

when started

move robot pen down

set robot pen to color red

set Distance to 1000

drive forward for Distance mm ▶

turn right for 120 degrees ▶

drive forward for $\text{Distance} \times 2$ mm ▶

turn right for 150 degrees ▶

drive forward for $\text{Distance} \times 1.73$ mm ▶

stop driving

stop project