

### **COMPARTMENTAL MODEL FRAMEWORK**

- Model: Differential equations of dynamic systems
- Compartment:
  - Abstract entity representing the quality of interest
  - Equivalent to a system state
  - Visually conceptualized as a box
  - Internally homogeneous
- Compartment Interactions: Through a set of rate equations
  - Visually conceptualized by arrows between compartments
- Net Flow Into a Compartment: A set of first order linear or nonlinear equations



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### **COMPARTMENTAL MODEL FRAMEWORK**

For an n compartment system,

- Ompartment/state variables  $x(t) = [x_1(t), ..., x_n(t)]^T$
- State-space model:

$$\dot{x}(t) = f(x(t), w(t); \theta(t), t)$$
  
$$y(t) = g(x(t); \theta(t), t) + v(t)$$

where,

 $f(\cdot)$  is the state dynamics function corresponding to the compartmental model

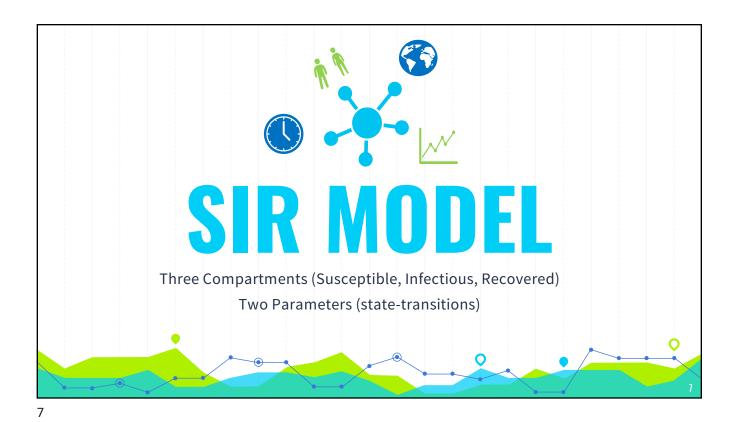
 $w(t) = [w_1(t), ..., w_1(t)]^T$  is the external system inputs

 $\mathbf{y}(t) = [y_1(t), ..., y_m(t)]^T$  is the vector of observable model invariables (i.e., outputs)

 $oldsymbol{g}(\cdot)$  is the function that maps state variables to observations (measurements)

 $\boldsymbol{v}(t) = [v_1(t), \dots, v_m(t)]^T$  is the vector of measurement error

 $\theta(t) = \left[\theta_1(t), \dots, \theta_p(t)\right]^T$  is the vector of model parameters to be set or identified



Susceptible (s)

Sir Compartment Model  $\beta \\
Infected \\
(I)$ Recovered (R)  $\frac{dS}{dt} = -\beta S(t)I(t) \\
\frac{dI}{dt} = \beta S(t)I(t) - \gamma I(t) \\
\frac{dS}{dt} + \frac{dI}{dt} + \frac{dR}{dt} = -\beta SI + (\beta IS - \gamma I) + \gamma I = 0$ Epidemix Model

### **SIR MODEL PARAMETERS**

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- Depends on effective contact per unit of time
- Most important parameter, but difficult to estimate directly
- O Can be estimated if we assume individuals mix randomly:  $\beta = \frac{R_0}{ND}$  (where D is duration of infectiousness)

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- o A measure of how infectious the disease is
- The average number of new infected individuals caused by one infectious individual
- Can be estimated by fitting model predictions to observed data:  $R_0 = \frac{\beta S_0}{\gamma}$  (where  $S_0$  is the initial number of susceptible individuals)

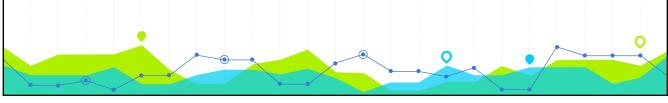


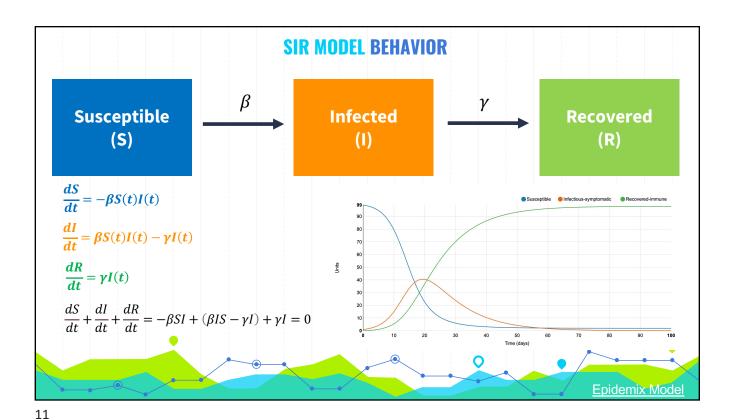
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## **SIR MODEL BEHAVIOR**

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- $\circ$  clearly affected by both transmission ( $\beta$ ) and recovery ( $\gamma$ ) rates.
- $\circ$  When R<sub>0</sub> >1, the occurrence of the disease will increase.
  - Here, I(t) increases, reaches a maximum, and then decreases to zero as  $t \to \infty$ .
- $\circ$  When  $R_0 < 1$ , the occurrence of the disease will decrease and eventually die out.
  - Here, I(t) decreases monotonically to zero as  $t \to \infty$ .
- $\circ$  However, when  $R_0 = 1$ , the disease occurrence will remain constant.
- We can see that values of R<sub>0</sub> close to 1 produce very slow-growing epidemics, while values of R<sub>0</sub> much greater than one produce fast, explosive epidemics.





Reduce to a single differential equation:

$$\frac{dI}{dS} = \frac{\frac{dI}{dt}}{\frac{dS}{dt}} = \frac{bIS - gI}{-bIS} = \frac{g}{bS} - 1$$

**SIR MODEL BEHAVIOR** 

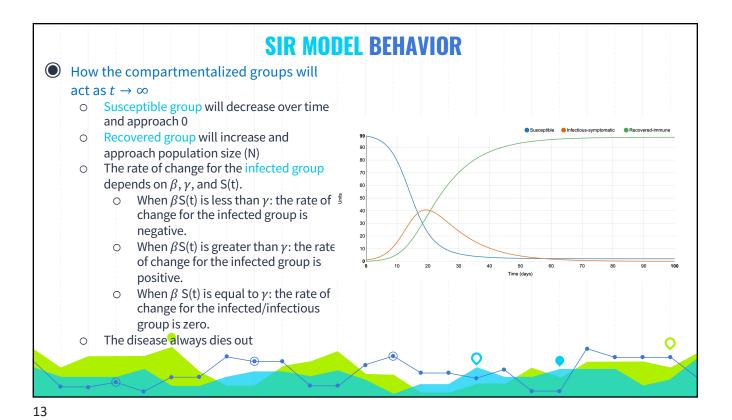
$$dI = \left(\frac{g}{bS}\right) - 1dS$$

$$\int dI = \int \left(\frac{g}{bS} - 1\right) dS$$

$$I = \frac{g}{b}\ln(S) - S + C$$

$$I(0) - \frac{g^b}{b} \ln(S0) + S(0) = C$$

© Given initial conditions, S(0), I(0),  $\beta$ , and  $\gamma$ , these values can be substituted to solve for C



LINKING MODEL TO DATA

sample

parameters  $\theta$ model trajectory  $X_0$ initial conditions  $X_0$ Elinking Model trajectory  $X_0$   $X_0$ 

#### **BAYESIAN INFERENCE**

- lacktriangle Calculate the posterior  $p(\theta|data)$ 
  - Inherent uncertainty in parameters
  - $\circ$  Posterior is the probability distribution of a random variable  $\theta$
- **O** Bayes' Rule  $p(\theta|data) = \frac{p(data|\theta)p(\theta)}{p(data)}$ 
  - $\circ$   $p(\theta|data)$  is the posterior
  - o  $p(data|\theta)$  is the likelihood
  - $\circ$   $p(\theta)$  is the prior
  - o p(data) is the normalization constant
- $\odot$  i.e., (posterior)  $\propto$  (normalization likelihood)  $\cdot$  (prior)

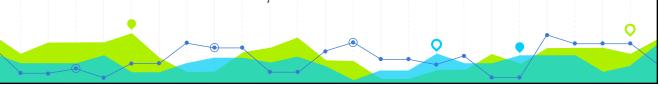


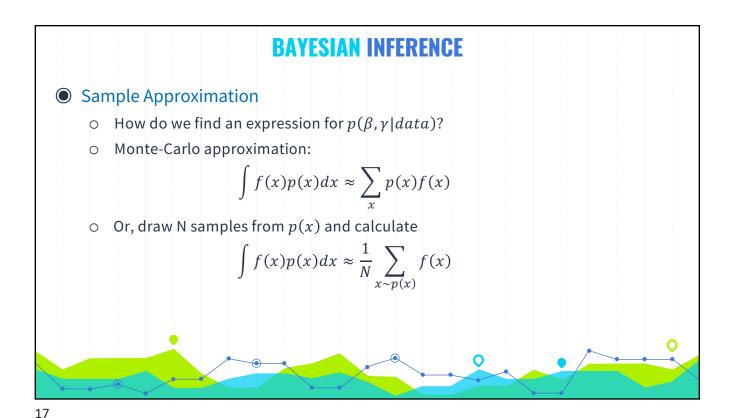
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# **BAYESIAN INFERENCE**

### Expectation Values

- O Parameter(s)  $\theta$  are interpreted as a random variable, distributed according to the posterior:  $p(\theta|data) \propto p(data|\theta)p(\theta)$
- $\circ$  We want to generate samples of  $\theta$  from this distribution
- O To calculate the expected value of any quantity, given the data, we integrate over  $p(\theta)$ :  $E[A] = \int p(\theta|data)X(\theta)d\theta$
- ο E.g., for SIR model, if we know  $p(\beta, \gamma)$ , we can calculate the expected value of  $R_0$ :  $E[R_0] = \int p(\beta, \gamma | data) \frac{\beta}{\gamma} d\beta d\gamma$





MARKOV CHAIN MONTE CARLO

A chain of samples where each proposed θ\* depends on the previous one

# **MARKOV CHAIN MONTE CARLO (MCMC)**

- Markov chain: stochastic sequence of states in which the next state depends only upon the current state  $\theta_{t+1} \sim \mathbb{D}(\theta_t)$
- lacktriangle Algorithms generates a sequence of parameter values  $\theta_1, \theta_2, \dots$ , whose empirical distribution, approaches the posterior distribution.
- The generation of the vectors in the chain, is done by random numbers (Monte Carlo) in such way that each new point may only depend on the previous point (Markov chain).
  - The chain is used as if it is a sample from the posterior.
- Metropolis-Hastings Algorithm: a particular way of using MCMC to sample from a distribution



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### **METROPOLIS-HASTINGS ALGORITHM**

Generate a Markov chain with a transition density

$$p(\theta, \theta^*) = q(\theta, \theta^*) \alpha(\theta, \theta^*), \theta \neq \theta^*$$

$$p(\theta, \theta) = 1 - \int q(\theta, \theta^*) \alpha(\theta, \theta^*) d\theta$$

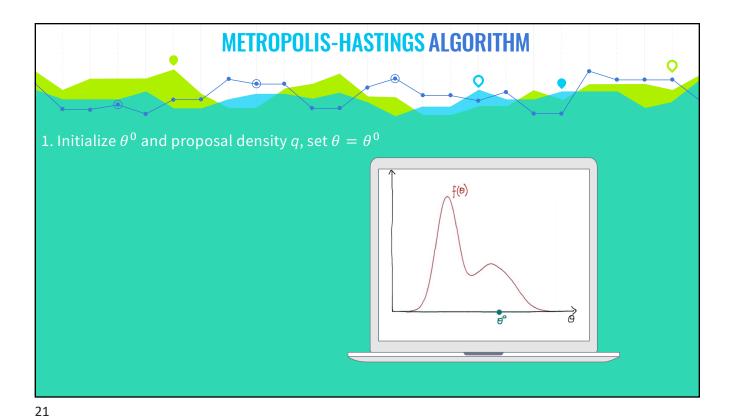
For some proposal density q and for acceptance probability  $\alpha$ 

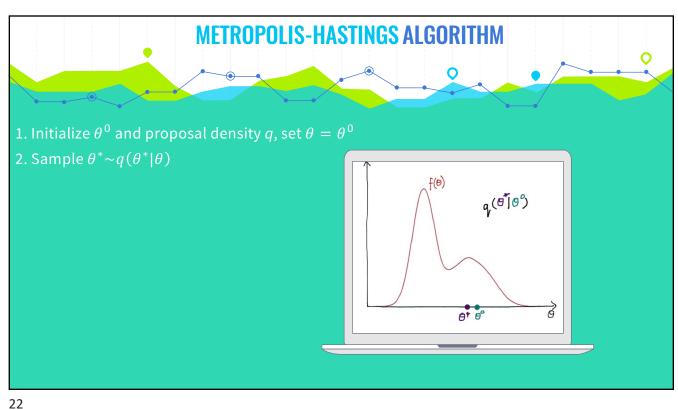
The chain is reversible IFF

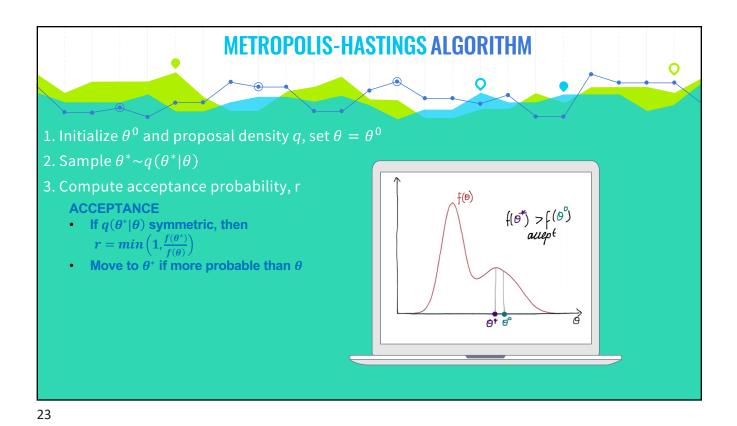
$$f(\theta)q(\theta,\theta^*)\alpha(\theta,\theta^*) = f(\theta^*)q(\theta^*,\theta)\alpha(\theta^*,\theta)$$

lacktriangle Thus, we choose  $\alpha$  as



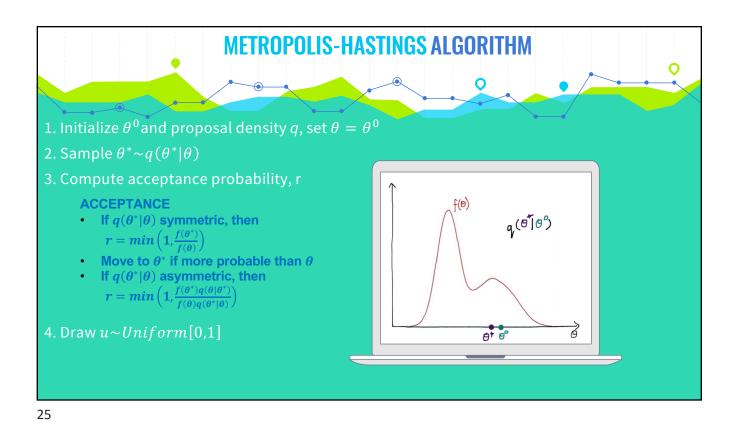


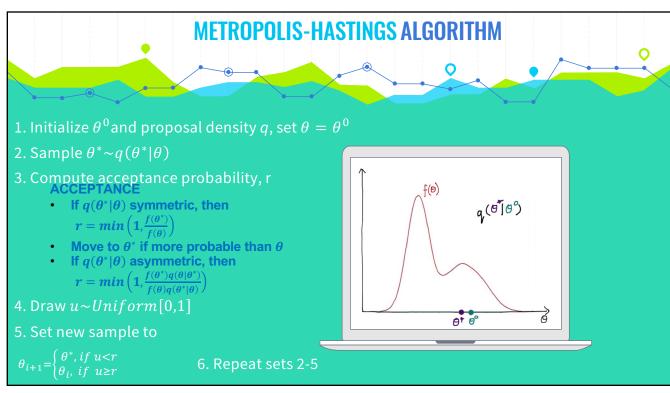


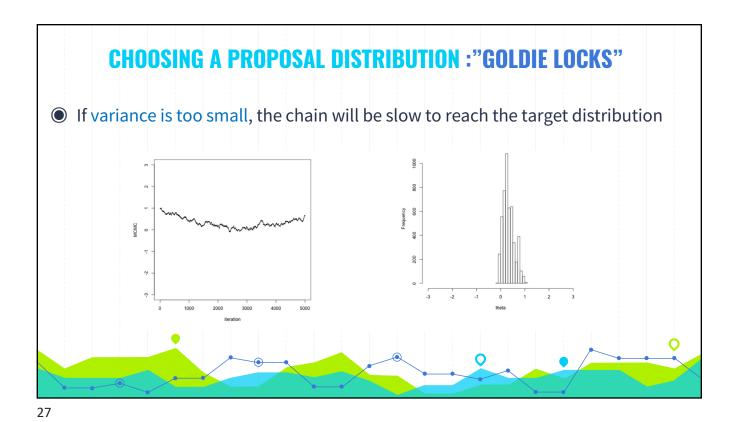


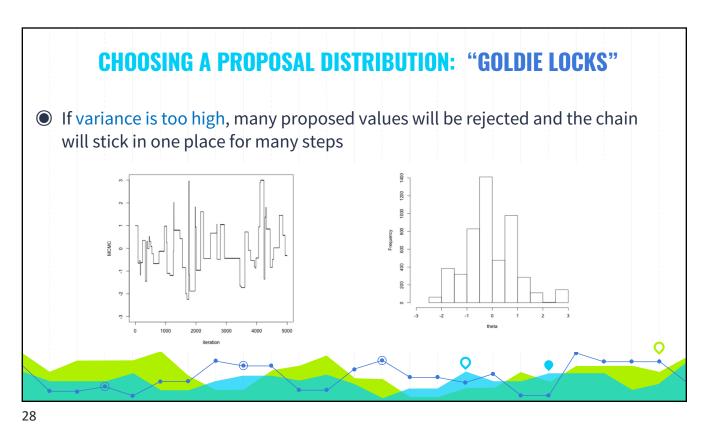
1. Initialize  $\theta^0$  and proposal density q, set  $\theta = \theta^0$ 2. Sample  $\theta^* \sim q(\theta^*|\theta)$ 3. Compute acceptance probability, rACCEPTANCE

• If  $q(\theta^*|\theta)$  symmetric, then  $r = min\left(1, \frac{f(\theta^*)}{f(\theta)}\right)$ • Move to  $\theta^*$  if more probable than  $\theta$ • If  $q(\theta^*|\theta)$  asymmetric, then  $r = min\left(1, \frac{f(\theta^*)q(\theta^*|\theta^*)}{f(\theta)q(\theta^*|\theta)}\right)$ 



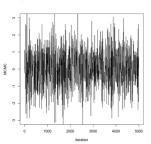


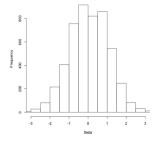




#### **CHOOSING A PROPOSAL DISTRIBUTION: "GOLDIE LOCKS"**

If variance is just right, the chain will efficiently explore the full shape of the target distribution





- We can either:
  - Trial and Error: Try several different proposal distributions (pilot runs), aiming for acceptance rate of 24-40%
  - Use Adaptive MCMC



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#### **ADAPTIVE MCMC**

- New point depends on previous point AND on earlier history of the chain
- The adaptation is based on an increasing part of the chain
- lacktriangle Uses a Gaussian proposal with covariance  $C_n$  that depends on the chain generated so far:

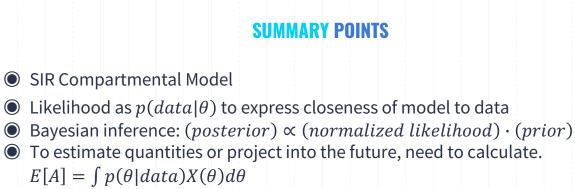
$$C_n = \begin{cases} C_0, & n \leq n_0 \\ s_d cov(\theta_1, \dots, \theta_n) + s_d \varepsilon I_d, & n > n_0 \end{cases}$$

Where

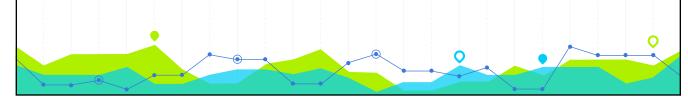
 $s_d$  is a parameter that depends only on the dimension d of the sample space (usually  $s_d=2.4^2/d$ )

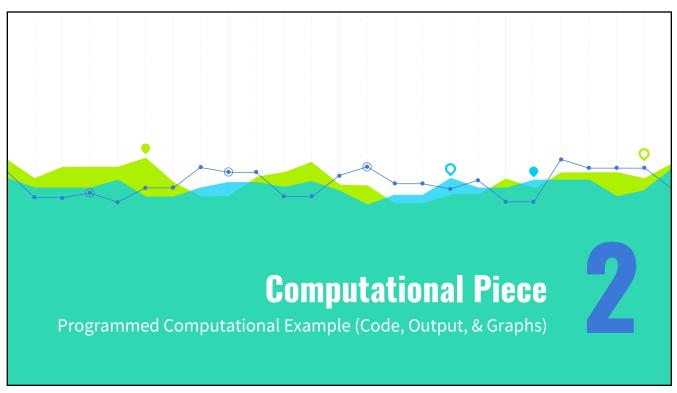
 $\varepsilon>0$  is a constant we keep very small

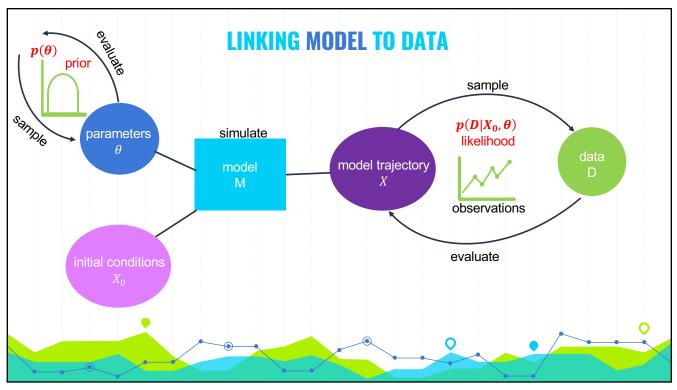
 $n_0>0$  is the length of the initial nonadaptive period

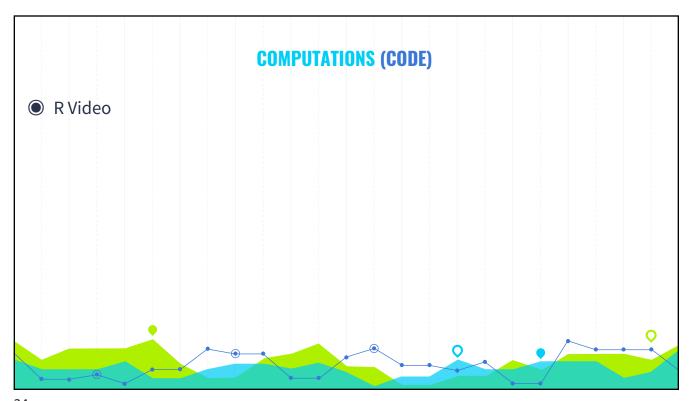


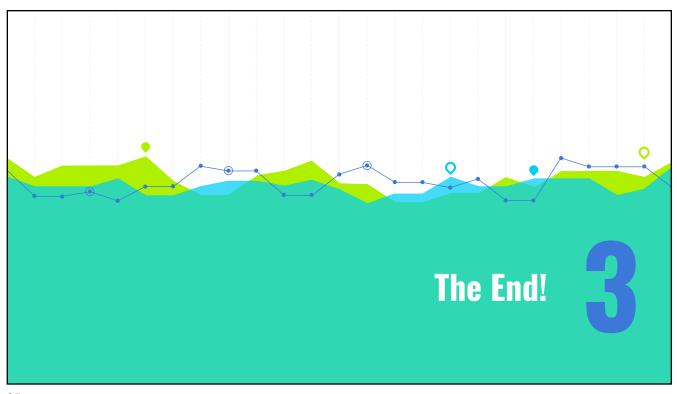
- Monte Carlo sampling as a method to calculate this
- Use Metropolis-Hastings Markov-Chain Monte Carlo Method
- Adaptive MCMC

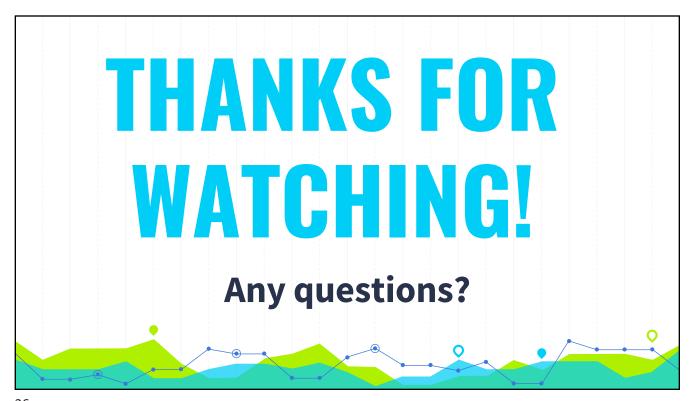












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