

Case of double drum

Cylinder-1

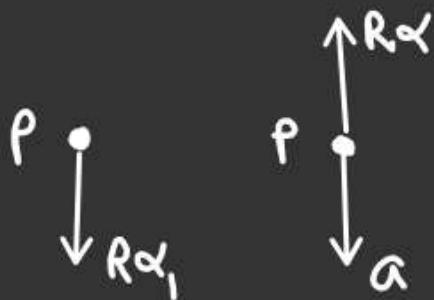
$$T \cdot R = \frac{2mR^2}{2} \alpha_1 \quad \text{--- } ①$$

$$\hookrightarrow \alpha_1 = \frac{T}{mR}$$

Cylinder-2

$$mg - T = ma \quad \text{--- } ②$$

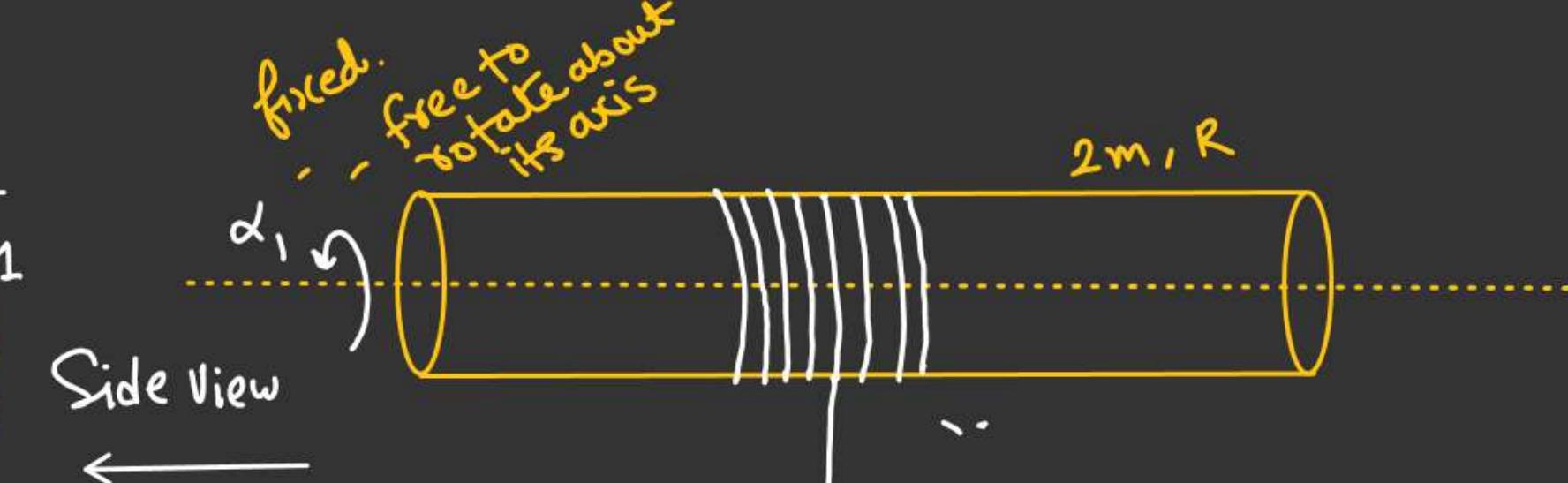
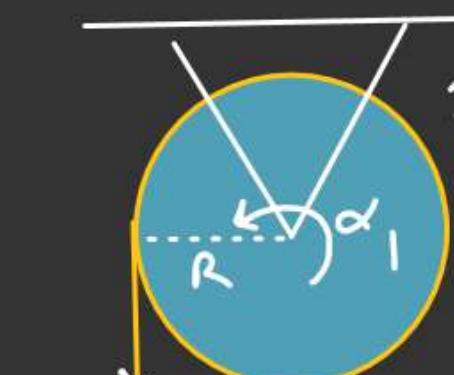
$$TR = \frac{mR^2}{2} \alpha \quad \text{--- } ③$$

Condition of No Slipping

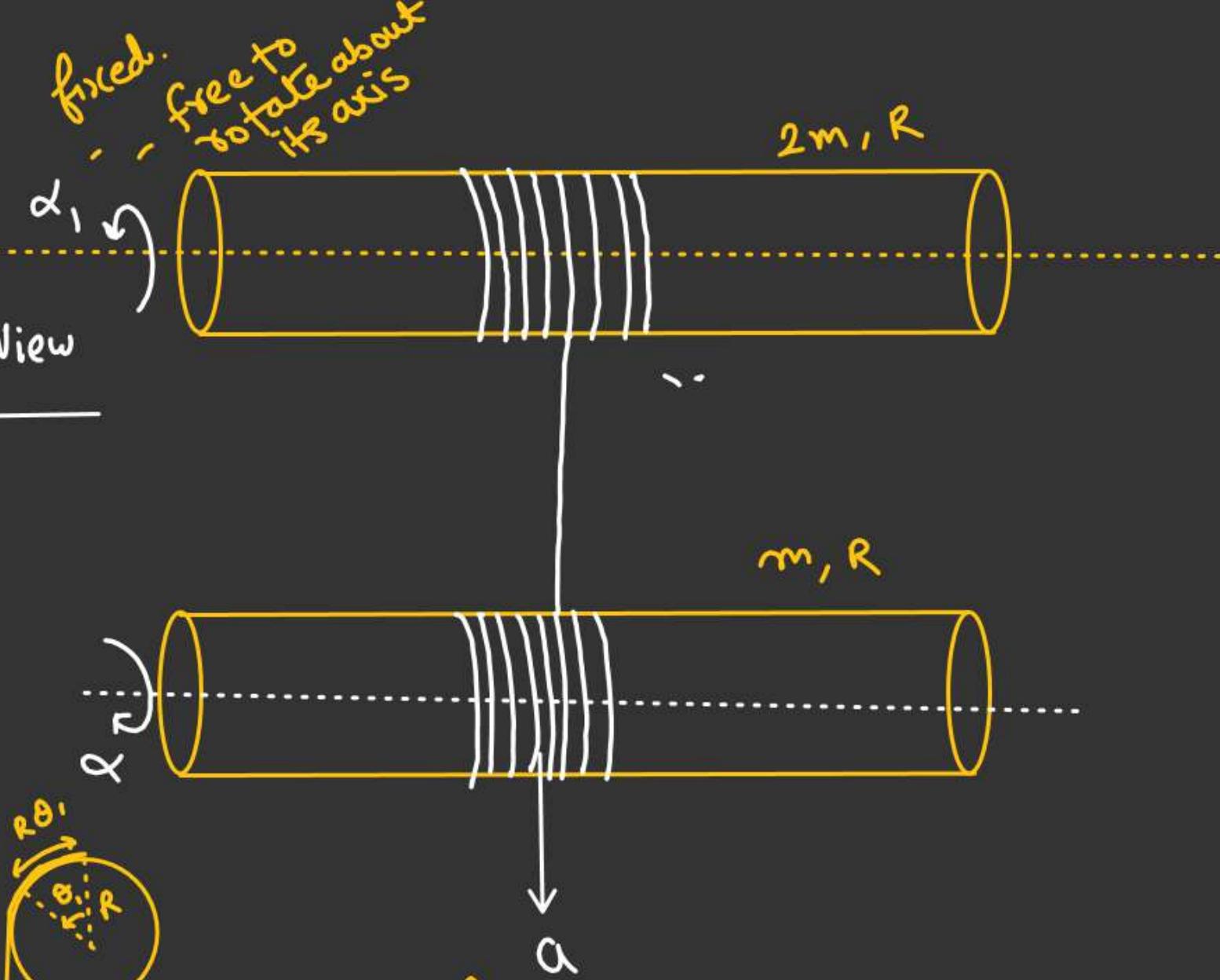
$$R\alpha_1 = a - R\alpha \quad \text{--- } ④$$

$$\frac{T}{m} + \frac{T}{m} + \frac{2T}{m} = g \quad R\left(\frac{T}{mR}\right) = \frac{(mg - T)}{m} - R\left(\frac{2T}{mR}\right)$$

$$T = \left(\frac{mg}{4}\right)$$



Side View  
←



$$R\theta_1 = x - R\theta$$

From 2

$$ma = mg - \frac{mg}{4}$$

$$a = \left(\frac{3g}{4}\right)$$

No Slipping of thread on the pulley

For No Slipping

$$y_2 = y_1 = R\theta.$$

(Torque)  $a_1 = a_2 = a = R\alpha \quad \text{--- } ①$

$$T_1 R - T_2 R = I \alpha \quad \rightarrow \quad \alpha = \frac{a}{R}$$

$$T_1 - T_2 = \left( \frac{I \alpha}{R} \right) \quad \text{--- } ②$$

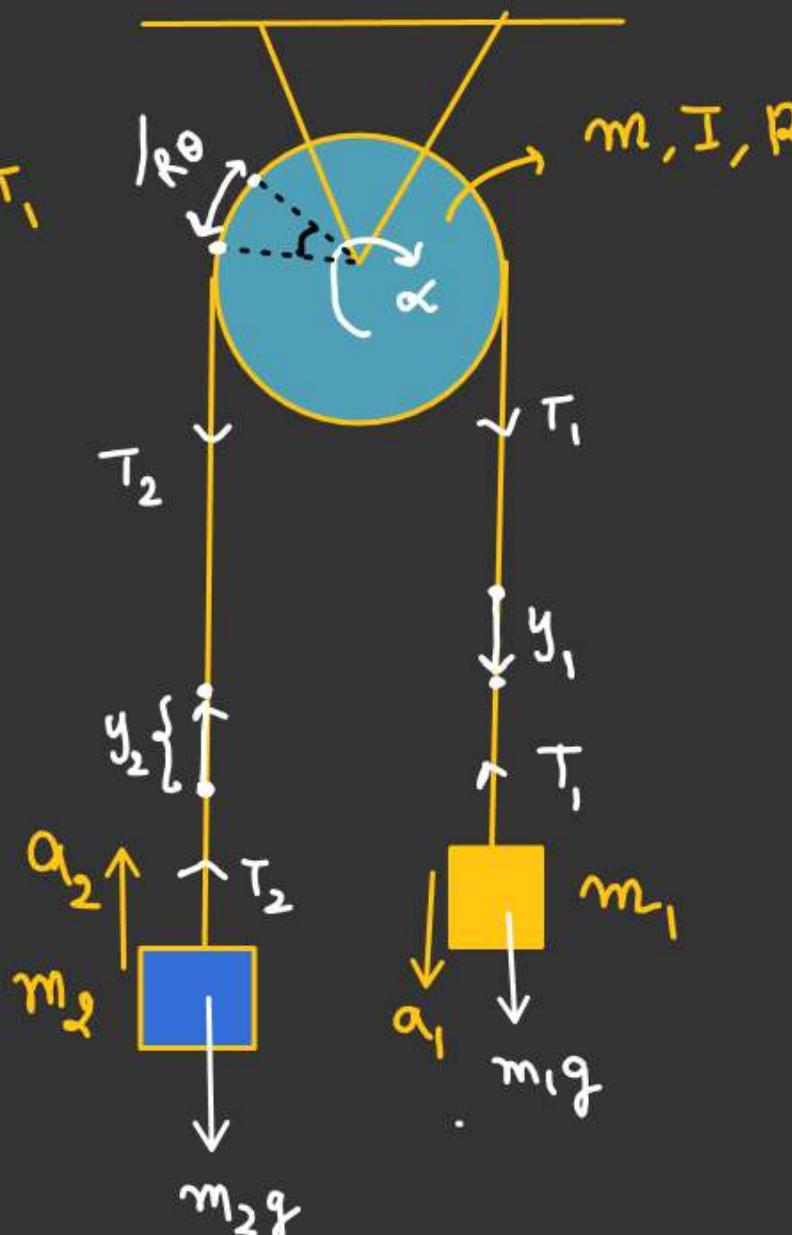
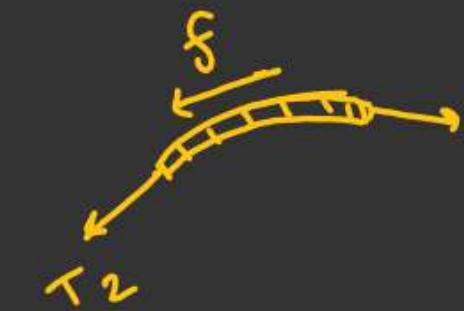
$$m_1 g - T_1 = m_1 a \quad \text{--- } ③$$

$$T_2 - m_2 g = m_2 a \quad \text{--- } ④$$

$$(T_2 - T_1) + (m_1 - m_2)g = (m_1 + m_2)a$$



$$-\frac{I \alpha}{R} + (m_1 - m_2)g = (m_1 + m_2)a$$

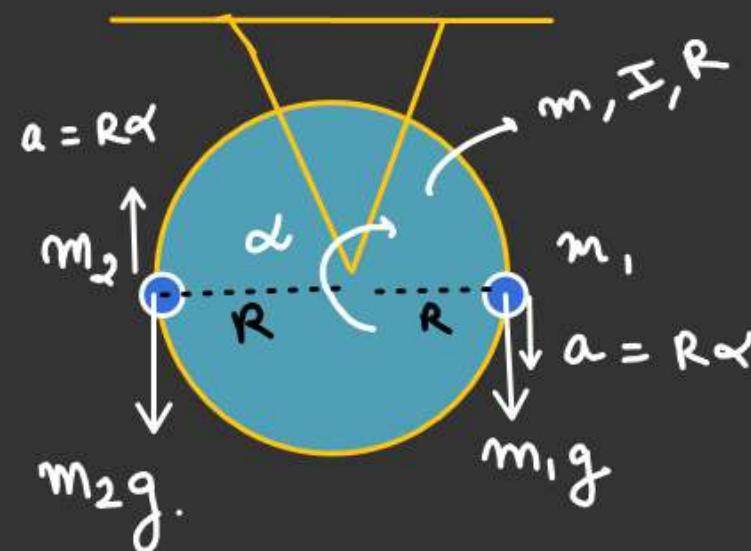


$$-\frac{I a}{R^2} + (m_1 - m_2)g = (m_1 + m_2)a$$

$$(m_1 - m_2)g = \left[ (m_1 + m_2) + \frac{I}{R^2} \right] a$$

$$\alpha = \left[ \frac{(m_1 - m_2)g}{(m_1 + m_2) + \frac{I}{R^2}} \right] \quad \checkmark$$

$\alpha_1 = \alpha_2 = \alpha$

M-2

$$\tau = I\alpha$$

$$m_1 g R - m_2 g \cdot R = [I + (m_1 + m_2)R^2]\alpha$$

$$\alpha = \frac{(m_1 - m_2)g R}{I + (m_1 + m_2)R^2}$$

$$\alpha = \frac{(m_1 - m_2)g}{R \left[ \frac{I}{R^2} + m_1 + m_2 \right]}$$

$$a = \alpha \cdot R = \left[ \frac{(m_1 - m_2)g}{\frac{I}{R^2} + (m_1 + m_2)} \right]$$



$$\text{Energy in Case of pure Rolling} \rightarrow K \cdot E = \left[ \frac{1}{2} I_{\text{com}} \omega^2 + \frac{1}{2} M V_{\text{com}}^2 \right]$$

velocity of Smaller Sphere when it loses contact with bigger Sphere.

$$U_i + K \cdot E_i = U_f + K \cdot E_f$$

$$mg(R+r) + 0 = mg(R+r)\cos\theta + \frac{1}{2}MV^2 + \frac{1}{2}\left(\frac{2}{5}Mr^2\right)\omega^2 \quad (1)$$

w.r.t C, G performing Circular Motion

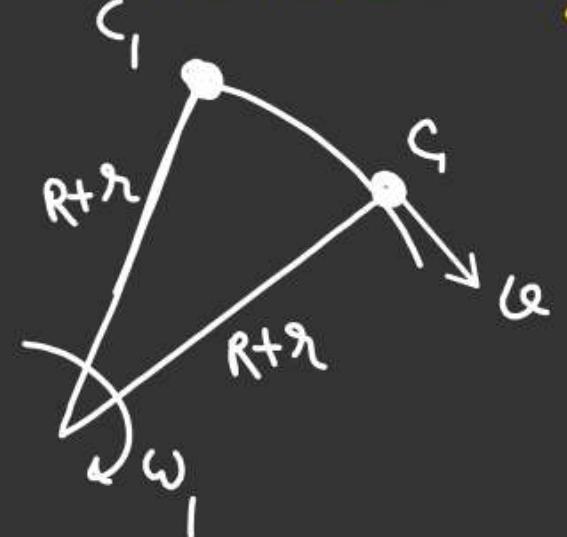
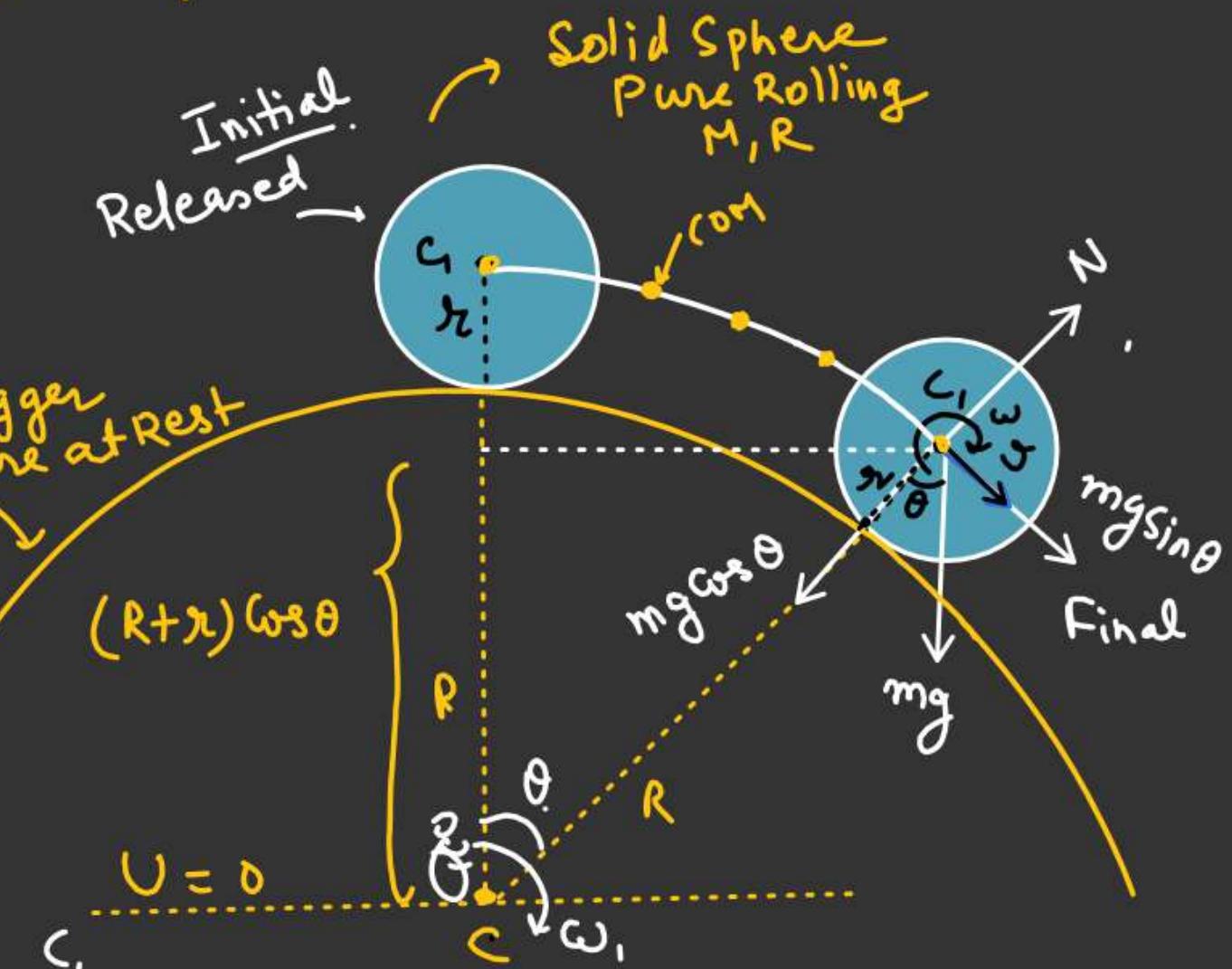
$$mg\omega s\theta - N = m\omega_1^2(R+r)$$

At the time of looping contact  $N=0$

$$mg\cos\theta = m\omega_1^2(R+r) \quad (2)$$

$$\begin{aligned} V &= (R+r)\omega_1 \\ \text{For pure Rolling} \quad V &= r\omega \end{aligned}$$

$\omega_1 = \left( \frac{r\omega}{R+r} \right)$



$$mg(R+r) + \frac{1}{2}mv^2 + \frac{1}{2}\left(\frac{2}{5}mr^2\right)\omega^2 = mg(R+r)\cos\theta \quad \text{--- (1)}$$

$$mg\cos\theta = m\omega_1^2(R+r) \quad \text{--- (2)}$$

For pure rolling

$$v = (R+r)\omega_1 \rightarrow (R+r)\omega_1 = r\omega$$

$$v = r\omega \rightarrow \omega_1 = \left(\frac{r\omega}{R+r}\right)$$

$$\omega = \frac{v}{R}, \quad \omega_1 = \left(\frac{v}{R+r}\right)$$

Put  $mg\cos\theta = m\omega_1^2(R+r)$  in (1)

$$mg(R+r) = (R+r)m(R+r)\omega_1^2 + \frac{1}{2}mv^2 + \frac{m}{5}r^2\omega^2$$

$$mg(R+r) = \cancel{m(R+r)^2} \times \frac{v^2}{(R+r)^2} + \frac{mv^2}{2} + \cancel{\frac{m}{5}r^2} \times \frac{v^2}{\cancel{r^2}}$$

$$mg(R+r) = \left( \frac{mv^2}{2} + \frac{mv^2}{5} + \frac{mv^2}{2} \right)$$

$$mg(R+r) = \frac{10mv^2 + 5mv^2 + 2mv^2}{10} = \left( \frac{17mv^2}{10} \right)$$

$$\sqrt{\frac{10g(R+r)}{17}} = v$$



Find  $v_{\min}$  so that Smaller Sphere  
Complete the Vertical Circular Motion  
With pure rolling

$$mg + N = \frac{mv_1^2}{(R-r)}$$

Energy Conservation

$$U_i^o + K \cdot E_i^o = U_f + K \cdot E_f$$

$$0 + \frac{1}{2}mv^2 + \frac{1}{2} \times \left(\frac{2}{5}Mg^2\right) \left(\frac{v}{r}\right)^2 = mg 2(R-r)$$

$N=0$  For  $v_{\min}$ ,  $v_1$  should be min  
& for  $v_1$  min,  $N=0$

$$mg = \frac{mv_1^2}{R-r}$$

$$g(R-r) = v_1^2 \rightarrow \text{Put in } ①$$

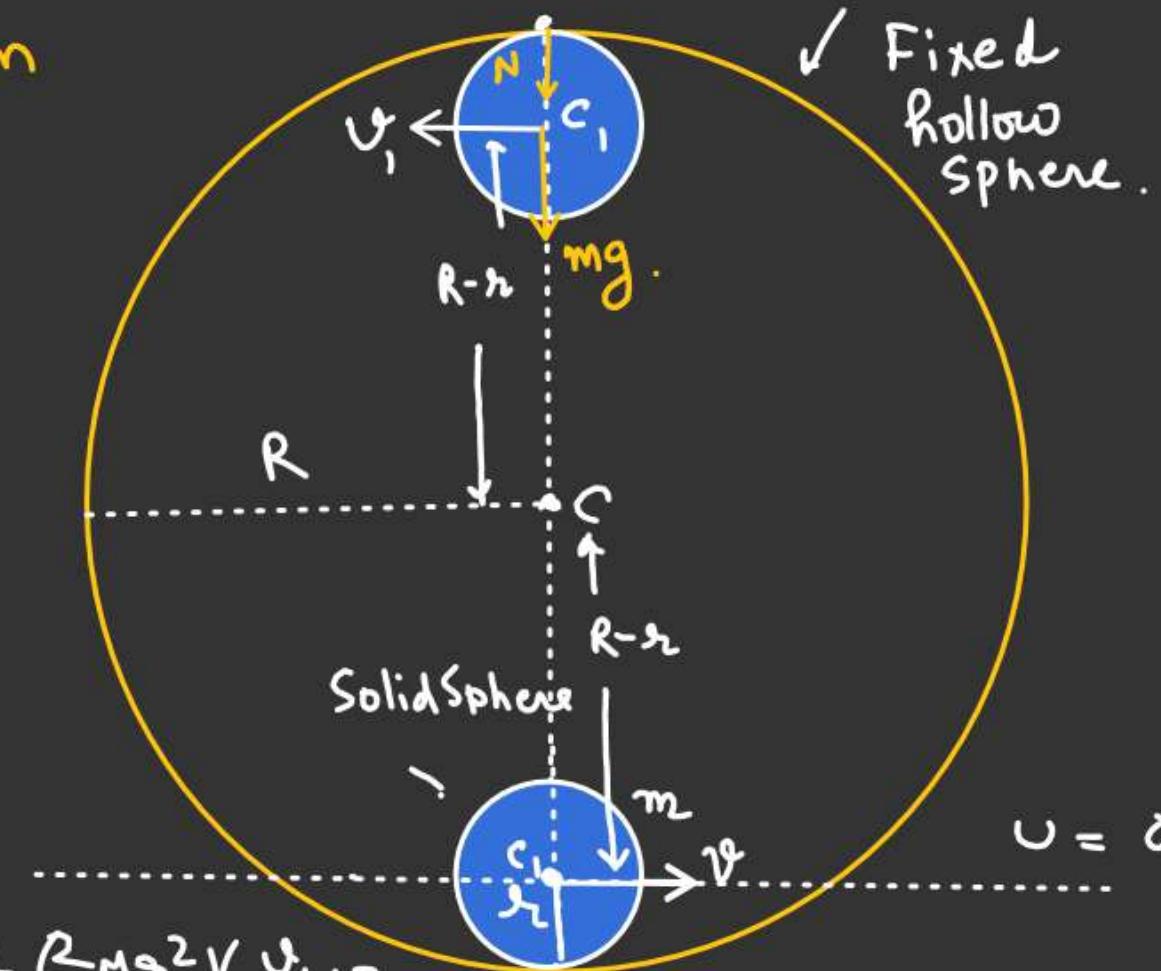
$$+ \frac{1}{2}mv_1^2 + \frac{1}{2} \left(\frac{2}{5}Mg^2\right) \left(\frac{v_1}{r}\right)^2 \rightarrow ①$$

$\omega r = v$  (Pure Rolling)

$\omega = \frac{v}{r}$

$$v = \sqrt{\frac{27g(R-r)}{7}}$$

$$\omega_1 = \frac{v_1}{R}$$



$$v = 0$$