

* Chain starts slipping when its overhanging part is $\frac{l}{3}$.

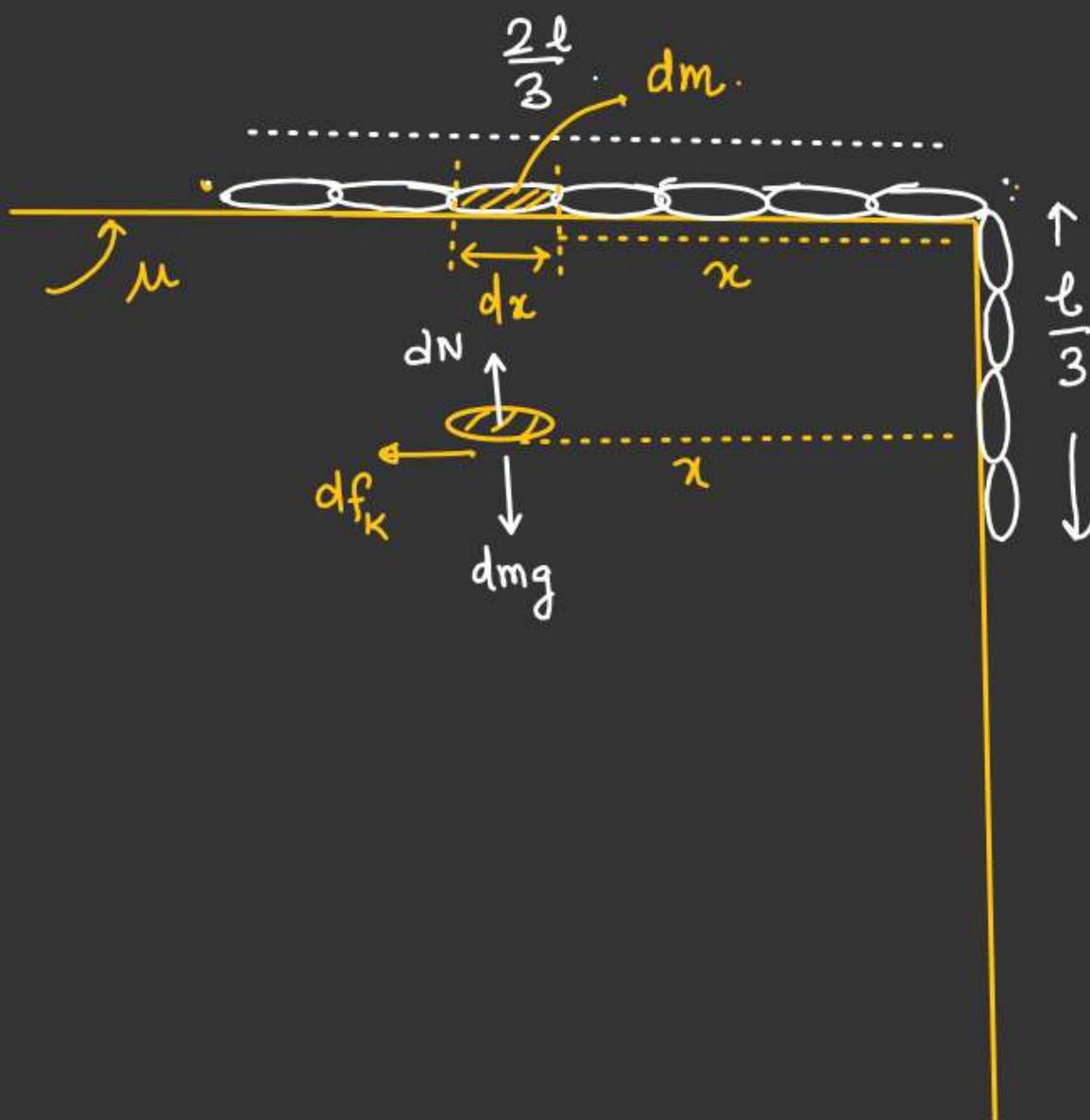
Find the kinetic energy of the chain when it just leaves the table.

Solⁿ: friction force is changing due to change in normal reaction as mass of the chain on the table is decreasing

$$W_{f_k} \frac{df_k}{dx} = \mu dN = \mu dm g = g \mu \left(\frac{M}{L} dx \right)$$

$$\int_0^{2l/3} dW_{f_k} = - \frac{\mu M g}{L} \int_0^{2l/3} x dx$$

$$W_{f_k} = - \frac{\mu M g}{L} \left(\frac{4l^2}{18} \right) = \left(- \frac{2 \mu m g l}{9} \right) J$$



$$W_{\text{gravity}} = \frac{mg l}{18}$$

By work-energy theorem

$$W_{\text{gravity}} + W_{f_K} = (\Delta K.E.)$$

$$\left(\frac{4mgl}{9} - \frac{2\mu mgl}{9} \right) = K.E_f - K.E_i$$

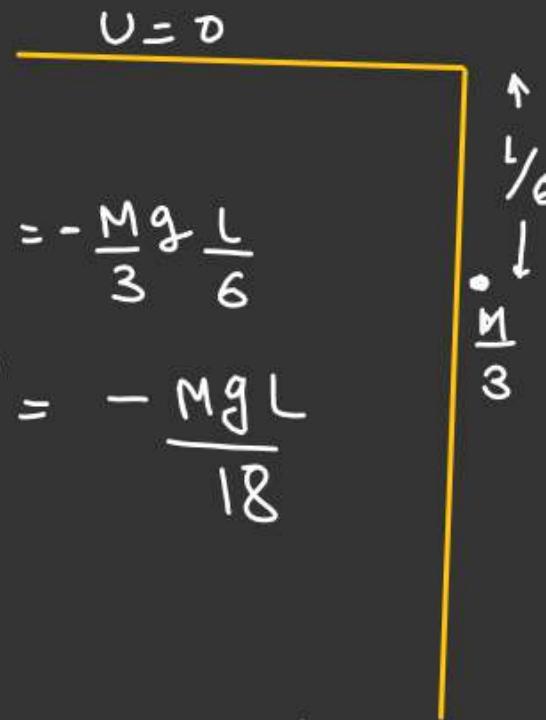
$$K.E_f = \frac{2mgl}{9}(2-\mu)$$

$$\begin{aligned} W_{\text{gravity}} &= -\Delta U \\ &= (U_i - U_f) \end{aligned}$$

$$\begin{aligned} U_i &= -\frac{Mg}{3} \frac{L}{6} \\ U_i &= -\frac{MgL}{18} \end{aligned}$$

$$U_f = -\frac{MgL}{2}$$

$$\begin{aligned} \Delta U &= (U_f - U_i) \\ &= -\frac{MgL}{2} + \frac{MgL}{18} \\ &= -\frac{8MgL}{18} = \left(-\frac{4mgl}{9} \right) \\ -\Delta U &= \left(\frac{4mgl}{9} \right) \end{aligned}$$

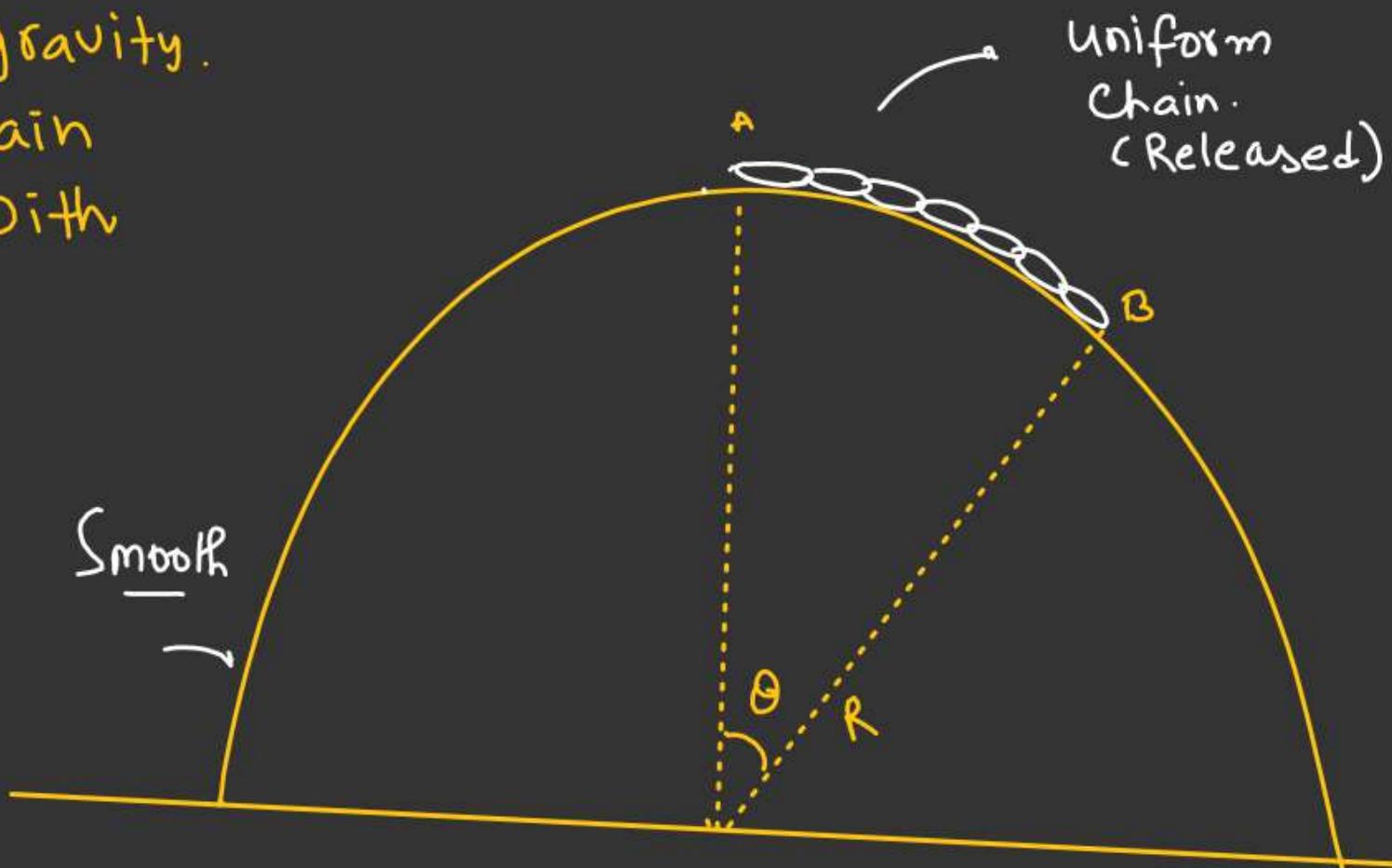


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Find the work done by gravity.

When upper end of the chain makes an angle α with vertical.

M = Total mass of the Chain.



$$\lambda = \left(\frac{M}{R\theta} \right)$$

$$l_{AB} = (R\theta) \quad \text{if } l_{AB} = L \\ L = R\theta.$$

$$dl = (R d\phi)$$

$$dm = \lambda dl$$

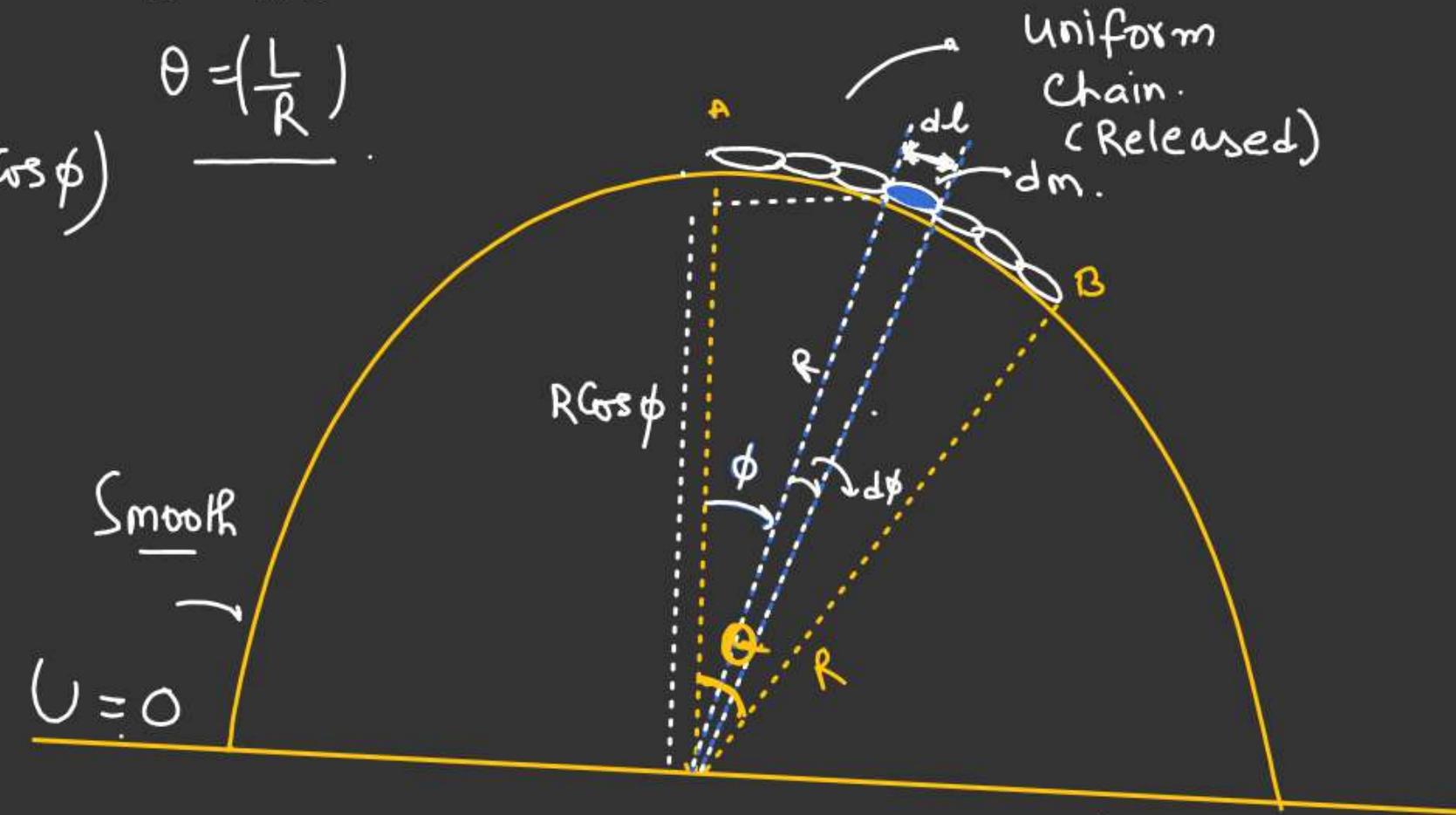
$$dm = \frac{M}{R\theta} \times R d\phi = \left(\frac{M}{\theta} d\phi \right)$$

$$dU = dmgh$$

$$dU = \left(\frac{M}{\theta} d\phi \right) g (R \cos \phi) \checkmark$$

$$\int_0^{\theta} dU = \frac{MgR}{\theta} \int_0^{\theta} \cos \phi \cdot d\phi \Rightarrow U_i = \frac{MgR}{\theta} (\sin \theta)$$

$$U_i = \frac{MgR}{\theta} \sin \left(\frac{L}{R} \right) v = \frac{MgR^2}{L} \sin \left(\frac{L}{R} \right)$$



$$\int_0^{\phi} dU_f = \frac{MgR}{\theta} \int_{\alpha}^{(\alpha+\theta)} \cos \phi \cdot d\phi$$

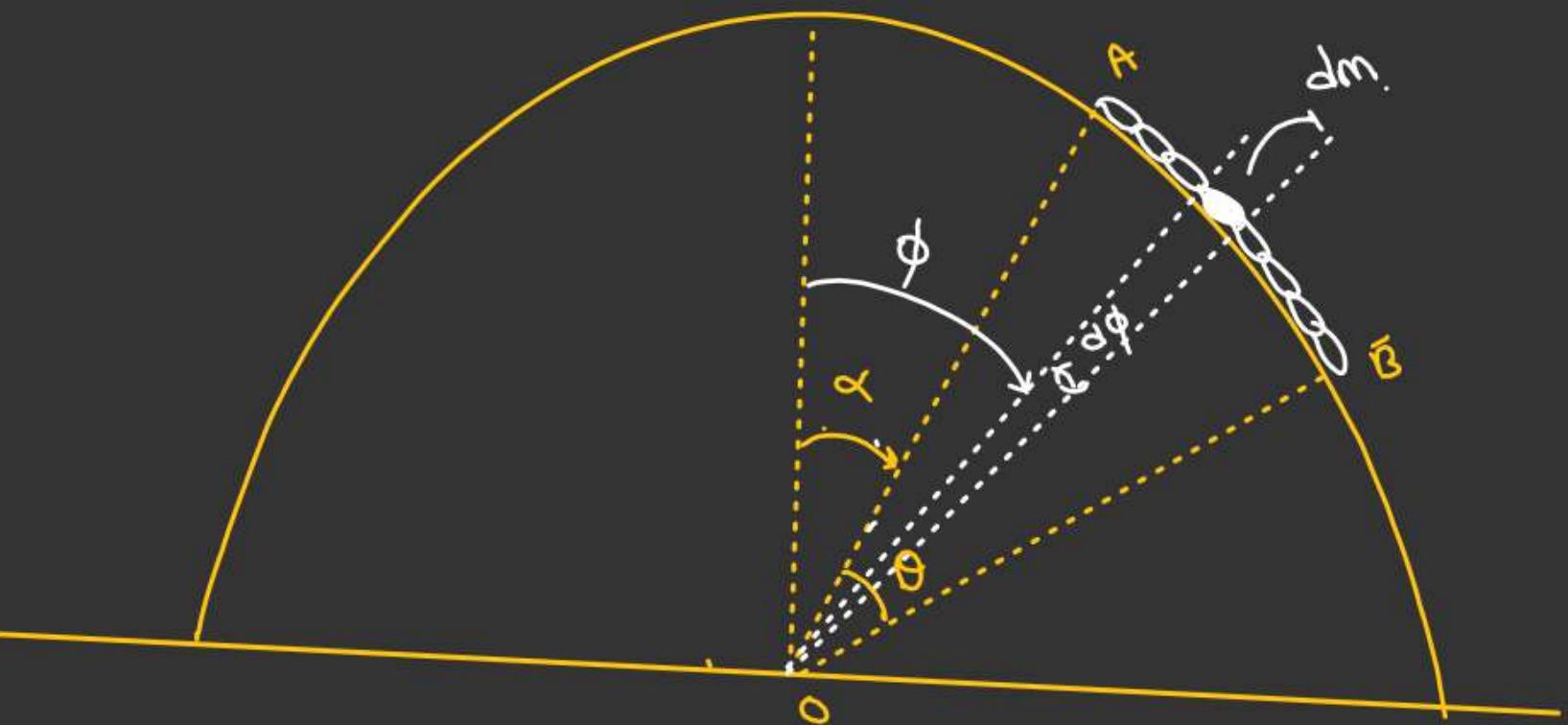
$$\theta = \left(\frac{L}{R} \right)$$

$$U_f = \frac{MgR}{\theta} \left[\sin \phi \right]_{\alpha}^{(\alpha+\theta)}$$

$$U_f = \frac{MgR}{\theta} \left[\sin(\alpha + \theta) - \sin(\alpha) \right]$$

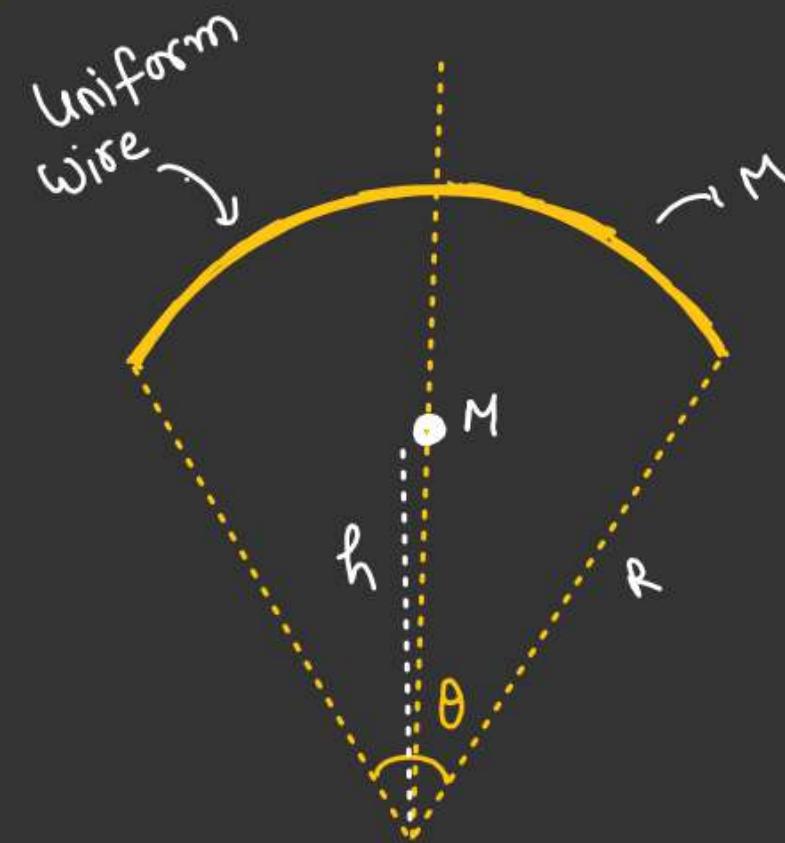
$$U_f = \frac{MgR^2}{L} \left[\sin \left(\alpha + \frac{L}{R} \right) - \sin \alpha \right]$$

$$\omega_{\text{gravity}} = -\Delta U = (U_i - U_f)$$



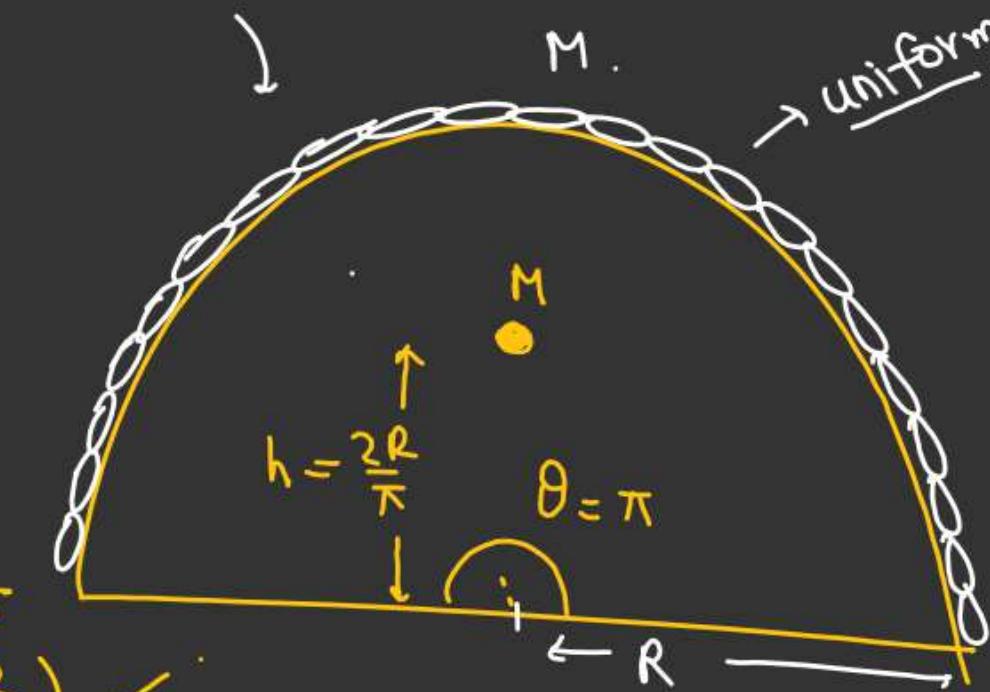


TRICK (Proof in next chapter)



$$h = \frac{2R}{\theta} \sin\left(\frac{\theta}{2}\right)$$

$U = ??$



$$U = \left(Mg \frac{2R}{\pi}\right) \checkmark$$

$$h = \frac{2R}{\sqrt{2}}$$

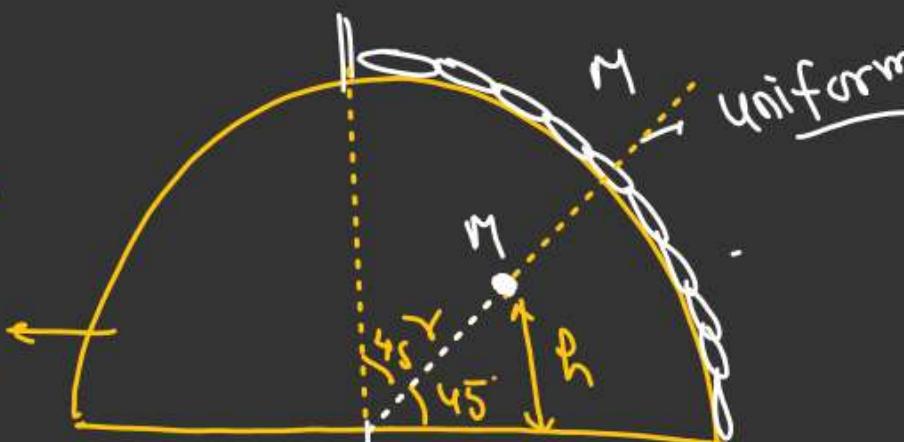
$$h = \left(\frac{2R}{\pi}\right) \checkmark$$

$$U = \left(Mg \frac{2R}{\pi}\right)$$

$$\theta = \pi/2$$

$$Y = \frac{2R}{\pi/2} \sin\frac{\pi}{4}$$

$$Y = \frac{\pi R \times 1}{\sqrt{2}} = \frac{2\sqrt{2}R}{\pi}$$



Find the Kinetic Energy of the chain when chain become horizontal.

Uniform Chain.

$$\underline{U_i^o + KE_i^o} = \underline{U_f^o + KE_f}$$

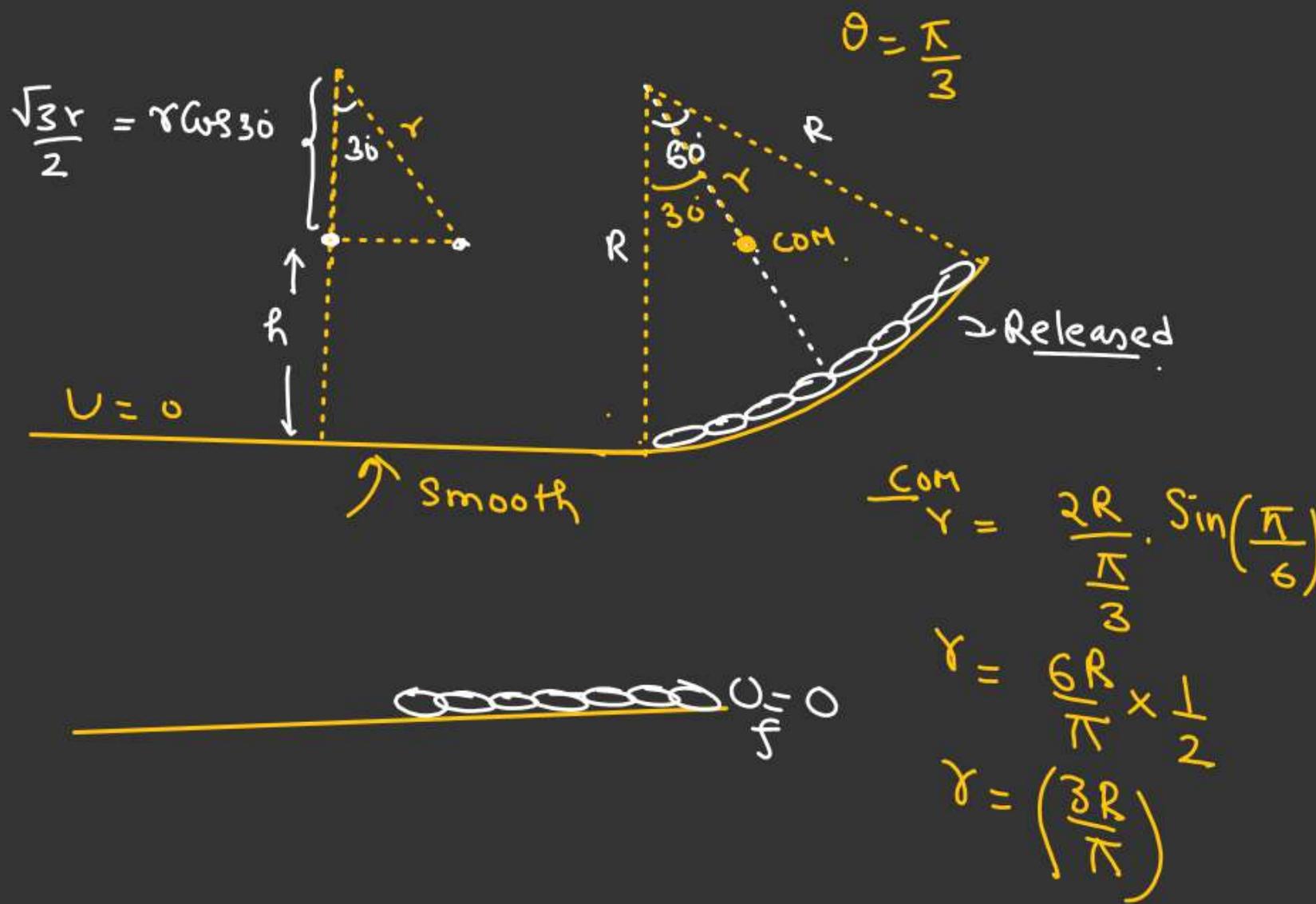
$$h = R - \frac{\sqrt{3}}{2} r$$

$$h = R - \frac{\sqrt{3}}{2} \times \frac{3R}{\pi}$$

$$h = \left(R - \frac{3\sqrt{3}R}{2\pi} \right)$$

$$Mg \left(R - \frac{3\sqrt{3}R}{2\pi} \right) = (KE_f)$$

M = Mass of chain.



$$\frac{COM}{r} = \frac{2R}{\frac{\pi}{3}} \cdot \sin\left(\frac{\pi}{6}\right)$$

$$\begin{aligned} r &= \frac{6R}{\pi} \times \frac{1}{2} \\ r &= \left(\frac{3R}{\pi}\right) \end{aligned}$$

- * Snake assumed to be uniform. It crawl and half of its length become vertical.

Find work done by snake against gravity.

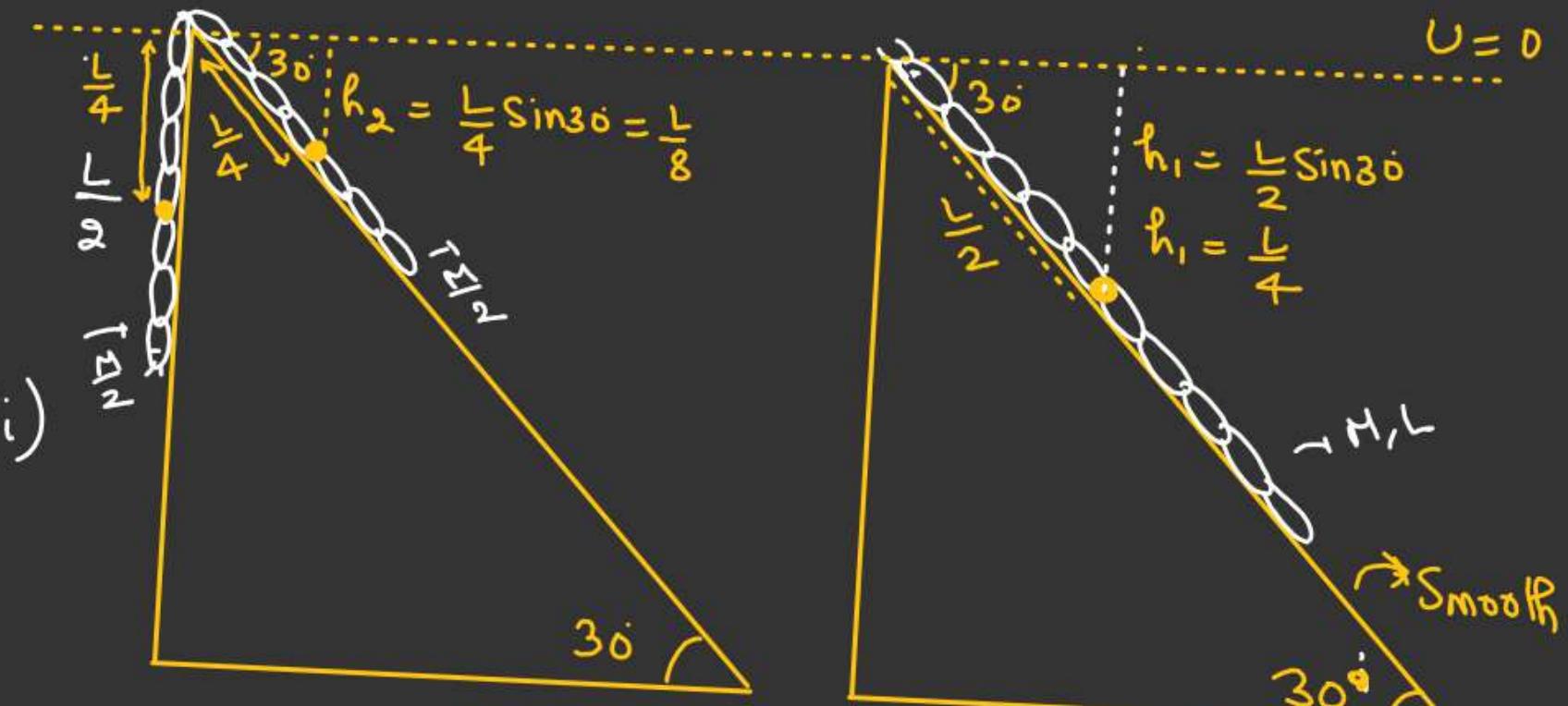
$$\begin{aligned} W_{\text{Snake}} &= -\Delta U = -(U_f - U_i) \\ &= (U_i - U_f) \end{aligned}$$

$$U_i = -\left(Mg \frac{L}{4}\right)$$

$$U_f = -\left[\frac{Mg}{2} \frac{L}{8} + \frac{Mg}{2} \frac{L}{4}\right]$$

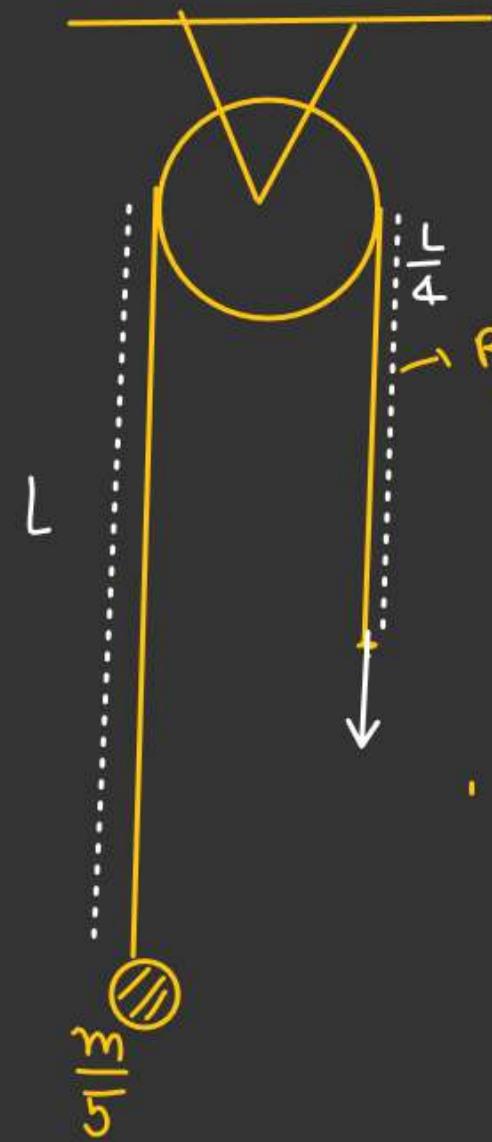
$$U_f = -\left[\frac{Mg}{16} L + \frac{Mg}{8} L\right]$$

$$U_f = -\left(\frac{3MgL}{16}\right)$$



$$W_{\text{Snake}} = \left(-\frac{MgL}{4} + \frac{3MgL}{16}\right)$$

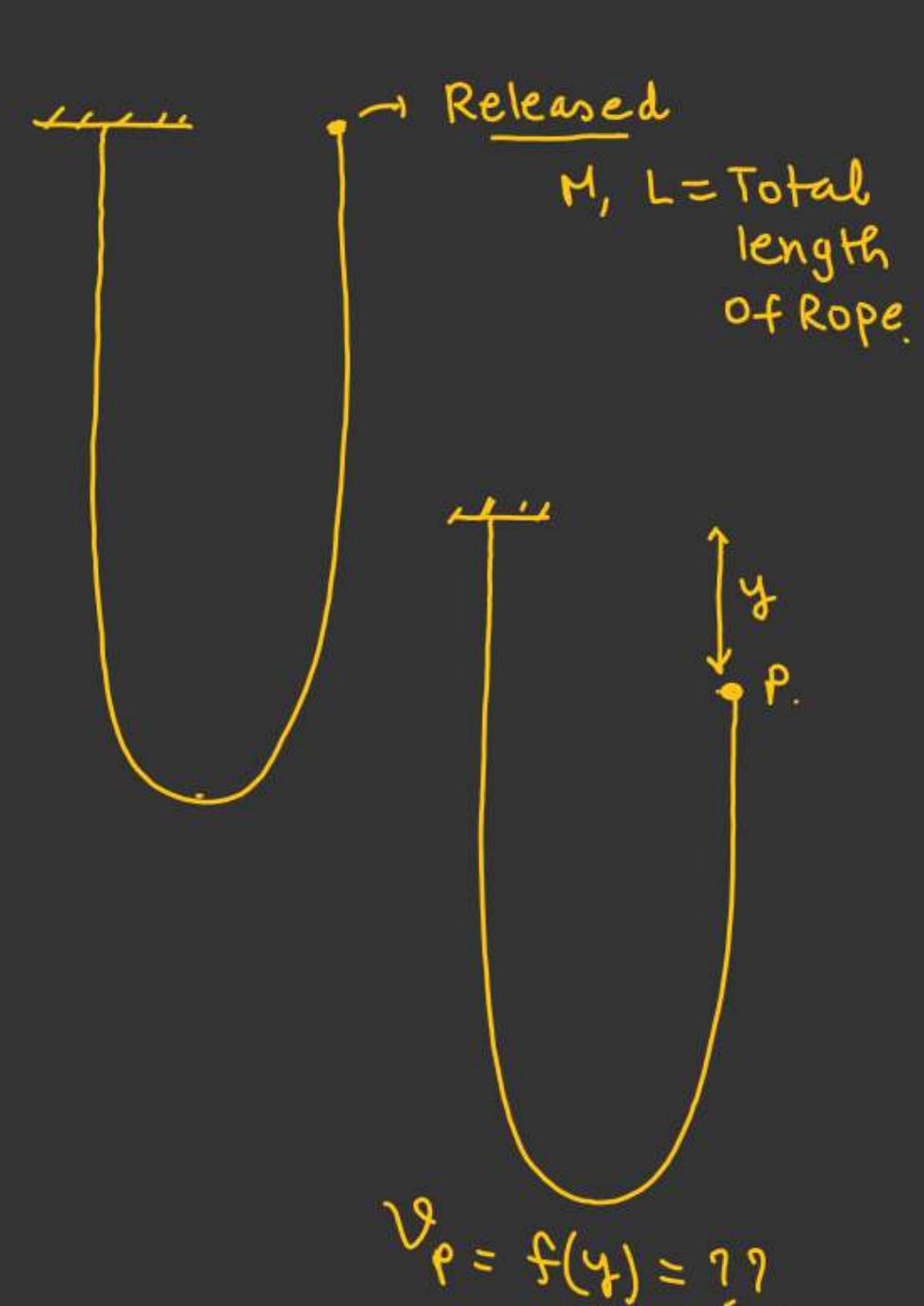
$$W_{\text{Snake}} = \left(-\frac{MgL}{16}\right)$$



m = Mass of Rope

$\frac{m}{5}$ = Mass of ball.

Rope Uniform Find min force applied by ext. agent to assure that ball reaches at pulley.



Sheet

Don't attempt

Ex:- ① Q-14.

Ex:- ② Q-6, Q-10, Q-12,

Ex:- ③ Q-1, Q-7, Q-12, Q-13,
Q-14, Q-24, Q-25

Except these
All have
to attempt from Ex ①, ②, & ③