

S.H.MMotion.

Oscillatory:- [A Type of periodic motion in which particle have to & fro motion about a fixed point called (Mean position) Under the influence of restoring force]



S.H.M → [Restoring force is directly proportional to displacement of the particle from the mean position
 $[F_r \propto x] \Rightarrow \boxed{F_r = -kx}$]

S. H. M

$$F_r \propto x$$

$$F_r = -Kx$$

$$a = -\frac{K}{m}x$$

$$a = -\omega^2 x$$

$$\therefore \frac{d^2 x}{dt^2} = -\omega^2 x$$

$$\frac{d^2 x}{dt^2} + \omega^2 x = 0$$

(-) F_r always opposite to x

$x \rightarrow$ displacement from mean position

$$\omega^2 = \frac{K}{m} \quad \omega = \text{Angular frequency}$$

$$\omega = \sqrt{\frac{K}{m}}$$

$$\omega = 2\pi f = \frac{2\pi}{T}$$

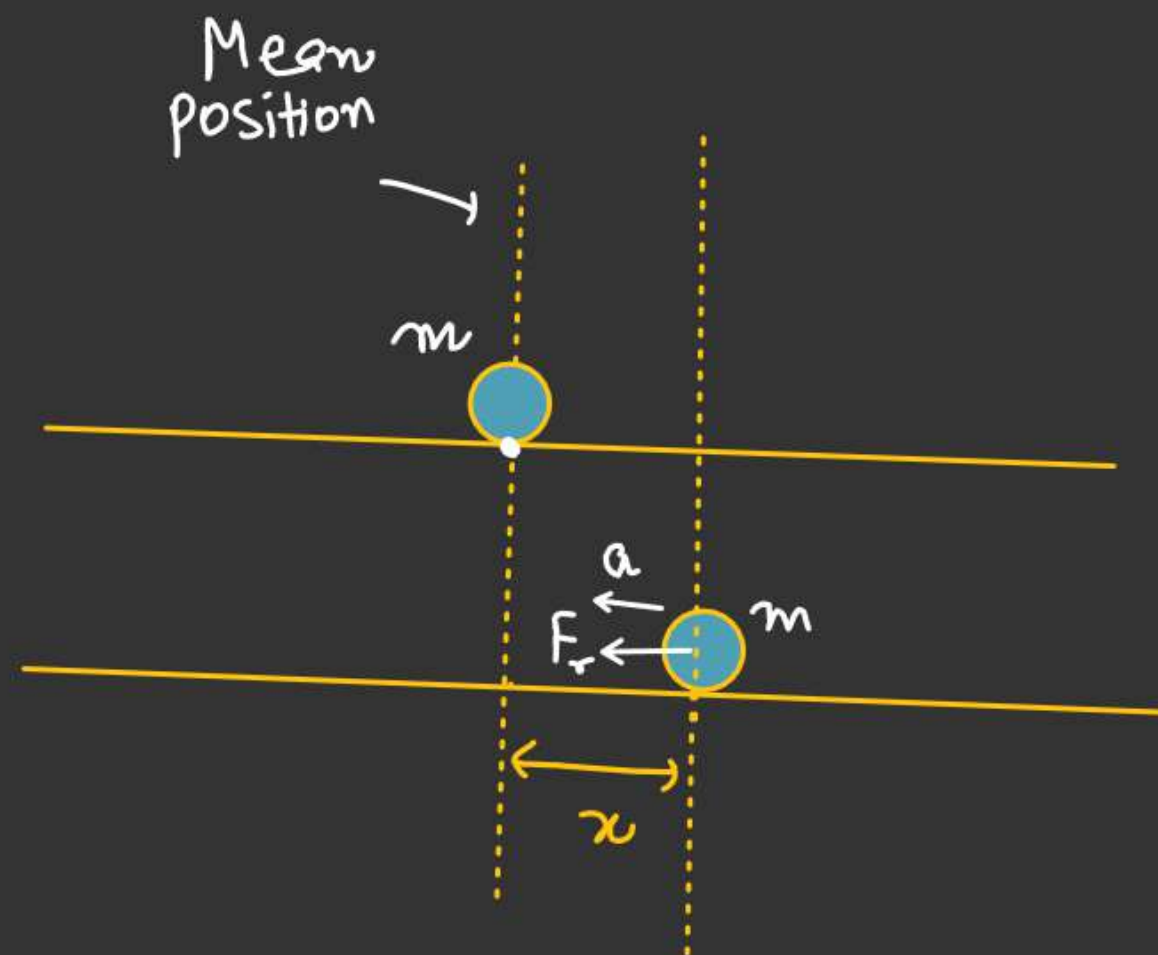
$$x = A \sin(\omega t + \phi)$$

Amplitude

Phase

Initial phase constant

(Maximum displacement of the particle from the mean position)



S.H.M

$$a = -\omega^2 x$$

↓

$$v \frac{dv}{dx} = -\omega^2 x$$

$$\int_{v_0}^v v dv = -\omega^2 \int_0^x x dx$$

$$\frac{v^2 - v_0^2}{2} = -\frac{\omega^2 x^2}{2}$$

$$v^2 = v_0^2 - \omega^2 x^2$$

$$v = \sqrt{v_0^2 - \omega^2 x^2}$$

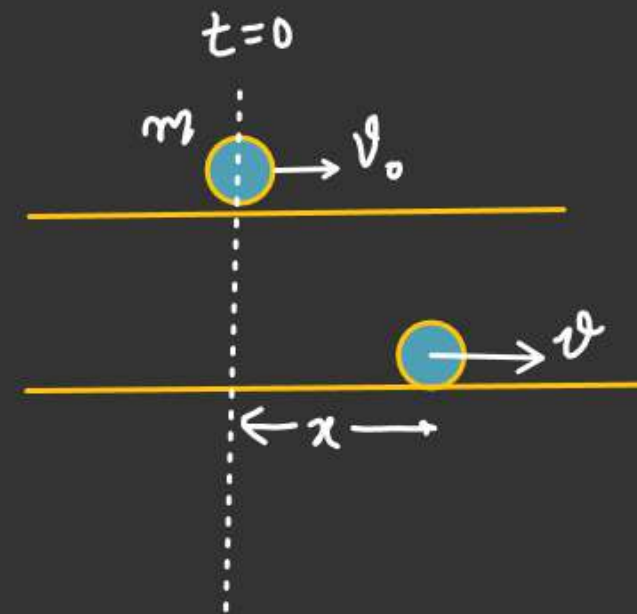
$$\frac{dx}{dt} = \sqrt{v_0^2 - \omega^2 x^2}$$

$$\int_0^x \frac{dx}{\sqrt{v_0^2 - \omega^2 x^2}} = \int_0^t dt$$

$$\int_0^x \frac{dx}{\omega \sqrt{\left(\frac{v_0}{\omega}\right)^2 - x^2}} = \int_0^t dt$$

$$\sin^{-1} \left[\frac{x}{\left(\frac{v_0}{\omega}\right)} \right]_0^x = \omega t$$

$$\frac{x}{\left(\frac{v_0}{\omega}\right)} = \sin \omega t$$



$$\frac{dx}{\sqrt{a^2 - x^2}} = \sin^{-1} \left(\frac{x}{a} \right)$$

$$x = \frac{v_0}{\omega} \sin \omega t$$

$$x = A \sin \omega t$$

$$\frac{v_0}{\omega} = A$$

$$v_0 = A\omega$$

$$v_{\max} = A\omega$$

$$x = A \sin(\omega t + \phi)$$

S.H.M

$$x = A \sin(\omega t + \phi)$$

$\phi \rightarrow$ Initial phase constant.

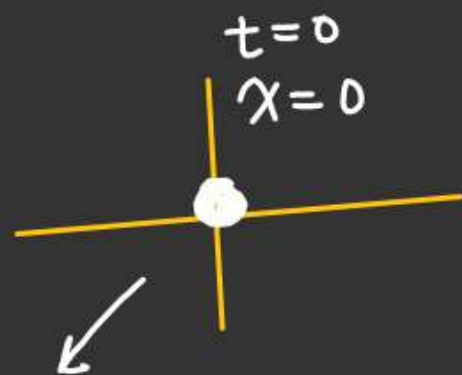
At $t = 0, x = 0$

$$x = A \sin \phi$$

$$0 = A \sin \phi$$

$$\phi = 0$$

$$x = A \sin \omega t$$



$$x = A \sin(\omega t + \phi)$$

At $t = 0, x = +A$

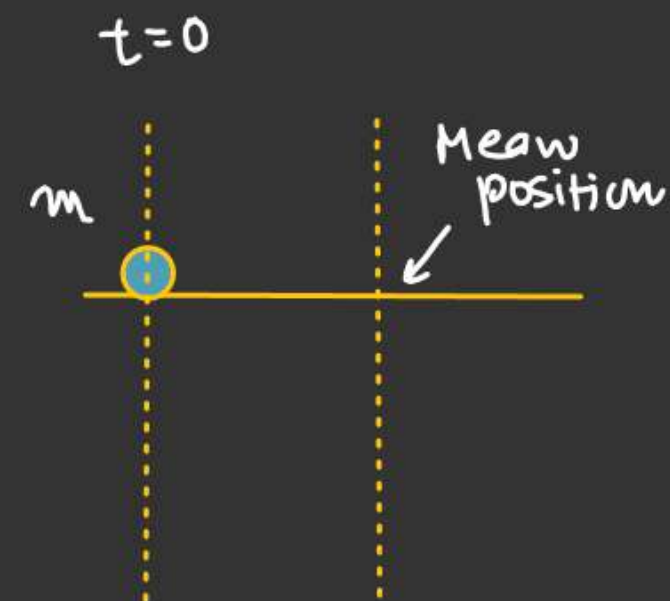
$$+A = A \sin \phi$$

$$\sin \phi = +1$$

$$\phi = \frac{\pi}{2}$$

$$x = A \sin\left(\omega t + \frac{\pi}{2}\right)$$

$$x = A \cos \omega t$$



$$x = -A$$

$$x = A \sin(\omega t + \phi)$$

At $t = 0, x = -A$

$$-A = A \sin \phi$$

$$\sin \phi = -1$$

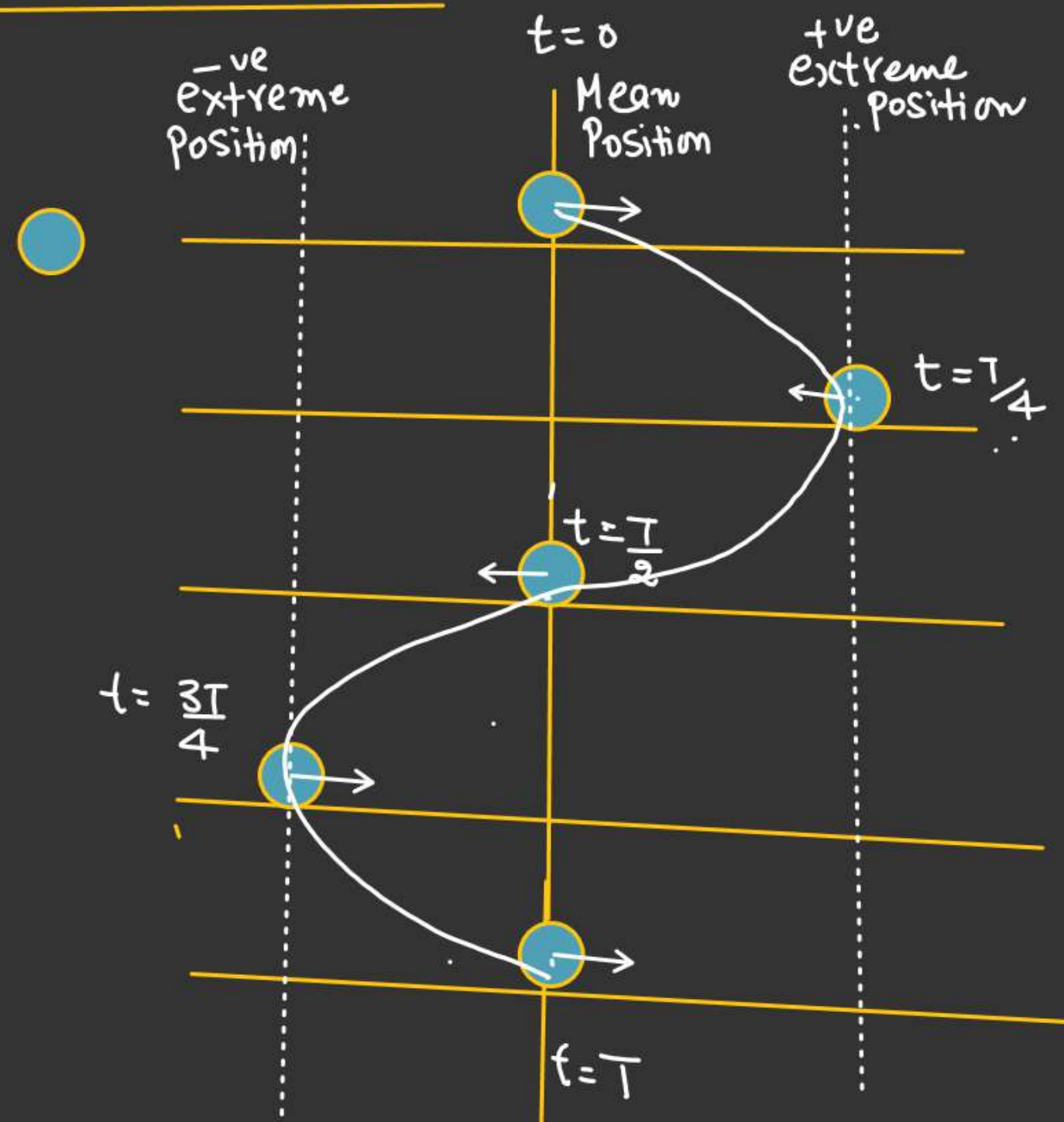
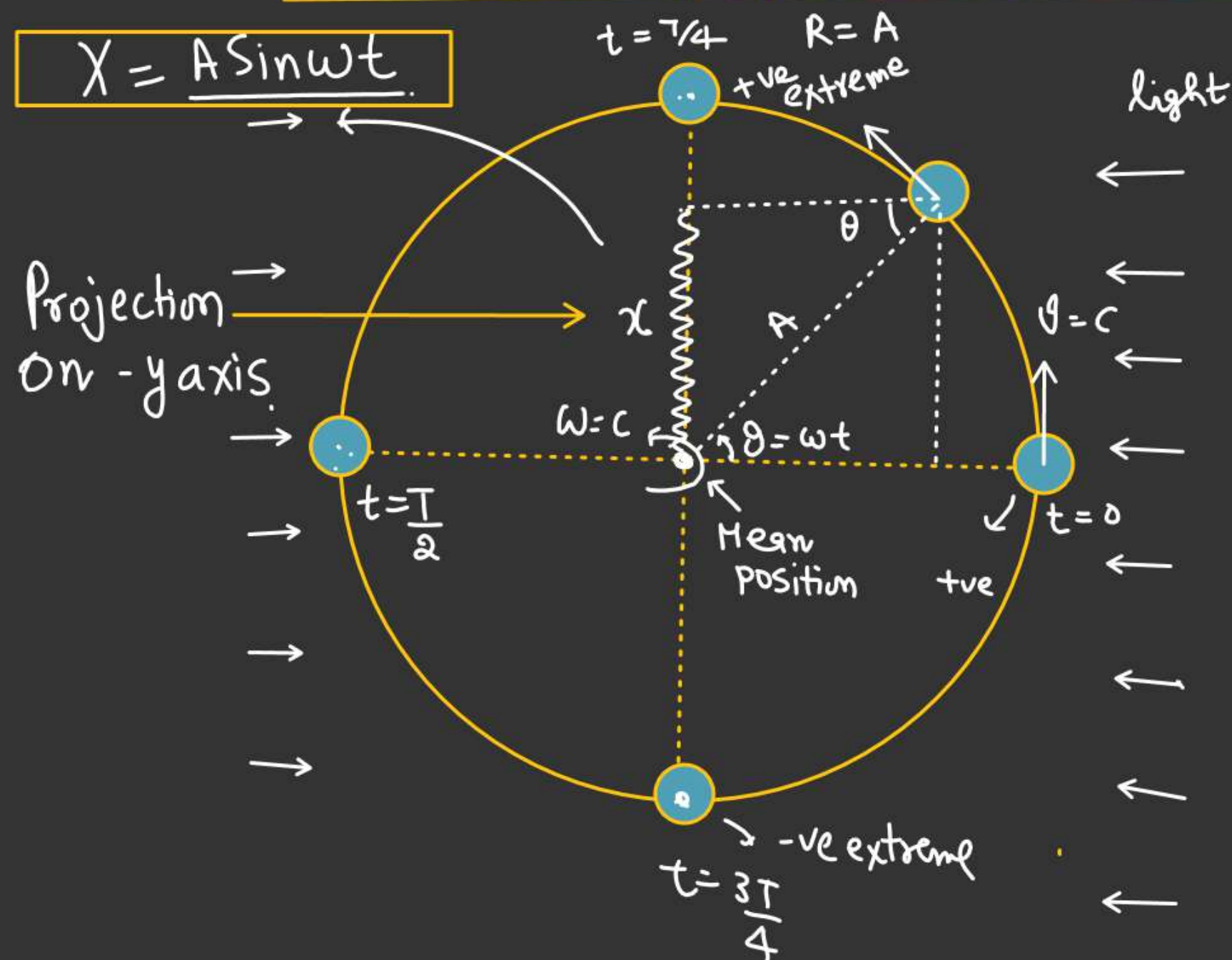
$$\phi = \frac{3\pi}{2}$$

$$x = A \sin\left(\omega t + \frac{3\pi}{2}\right)$$

S.H.M

S.H.M as a projection of uniform Circular Motion

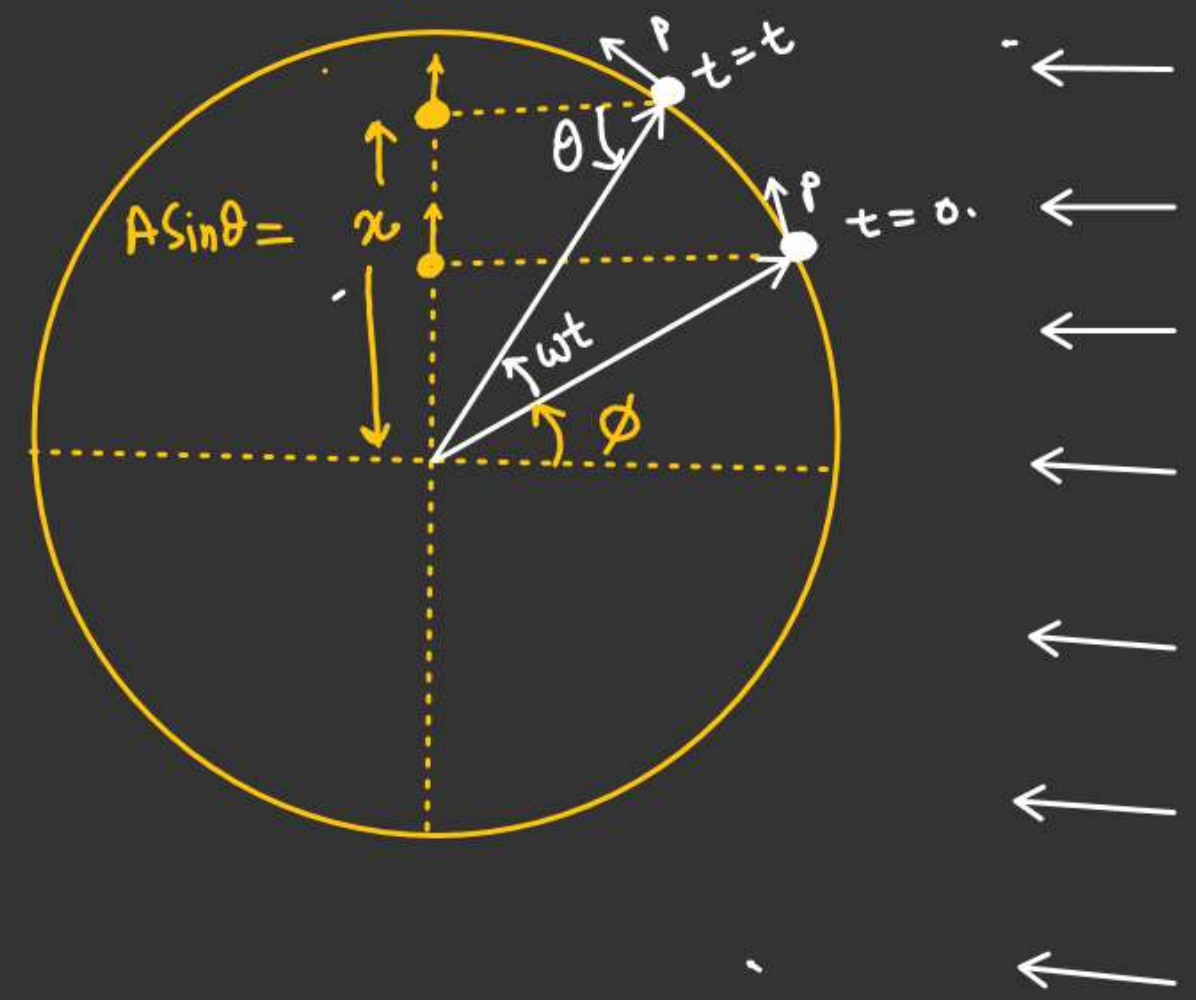
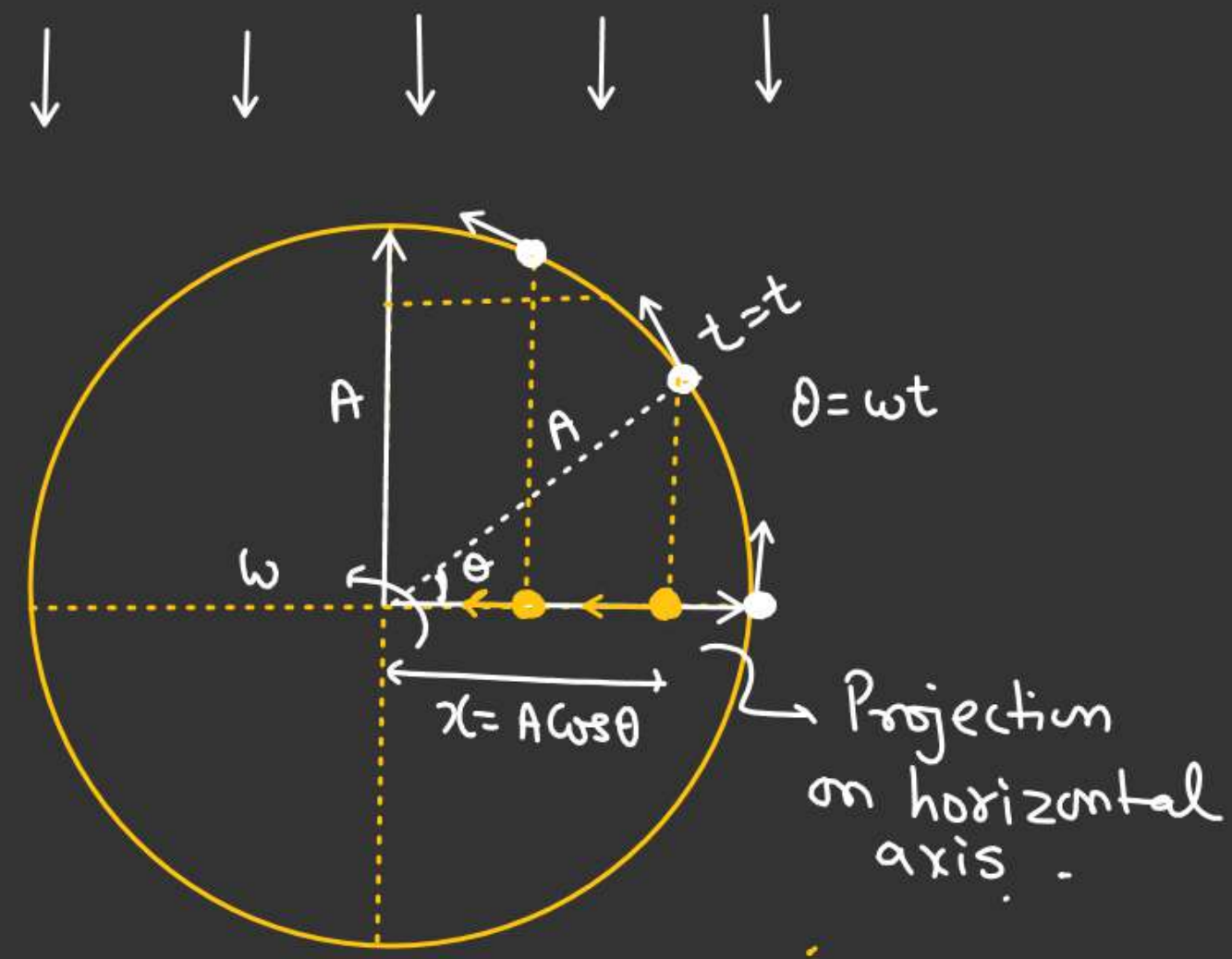
$$X = A \sin \omega t$$



$$x = A \cos \omega t =$$

S.H.M

$$x = A \sin(\omega t + \phi) \quad \theta = (\omega t + \phi)$$

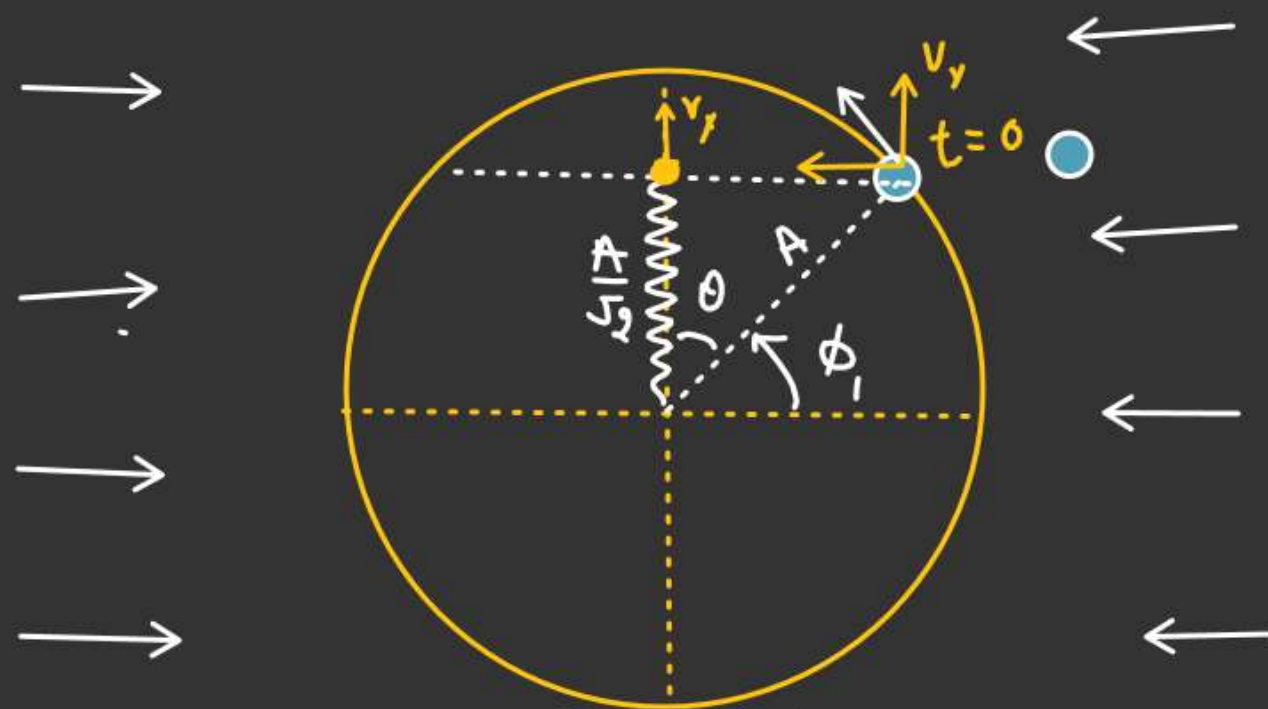


At $t=0$ S.H.M

At $t=0$ position of P_1 and P_2 as shown in fig. Both have same amplitude and same angular frequency.
Find the phase difference b/w P_1 and P_2

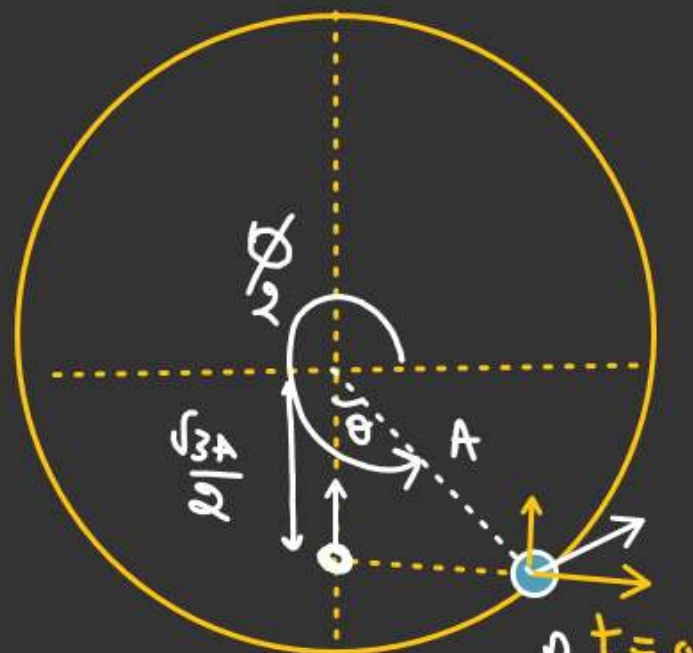
$$X_{P_1} = A \sin(\omega t + \frac{\pi}{4})$$

$$X_{P_2} = A \sin(\omega t + \frac{5\pi}{3})$$



$$\cos \theta = \frac{A/\sqrt{2}}{A} = \frac{1}{\sqrt{2}}$$

$$\theta = \frac{\pi}{4} \Rightarrow \phi_1 = \frac{\pi}{4}$$

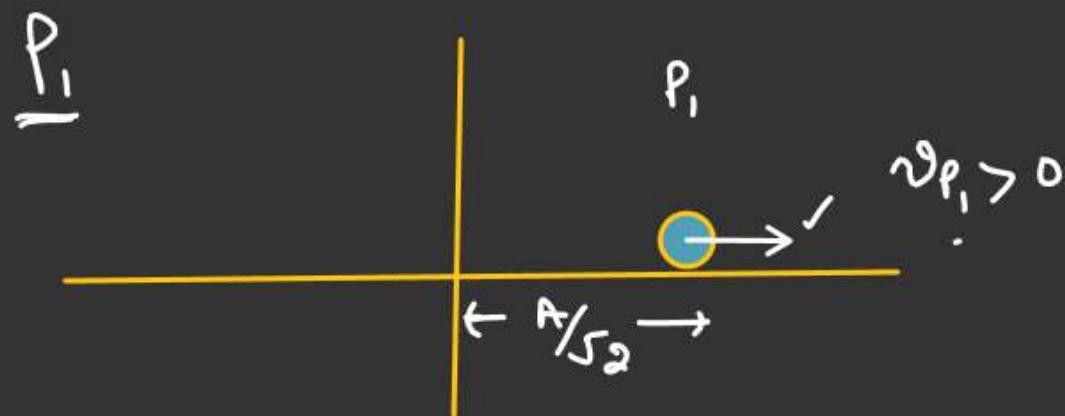


$$\cos \theta = \frac{\sqrt{3}A/2}{A} = \frac{\sqrt{3}}{2}$$

$$\theta = \frac{\pi}{6}$$

$$\begin{aligned} \phi_2 &= \frac{3\pi}{2} + \theta \\ &= \frac{3\pi}{2} + \frac{\pi}{6} \\ &= \frac{9\pi + \pi}{6} \\ &= \frac{10\pi}{6} \\ &= \frac{5\pi}{3} \checkmark \end{aligned}$$

$$\begin{aligned} \Delta \phi &= \phi_2 - \phi_1 \\ &= \frac{5\pi}{3} - \frac{\pi}{4} \\ &= \frac{20\pi - 3\pi}{12} \\ &= \left(\frac{17\pi}{12} \right) \checkmark \end{aligned}$$

S.H.M

$$x = A \sin(\omega t + \phi_1)$$

$$At t=0, x = +\frac{A}{\sqrt{2}}$$

$$\frac{+A}{\sqrt{2}} = A \sin \phi_1$$

$$\sin \phi_1 = \frac{1}{\sqrt{2}} \quad \phi_1 = \left(\frac{\pi}{4}, \frac{3\pi}{4} \right)$$

$$y_1 = \sin \phi$$

$$y_2 = \frac{1}{\sqrt{2}}$$

$$\left(\phi_1 = \frac{\pi}{4} \text{ ans } \begin{cases} v_{P_1} \text{ +ve at } \frac{\pi}{4} \\ v_{P_1} \text{ -ve at } \frac{3\pi}{4} \end{cases} \right)$$

$$v_{P_1} = A\omega \cos(\omega t + \phi_1)$$

$$At t=0$$

$$v_{P_1} = (A\omega \cos \phi_1)$$

$$\begin{cases} (v_{P_1}) \text{ at } \frac{\pi}{4} \text{ is +ve} \\ (v_{P_1}) \text{ at } \frac{3\pi}{4} \text{ is -ve} \end{cases}$$

