

# MAGNETIC FIELD

## Motion of charge particle in a magnetic field

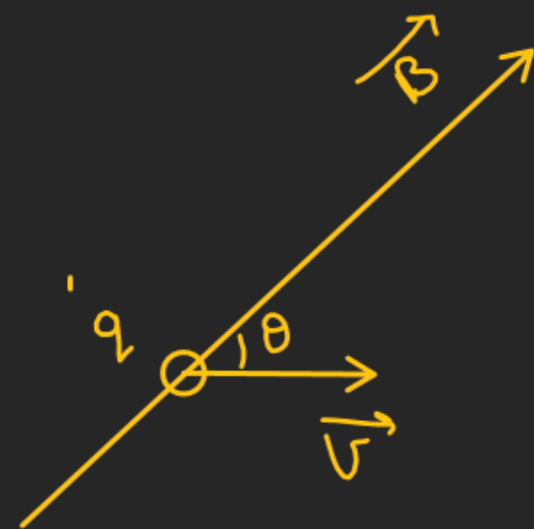
(\*) Force acting on a Charge particle place in a uniform Magnetic field :-

$$\vec{F} = q (\vec{v} \times \vec{B}) \quad **$$

$$|\vec{F}| = [q v B \sin \theta]$$

$\theta = \text{Angle b/w } (\vec{B} \text{ \& } \vec{v})$

Direction of  $\vec{F}$  :- Always perpendicular to the plane containing both  $\vec{v}$  &  $\vec{B}$ .



Note

For  $e^-$

$$\vec{F} = -q (\vec{v} \times \vec{B})$$

Direction of Magnetic force is opposite w.r.t +ve Charge direction

Magnetic field

↳ Influence of a moving Charge.

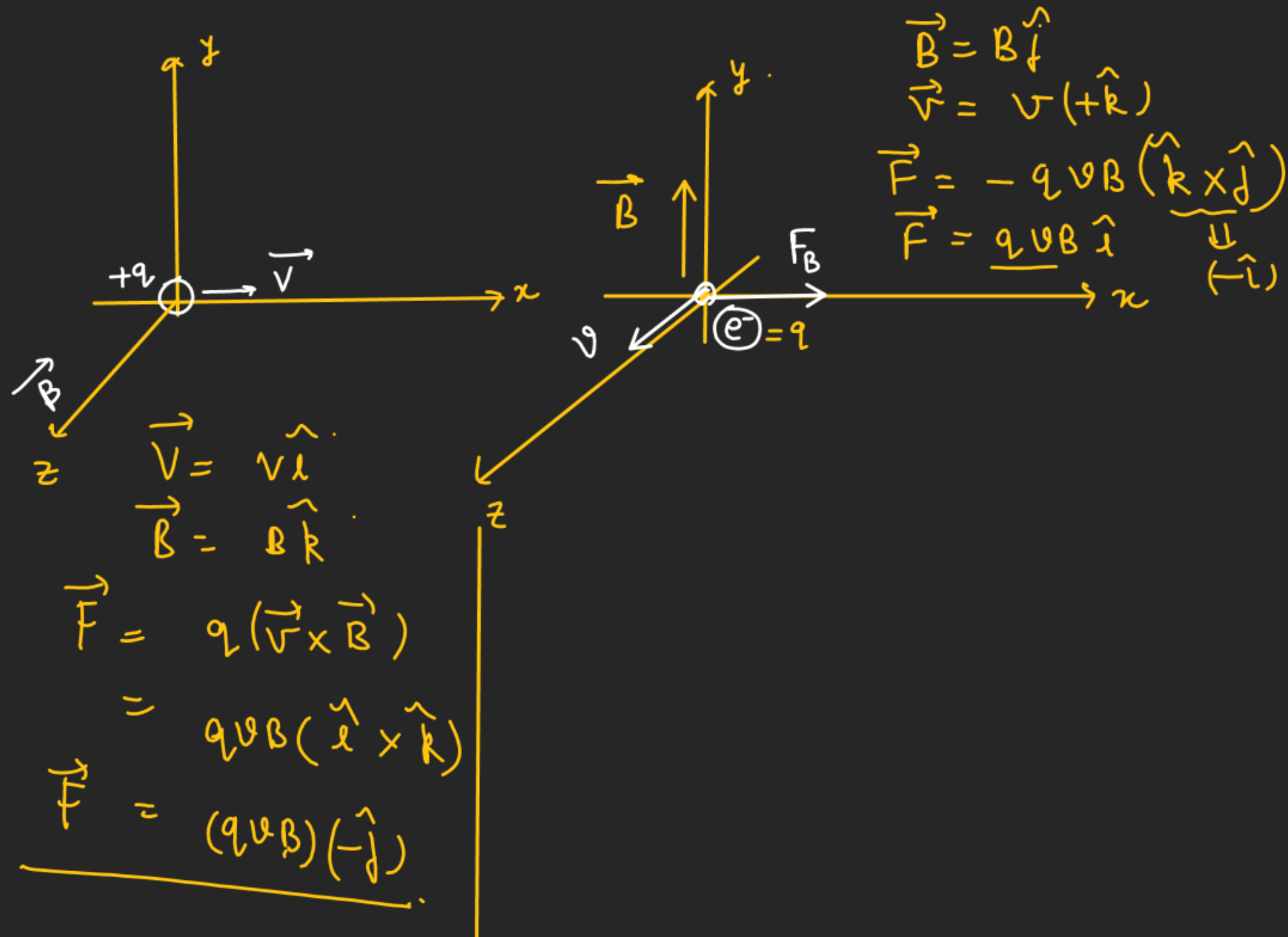
$(+q) \rightarrow v = c$  
 $\left\{ \begin{array}{l} \text{Electric field} \\ \text{Magnetic field} \end{array} \right.$

$(+q) \rightarrow a = c$  
 $\left\{ \begin{array}{l} \text{Electric field} \\ \text{Magnetic field} \\ \text{Electromagnetic Radiation} \end{array} \right.$

-  $\rightarrow$  Constant

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## Cross product

$$\vec{A} \times \vec{B} = [AB \sin \theta] \hat{n}$$

$\theta \rightarrow$  Angle b/w  $\vec{A}$  &  $\vec{B}$

$$|\vec{A} \times \vec{B}| = \underbrace{AB \sin \theta}_{\text{Magnitude of } (\vec{A} \times \vec{B})}$$

$\hat{n} =$  Unit Vector  $\perp$  to the plane containing both  $\vec{A}$  &  $\vec{B}$ .

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Ex:-  $\vec{F} = 2\hat{i} + 3\hat{j} + 4\hat{k}$

$$\vec{v} = -\hat{i} + \hat{j} + \hat{k}$$

$\vec{F}$  is acting on a charge particle having magnitude 2C in a uniform magnetic field. Find  $|\vec{B}| = ?$

Sol<sup>n</sup>  $\Rightarrow$  Let,  $\vec{B} = B_x\hat{i} + B_y\hat{j} + B_z\hat{k}$

$$\vec{F} = q(\vec{v} \times \vec{B})$$

$$2\hat{i} + 3\hat{j} + 4\hat{k} = \vec{F} = 2(B_z - B_y)\hat{i} + 2(B_z + B_x)\hat{j} - 2(B_y + B_x)\hat{k}$$

$$2(B_z - B_y) = 2 \Rightarrow B_z - B_y = 1 \quad \text{--- (1)}$$

$$2(B_z + B_x) = 3 \Rightarrow B_z + B_x = \frac{3}{2} \quad \text{--- (2)}$$

$$\vec{v} \times \vec{B} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ -1 & 1 & 1 \\ B_x & B_y & B_z \end{vmatrix}$$

$$\vec{v} \times \vec{B} = \hat{i}(B_z - B_y) - \hat{j}(-B_z - B_x) + \hat{k}(-B_y - B_x)$$

$$-2(B_y + B_x) = 4$$

$$B_y + B_x = -2 \quad \text{--- (3)}$$

$$\begin{cases} B_x = \\ B_y = \\ B_z = \end{cases} \quad \checkmark$$

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### Magnetic force

⇒ It change the direction of Charge particle not the Speed of the Charge particle.  
as it always acts perpendicular to  $\vec{v}$  so it doesn't perform any work. So kinetic energy of charge particle remain same.

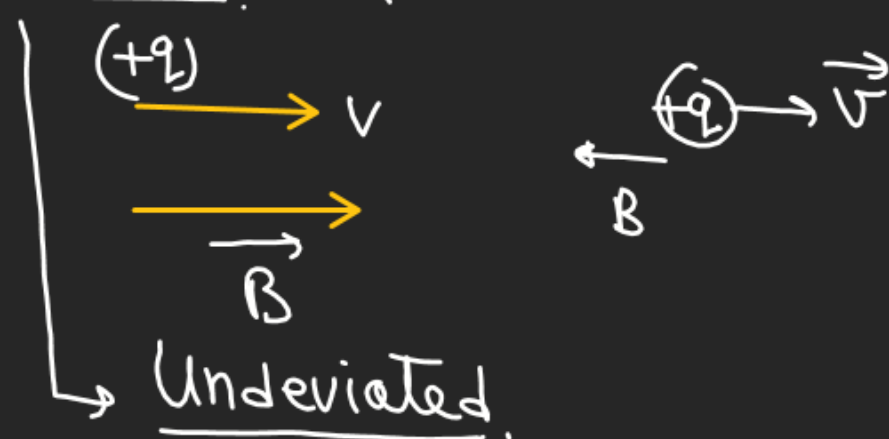
$$(F_B)_{\max} = ??$$

$$\vec{v} \perp \vec{B}$$

$$F_B = qvB \sin \theta$$

$$(F_B)_{\max} = qvB \quad \theta = 90^\circ$$

$$(F_B)_{\min} = 0 \text{ or } (\vec{v} \parallel \vec{B}), (\vec{v} \uparrow \downarrow \vec{B})$$





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## Motion of charge particle in a magnetic field

Case-1,  $[\vec{v} \perp \vec{B}]$

⇒ Locus is a Uniform Circular Motion.

⇒  $F_B$  acts as a Centripetal force.

$$F_B = \frac{mv^2}{R}$$

$$(\vec{v} \perp \vec{B})$$

$$\theta = 90^\circ$$

$$qvB = \frac{mv^2}{R} \Rightarrow$$

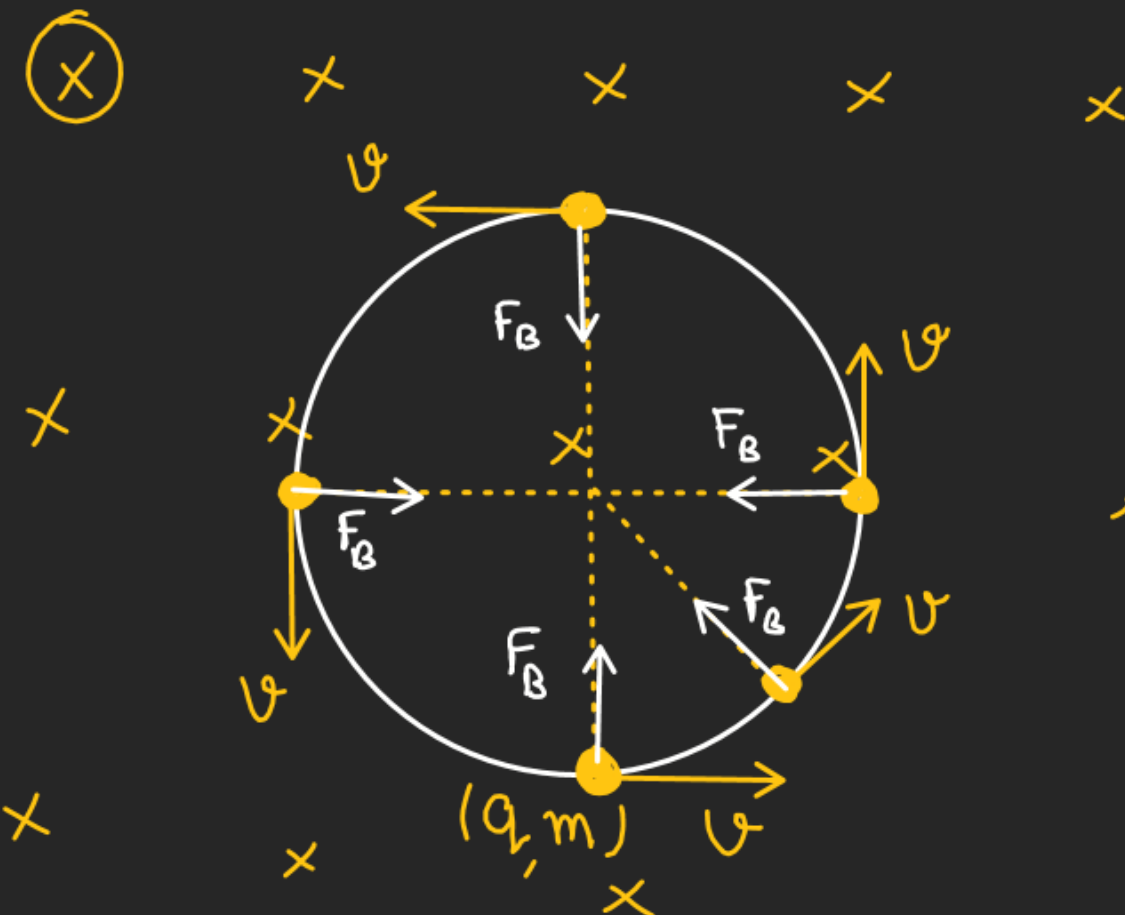
$$R = \frac{mv}{qB}$$

$$T = \frac{2\pi R}{v}$$

$$T = \frac{2\pi}{v} \times \frac{mv}{qB} \Rightarrow$$

$$T = \frac{2\pi m}{qB}$$

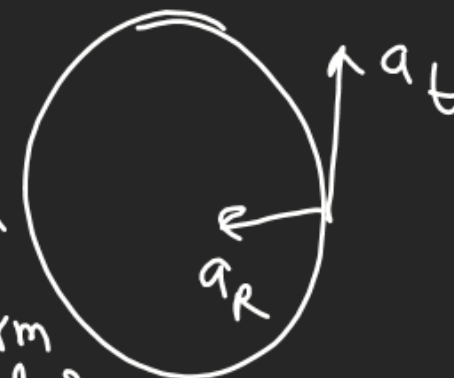
$B \Rightarrow$  Uniform.



$$a_t = \frac{d|v|}{dt}$$

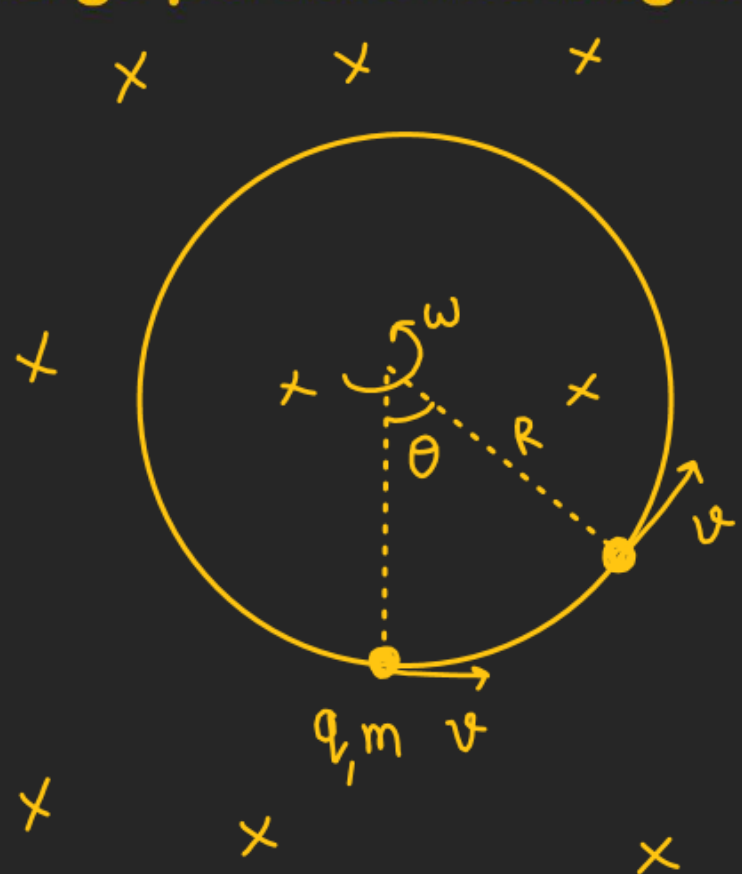
$$a_R = \frac{v^2}{R} = \omega^2 R$$

If  $a_t = 0$   
 $a_R = \frac{v^2}{R} \Rightarrow$  Uniform Circular Motion.



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$\otimes B$ .

$$v = R\omega$$

$$\omega = \left( \frac{v}{R} \right)$$

$$\omega = \frac{2\pi}{T} = 2\pi f$$

$$f = \frac{1}{T}$$

(frequency)

$$\omega = \frac{2\pi}{T} = \frac{2\pi}{\left( \frac{2\pi m}{qB} \right)}$$

↓

$$\omega = \frac{qB}{m}$$

$$\theta = \omega t$$

$$\theta = \frac{qB}{m} t$$

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## Motion of charge particle in a magnetic field

(\*) general velocity vector and position vector of the charged particle  
When  $\vec{v} \perp \vec{B}$ .

$$R = \left( \frac{mv}{qB} \right)$$

$$\theta = \omega t = \left( \frac{qB}{m} t \right)$$

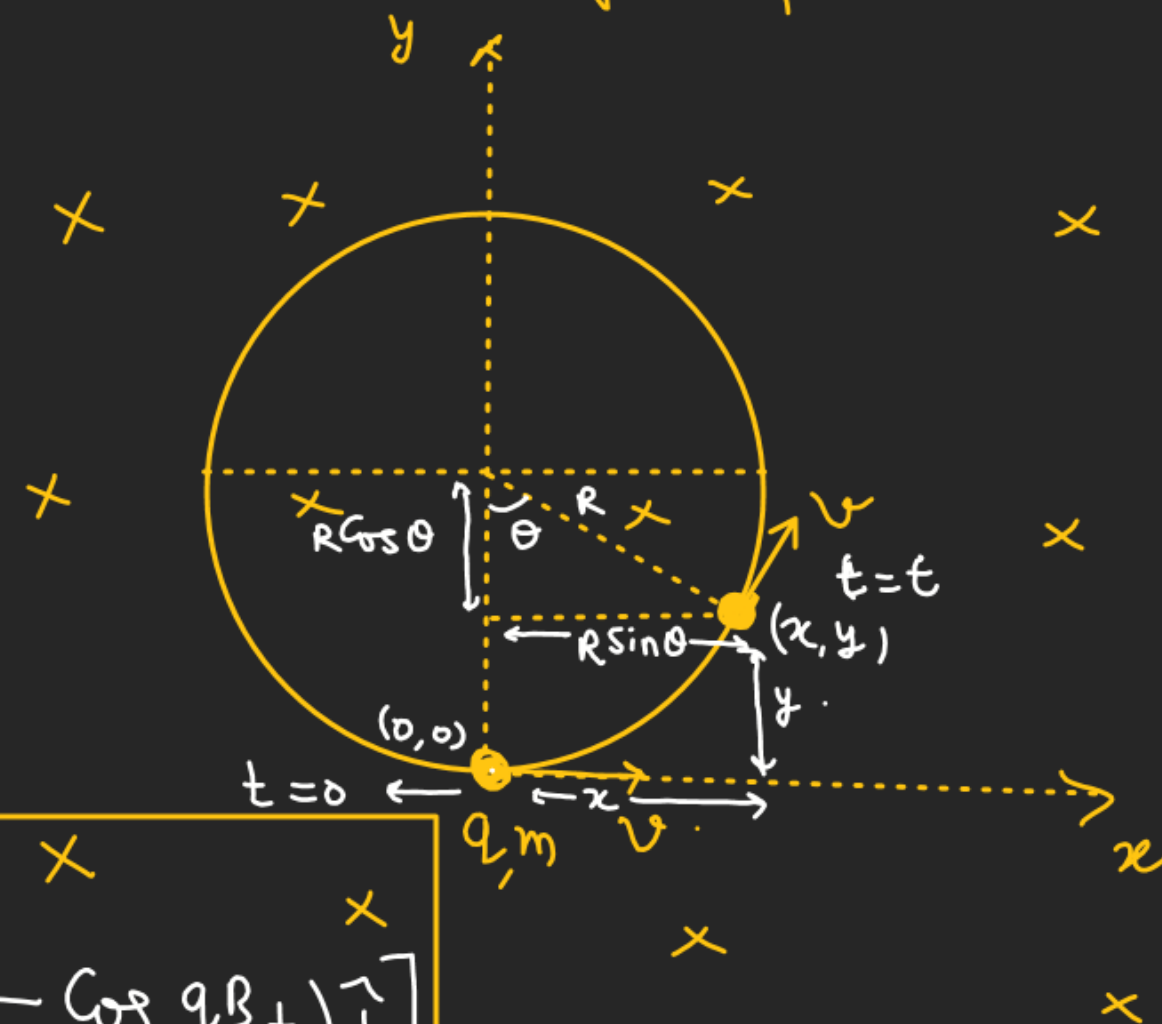
$$x = R \sin \theta$$

$$x = \frac{mv}{qB} \sin \omega t$$

$$x = \frac{mv}{qB} \sin \left( \frac{qB}{m} t \right)$$

$$Y = R(1 - \cos \theta) = \frac{mv}{qB} \left[ 1 - \cos \left( \frac{qB}{m} t \right) \right]$$

$$\vec{r} = x\hat{i} + Y\hat{j} = \frac{mv}{qB} \left[ \sin \left( \frac{qB}{m} t \right) \hat{i} + \left( 1 - \cos \frac{qB}{m} t \right) \hat{j} \right]$$



general velocity vector

$$\theta = \omega t$$

$$\theta = \frac{qB}{m} t$$

$$\vec{v} = v \cos \theta \hat{i} + v \sin \theta \hat{j}$$

$$\vec{v} = v \cos\left(\frac{qB}{m} t\right) \hat{i} + v \sin\left(\frac{qB}{m} t\right) \hat{j}$$

$$\vec{a} = \frac{d\vec{v}}{dt} = -v \sin\left(\frac{qB}{m} t\right) \left(\frac{qB}{m}\right) \hat{i} + v \cos\left(\frac{qB}{m} t\right) \left(\frac{qB}{m}\right) \hat{j}$$

$$\vec{a} = \left(v \times \frac{qB}{m}\right) \left[-\sin\left(\frac{qB}{m} t\right) \hat{i} + \cos\left(\frac{qB}{m} t\right) \hat{j}\right]$$

$\omega = \frac{v}{R}$

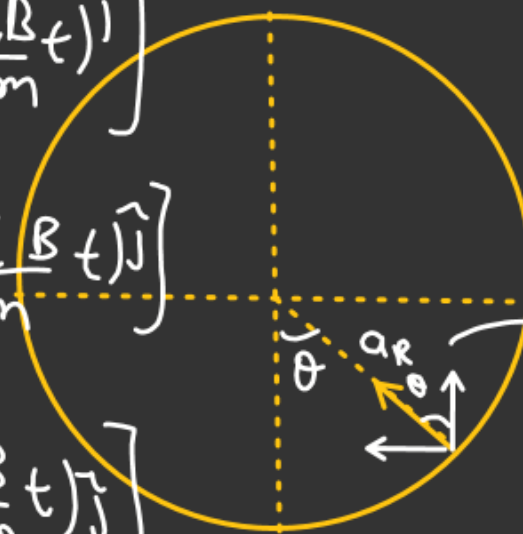
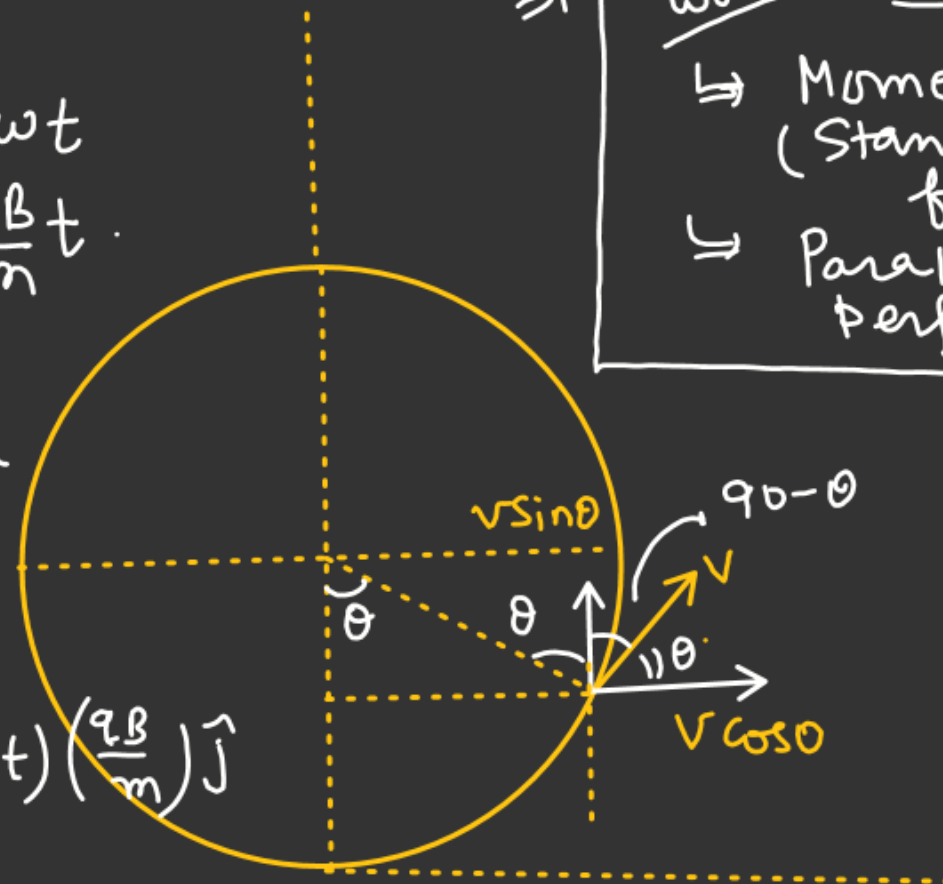
$$\vec{a} = v \times \frac{v}{R} \left[-\sin\left(\frac{qB}{m} t\right) \hat{i} + \cos\left(\frac{qB}{m} t\right) \hat{j}\right]$$

$$\vec{a} = \left(\frac{v^2}{R}\right) \left[-\sin\left(\frac{qB}{m} t\right) \hat{i} + \cos\left(\frac{qB}{m} t\right) \hat{j}\right]$$

→ Home work ⇨ Torque

⇨ Moment of Inertia (Standard body formula)

⇨ Parallel axis and perpendicular axis



$$a_R = a_{net} = \omega^2 R = \frac{v^2}{R}$$

$$a_R = -a_R \sin \theta \hat{i} + a_R \cos \theta \hat{j}$$

$$a_R = \frac{v^2}{R} \left[-\sin\left(\frac{qB}{m} t\right) \hat{i} + \cos\left(\frac{qB}{m} t\right) \hat{j}\right]$$