Stability Analysis of the Structural Agnostic Modeling Method

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Overview

- Introduction
- 2 Foundation of causality
- Causal discovery
- Acyclicity constraint $a_{i,j} = 0$ initialization
 Structural gates initialization
- **Structural gates** initialization
- Conclusion

Stability

Stability: a small perturbation on the inputs of an algorithm does not change too much its output.

Unstable algorithms limitations:

- How can we rely on their results?
- Lack of replicability



Why causality?

• Spurious correlations might lead to wrong interventions.



Figure 1: Smoking may lead to yellow fingers (image generated by DALL-E mini).

Main idea:

Causality gives more information than correlations



Randomized Controlled Trial (RCT)

RCT:

- Experiment controlled by the researcher.
- The gold standard.

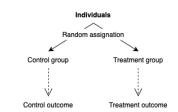


Figure 2: Example of RCT schema.

Not always feasible: e.g. economical or ethical limitations.

Observational data: data without any manipulation.



Internship aim

Structural Agnostic Model (SAM) Kalainathan et al. 2022 model: Generative Adversarial Network (GAN) Goodfellow et al. 2014 model

aiming to discover causal relationships.

Main problem:

• Even with the same initialization, SAM is not stable.

Our goal:

Explore SAM instability.

Main question:

Under which conditions SAM is stable?



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Functional Causal Model (FCM) Pearl 2003

Functional Causal Model (FCM) Pearl 2003

Considering a set of random variables X_1, \dots, X_n , a FCM is a set of equations

$$x_i = f_i(x_{\mathsf{pa}_i}, u_i) \quad i = 1, \cdots, n. \tag{1}$$

- X_{pa_i} : set of observed variables that directly determine the value of X_i .
- U_i : random variable modelling the noise.
- f_i : causal mechanism.

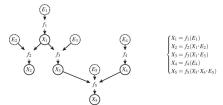


Figure 3: Example of FCM (Figure from Goudet et al. 2018)

Causal graphical models

Causal graph:

- Variables as nodes.
- Each direct edge (\rightarrow) is a cause-effect oriented relation.

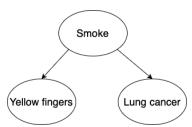


Figure 4: Causal graph relating smoking, yellow fingers and lung cancer.

Remark:

• A causal graph and a Bayesian Network are not equivalent!



Causal Markov Condition (CMC)

Acyclicity: the graph does not have any (direct) cycle.

Directed Acyclic Graph (DAG)

A direct graph without any direct cycle is called a DAG.

Causal Markov Assumption (CMA): For a given causal graph, all the considered variables are independent of their non-descendants minus their parents by conditioning on their parents.

Causal Markov Condition (CMC) Pearl and Verma 1991

A probability distribution is compatible with a DAG G if, and only if, CMA is verified.



Consequences of CMC

Consequences:

- The joint density p verifies $p(x) = \prod_{i=1}^{d} p(x_i | x_{pa_i})$.
- FCM ⇔ causal graph.

Markov Blanket (MB)

For a given variable X_i , any minimal subset of the other variables such that any disjoint set of variables is independent of X_i conditioned on the subset is known as MB of X_i .

Moral graph

A moral graph of a DAG G is the undirected graph where each node is connected where the original node is connected with its MB in G.



Faithfulness

Causal Faithfulness

A graph G and a joint density p(x) verify the Causal Faithfulness Assumption (CFA) if every Conditional Independence (CI) relation verified by p is entailed by G.

Causal Sufficiency

The Causal Sufficiency Assumption (CSA) states that the observed variables X_1, \dots, X_n are causally sufficient, *ie* each par of variables $\{X_i, X_j\} \subseteq \{X_1, \dots, X_n\}$ do not has a common cause external to $\{X_1, \dots, X_n\} \setminus \{X_i, X_i\}$.



Some basic three node structures

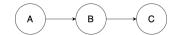


Figure 5: Example of a chain structure.

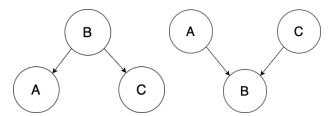


Figure 6: Example of a fork structure (left) and v-structure (right).

d-separation

A set of nodes W blocks a path t if

- 1 t contains at least one arrow-emiting node w (i → w → j) or (i ← w → j) verifying w ∈ W.
 2 t contains at least one collider node w (i → w ← i) verifying w ← least one collider node w (i → w ← i) verifying w ← least one collider node w (i → w ← i) verifying w ← least one collider node w (i → w ← i) verifying w ← least one collider node w (i → w ← i) verifying w ← least one collider node w (i → w → j) verifying w ← least one collider node w (i → w → j) verifying w ← least one collider node w (i → w → j) verifying w ← least one collider node w (i → w → j) verifying w ← least one collider node w (i → w → j) verifying w ← least one collider node w (i → w → j) verifying w ← least one collider node w (i → w → j) verifying w ← least one collider node w (i → w ← j) verifying w ← least one collider node w (i → w ← j) verifying w ← least one collider node w (i → w ← j) verifying w ← least one collider node w (i → w ← j) verifying w ← least one collider node w (i → w ← j) verifying w ← least one collider node w (i → w ← j) verifying w ← least one collider node w (i → w ← j) verifying w ← least one collider node w (i → w ← j) verifying w ← least one collider node w (i → w ← j) verifying w ← least one collider node w (i → w ← j) verifying w ← least one collider node w (i → w ← j) verifying w ← least one collider node w (i → w ← j) verifying w ← least one collider node w (i → w ← j) verifying w (i → w ← j) verifying
- 2 t contains at least one collider node w $(i \rightarrow w \leftarrow j)$ verifying $w \notin W$ and not having any descendant on W.

The set W d-separate A and B in the graph G when W blocks all the paths between A and B.

Under CFA: d-separation ⇔ CI.



Markov Equivalence Class and CPDAG

Markov Equivalent DAG Pearl and Verma 1990

Two DAGs with same skeleton and same v-structures are said to be Markov equivalent.

Completed Partially Directed Acyclic Graph (CPDAG)

Graph with both directed and undirected edges representing a Markov Equivalence class.

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Algorithms classification

Finding the causal graph only from observational data is a NP-hard problem Chickering, Heckerman, and Meek 2004.

Different basis algorithms:

- 1 Combinatorial: constrained and score-based: only able to find a CPDAG.
 - PC Spirtes, Glymour, and Scheines 2000.
 - GES Chickering 2002.
- 2 Continuous Optimization-based Approaches: find a DAG from distributional assymetries (usually based on additional assumptions).
 - NOTEARS Zheng et al. 2018: the first algorithm.
 - CGNN Goudet et al. 2018.
 - SAM.



SAM architecture

- GAN
 - A generator for each variable
 - 2 An unique discriminator

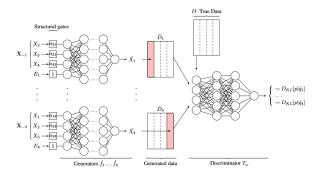


Figure 7: Architecture used in SAM (Figure from Kalainathan et al. 2022).



Optimization function

Aim: to minimize a loss combining both CI and distribution asymmetries. Loss: based on the Markov Kernel of each variable.

$$\sum_{j=1}^{d} \left[\hat{I}^{n}(X_{j}, X_{\overline{P_{d}(j;\hat{G})}} | X_{P_{d}(j;\hat{G})}) \right] + \lambda_{S} |\hat{G}| + \sum_{j=1}^{d} \left[\frac{1}{n} \sum_{l=1}^{n} \log \frac{p(x_{j}^{(l)} | x_{P_{d}(j;\hat{G})}^{(l)})}{q(x_{j}^{(l)} | x_{P_{d}(j;\hat{G})}^{(l)}, \theta_{j})} + \lambda_{F} ||\theta_{j}||_{F} \right] + \lambda_{D} \sum_{k=1}^{d} \frac{\operatorname{tr} A^{k}}{k!}$$

- Structural gate matrix A.
- Structural loss: Identify the Markov Blanket of each variable.
- Parametric loss: Data fitting.
- Constraints: sparsity, causal mechanism power and acyclicity.



SAM key points

Theoretically:

- Structural gates as probabilities to make them differentiable Maddison, Mnih, and Teh 2017.
- Acyclicty constraint optimized through Augmented Lagrangian (AL) technique.
- It exists at least one positive value for the structural loss regularizer allowing the CPDAG identification by the minimization of the structural loss.

Experimentally

- Main benefit: versatility.
- Generally able to recover the true MB.
- Sensitive to the random initialization weights in the NN.



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Acyclicity constraint

Why looking to the acyclicity constraint?

Motivation:

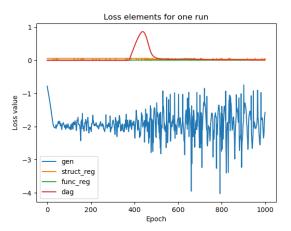


Figure 8: Evolution of the different loss elements, with a huge variability increment after the acyclicity constraint initialization.

Acyclicity constraint

Main question:

Is the stability affected by the AL optimization method?

In SAM:

AL optimization penalization weight with additive increment.

My proposal:

• Consider a multiplicative increment on the AL.



 $a_{i,j} = 0$ initialization

Motivation

Main question:

• If $a_{i,j} = 0$, then it remains equal to zero?

My hypothesis:

• If $a_{i,j} = 0$ then it is probability of being selected is zero, then the NN is restricted to look for the space where it has another value.

Possible benefits:

- A way to encode prior knowledge of the non-existence of an edge.
- With the acyclicity assumption, a way to partially incorporate knowledge from the existence of an edge (through its reverse edge).



Foundation of causality Causal discovery Source of instability Experimental results References

Initialization with a DAG

Main question:

 How does affect a DAG initialization to the random weights sensitivity?

Auxiliary questions:

- From the true graph?
- From the CPDAG?
- From adding an edge to the true graph?
- From removing an edge to the true graph?
- From reversing an edge to the true graph?

Possible benefits

- Analyze the interest of incorporating prior knowledge.
- Use SAM to test a solution through its stability.



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Acyclicity constraint

Simulation setup

Datasets: 20 synthetic datasets based on Kalainathan, Goudet, and Dutta 2020.

- Number of observations: 1000.
- Number of nodes: 5.
- Number maximum of parents: 2
- Mechanisms: linear and neural network.
- Noise: *U*(0, 0.4), additive.

Evaluation measure: Standard deviation of the last epoch probabilities (without considering self-loops).

Methodology:

5 independent trials.



Acyclicity constraint

Numerical results

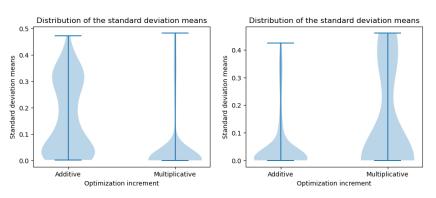


Figure 9: Impact of the increment for linear mechanism (left) and NN mechanism (right).



Foundation of causality Causal discovery Source of instability Experimental results

Simulation setup

Datasets: 10 synthetic datasets based on Kalainathan, Goudet, and Dutta 2020.

- Number of observations: 1000.
- Number of nodes: 2.
- Mechanism: linear.
- Noise : *U*(0, 0.2), additive.

Evaluation measure:

Maximum value of any structural gate during the training.

Methodology:

- 5 independent trials.
- SAM parameters:
 - 750 epochs
 - $\Lambda_S = 0$
 - $\lambda_F = 2 \cdot 10^{-6}$.
 - $\lambda_D = 0.0$

Structural gates $a_{i,j} = 0$

Results

The structural gates value is always constant and equal to zero in all the graphs and independent trials.



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Simulation setup

Datasets: 10 synthetic datasets based on Kalainathan, Goudet, and Dutta 2020.

- Number of observations: 1000.
- Number of nodes: 5.
- Mechanisms: linear.
- Noise: *U*(0, 0.4), additive.

Evaluation measure: Standard deviation of the last epoch probabilities (without considering self-loops).

Methodology:

- 5 independent trials.
- SAM parameters:
 - 1500 epochs
 - $\lambda_{5} = 0.02$
 - $\lambda_F = 2 \cdot 10^{-6}$.
 - $\lambda_D = 0.01$



Experimental results Foundation of causality Causal discovery Source of instability

Structural gates initialization

Numerical results

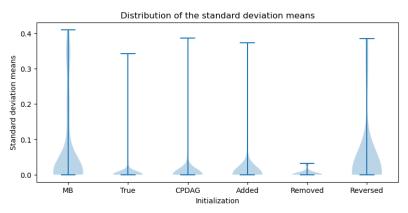


Figure 10: Violin plot for the standard deviation of the returned structural gates (without considering self-loops) for the different initializations.



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Conclussion and discussion

AL penalized weight increment:

The acyclicity constraint optimization method affects the stability.

Structural gates $a_{i,j} = 0$

• The structural gate seems constant if initialized to zero.

Initialize SAM with additional information

- One of the major sources of instability.
- The stability of SAM seems improved by all the initialization except when reversing an edge.

Further work

- Is SAM stability related to the causal mechanisms?
- Analyze the stability by pruning edges during the optimization procedure.
- Is the performance increased by considering an initialization obtained as a result from another causal discovery algorithm?

Thanks, any question?



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Greedy Equivalence Search (GES)

Pseudo-code:

- Select Bayesian Information Criterion (BIC) as scoring function
- Initialize an empty graph.
- Forward Equivalence Search:
 Find the best directed edge to add to the candidate CPDAG amongst all the missing edges. Repeat until score no longer improves.
- Backward Equivalence Search:
 Find the best directed edge to remove to the candidate CPDAG amongst all the present edges. Repeat until score no longer improves.
- Return directed graph.

Peter-Clark (PC) base algorithm

- Identify the skeleton:
 - Start with a complete graph
 - If $X \perp Y | Z$, remove edges X Y for some (initially empty) conditioning set Z and store Z as Sepset(X, Y).
 - Repeat until possible by increasing the size of Z for each pair (X, Y).
- Identify v-structures and orient them.
 - For any undirected paths X-Z-Y, if $Z \notin Sepset(X,Y)$, then orient the undirected path as $X \to Z \leftarrow Y$.
- Orient qualifying edges that are incident on colliders.
 - For all $A \rightarrow B C$, if A and C not adjacent then $B \rightarrow C$.
 - If it exists an undirected edge A-B and a direct path from A to B, orient the edge as $A \rightarrow B$.

NOTEARS

Pseudo-code:

- Input: Initial guess (W_0, α_0), progress rate $c \in (0, 1)$, tolerance $\varepsilon > 0$, threeshold $\omega > 0$.
- Do:
 - Solve primal: $W_{t+1} \leftarrow \arg \min_{W} L^{\rho}(W, \alpha_t)$ with ρ such that $h(t_{W_{t+1}}) < ch(W_t)$.
 - Dual ascent: $\alpha_{t+1} \leftarrow \alpha_t + \rho h(W_{t+1})$.
 - If $h(W_{t+1}) < \varepsilon$, set $\tilde{W}_{\mathsf{ECP}} = W_{t+1}$ and break.
- Threshold and return the matrix.