

# ALCF Datascience frameworks: Tensorflow, PyTorch, Keras, and Horovod

Huihuo Zheng  
Data science group

[huihuo.zheng@anl.gov](mailto:huihuo.zheng@anl.gov)

# Outline

- Datascience modules on Theta
  - How we built Tensorflow, Pytorch, Keras, and Horovod
  - Best practices for using the modules / installing other python packages
  - OMP threading and environmental variables setup (Tensorflow)
- Data distribution parallelization with Horovod and Cray ML plugin
- Visualization through Tensorboard
- Profiling using timeline trace and Vtune

# “datascience” modules on Theta

```
[user@thetalogin4 ~]$ module avail datascience  
----- /soft/environment/modules/modulefiles -----  
datascience/horovod-0.13.11      datascience/tensorflow-1.4  
datascience/keras-2.2.2          datascience/tensorflow-1.6  
datascience/pytorch-0.5.0-mkldnn datascience/tensorflow-1.10  
datascience/tensorboard
```

- Specifically optimized for KNL(*CPU*), with AVX512
- Using intel python 3.5 (based on intelpython35 module)
- GCC/7.3.0
- With -g, could be used for profiling
- Linked to MKL and MKL-DNN (home build)
- Dynamically linked to external libraries (be careful of your LD\_LIBRARY\_PATH, PYTHONPATH)
- With MPI through Horovod

Contact me [huihuo.zheng@anl.gov](mailto:huihuo.zheng@anl.gov) if you find any issues.



# How to use the “datascience” modules

- The packages are compiled with AVX512 vectorization, it does NOT run directly on login nodes or mom nodes.

```
>>> import tensorflow as tf
2018-09-23 20:08:54.289480: F tensorflow/core/platform/cpu_feature_guard.cc:37]
The TensorFlow library was compiled to use AVX512F instructions, but these aren't
available on your machine.
Aborted (core dumped)          Or Illegal instruction (core dumped)
```

- Run with qsub script.sh, or on mom node interactively through aprun.

```
#!/bin/bash
#COBALT -A SDL_Workshop
#COBALT -n 128
#COBALT -q default --attrs mcdram=cache:numa=quad

module load datascience/tensorflow-1.10 datascience/horovod-0.13.11 datascience/keras-2.2
aprun -n nproc -N nproc_per_node -cc depth -j 2 python script
```

# How to use the “datascience” modules

- We suggest you **DO NOT use virtual environment**. If your applications need other custom python packages, **pip install the package** to a separate directory and add the path to PYTHONPATH:

```
> module load intelpython35 gcc/7.3.0  
> pip install package_name --target=/path_to_install  
> export PYTHONPATH=$PYTHONPATH:/path_to_install/
```

- Or you could try to **build your own package as follows**:

```
> module load intelpython35 gcc/7.3.0 datascience/tensorflow-1.10  
> python setup.py build  
> export PYTHONPATH= $PYTHONPATH:/path_to_install/lib/python3.5/site-packages  
> python setup.py install --prefix=/path_to_install/
```

In some cases, you might need to run “*aprun -n 1 -cc none python setup.py build*”

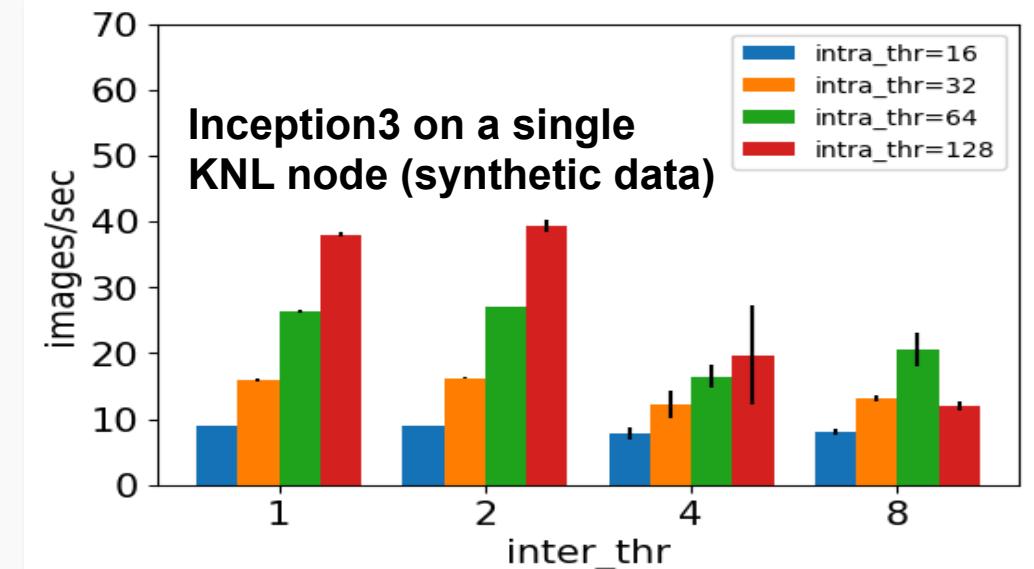
- Other suggestions:
  - unset PYTHONPATH and LD\_LIBRARY\_PATH, and then load “datascience” modules.
  - Always check currently loaded modules: “module list”
  - Always load datascience modules after you have loaded other modules.
  - Do not install packages to .local/lib/python3.5/site-packages (~~pip install XXX --user~~)

# Tensorflow threading and OMP environmental variables

- **inter\_op\_parallelism\_threads**: Number of thread teams for executing different operations concurrently.
- **intra\_op\_parallelism\_threads**: The total number threads in the threads pool. This value should equal to **OMP\_NUM\_THREADS**
- **Threading setup**

```
config = tf.ConfigProto()
config.intra_op_parallelism_threads = num_intra_threads
config.inter_op_parallelism_threads = num_inter_threads
tf.Session(config=config)
```

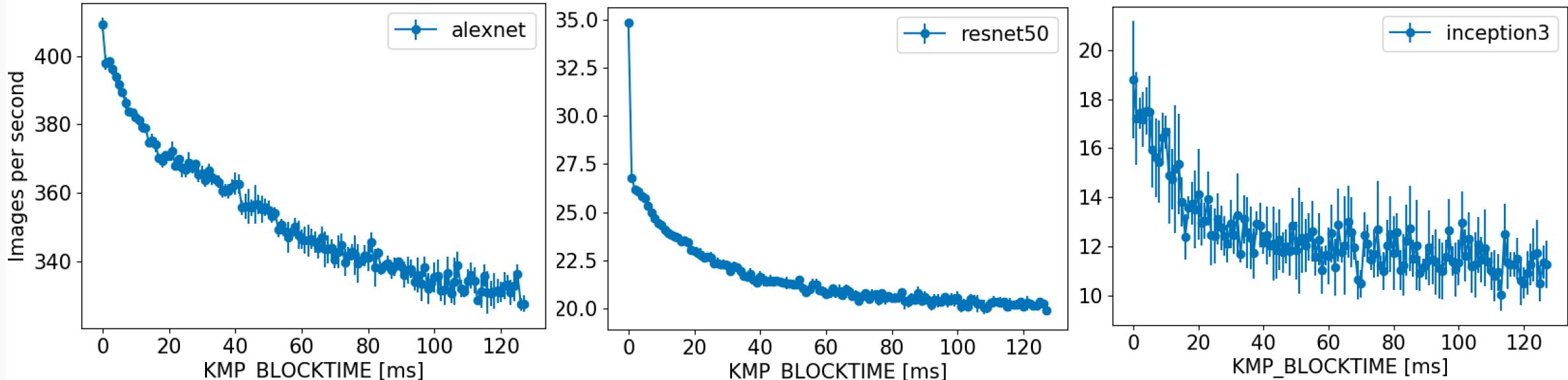
- Optimal setup on Theta based on benchmarks
  - inter\_op\_parallelism\_threads = 1, 2
  - Intra\_op\_parallelism\_threads = OMP\_NUM\_THREADS ( $64 \times j / ppn$ )
  - Use aprun -e OMP\_NUM\_THREADS=.. to setup threads
  - aprun -j 2 is slightly better than aprun -j 1



Tensorflow thread performance benchmarks  
[https://github.com/tensorflow/benchmarks/blob/mkl\\_experiment/scripts/tf\\_cnn\\_benchmarks/tf\\_cnn\\_benchmarks.py](https://github.com/tensorflow/benchmarks/blob/mkl_experiment/scripts/tf_cnn_benchmarks/tf_cnn_benchmarks.py)

# Tensorflow threading and OMP environmental

**variables** `KMP_BLOCKTIME=0`

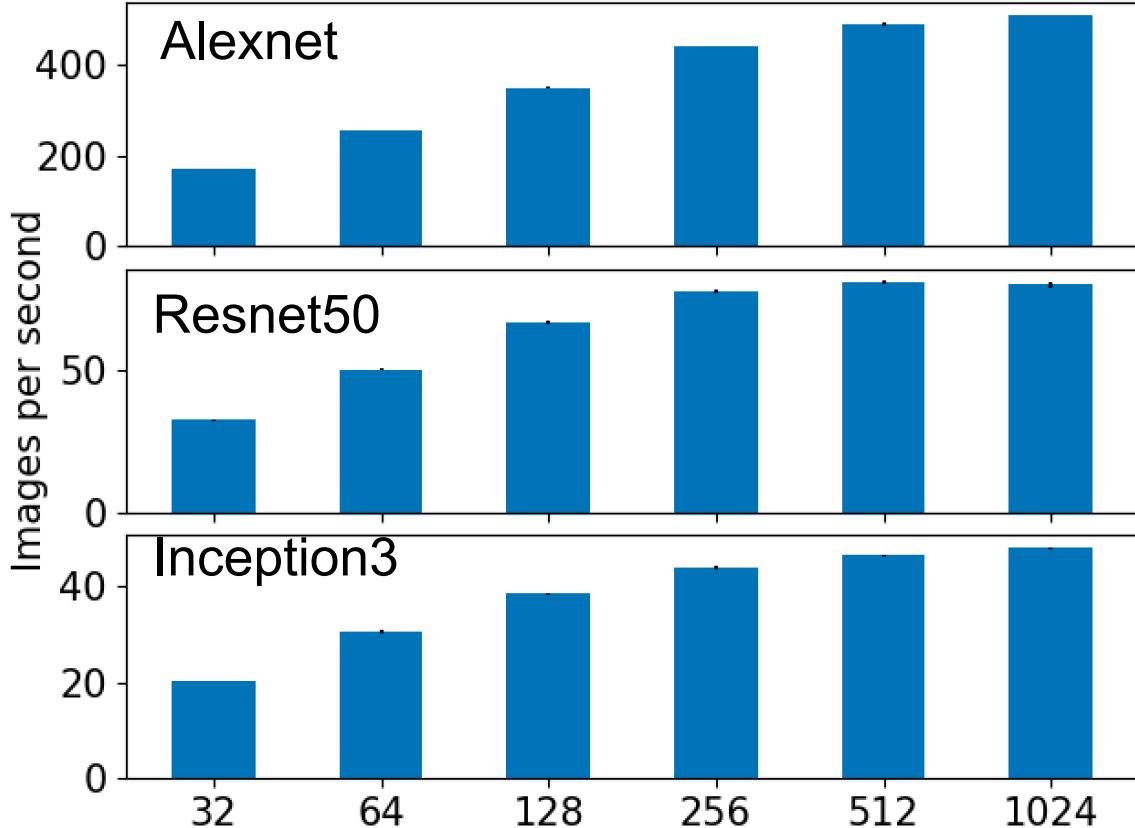


- The MKL default is 200ms, which was not optimal in our testing.
- You could set `KMP_BLOCKTIME` in two ways:
  1. Parse through aprun: `aprun ... -e KMP_BLOCKTIME=0 ...`
  2. Set inside your python script: `os.environ['KMP_BLOCKTIME']=0`

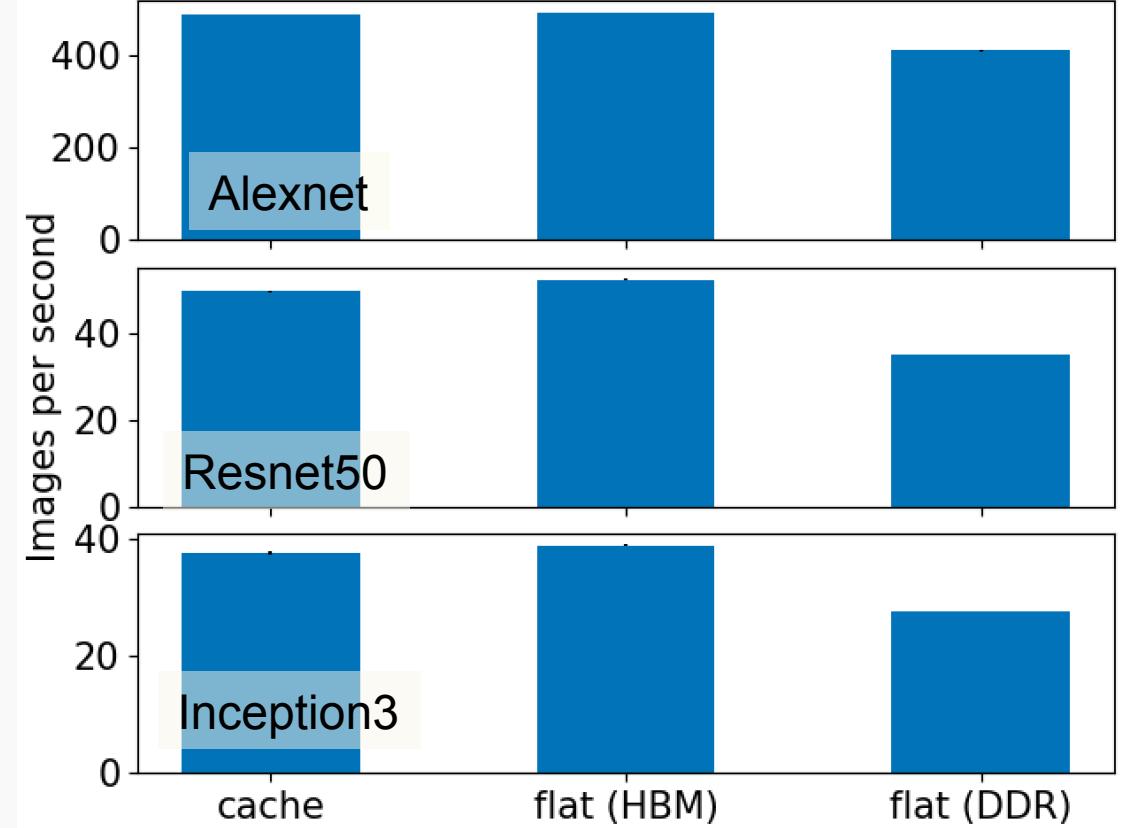
**`KMP_AFFINITY=granularity=fine,verbose,compact,1,0`**

If you set “`aprun ... -cc depth ...`”, it automatically sets `KMP_AFFINITY`.

# Batch size and memory mode (Tensorflow)

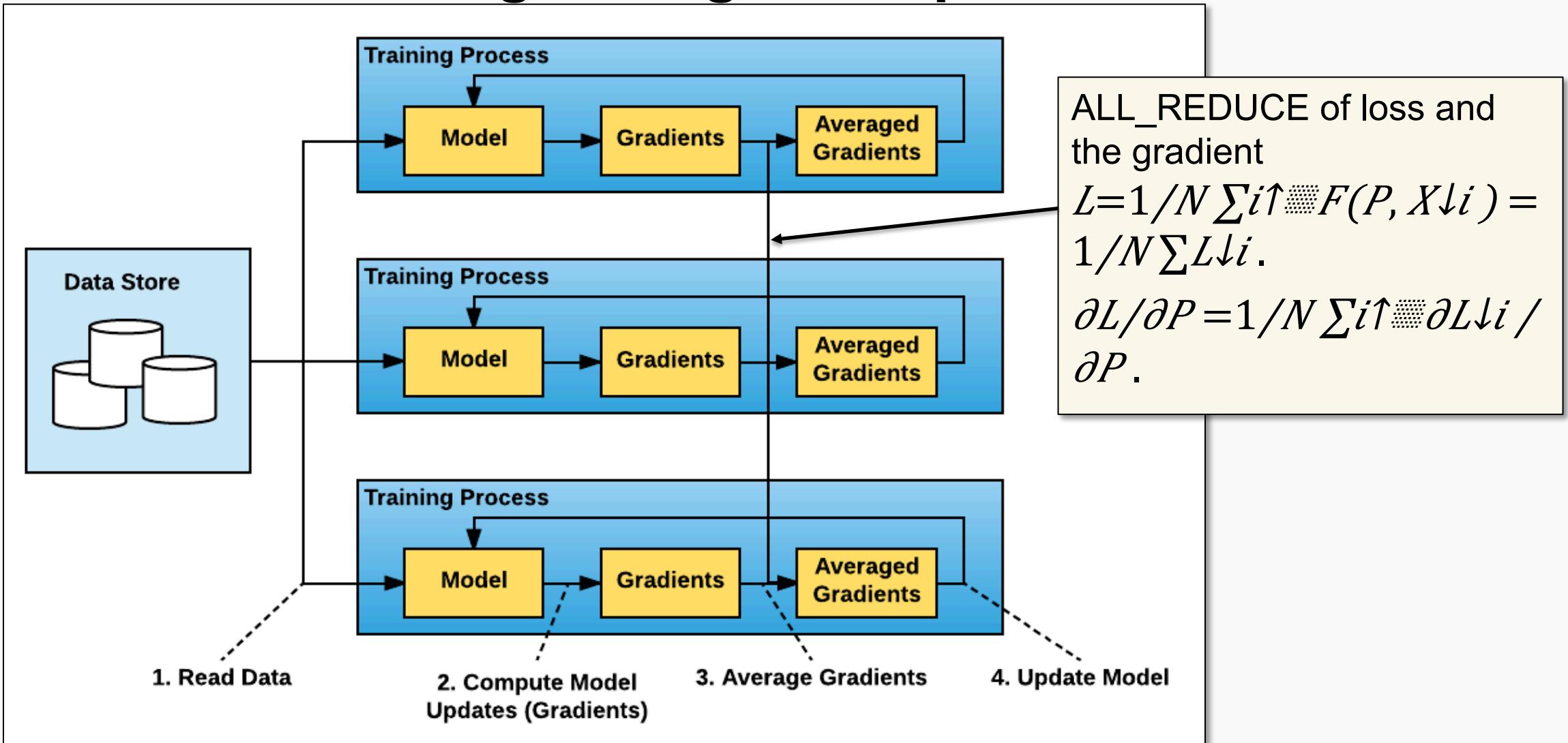


Batch size dependence



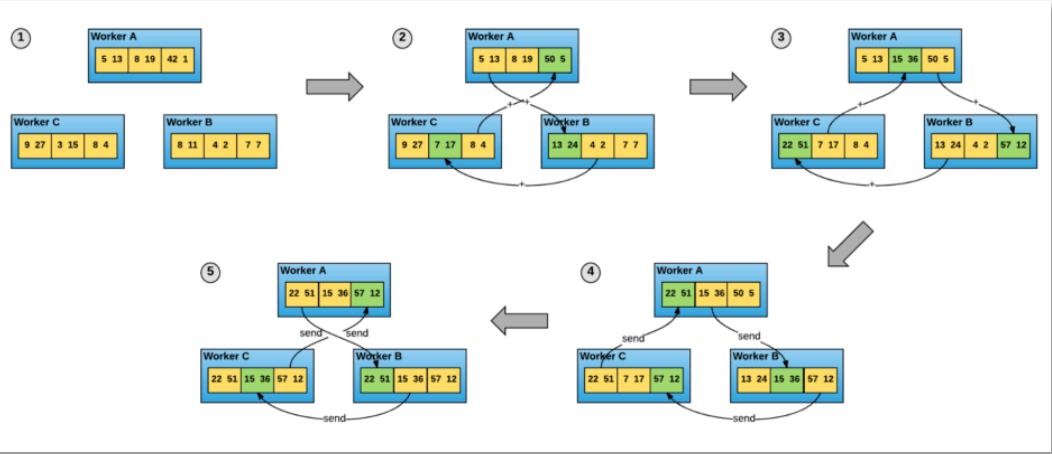
Different memory modes

# Distributed learning through data parallelization



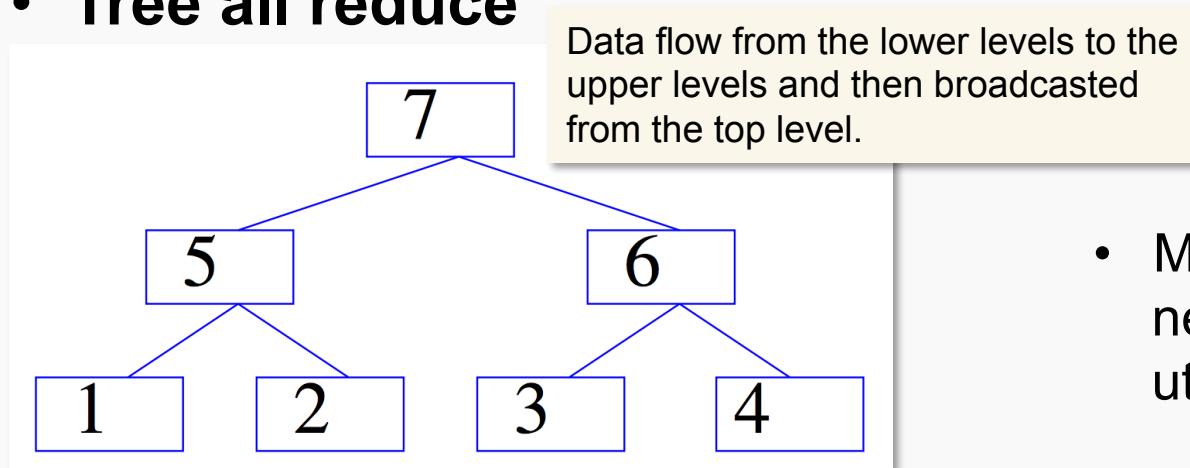
# All Reduce in HOROVOD

- **Ring all reduce**



- Simultaneously utilize all the network connection.
- The message communicated each time is  $M/nproc$ . (potentially becomes latency bound → fusion)

- **Tree all reduce**



- Message size is larger. However, not all the network connections are simultaneously utilized

# Distributed learning with HOROVOD

- Load the module in your environment

```
> module load datascience/horovod-0.11.13  
> module load datascience/keras-2.2 datascience/tensorflow-1.10
```

- Change your python script

- Initialize horovod (similar to MPI\_init)

```
import horovod.keras as hvd  
hvd.init() # hvd.rank() – rank id; hvd.size() – total number of process
```

- Wrap the optimizer with Distributed optimizer (adjust learning rate)

```
#Adjust the learning rate proportionally  
opt = keras.optimizers.Adadelta(1.0 * hvd.size())  
opt = hvd.DistributedOptimizer(opt)
```

- Broadcast the model from rank 0, so that all the ranks have the same beginning

```
callbacks=[hvd.callbacks.BroadcastGlobalVariablesCallback(0)]
```

# Tensorflow with HOROVOD

```
import tensorflow as tf
import horovod.tensorflow as hvd
layers = tf.contrib.layers
learn = tf.contrib.learn
def main():
    # Horovod: initialize Horovod.
    hvd.init() ←
    # Download and load MNIST dataset.
    mnist = learn.datasets.mnist.read_data_sets('MNIST-data-%d' % hvd.rank()) ←
    # Horovod: adjust learning rate based on number of GPUs.
    opt = tf.train.RMSPropOptimizer(0.001 * hvd.size()) ←
    # Horovod: add Horovod Distributed Optimizer
    opt = hvd.DistributedOptimizer(opt) ←
    hooks = [
        hvd.BroadcastGlobalVariablesHook(0),
        tf.train.StopAtStepHook(last_step=20000 // hvd.size()),
        tf.train.LoggingTensorHook(tensors={'step': global_step, 'loss': loss},
                                  every_n_iter=10),
    ]
    checkpoint_dir = './checkpoints' if hvd.rank() == 0 else None ←
    with tf.train.MonitoredTrainingSession(checkpoint_dir=checkpoint_dir,
                                           hooks=hooks,
                                           config=config) as mon_sess
```

[https://github.com/uber/horovod/blob/master/examples/tensorflow\\_mnist.py](https://github.com/uber/horovod/blob/master/examples/tensorflow_mnist.py)

# PyTorch with HOROVOD

```
#...
import torch.nn as nn
import horovod.torch as hvd
hvd.init() ←
train_dataset = datasets.MNIST('data-%d' % hvd.rank(), train=True, download=True,
                               transform=transforms.Compose([
                                   transforms.ToTensor(),
                                   transforms.Normalize((0.1307,), (0.3081,))])
                               ])
train_sampler = torch.utils.data.distributed.DistributedSampler(←
    train_dataset, num_replicas=hvd.size(), rank=hvd.rank())
train_loader = torch.utils.data.DataLoader(
    train_dataset, batch_size=args.batch_size, sampler=train_sampler, **kwargs)
# Horovod: broadcast parameters.
hvd.broadcast_parameters(model.state_dict(), root_rank=0) ←
# Horovod: scale learning rate by the number of GPUs.
optimizer = optim.SGD(model.parameters(), lr=args.lr * hvd.size(), ←
                      momentum=args.momentum)
# Horovod: wrap optimizer with DistributedOptimizer.
optimizer = hvd.DistributedOptimizer(
    optimizer, named_parameters=model.named_parameters()) ←
```

[https://github.com/uber/horovod/blob/master/examples/pytorch\\_mnist.py](https://github.com/uber/horovod/blob/master/examples/pytorch_mnist.py)

# Keras with HOROVOD

```
import keras
import tensorflow as tf
import horovod.keras as hvd
# Horovod: initialize Horovod.
hvd.init() ←
# Horovod: adjust learning rate based on number of GPUs.
opt = keras.optimizers.Adadelta(1.0 * hvd.size()) ←
# Horovod: add Horovod Distributed Optimizer.
opt = hvd.DistributedOptimizer(opt) ←
model.compile(loss=keras.losses.categorical_crossentropy,
               optimizer=opt,
               metrics=['accuracy'])
callbacks = [
    # Horovod: broadcast initial variable states from rank 0 to all other processes.
    hvd.callbacks.BroadcastGlobalVariablesCallback(0), ←
]
# Horovod: save checkpoints only on worker 0 to prevent other workers from corrupting them.
if hvd.rank() == 0:
    callbacks.append(keras.callbacks.ModelCheckpoint('./checkpoint-{epoch}.h5'))
model.fit(x_train, y_train, batch_size=batch_size,
          callbacks=callbacks, ←
          epochs=epochs,
          verbose=1, validation_data=(x_test, y_test))
```

[https://github.com/uber/horovod/blob/master/examples/keras\\_mnist.py](https://github.com/uber/horovod/blob/master/examples/keras_mnist.py)

# Cray ML Plugin

Check - Mike Ringenburg's talk: Scaling Deep Learning Frameworks (Cray)

- **Module setup**

```
module load cray-python/3.6.1.1
module load /lus/theta-fs0/projects/SDL_Workshop/mendygra/tmp_inst/modulefiles/craype-ml-plugin-py3/1.1.0
export PYTHONUSERBASE=/lus/theta-fs0/projects/SDL_Workshop/mendygra/pylibs
```

Example script: \$CRAYPE\_ML\_PLUGIN\_BASEDIR/examples/tf\_mnist/mnist.py  
Look for "CRAY ADDED" region

- **Initialization**

```
# initialize the Cray PE ML Plugin (assume 20M variables max)
mc.init(1, 1, 20*1024*1024, "tensorflow")
# config the thread team (correcting the number of epochs for the effective batch size)
FLAGS.train_epochs = int(FLAGS.train_epochs / mc.get_nranks())
max_steps = int(math.ceil(FLAGS.train_epochs * (_NUM_IMAGES['train'] +
_NUM_IMAGES['validation']) / FLAGS.batch_size))
mc.config_team(0, 0, 100, max_steps, 2, 200) # give each rank its own directory to save in
FLAGS.model_dir = FLAGS.model_dir + '/rank' + str(mc.get_rank())
```

- **Finalization**

```
mc.finalize()
```

# Cray ML Plugin

- Update optimizer to synchronize and apply

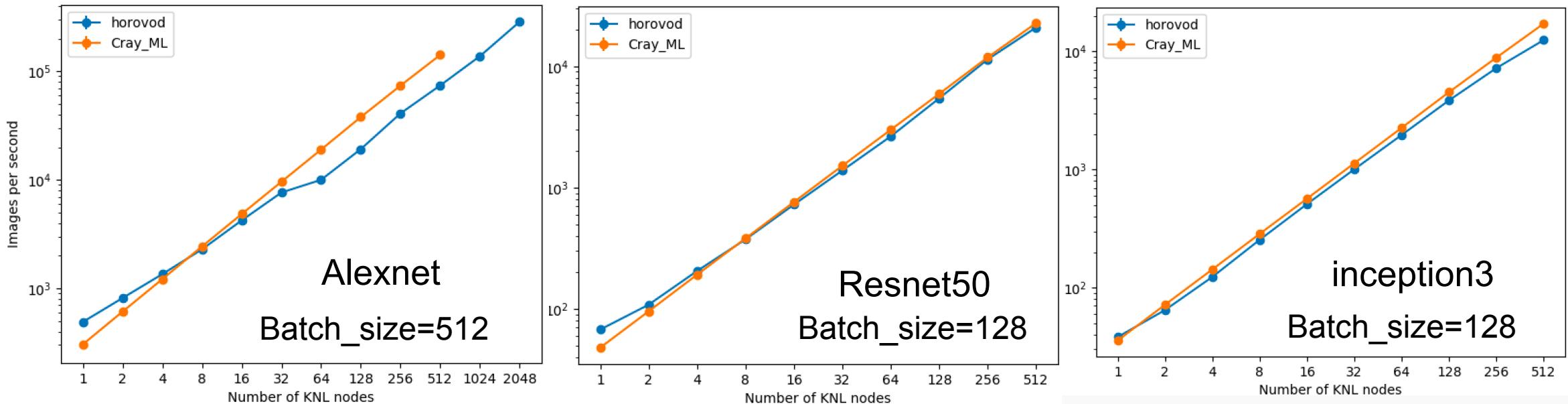
```
if FLAGS.enable_ml_comm:  
    # we need to split out the minimize call below so we can  
    # modify gradients  
    grads_and_vars = optimizer.compute_gradients(loss)  
    grads = mc.gradients([gv[0] for gv in grads_and_vars],  
                         0)  
    gs_and_vs = [(g,v) for (_,v), g in zip(grads_and_vars,  
                                             grads)]  
    train_op = optimizer.apply_gradients(gs_and_vs,  
                                         # END CRAY ADDED  
                                         global_step=tf.train.get_or_create_global_step())
```

# Cray ML Plugin

- Create a hook to initialize variables

```
class BcastTensors(tf.train.SessionRunHook):  
    def __init__(self): self.bcast = None  
    def begin(self):  
        if not self.bcast:  
            new_vars = mc.broadcast(tf.trainable_variables(),0)  
            self.bcast = tf.group(*[tf.assign(v,new_vars[k]) for k,v in  
                enumerate(tf.trainable_variables())])  
    def after_create_session(self, session, coord):  
        session.run(self.bcast)  
        if FLAGS.ml_comm_validate_init:  
            py_all_vars = [session.run(v) for v  
                in tf.trainable_variables()]  
            if (mc.check_buffers_match(py_all_vars,  
                print("ERROR: not all processes have  
model!")  
            else:  
                print("Initial model is consistent on  
  
sess_hooks = []  
if FLAGS.enable_ml_comm:  
    sess_hooks = [BcastTensors()] # END CRAY ADDED  
# ...  
tf.estimator.EstimatorSpec(  
    mode=mode,  
    predictions=predictions,  
    loss=loss, train_op=train_op,  
    training_hooks=sess_hooks,  
    eval_metric_ops=metrics)
```

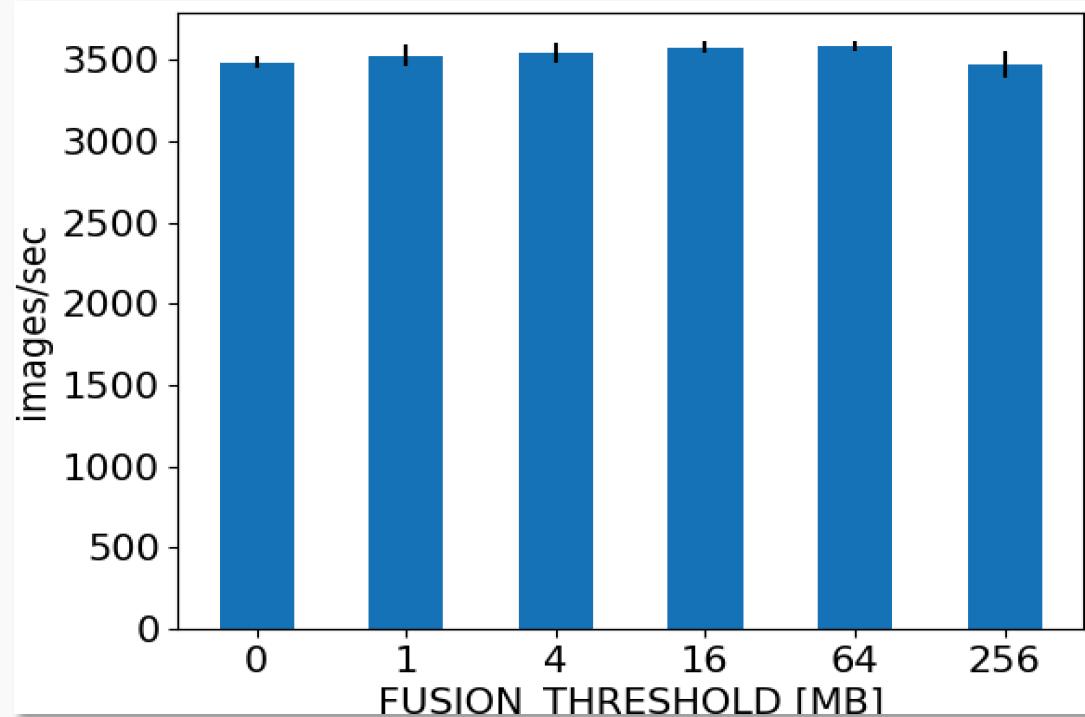
# Scaling Tensorflow: HOROVOD / Cray ML Plugin (Synthetic data)



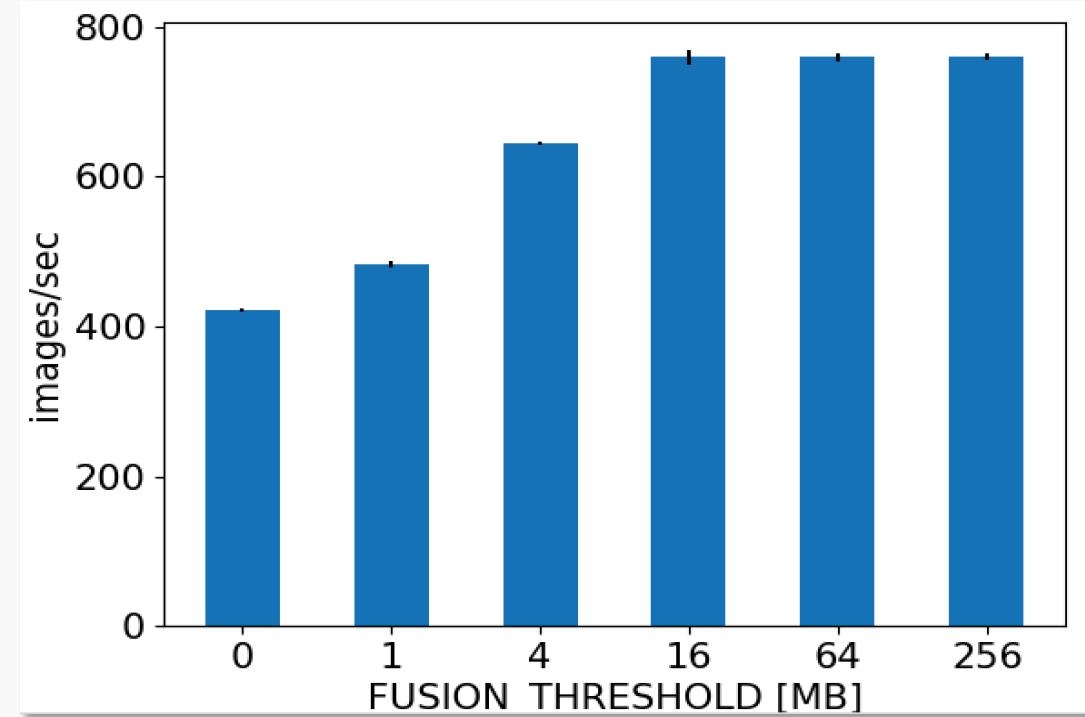
Cray ML plugins has better scaling efficiency than horovod. [The fact that Cray ML plugin in 1 KNL case is slower than horovod is probably due to different tensorflow builds (1.10 intel vs 1.5 cray)]

# HOROVOD environmental variables: FUSION\_THRESHOLD (default: 64MB)

Alexnet (16 KNL)

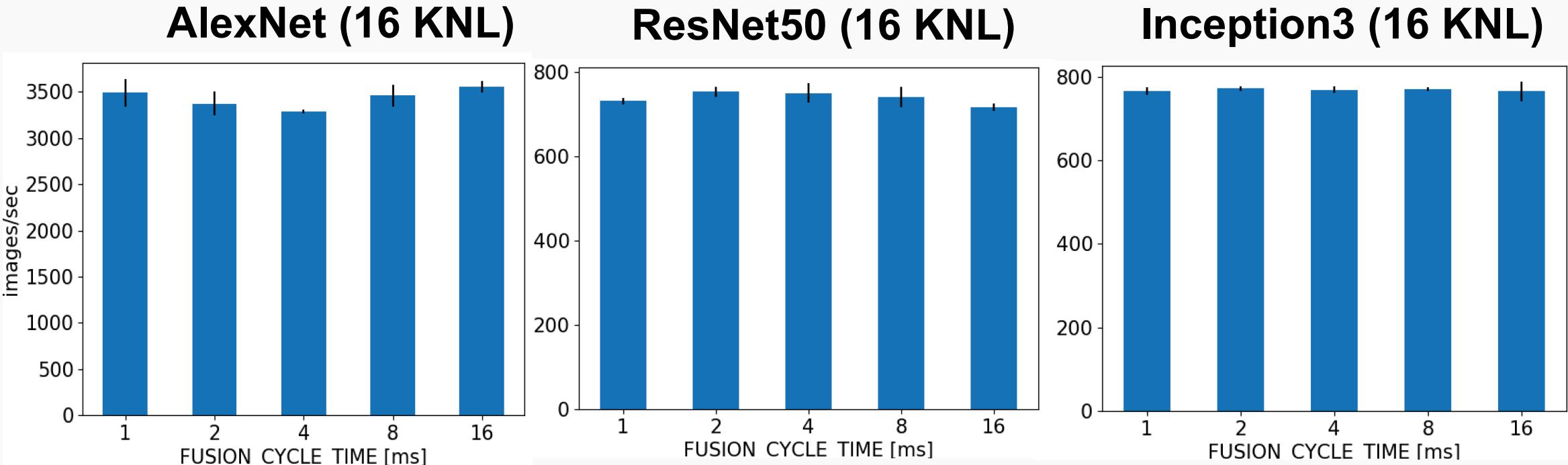


Inception3 (16 KNL)



FUSION\_THRESHOLD = 64 MB already gets optimal performance.

# HOROVOD environmental variables: FUSION\_CYCLE\_TIME (default: 3.5ms)



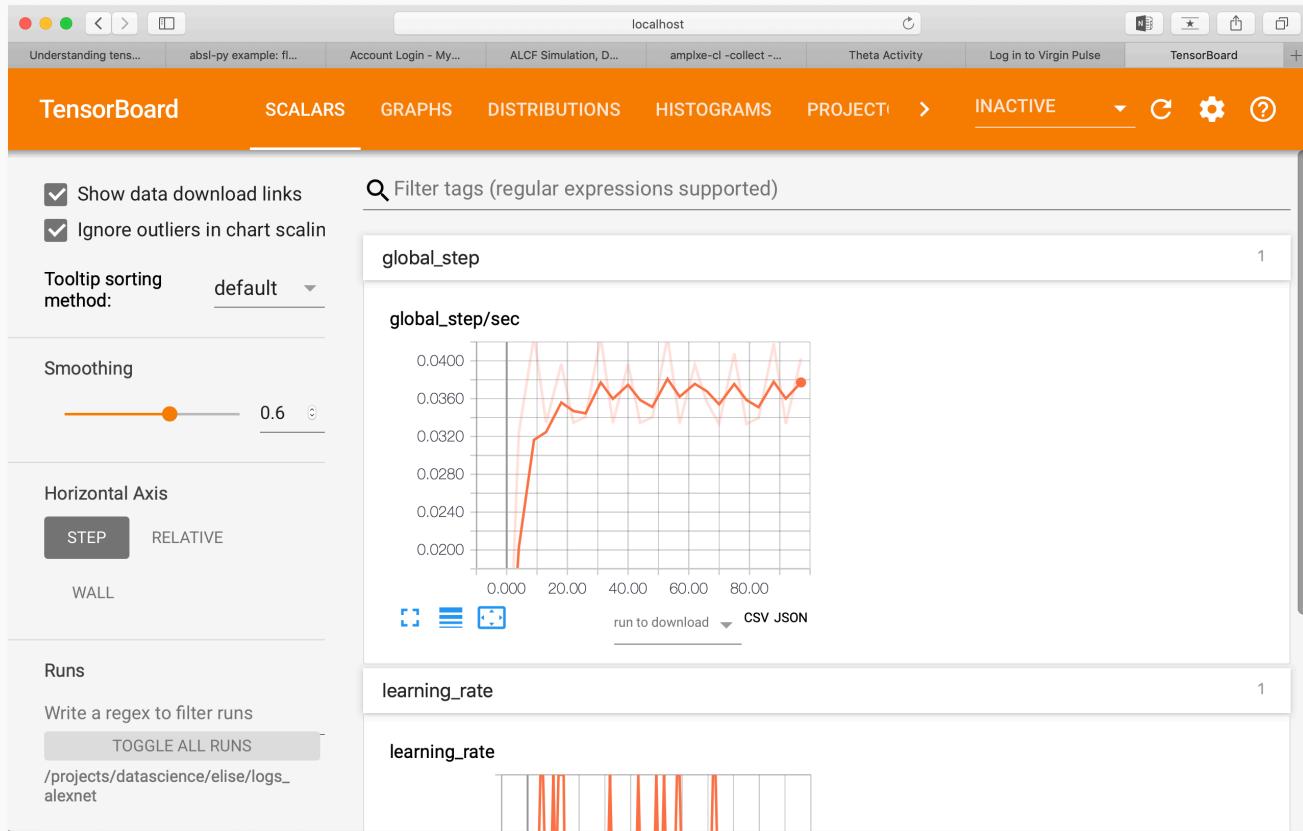
The runtime is not sensitive with respect to the changing of FUSION\_CYCLE\_TIME

# Comments about distributed deep learning

Increasing workers increases the global batch size and the learning rate:

- This reduces the number of updates to the model (iterations) per epoch
- Might require more iterations to converge to same validation accuracy;
- Might have different convergence;
- Might need warm up steps with smaller learning rate.

# Visualization with Tensorboard



## Read log files through ssh tunneling

### (1) SSH tunnel to Theta

```
ssh -XL 16006:127.0.0.1:6006  
user@theta.alcf.anl.gov
```

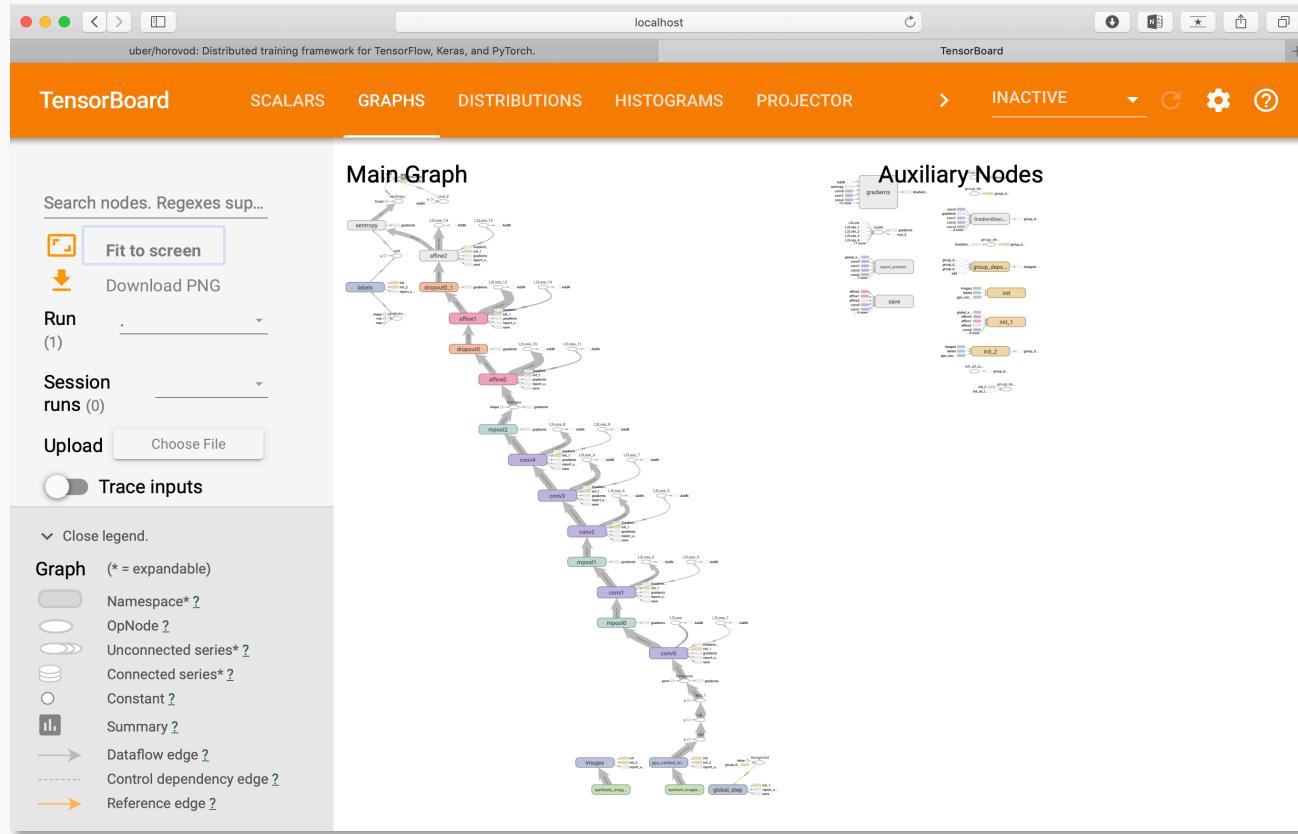
### (2) Run tensorboard on Theta

```
> module load tensorflow  
> tensorboard --logdir DIR
```

### (3) Open browser from local machine: <https://localhost:16006>

Interactive job controlling through Tensorboard is not supported on Theta yet.  
<https://www.datacamp.com/community/tutorials/tensorboard-tutorial>

# Visualization with Tensorboard



## Read log files through ssh tunneling

(1) SSH tunnel to Theta

```
ssh -XL 16006:127.0.0.1:6006  
user@theta.alcf.anl.gov
```

(2) Run tensorboard on Theta

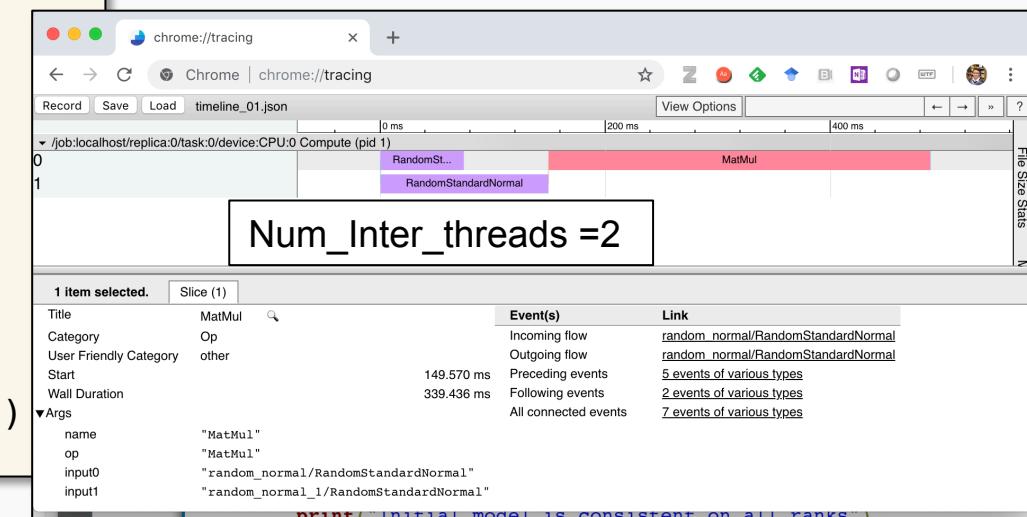
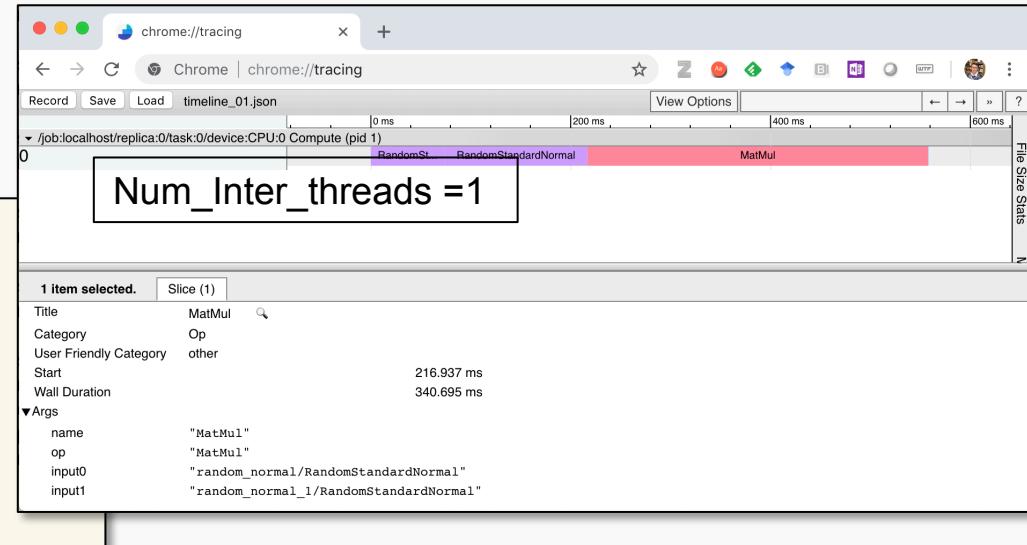
```
> module load tensorflow  
> tensorboard --logdir DIR
```

(3) Open browser from local machine:  
<https://localhost:16006>

Interactive job controlling through Tensorboard is not supported on Theta yet.  
<https://www.datacamp.com/community/tutorials/tensorboard-tutorial>

# Tracing profile

```
import tensorflow as tf
from tensorflow.python.client import timeline ←
import sys
a = tf.random_normal([2000, 5000])
b = tf.random_normal([5000, 1000])
res = tf.matmul(a, b)
sess = tf.Session(config=tf.ConfigProto(\n    inter_op_parallelism_threads=1,\n    intra_op_parallelism_threads=1 ))
# add additional options to trace the session execution
options = tf.RunOptions(trace_level=tf.RunOptions.FULL_TRACE)
run_metadata = tf.RunMetadata()
sess.run(res, options=options, run_metadata=run_metadata)
# Create the Timeline object, and write it to a json file
fetched_timeline = timeline.Timeline(run_metadata.step_stats)
chrome_trace = fetched_timeline.generate_chrome_trace_format()
f=open('timeline_01.json', 'w'); f.write(chrome_trace);f.close()
```

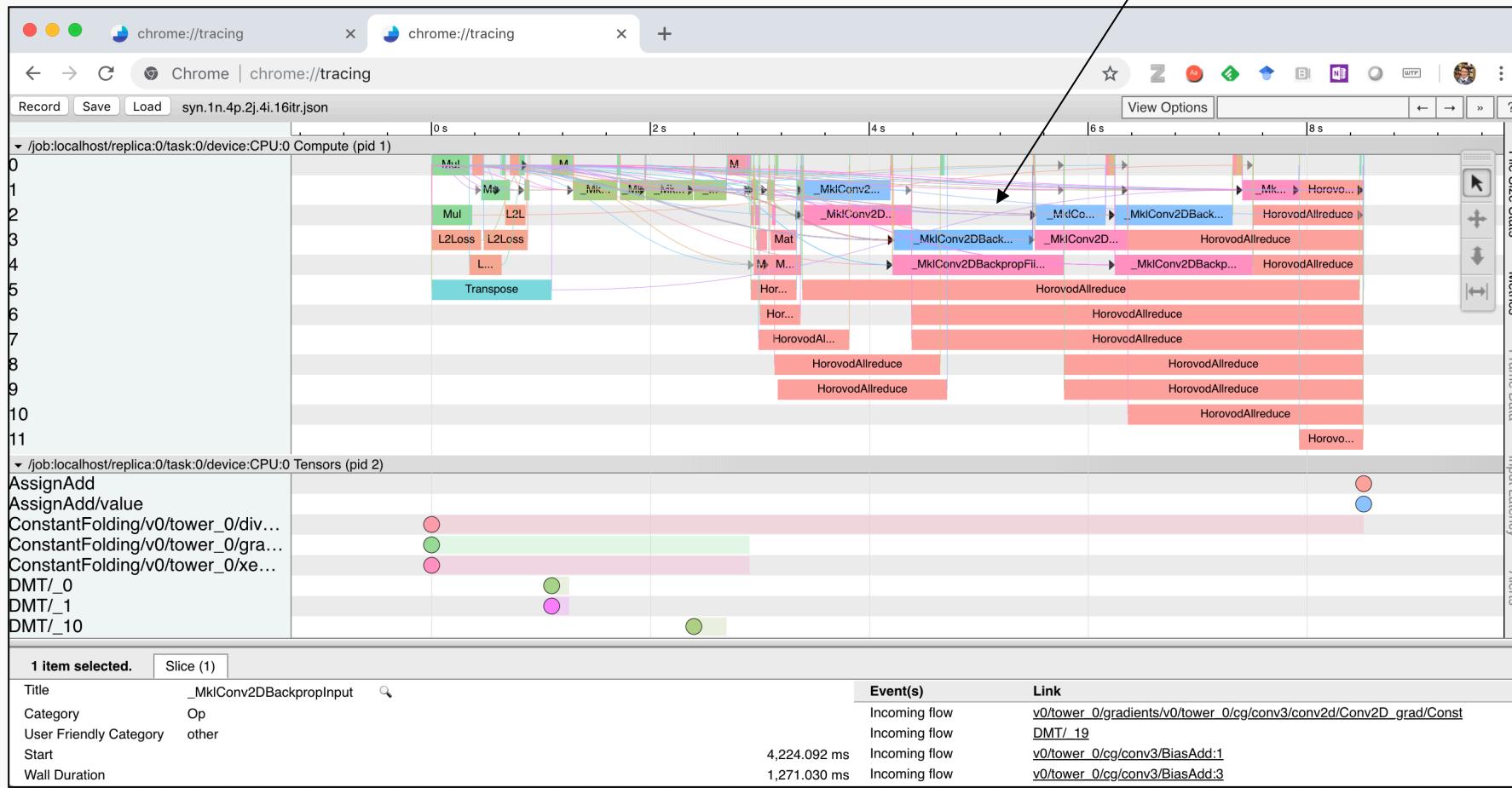


Open timeline\_01.json using Chrome.

Go to the page chrome://tracing. "Load" the JSON file.

# Tracing profile (Alexnet)

Dataflow



# Time spent on different kernels (Alexnet)

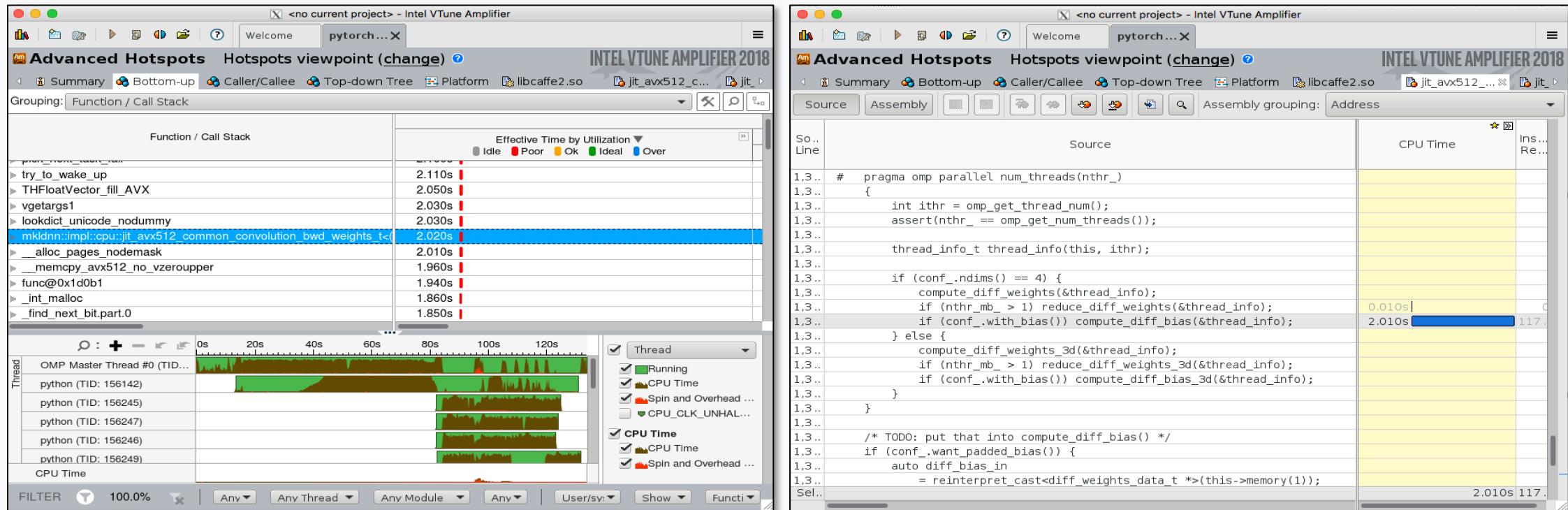
294 items selected. Slices (294)		Wall Duration	Self time	Average Wall Duration	Occurrences
Name					
<a href="#">MklConv2DBackpropFilterWithBias</a>		1,680.151 ms	1,680.151 ms	336.030 ms	5
<a href="#">MklConv2DBackpropInput</a>		884.677 ms	884.677 ms	221.169 ms	4
<a href="#">MklConv2DWithBias</a>		791.824 ms	791.824 ms	158.365 ms	5
<a href="#">Transpose</a>		555.096 ms	555.096 ms	555.096 ms	1
<a href="#">MatMul</a>		308.802 ms	308.802 ms	34.311 ms	9
<a href="#">MklAddN</a>		45.058 ms	45.058 ms	2.816 ms	16
<a href="#">MklReluGrad</a>		43.725 ms	43.725 ms	6.246 ms	7
<a href="#">MklRelu</a>		34.106 ms	34.106 ms	4.872 ms	7
<a href="#">BiasAddGrad</a>		29.678 ms	29.678 ms	9.893 ms	3
<a href="#">MklMaxPoolGrad</a>		28.922 ms	28.922 ms	9.641 ms	3
<a href="#">Mul</a>		21.469 ms	21.469 ms	0.613 ms	35
<a href="#">MklMaxPool</a>		16.323 ms	16.323 ms	5.441 ms	3
<a href="#">ApplyGradientDescent</a>		10.671 ms	10.671 ms	0.667 ms	16
<a href="#">L2Loss</a>		8.933 ms	8.933 ms	0.558 ms	16
<a href="#">SparseSoftmaxCrossEntropyWithLogits</a>		7.694 ms	7.694 ms	7.694 ms	1
<a href="#">BiasAdd</a>		2.790 ms	2.790 ms	0.930 ms	3
<a href="#">Const</a>		2.061 ms	2.061 ms	0.027 ms	75
<a href="#">MklReshape</a>		1.587 ms	1.587 ms	0.794 ms	2
<a href="#">MklToTf</a>		0.864 ms	0.864 ms	0.041 ms	21
<a href="#">VariableV2</a>		0.609 ms	0.609 ms	0.034 ms	18
<a href="#">Identity</a>		0.370 ms	0.370 ms	0.019 ms	20
<a href="#">MklIdentity</a>		0.353 ms	0.353 ms	0.035 ms	10
<a href="#">NoOp</a>		0.125 ms	0.125 ms	0.031 ms	4
<a href="#">RandomUniformInt</a>		0.124 ms	0.124 ms	0.124 ms	1

# VTune profiling

More details: Profiling Your Application with Intel VTune and Advisor - Carlos Rosales-Fernandez and Paulius Velesko, Intel

```
source /opt/intel/vtune_amplifier/amplxe-vars.sh  
aprun -n ... -e OMP_NUM_THREADS=128 \  
-e LD_LIBRARY_PATH=$LD_LIBRARY_PATH:/opt/intel/vtune_amplifier/lib64 \  
ampxle-cl -collect advance-hotspots -r output_dir python script.py
```

Remember to set LD\_LIBRARY\_PATH,  
Put vtune library at the end!! Otherwise, it  
might complain about the GLIBCXX version.



The python modules are compiled using -g flag. Therefore, the user could trace the source file in Vtune.



# Thank you!

[huihuo.zheng@anl.gov](mailto:huihuo.zheng@anl.gov)