view_frames Result Recorded at time: 1639616445.808 world Broadcaster: /map_link_broadcaster Average rate: 10000.000 Hz Most recent transform: 0.000 (1639616445.808 sec old) Buffer length: 0.000 sec map Broadcaster: /odom_link_broadcaster Average rate: 10000.000 Hz Most recent transform: 0.000 (1639616445.808 sec old) Buffer length: 0.000 sec odom Broadcaster: /base_link_broadcaster Average rate: 10000.000 Hz Most recent transform: 0.000 (1639616445.808 sec old) Buffer length: 0.000 sec base_link Broadcaster: /front_cam_broadcaster Broadcaster: /gps_broadcaster Broadcaster: /imu_broadcaster Broadcaster: /arm_base_broadcaster Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1639616445.808 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec gps_link front_cam_link imu_link px100/base_link Broadcaster: /px100/robot_state_publisher Average rate: 31.559 Hz Most recent transform: 1639616445.786 (0.022 sec old) Buffer length: 4.880 sec px100/shoulder_link Broadcaster: /px100/robot_state_publisher Average rate: 31.559 Hz Most recent transform: 1639616445.786 (0.022 sec old) Buffer length: 4.880 sec px100/upper_arm_link Broadcaster: /px100/robot_state_publisher Average rate: 31.559 Hz Most recent transform: 1639616445.786 (0.022 sec old) Buffer length: 4.880 sec px100/forearm_link Broadcaster: /px100/robot_state_publisher Average rate: 31.559 Hz Most recent transform: 1639616445.786 (0.022 sec old) Buffer length: 4.880 sec px100/gripper_link Broadcaster: /px100/robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1639616445.808 sec old) Buffer length: 0.000 sec px100/ee_arm_link Broadcaster: /px100/robot_state_publisher Broadcaster: /px100/robot_state_publisher Average rate: 31.559 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1639616445.808 sec old) Most recent transform: 1639616445.786 (0.022 sec old) Buffer length: 0.000 sec Buffer length: 4.880 sec px100/gripper_prop_link px100/gripper_bar_link Broadcaster: /px100/robot_state_publisher Broadcaster: /arm_cam_broadcaster Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1639616445.808 sec old) Most recent transform: 0.000 (1639616445.808 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec px100/fingers_link arm_cam_link Broadcaster: /px100/robot_state_publisher Broadcaster: /px100/robot_state_publisher Broadcaster: /px100/robot_state_publisher Average rate: 10000.000 Hz Average rate: 31.559 Hz Average rate: 31.559 Hz Most recent transform: 0.000 (1639616445.808 sec old) Most recent transform: 1639616445.786 (0.022 sec old) Most recent transform: 1639616445.786 (0.022 sec old) Buffer length: 4.880 sec Buffer length: 0.000 sec Buffer length: 4.880 sec px100/ee_gripper_link px100/left_finger_link px100/right_finger_link