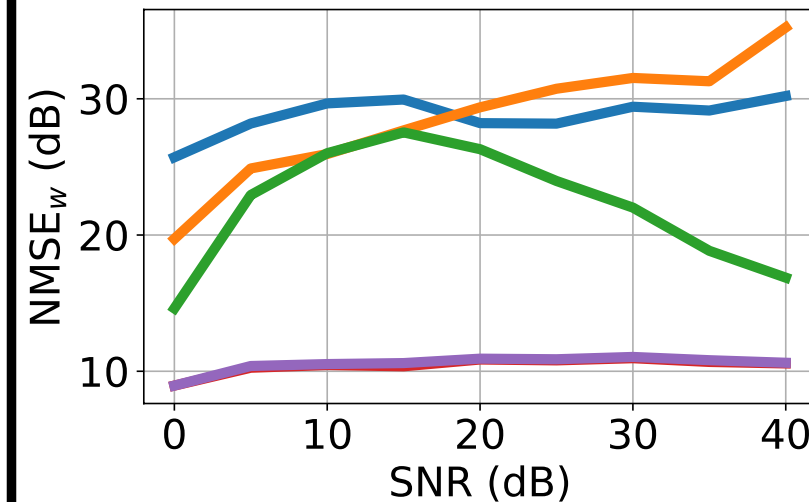
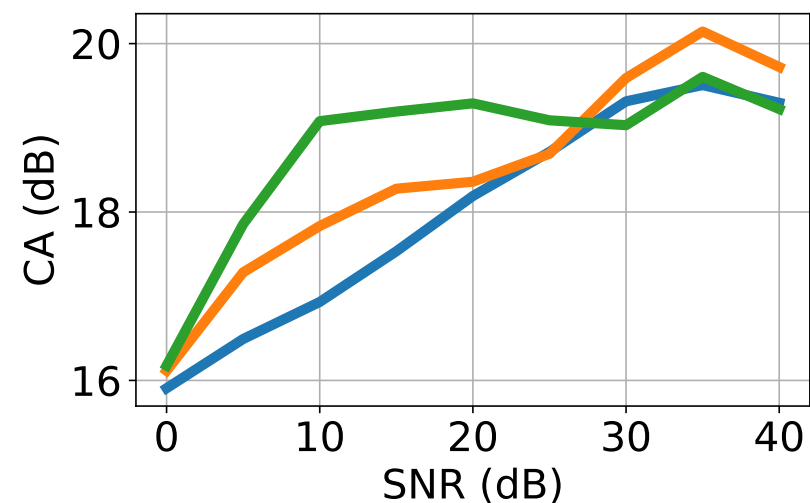


Mixing matrix

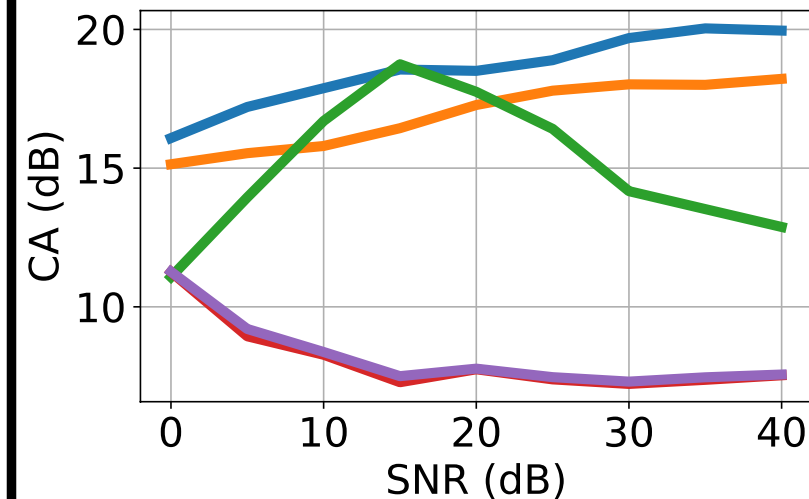
Objective 1:
characterize
SDecGMCA



--- Oracle
— $C_{opt} \approx 0.5$
— $10^{0.5} C_{opt}$
— $10^{-0.5} C_{opt}$




Objective 2:
compare
SDecGMCA



— SDecGMCA
— *Jiang et al.*
— GMCA
— HALS
— β -NMF S

Conclusion

- New method to perform joint **spherical deconvolution** and **blind source separation** problems
- **Robust** and **effective** minimization algorithm, evaluated on both **synthetic** and **realistic** data
- Open-source Python code available online
 github.com/RCarlioniGertosio/SDecGMCA
- **Perspectives:**
 - Journal paper under revision
 - Method to be tested on MeerKAT data (SKA precursor)