view_frames Result Recorded at time: 1638906020.482 world Broadcaster: /px100/robot_state_publisher Broadcaster: /map_link_broadcaster Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1638906020.482 sec old) Most recent transform: 0.000 (1638906020.482 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec px100/base_link map Broadcaster: /px100/robot_state_publisher Broadcaster: /odom_link_broadcaster Average rate: 10000.000 Hz Average rate: 31.458 Hz Most recent transform: 1638906020.450 (0.031 sec old) Most recent transform: 0.000 (1638906020.482 sec old) Buffer length: 0.000 sec Buffer length: 4.864 sec px100/shoulder_link odom Broadcaster: /px100/robot_state_publisher Broadcaster: /base_link_broadcaster Average rate: 31.458 Hz Average rate: 10000.000 Hz Most recent transform: 1638906020.450 (0.031 sec old) Most recent transform: 0.000 (1638906020.482 sec old) Buffer length: 0.000 sec Buffer length: 4.864 sec base_link px100/upper_arm_link Broadcaster: /px100/robot_state_publisher Broadcaster: /imu_broadcaster Broadcaster: /front_cam_broadcaster Average rate: 31.458 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 1638906020.450 (0.031 sec old) Most recent transform: 0.000 (1638906020.482 sec old) Most recent transform: 0.000 (1638906020.482 sec old) Buffer length: 0.000 sec Buffer length: 4.864 sec Buffer length: 0.000 sec imu_link front_cam_link Broadcaster: /px100/robot_state_publisher Average rate: 31.458 Hz Most recent transform: 1638906020.450 (0.031 sec old) Buffer length: 4.864 sec Broadcaster: /px100/robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1638906020.482 sec old) Buffer length: 0.000 sec px100/ee_arm_link Broadcaster: /px100/robot_state_publisher Broadcaster: /px100/robot_state_publisher Average rate: 10000.000 Hz Average rate: 31.458 Hz Most recent transform: 0.000 (1638906020.482 sec old) Most recent transform: 1638906020.450 (0.031 sec old) Buffer length: 0.000 sec Buffer length: 4.864 sec px100/gripper_prop_link Broadcaster: /arm_cam_broadcaster Average rate: 10000.000 Hz Most recent transform: 0.000 (1638906020.482 sec old) Buffer length: 0.000 sec Broadcaster: /px100/robot_state_publisher Average rate: 31.458 Hz Most recent transform: 1638906020.450 (0.031 sec old) Buffer length: 4.864 sec px100/right_finger_link

px100/forearm_link

px100/gripper_link

arm_cam_link

px100/gripper_bar_link

Broadcaster: /px100/robot_state_publisher

Average rate: 10000.000 Hz

Most recent transform: 0.000 (1638906020.482 sec old)

Buffer length: 0.000 sec

Broadcaster: /px100/robot_state_publisher

Average rate: 31.458 Hz

Buffer length: 4.864 sec

px100/fingers_link

Most recent transform: 0.000 (1638906020.482 sec old) Most recent transform: 1638906020.450 (0.031 sec old)

px100/left_finger_link

Broadcaster: /px100/robot_state_publisher

Average rate: 10000.000 Hz

Buffer length: 0.000 sec

px100/ee_gripper_link

Broadcaster: /gps_broadcaster

Average rate: 10000.000 Hz

Most recent transform: 0.000 (1638906020.482 sec old)

Buffer length: 0.000 sec

gps_link