

# Shuyan Dong

1-4-2, No. 51, 2nd Road, BaiTaHe, Hunnan District, Shenyang, China, 110003

86 Trevethan Road, Falmouth, TR11 2AX

Mobile: +44 7907432757

Email: [shuyandong1998@gmail.com](mailto:shuyandong1998@gmail.com); [sd746@exeter.ac.uk](mailto:sd746@exeter.ac.uk)

---

## EDUCATION

**University of Edinburgh**      **Scotland, UK**      09/2017-06/2021

Major: **Artificial Intelligence BSc (Hons)**

Core Modules: *Computation and Logic, Data and Analysis, Introduction to Linear Algebra, Foundations of Natural Language Processing, Computer Security, Computer Communications and Networks, Algorithmic Game Theory and its Applications*

**University of Exeter**      **England, UK**      09/2021--

Program Title: **Doctor of Philosophy in Mathematics**

Research Synopsis: The performance of group behaviours through metaheuristic algorithms.

---

## RESEARCH EXPERIENCE

**2020.09-2021.05**

**Explore the firing rules of the Kenyon cells and a corresponding 'Kenyon field'**

Under the supervision of Professor Babara Webb

- Investigated whether Kenyon cells in the Mushroom Body of the insect brain exhibit properties similar to place cells, which increase their firing rate in specific spatial locations.
- Start with a simulated neural network model of the Mushroom Body to analyze the firing patterns of Kenyon cells. Observed that each Kenyon cell demonstrates a preferred firing region within a given environment, suggesting spatially selective activity.

**2020.01-2020.05**

## System Design Project

- Established a physical automatic sorting bin **Recylotron** with Raspberry Pi, which is designed to increase the ease and frequency of recycling.
- Responsible for architect designs, 3D modelling and hardware-related challenges.

2019.09-2020.12

## PowerGrab Game Design

- Design a program that implements a PowerGrab game that uses an autonomous drone, which is able to play against a human component in a location-based strategy game.
  - Implement an **object-oriented programming approach** to ensure the drone can engage in **both stateless and stateful game modes**, while accurately recording its flight path.
- 

## Job and Internship

2022.09 -- 2025.02

## Postgraduate Teaching Associates (PTAs) at the University of Exeter

Course name:

- Tackling Sustainability Challenges Using Data and Models
- Trends in Data Science and AI

2020.05-2020.12

## Seven months internship in the National Natural Science Foundation of China (Grant No.51904144)

- Collaborated with the project lead to optimize algorithms for parameter and function identification, enhancing computational efficiency and accuracy. Additionally, contributed to program debugging, ensuring robust performance and reliability.
- 

## ALGORITHMIC SKILLS

- Well-versed in supervised learning techniques, including support vector machines, linear discriminant analysis, k-nearest neighbour algorithm, decision trees, and clustering methods such as hierarchical clustering and k-means clustering.
- Proficient in statistical modelling and machine learning algorithms, including linear regression, logistic regression, Naïve Bayes, neural networks, and Hidden Markov Models.
- Strong interest in metaheuristic optimization, with ongoing research focused on utilizing Particle Swarm Optimization (PSO), Genetic Algorithms (GA), and Genetic Programming (GP) to optimize neural network weight training.

---

## ADDITIONAL SKILLS AND ACHIEVEMENTS

### Academic Skills

- Proficient in **Java, Python, Matlab, SQL, Basic 3D Modelling**
- Experience with **Festival (Speech Synthesis System from Edinburgh), MIPS (MARS)**
- **Core Machine Learning Methods** (Supervised, Unsupervised Learning)  
**Reinforcement Learning** (Q-learning, Actor-Critic)  
**Generative AI** (GANs)  
**Computer Vision & NLP** (CNNs)  
**Time Series Analysis** (ARIMA)  
**Evolutionary Algorithms** (GA, GP, PSO, ACO)

### Teaching & Educational Skills

- Experience as a **Postgraduate Teaching Assistant (TA) in Tackling Sustainability Challenges Using Data and Models and Trends in Data Science and AI** responsible for tutorials, workshops and student supervision.
- Curriculum development experience in **Tackling Sustainability Challenges Using Data and Models and Trends in Data Science and AI**, including assessment and presentation marking.
- Commitment to completing the 1-3 Unit of Learning and Teaching in Higher Education (LTHE). Successfully obtained a **Certificate of Completion** for partial LTHE assessment. Upon completing all five units of the LTHE program, eligibility will be granted for recognition as an Associate Fellow of the Higher Education Academy (AFHEA).

## Research & Academic Achievements

- Published peer-reviewed journal on **Systems Science & Control Engineering**.
- Published conference papers at the **International Conference on Control, Automation, Robotics and Vision (ICARCV)**, IEEE and the **International Conference on Automation and Computing (ICAC)**.
- Presented research at **ICARCV 2024**, **ICAC 2023** and the **Department of Earth and Environmental Sciences (DEES)** ECR seminar.

## Academic and institutional matters Development

Acted as a **Postgraduate Research (PGR) Student Representative** for **CEM**, advocating for the needs and interests of research students. Played an active role in addressing key aspects of the **doctoral experience**

---

### Publication:

S. Dong, S. Das, A. Thornton and S. Townley, "Control System Autonomy Improvement: An Attempt to Introduce Meta-Heuristic Algorithms into Closed-loop UAV Control Systems," Proceedings of the IEEE, *18th International Conference on Control, Automation, Robotics and Vision (ICARCV)*, Dubai, United Arab Emirates, 2024, pp. 454-459

S. Dong, S. Das, S. Townley (2024) 'Drone motion prediction from flight data: a nonlinear time series approach', *Systems Science & Control Engineering*, 12(1). doi: 10.1080/21642583.2024.2409098.

S. Dong, S. Das, S. Townley and A. Thornton, "Swarm Intelligence Based Drone Flocking Model," Proceedings of the IEEE, *28th International Conference on Automation and Computing (ICAC)*, Birmingham, United Kingdom, 2023, pp. 1-6