

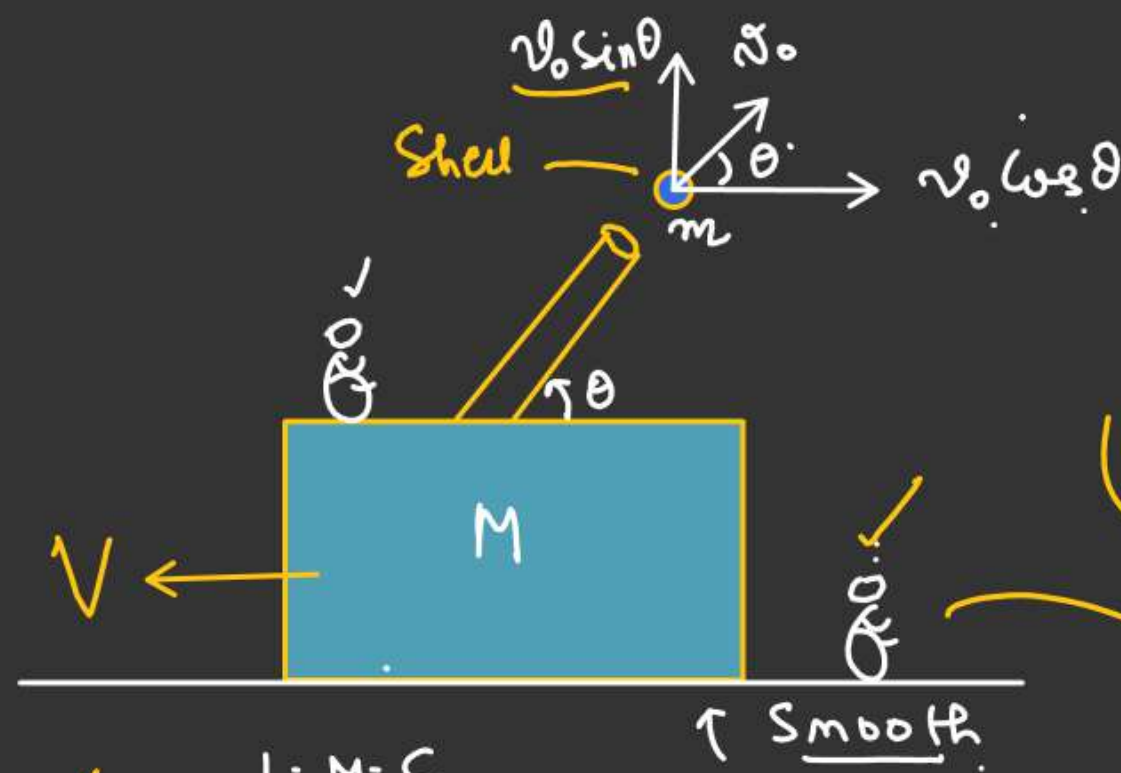
# Case of firing of shell through a Cannon

$v_0$  = velocity of shell w.r.t Cannon ✓

$$(\vec{v}_{\text{shell}/\varepsilon})_x = (\vec{v}_{\text{shell}/\text{Cannon}})_x + (\vec{v}_{\text{Cannon}/\varepsilon})_x$$

$$(\vec{v}_{\text{shell}/\varepsilon})_x = (v_0 \cos \theta \hat{i} - V \hat{i}) \quad \checkmark$$

$$(\vec{v}_{\text{shell}/\varepsilon})_y = v_0 \sin \theta \hat{j}$$



L.M.C.

$$(\vec{P}_i)_x = (\vec{P}_f)_x$$

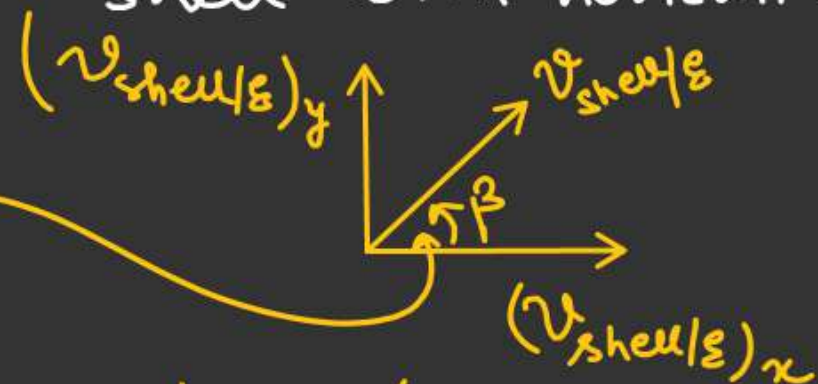
$$0 = m(v_0 \cos \theta - V) - MV$$

$$(M+m)V = mv_0 \cos \theta$$

$$V = \left( \frac{mv_0 \cos \theta}{M+m} \right) \quad \checkmark$$

w.r.t earth

Angle made by Shell with horizontal



$$\tan \beta = \left( \frac{v_0 \sin \theta}{v_0 \cos \theta - V} \right)$$

$$\beta = ??$$

# L.M.C IN COM FRAME

By Δ Law.

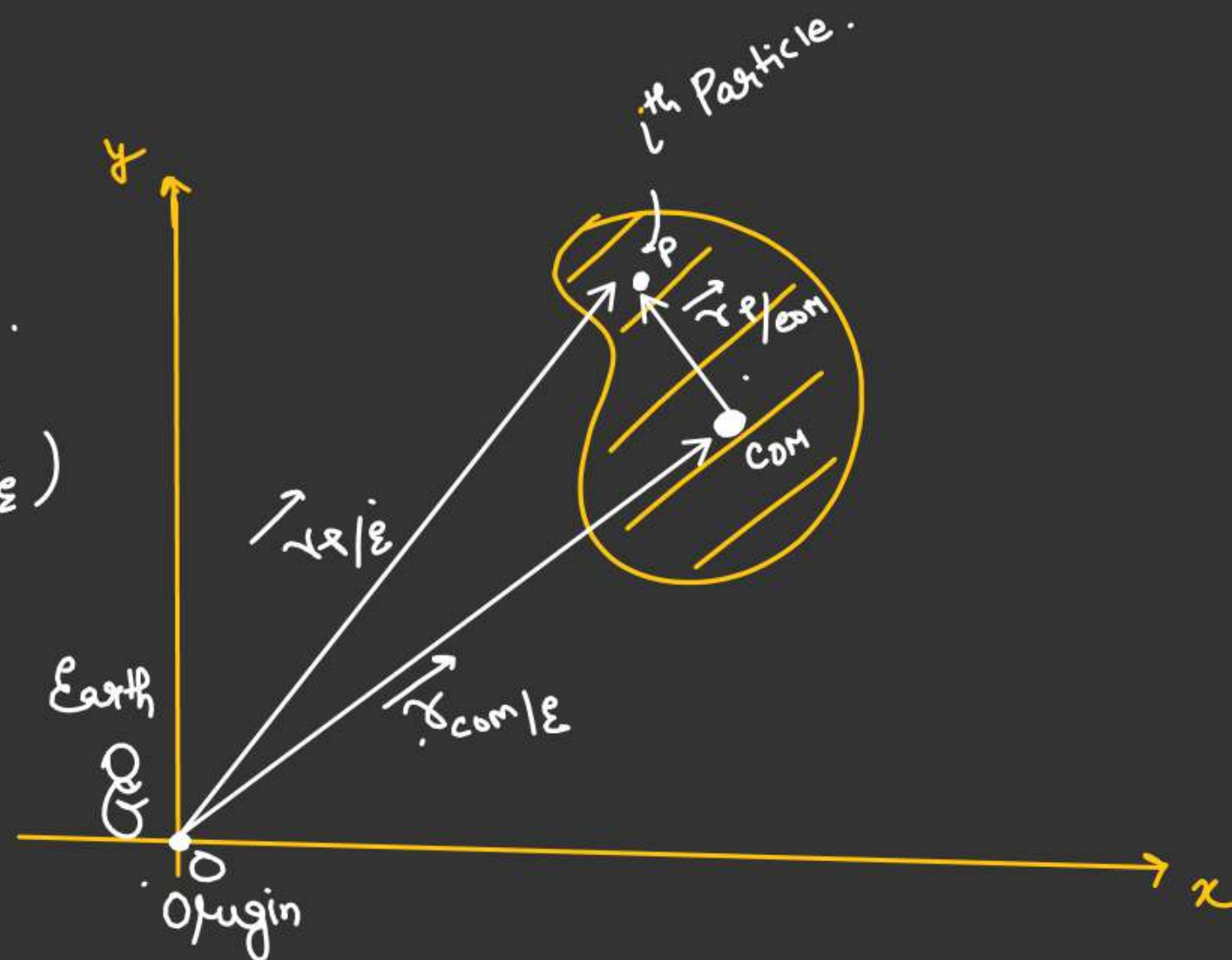
$$\vec{r}_{P/E} = \vec{r}_{P/COM} + \vec{r}_{COM/E}$$

Differentiating both side w.r.t time.

$$\frac{d}{dt}(\vec{r}_{P/E}) = \frac{d}{dt}(\vec{r}_{P/COM}) + \frac{d}{dt}(\vec{r}_{COM/E})$$

$$\Downarrow$$

$$\vec{v}_{P/E} = \vec{v}_{P/COM} + \vec{v}_{COM/E}$$

$$\Downarrow$$
  
 Relative velocity  
 of P w.r.t COM




★★

L.M.C IN COM FRAME

$$\vec{v}_{P/E} = \vec{v}_{P/COM} + \vec{v}_{COM/E}$$

Relative velocity  
of P w.r.t COM

w.r.t COM frame.

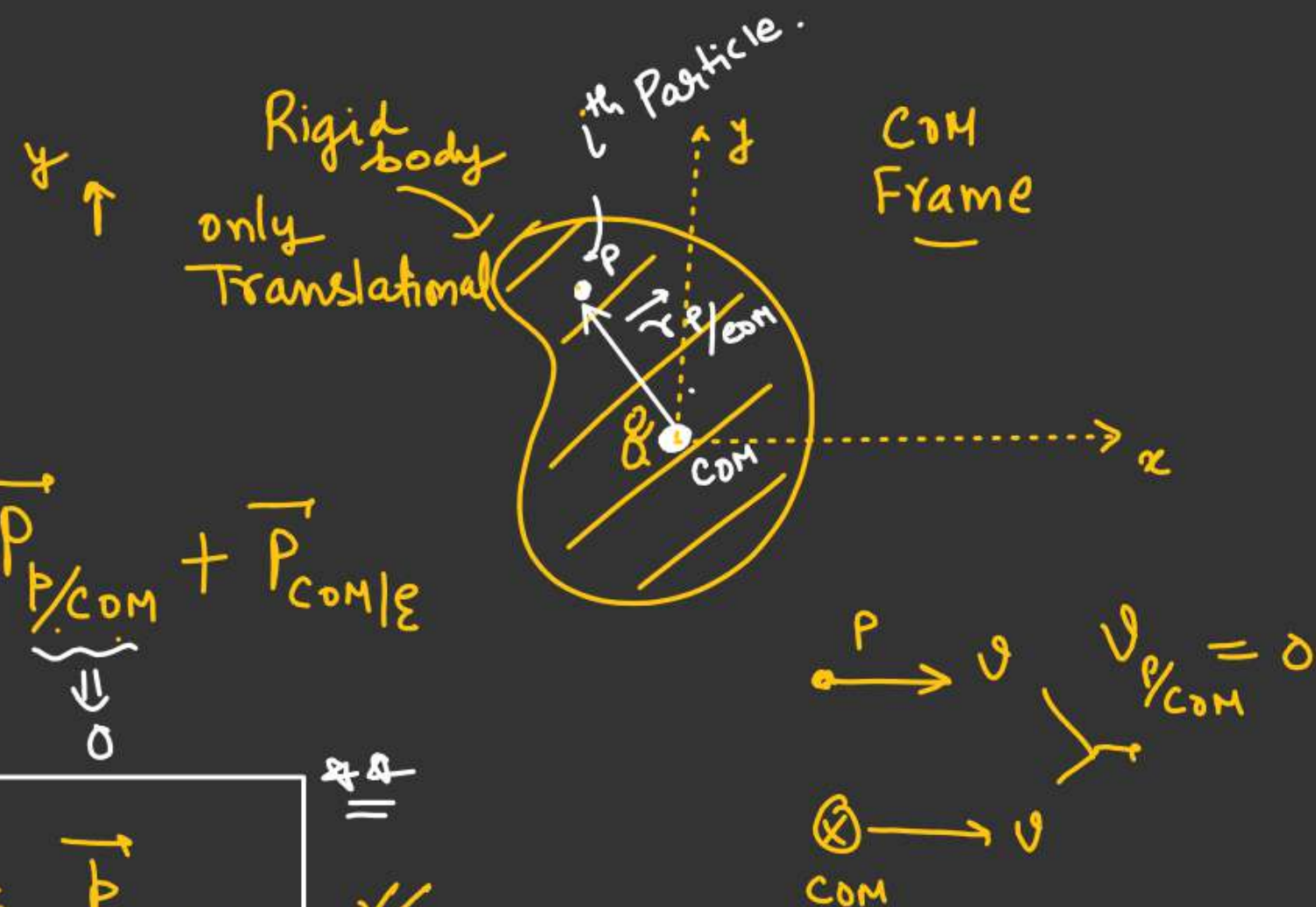
$$\vec{v}_{P/COM} = 0 \checkmark$$

$$\vec{v}_{P/E} = \vec{v}_{COM/E}$$

$$\vec{p}_{P/E} = \vec{p}_{P/COM} + \vec{p}_{COM/E}$$

$$\vec{p}_{P/E} = \vec{p}_{COM/E} \checkmark$$

when particle P at rest  
w.r.t COM frame OR  
both particle & COM move with  
same velocity w.r.t Earth frame



✖✖

## L.M.C of two mass system in COM FRAME

$$\vec{v}_{com} = \frac{m_2 v_2 \hat{i} + m_1 v_1 \hat{i}}{(m_1 + m_2)}$$

$$\vec{v}_{com} = \left( \frac{m_2 v_2 + m_1 v_1}{m_1 + m_2} \right) \hat{i}$$

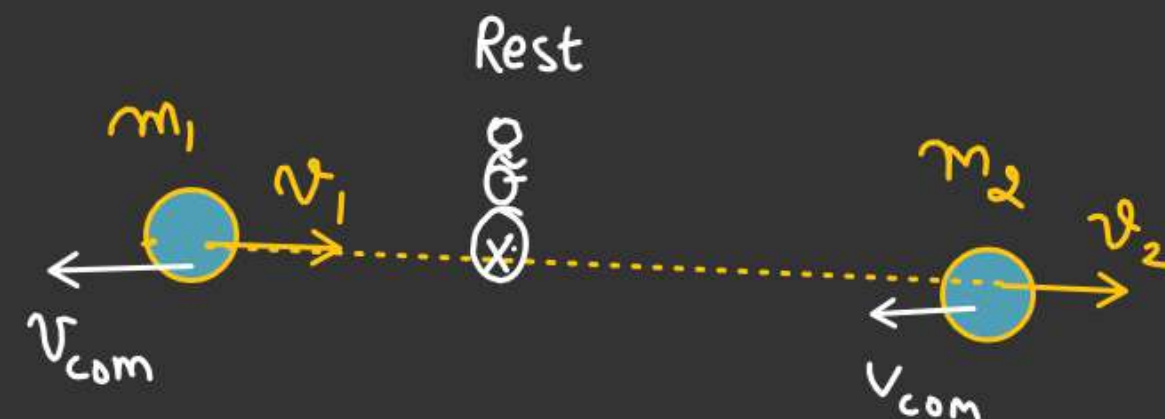
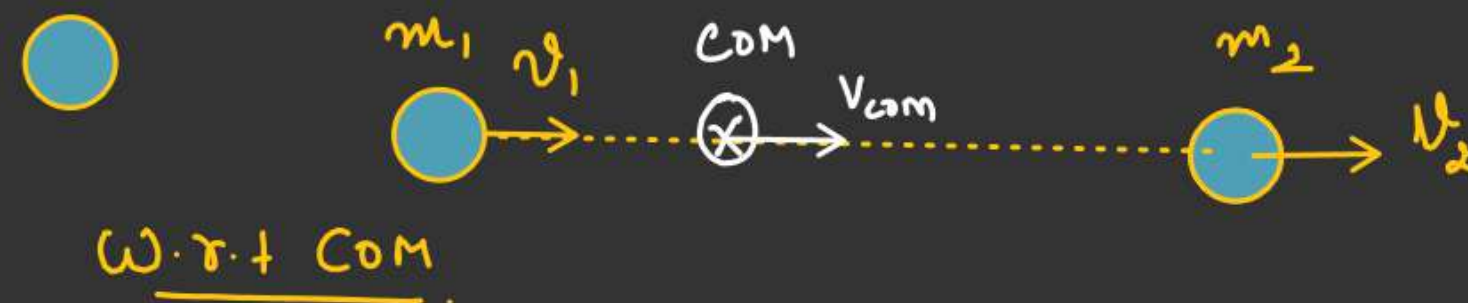
$$\vec{v}_{m_1/com} = \vec{v}_{m_1/\varepsilon} - \vec{v}_{com/\varepsilon}$$

$$= \left[ v_1 - \left( \frac{m_2 v_2 + m_1 v_1}{m_1 + m_2} \right) \right] \hat{i}$$

$$= \left( \frac{m_2 v_1 - m_2 v_2}{m_1 + m_2} \right) \hat{i}$$

$$\vec{v}_{m_1/com} = \frac{m_2}{m_1 + m_2} (v_1 - v_2) \hat{i}$$

$$\vec{v}_{m_1/com} = \left( \frac{m_2}{m_1 + m_2} \right) (\vec{v}_{m_1/m_2})$$



$$\begin{aligned} \vec{p}_{m_1/com} &= m_1 \vec{v}_{m_1/com} \\ &= \left( \frac{m_1 m_2}{m_1 + m_2} \right) (\vec{v}_{m_1/m_2}) \end{aligned}$$

$\mu$

$$\vec{p}_{m_1/com} = \mu \vec{v}_{rel}$$



✖✖

## L.M.C of two mass system in COM FRAME

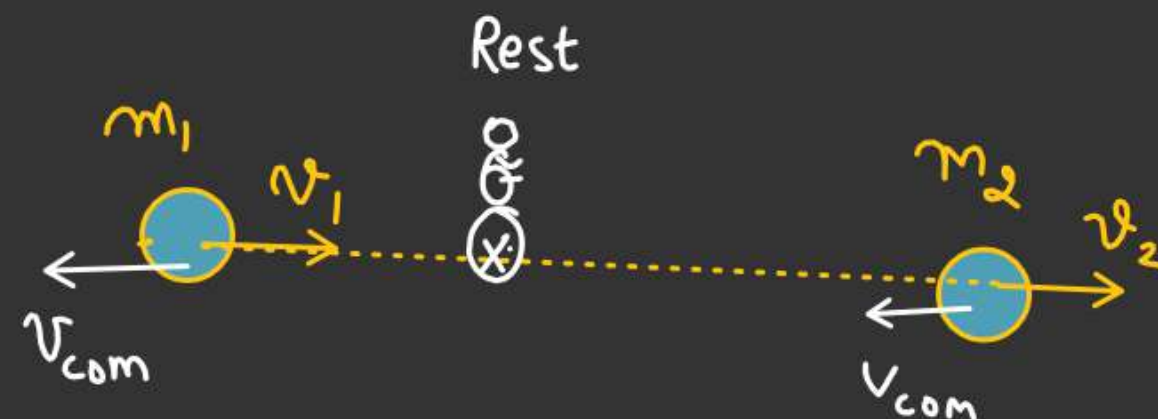
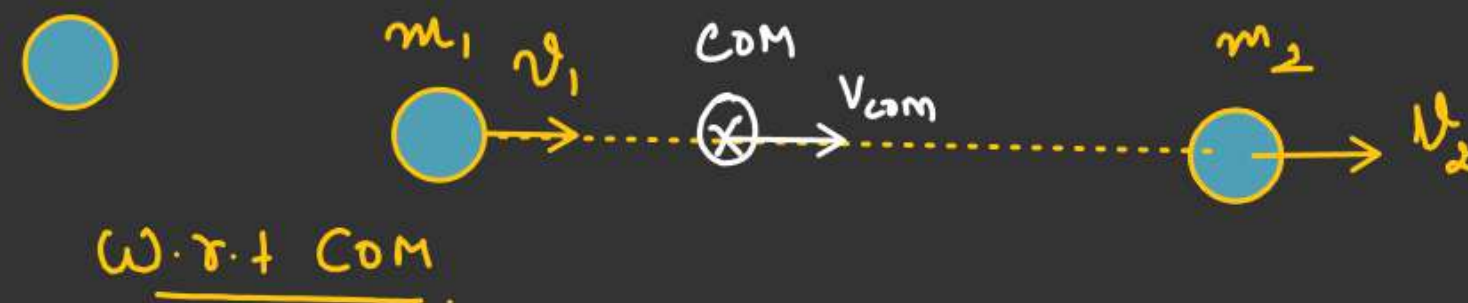
$$\vec{v}_{com} = \frac{m_2 v_2 \hat{i} + m_1 v_1 \hat{i}}{(m_1 + m_2)}$$

$$\vec{v}_{com} = \left( \frac{m_2 v_2 + m_1 v_1}{m_1 + m_2} \right) \hat{i}$$

$$\begin{aligned} \vec{v}_{m_2/com} &= \vec{v}_{m_2/E} - \vec{v}_{com/E} \\ &= v_2 \hat{i} - \left( \frac{m_2 v_2 + m_1 v_1}{m_1 + m_2} \right) \hat{i} \\ &= \frac{m_1}{m_1 + m_2} (v_2 - v_1) \hat{i} \end{aligned}$$

$$\vec{p}_{m_2/com} = m_2 \vec{v}_{m_2/com} = \left( \frac{m_1 m_2}{m_1 + m_2} \right) \left( \vec{v}_{m_2/m_1} \right) = \left( \mu \vec{v}_{m_2/m_1} \right)$$

$\Downarrow$   
 $\mu$



TRICK

For two point mass system.

$$\vec{p}_{m_1/\text{COM}} = \mu \vec{v}_{\text{rel}}$$

$$\vec{p}_{m_2/\text{COM}} = -\mu \vec{v}_{\text{rel}}$$

$$m_1 \quad \odot \rightarrow v_1 \quad \otimes \quad m_2 \quad \odot \rightarrow v_2$$

$$\vec{v}_{\text{rel}} = (\underline{v_1 - v_2}) \hat{i}$$

$$\mu = \frac{m_1 m_2}{m_1 + m_2}$$

(Reduced Mass)



$$\mu \quad \otimes \rightarrow v_{\text{rel}} = (v_1 - v_2)$$

$$|\vec{p}_{m_1/\text{COM}}| = |\vec{p}_{m_2/\text{COM}}| = \mu(v_{\text{rel}})$$

K.E in COM frameK.E of  $m_1$  w.r.t COM =

$$\frac{1}{2} m_1 (v_{m_1/\text{COM}})^2$$

$$= \frac{1}{2} m_1 \left[ \frac{m_2}{m_1 + m_2} (v_1 - v_2) \right]^2$$

$$= \frac{1}{2} \left( \frac{m_1^2}{m_1} \times \frac{m_2^2}{(m_1 + m_2)^2} \right) \times (v_{\text{rel}})^2$$

$$= \frac{1}{2} m_1 \left( \frac{m_1 m_2}{m_1 + m_2} \right)^2 \cdot v_{\text{rel}}^2$$

$$\approx \frac{1}{2} \mu v_{\text{rel}}^2$$

$$|v_{\text{rel}}| = |v_{m_1/m_2}| = |v_{m_2/m_1}|$$

K.E of  $m_2$  w.r.t COM

$$\frac{1}{2} m_2 (v_{m_2/\text{COM}})^2$$

$$= \frac{1}{2} \mu v_{\text{rel}}^2$$

$$K.E_{\text{system/COM}} = \frac{1}{2} m_1 (v_{m_1/\text{COM}})^2 + \frac{1}{2} m_2 (v_{m_2/\text{COM}})^2$$

$$K.E_{\text{system/COM}} = \frac{1}{2} \mu v_{\text{rel}}^2$$

$$= \frac{\mu^2 v_{\text{rel}}^2}{2} \left( \frac{1}{m_1} + \frac{1}{m_2} \right)$$

$$= \left( \frac{m_1 m_2}{m_1 + m_2} \right)^2 \times \frac{m_1 + m_2}{m_1 m_2} \times \frac{1}{2} v_{\text{rel}}^2$$



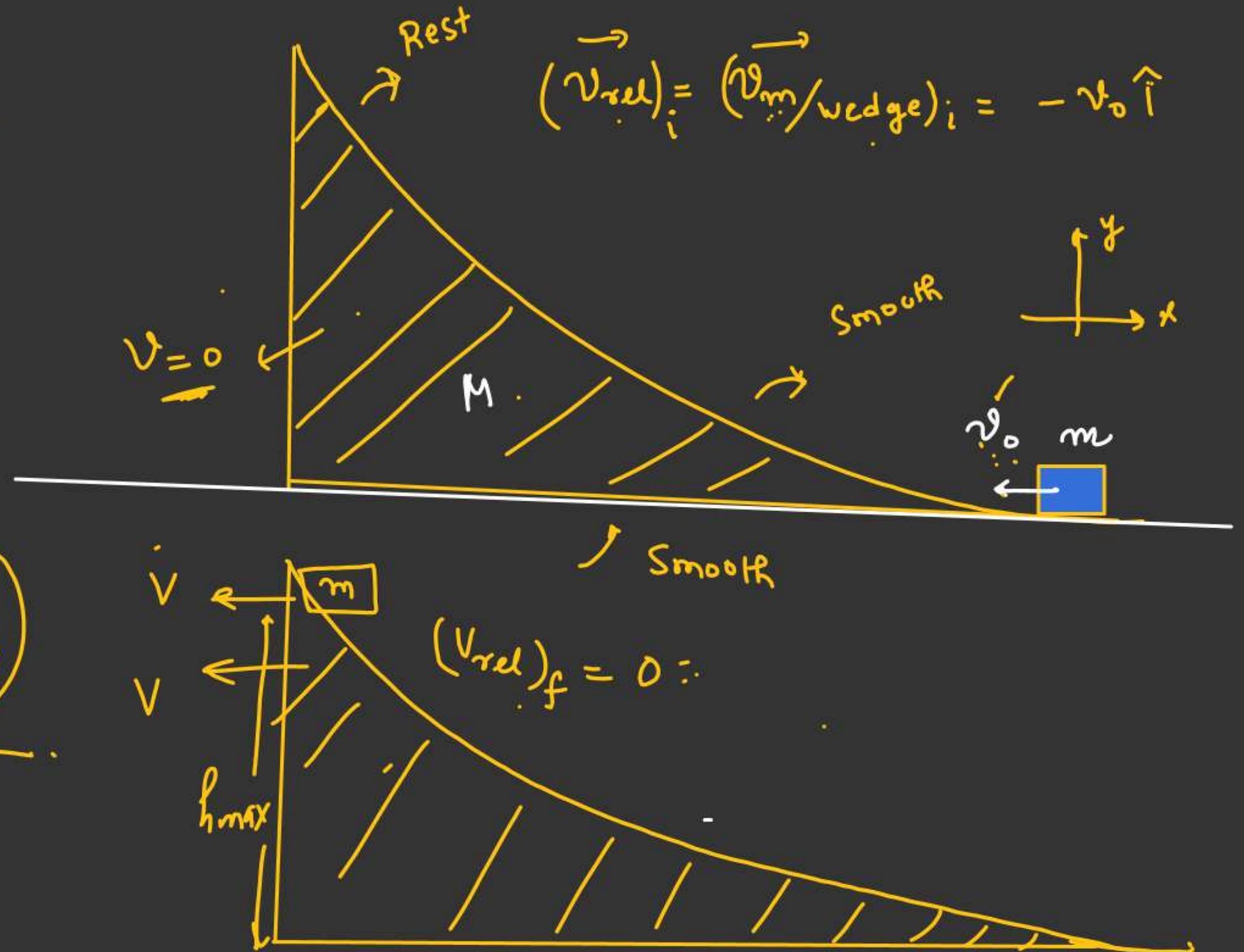
$$h_{\max} = ??$$

$$\frac{1}{2} \mu \underline{v_{\text{rel}}}^2 = m g h_{\max}$$

$$\mu = \left( \frac{M m}{M + m} \right)$$

$$\frac{1}{2} \left( \frac{M m}{M + m} \right) v_0^2 = m g h_{\max}$$

$$h_{\max} = \frac{v_0^2}{2g} \left( \frac{M}{M + m} \right)$$





# L.M.C IN SPRING BLOCK SYSTEM

## Maximum Compression in the

### Spring

For two blocks and Spring as system  $kx$  is an internal force so no net external force in  $x$ -direction

L.M.C

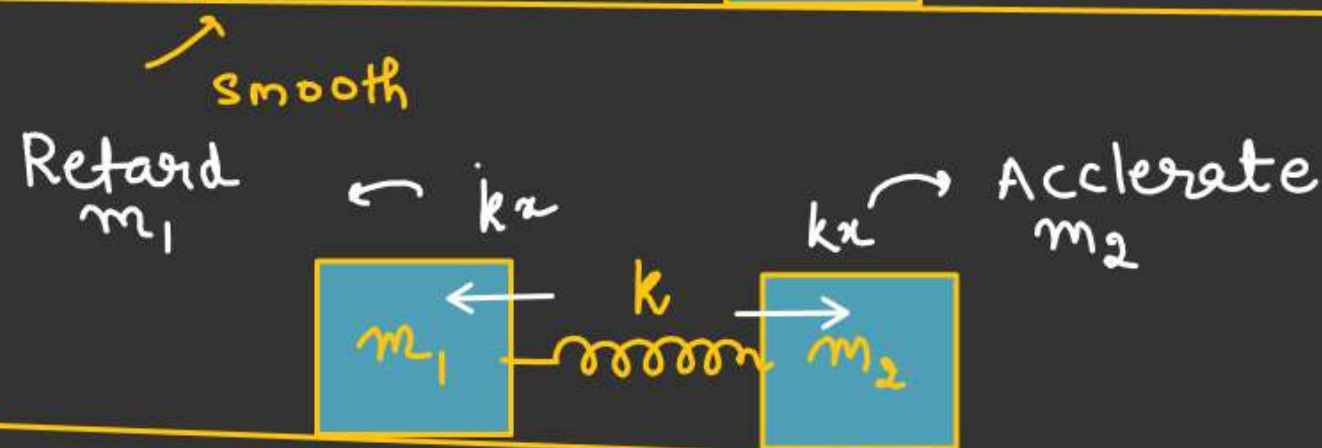
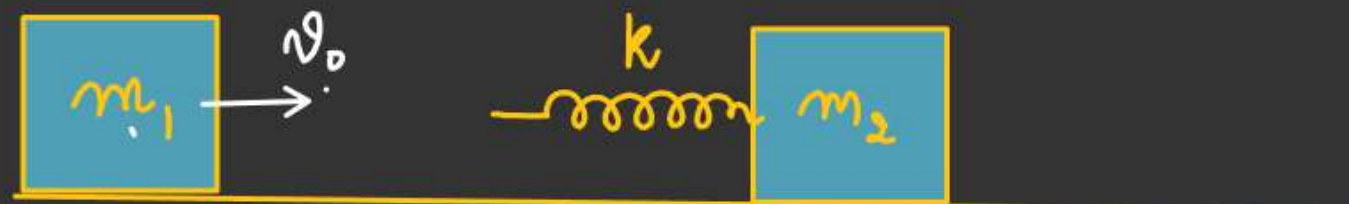
$$m_1 v_0 = (m_1 + m_2) v_c$$

$$v_c = \left( \frac{m_1 v_0}{m_1 + m_2} \right) \checkmark \text{--- (1)}$$

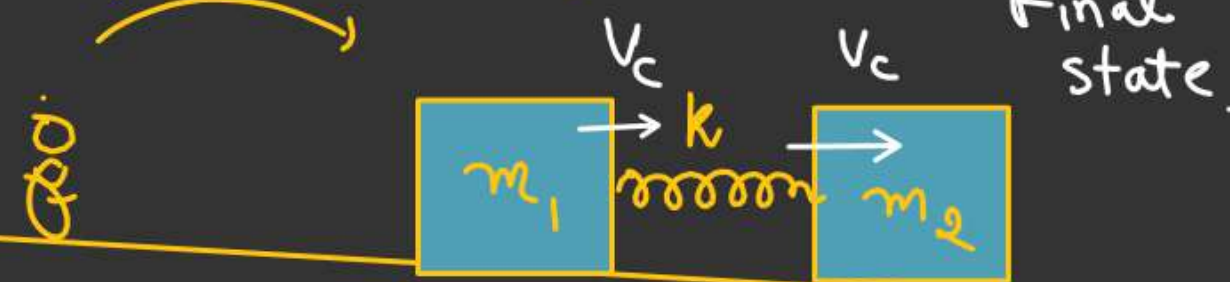
### Energy Conservation

$$\frac{1}{2} m_1 v_0^2 = \frac{1}{2} (m_1 + m_2) v_c^2 + \frac{1}{2} k x_{\max}^2 \text{--- (2)}$$

Initial State



At the time of Maximum compression



$$v_c = \frac{m_1 v_0}{m_1 + m_2} \quad - (1)$$

$$\frac{1}{2} m_1 v_0^2 = \frac{1}{2} (m_1 + m_2) v_c^2 + \frac{1}{2} k x_{\max}^2 \quad - (2)$$

$$\frac{1}{2} k x_{\max}^2 = \frac{1}{2} m_1 v_0^2 - \frac{1}{2} (m_1 + m_2) \frac{m_1^2 v_0^2}{(m_1 + m_2)^2}$$

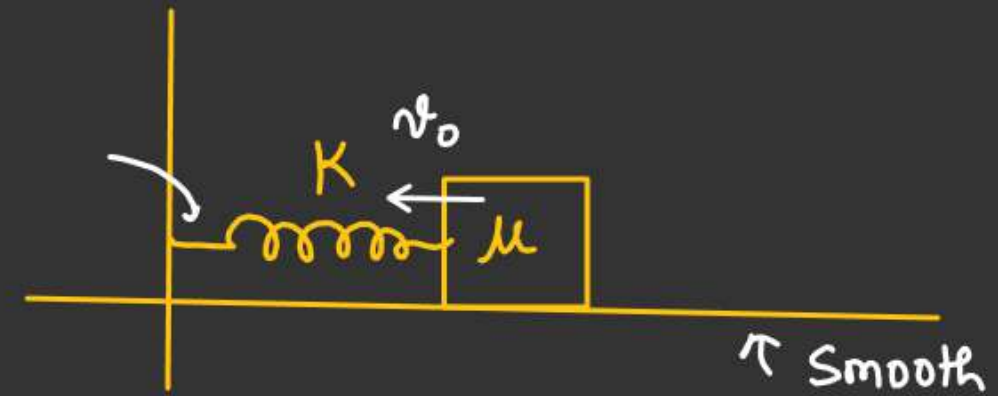
$$\frac{1}{2} k x_{\max}^2 = \frac{1}{2} m_1 v_0^2 \left[ 1 - \frac{m_1}{m_1 + m_2} \right]$$

$$\frac{1}{2} k x_{\max}^2 = \frac{1}{2} \left( \frac{m_1 m_2}{m_1 + m_2} \right) v_0^2$$

$$x_{\max} = \sqrt{\frac{\left( \frac{m_1 m_2}{m_1 + m_2} \right)}{k}} v_0^2$$

$$\Rightarrow x_{\max} = \sqrt{\frac{\mu}{k}} v_0$$

$\mu = \text{Reduced Mass}$



$$\frac{1}{2} \mu v_0^2 = \frac{1}{2} k x_{\max}^2$$

$$x_{\max} = \sqrt{\frac{\mu}{k}} v_0$$





$$v_c = \frac{m_1 v_0}{m_1 + m_2} \quad - (1)$$

$$\frac{1}{2} m_1 v_0^2 = \frac{1}{2} (m_1 + m_2) v_c^2 + \frac{1}{2} k x_{\max}^2 \quad - (2)$$

$$\frac{1}{2} k x_{\max}^2 = \frac{1}{2} m_1 v_0^2 - \frac{1}{2} (m_1 + m_2) \frac{m_1^2 v_0^2}{(m_1 + m_2)^2}$$

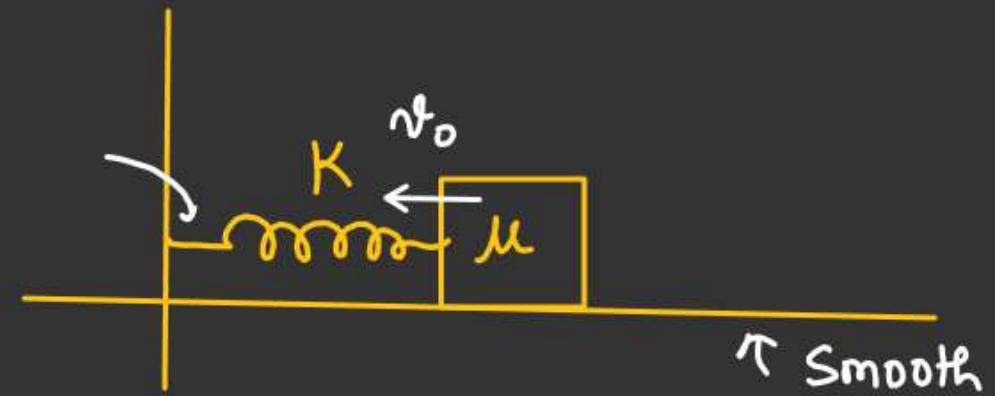
$$\frac{1}{2} k x_{\max}^2 = \frac{1}{2} m_1 v_0^2 \left[ 1 - \frac{m_1}{m_1 + m_2} \right]$$

$$\frac{1}{2} k x_{\max}^2 = \frac{1}{2} \left( \frac{m_1 m_2}{m_1 + m_2} \right) v_0^2$$

$$x_{\max} = \sqrt{\frac{\left( \frac{m_1 m_2}{m_1 + m_2} \right)}{k}} v_0^2$$

$$\Rightarrow x_{\max} = \sqrt{\frac{\mu}{k}} v_0$$

$\mu = \text{Reduced Mass}$



$$\frac{1}{2} \mu v_0^2 = \frac{1}{2} k x_{\max}^2$$

$$x_{\max} = \sqrt{\frac{\mu}{k}} v_0$$



# Find  $x_{\max} = ??$ 

$\frac{m-2}{H.W}$   
Solve w.r.t  
Earth frame.

$\frac{M-1}{W.r.t. COM}$  ✓

$$\frac{1}{2} \mu v_{rel}^2 = \frac{1}{2} K x_{\max}^2$$

⇓

$(v_{rel})_i$

$$\frac{1}{2} \mu (v_{rel})_i^2 + \frac{1}{2} \mu (v_{rel})_f^2 = \frac{1}{2} K x_{\max}^2$$

⇓

0

$$\frac{1}{2} \left( \frac{2m \cdot m}{2m+m} \right) v_0^2 = \frac{1}{2} K x_{\max}^2$$

$$\frac{m}{3} v_0^2 = \frac{1}{2} K x_{\max}^2$$

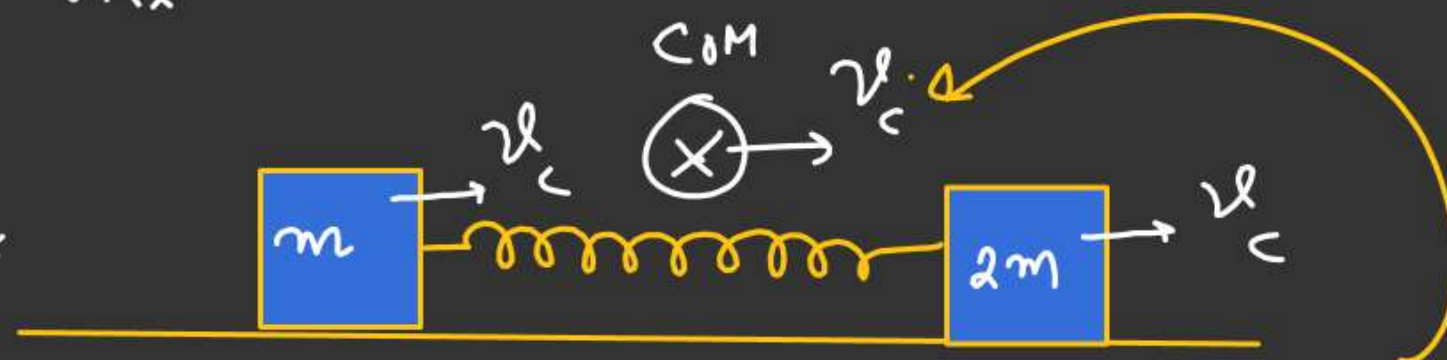
$$x_{\max} = \left( \sqrt{\frac{2m}{3K}} \right) v_0$$

At  $t=0$ .  
Spring at its Natural  
length.



⇓

At the time of  
Maximum  
elongation  
both move with  
common velocity.



$$v_{cm} = \frac{2m v_c + m v_c}{(2m+m)} = v_c$$