

Simple pendulum.

$$\tau_r = -(mg \sin \theta) l \quad \sin \theta \approx \theta$$

$$\tau_r = -mgl\theta$$

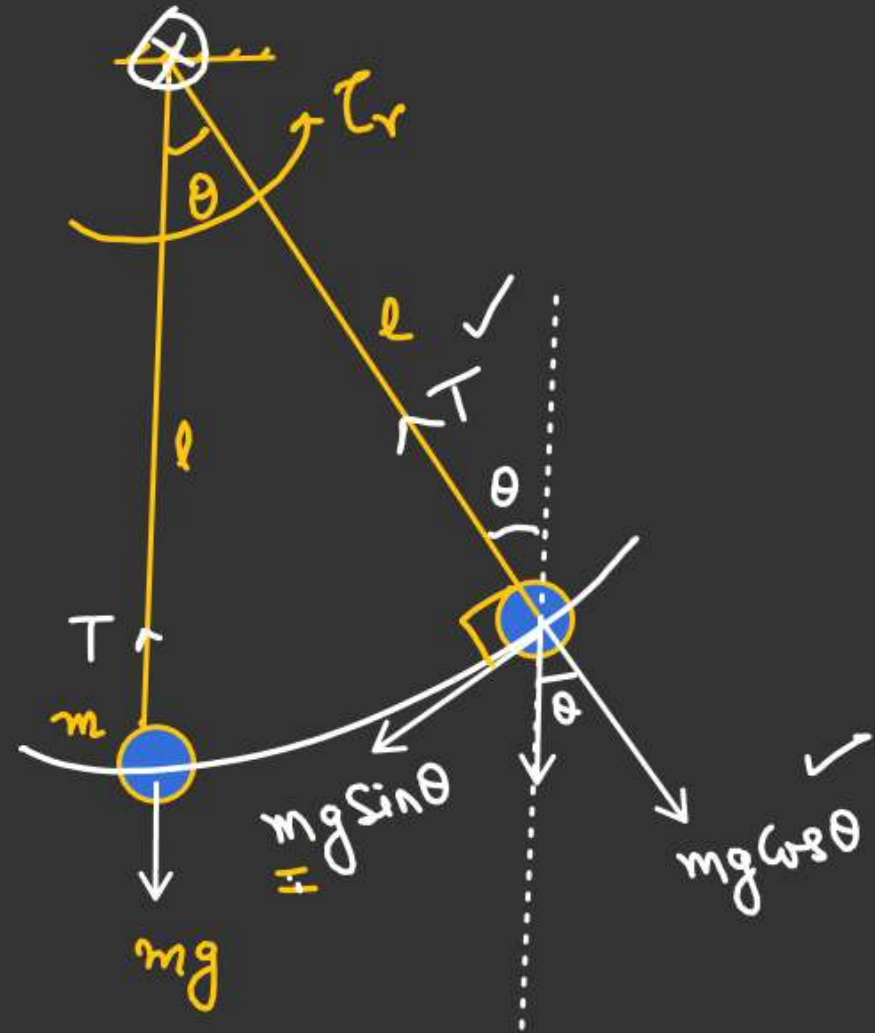
$$\alpha = -\frac{mgl\theta}{ml^2}$$

$$\alpha = -\frac{g}{l}\theta$$

$$\alpha = -\omega^2 \theta$$

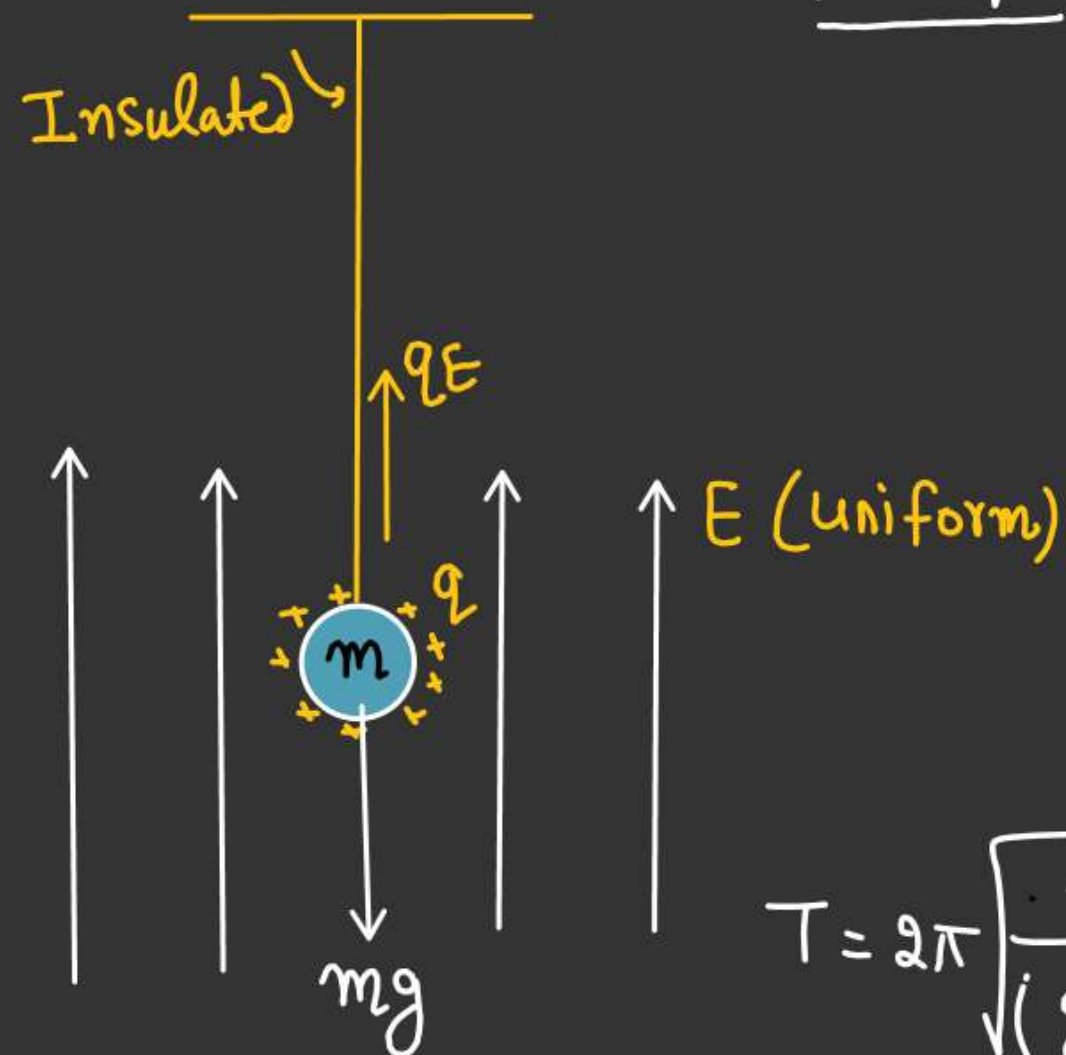
$$\omega^2 = g/l$$

$$T = 2\pi \sqrt{l/g}$$



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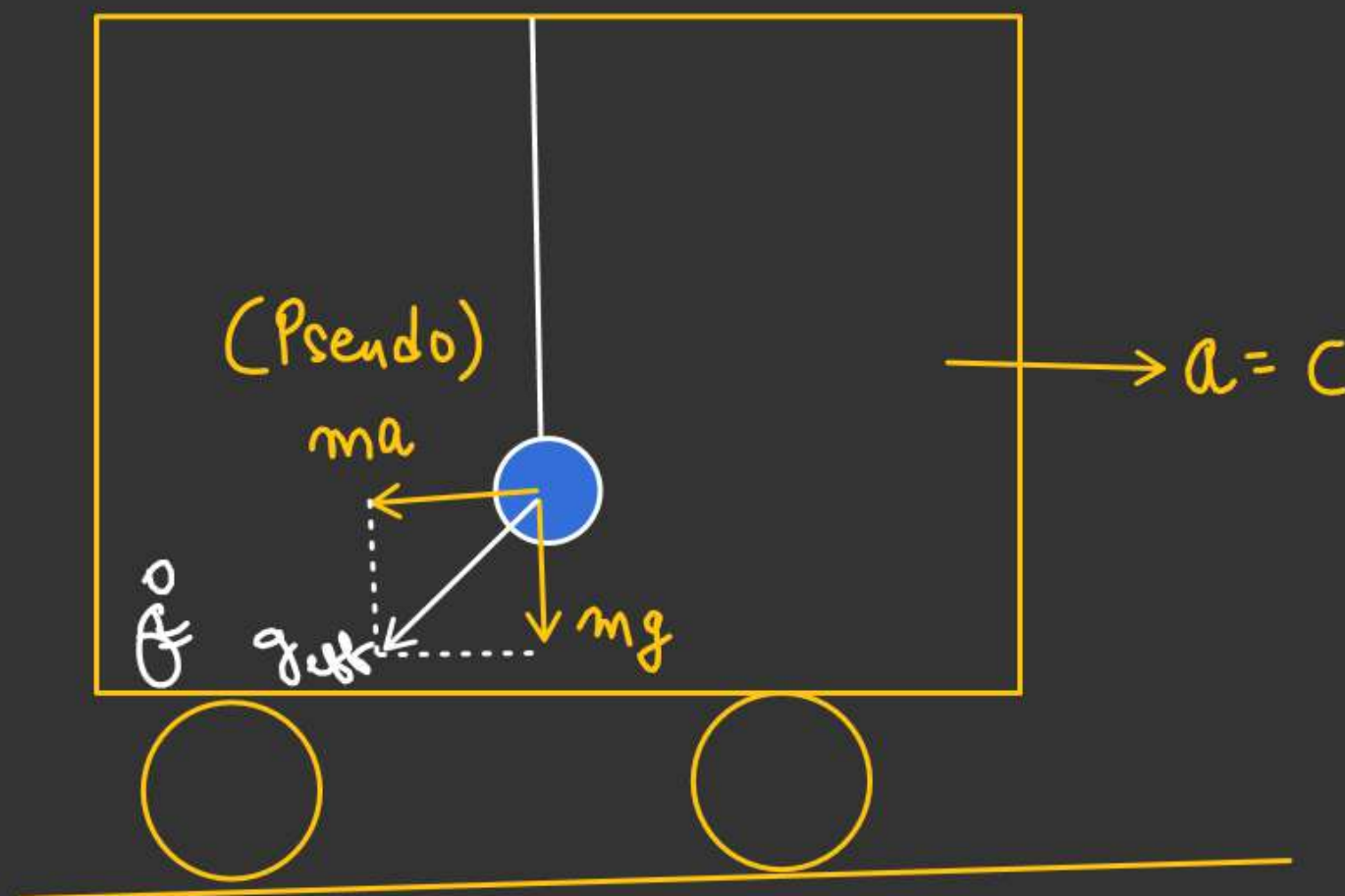
$$\vec{F} = q \vec{E}$$



$$T = 2\pi \sqrt{\frac{l}{\left(g - \frac{qE}{m}\right)}}$$

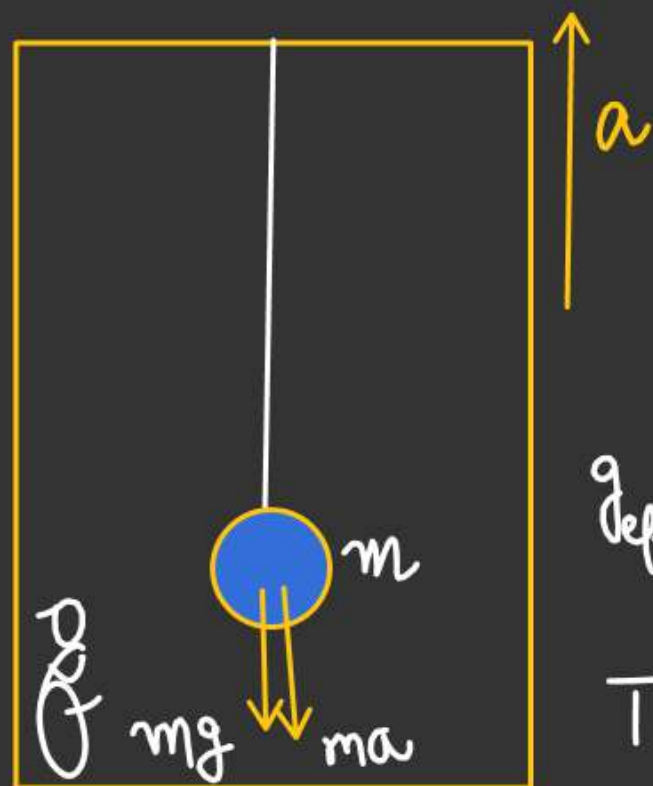
$$F_{\text{net}} = mg - qE$$

$$a_{\text{net}} = g_{\text{eff}} = \left(g - \frac{qE}{m}\right) \checkmark$$



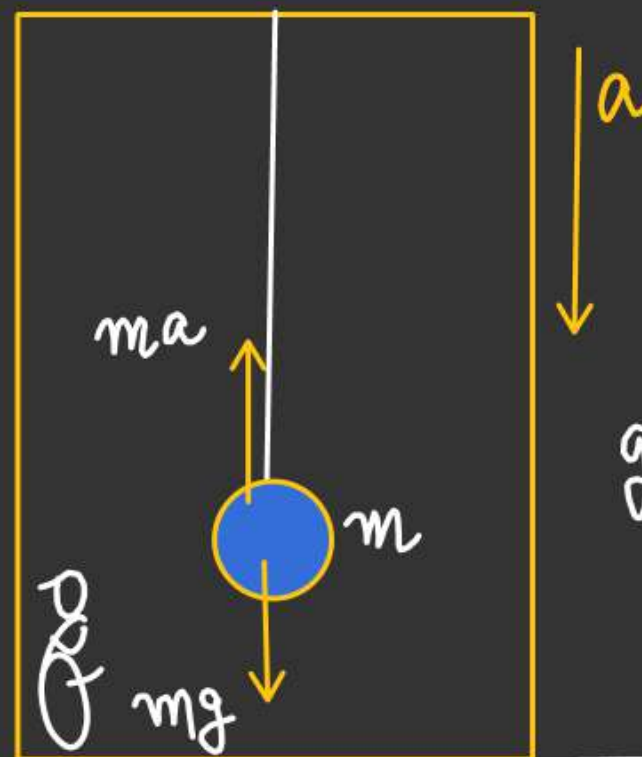
$$g_{\text{eff}} = \sqrt{g^2 + a^2}$$

$$T = 2\pi \sqrt{\frac{l}{\sqrt{g^2 + a^2}}}$$



$$g_{\text{eff}} = (g + a)$$

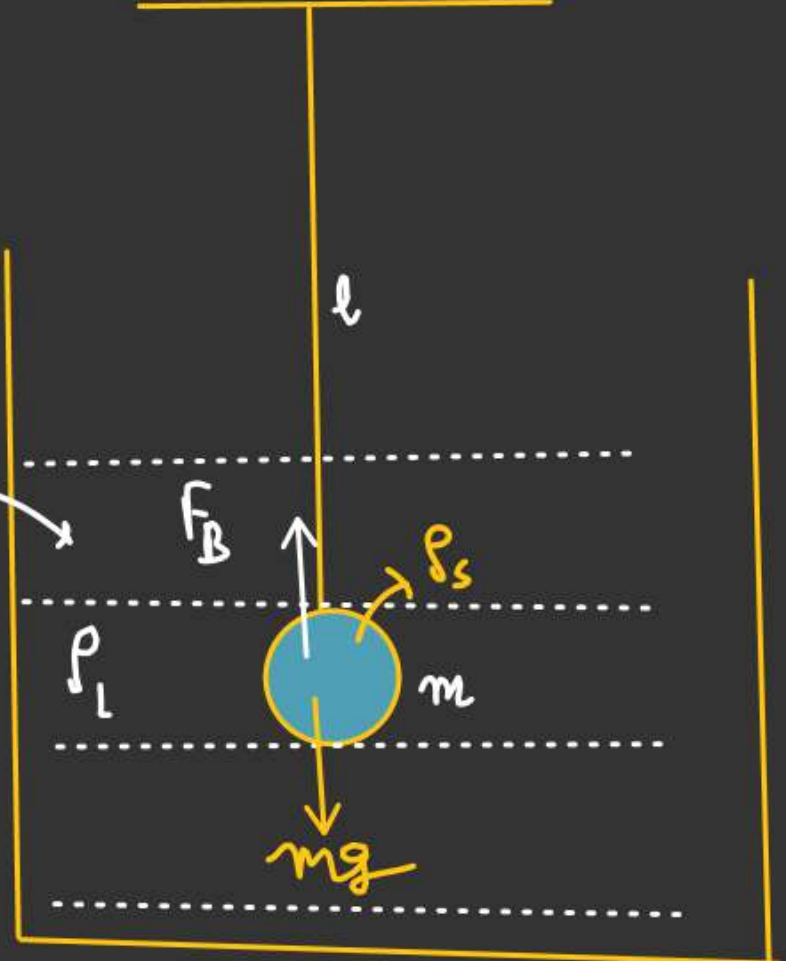
$$T = 2\pi \sqrt{\frac{l}{(g + a)}}$$



$$g_{\text{eff}} = (g - a)$$

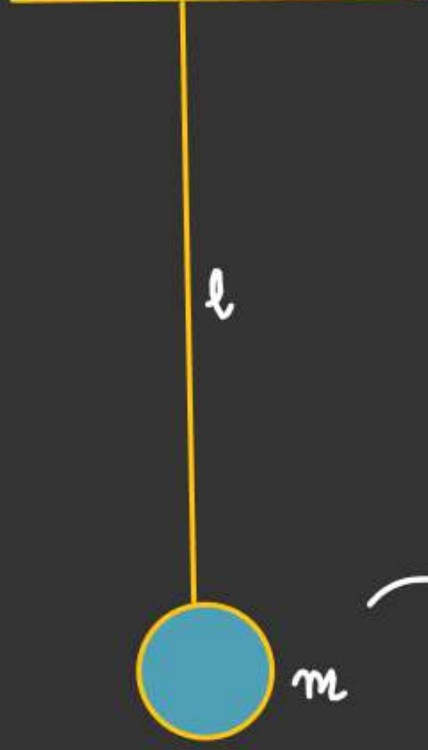
$$T = 2\pi \sqrt{\frac{l}{(g - a)}}$$

Non viscous liquid



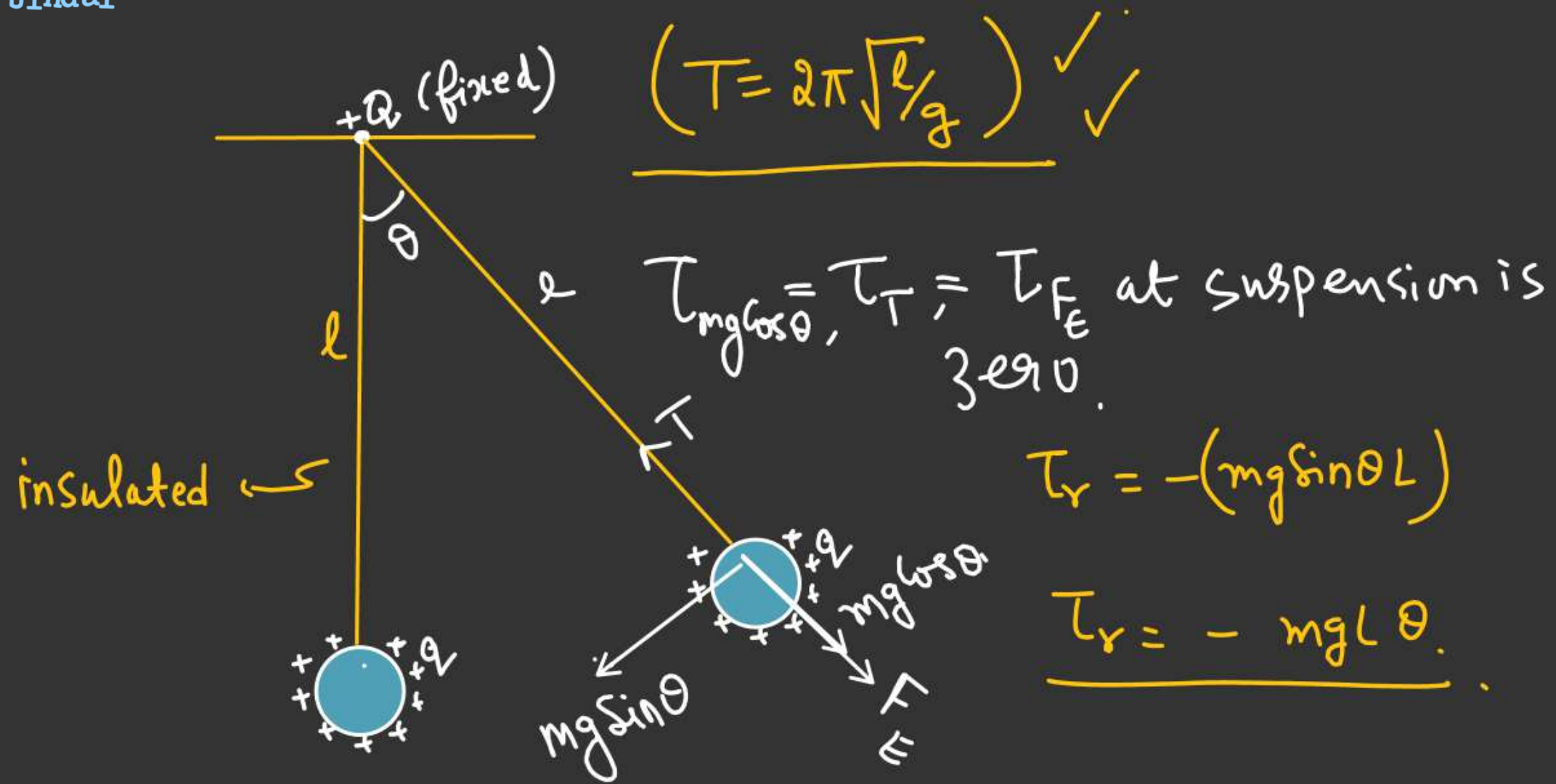
$W_{app} = W \left(1 - \frac{\rho_L}{\rho_s} \right)$
 \Downarrow
 $mg_{eff} = mg \left(1 - \frac{\rho_L}{\rho_s} \right)$
 $g_{eff} = g \left(1 - \frac{\rho_L}{\rho_s} \right)$

$T \uparrow \Rightarrow$ clock slow down
 $T \downarrow \Rightarrow$ clock become fast



$T = \frac{T_0}{\sqrt{1 - \frac{\rho_L}{\rho_s}}}$ ✓

$T = 2\pi \sqrt{\frac{l}{g \left(1 - \frac{\rho_L}{\rho_s} \right)}}$
 $T = \frac{2\pi \sqrt{\frac{l}{g}}}{\sqrt{1 - \frac{\rho_L}{\rho_s}}}$



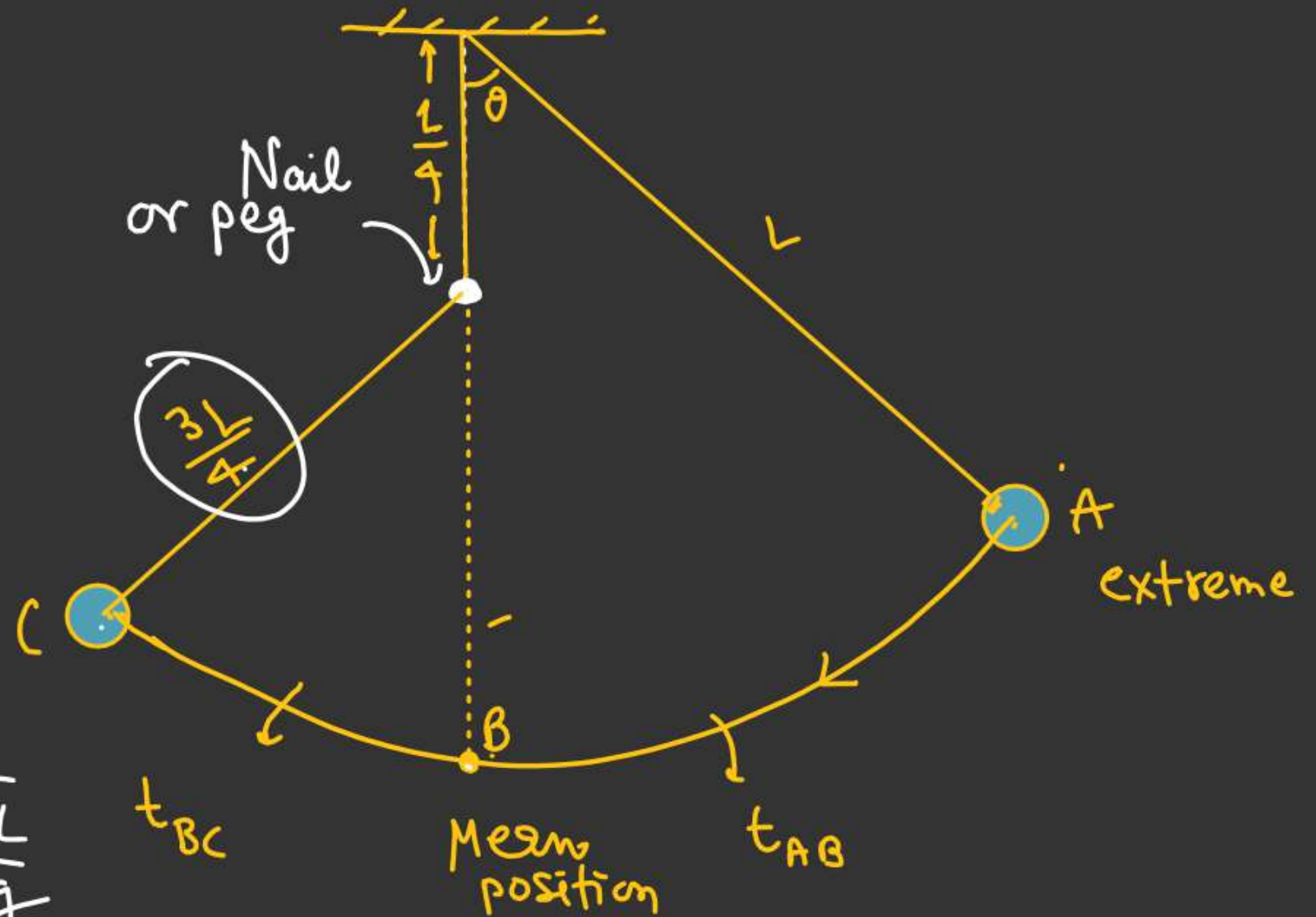
Pendulum is released from its extreme position. Find the time period of the String-bob system. Peg or Nail is at a distance $\frac{L}{4}$ from point of suspension.

$$T = 2(t_{BC} + t_{AB})$$

$$t_{AB} = \frac{T_{AB}}{4} = \frac{2\pi}{4} \sqrt{\frac{L}{g}} = \frac{\pi}{2} \sqrt{\frac{L}{g}}$$

$$t_{BC} = \frac{T_{BC}}{4} = \frac{1}{4} \times 2\pi \sqrt{\frac{3L}{4g}} = \frac{\pi}{4} \sqrt{\frac{3L}{g}}$$

$$T = 2 \left[\frac{\pi}{2} \sqrt{\frac{L}{g}} + \frac{\pi}{4} \sqrt{\frac{3L}{g}} \right] = \pi \sqrt{\frac{L}{g}} \left(1 + \frac{\sqrt{3}}{2} \right) = \frac{\pi}{2} \sqrt{\frac{L}{g}} (\sqrt{3} + 2)$$



$\beta \rightarrow$ Inclination of wall from vertical.

Find time period of the pendulum

If 1) $\theta < \beta \checkmark \rightarrow T = 2\pi \sqrt{l/g}$

2) $\theta > \beta$

Collision of bob with wall is perfectly elastic \checkmark

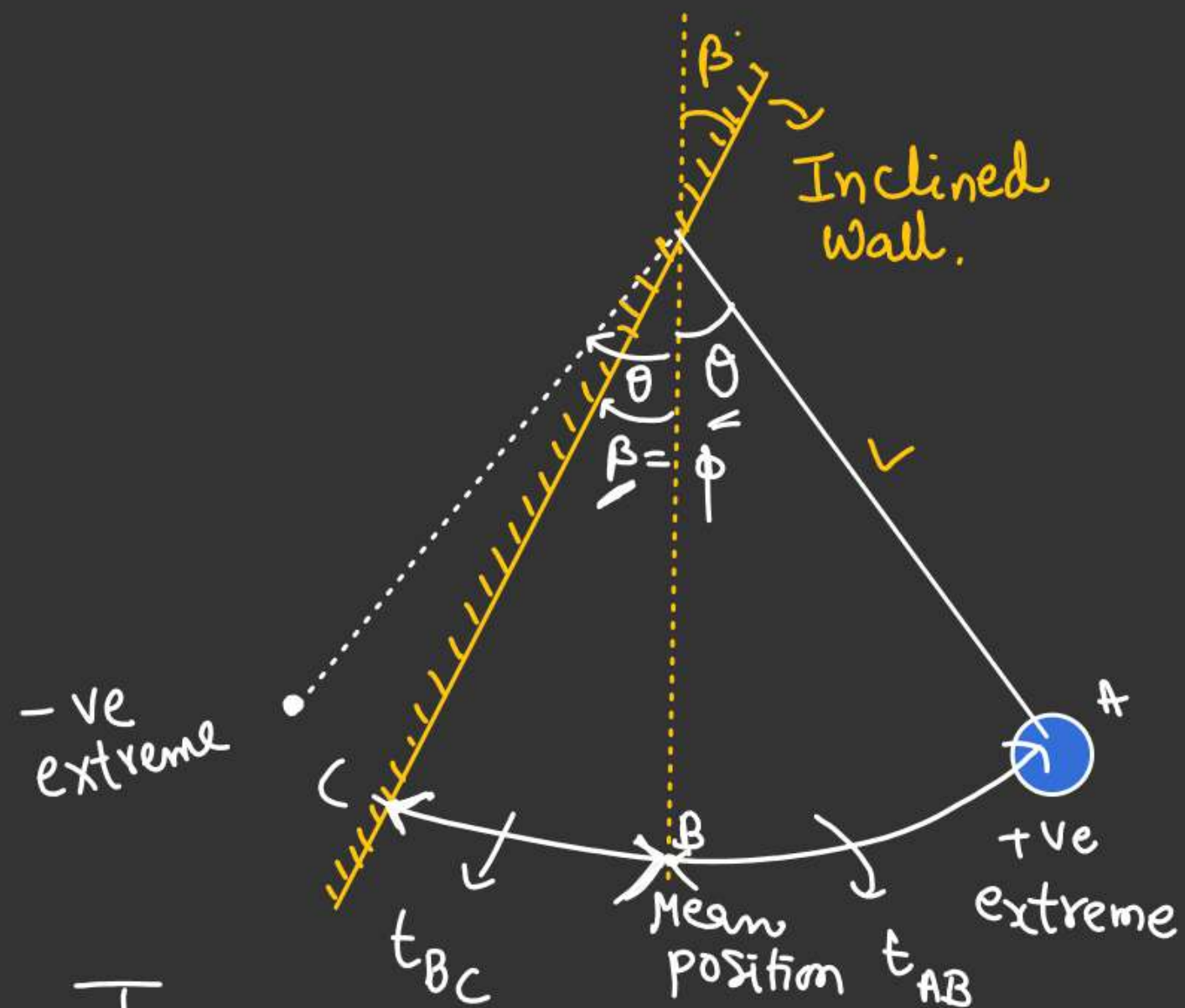
$$t_{AB} = T/4 = \frac{1}{4} \times 2\pi \sqrt{\frac{l}{g}} = \frac{\pi}{2} \sqrt{\frac{l}{g}}$$

$$t_{BC} = ?? \quad [\phi = \theta_{\max} \sin \omega t]$$

$$\beta = \theta \sin \omega t_{BC}$$

$$\sin \omega t_{BC} = (\beta/\theta) \quad \left[t_{BC} = \frac{1}{\omega} \sin^{-1} \left(\frac{\beta}{\theta} \right) \right]$$

$$\omega t_{BC} = \sin^{-1} \left(\frac{\beta}{\theta} \right) \quad \left[\underline{t_{BC} = \frac{1}{\omega} \sin^{-1} \left(\frac{\beta}{\theta} \right)} \right] = \pi \sqrt{\frac{l}{g}} + \frac{2}{\omega} \sin^{-1} \left(\frac{\beta}{\theta} \right)$$



$$T = 2(t_{AB} + t_{BC})$$

△△

Case of Simple pendulum when length of the string is comparable w.r.t radius of earth.

$$F_r = - \left[mg \sin \phi + T' \sin \theta \right]$$

For vertical Equilibrium

$$T' \cos \theta = mg \cos \phi$$

θ & ϕ are very small

$$\sin \phi \approx \phi$$

$$\sin \theta \approx \theta$$

$$\cos \phi \rightarrow 1, \phi \rightarrow 0$$

$$\cos \theta \rightarrow 1, \theta \rightarrow 0$$

$$(T' = mg)$$

$$F_r = - mg [\phi + \theta]$$

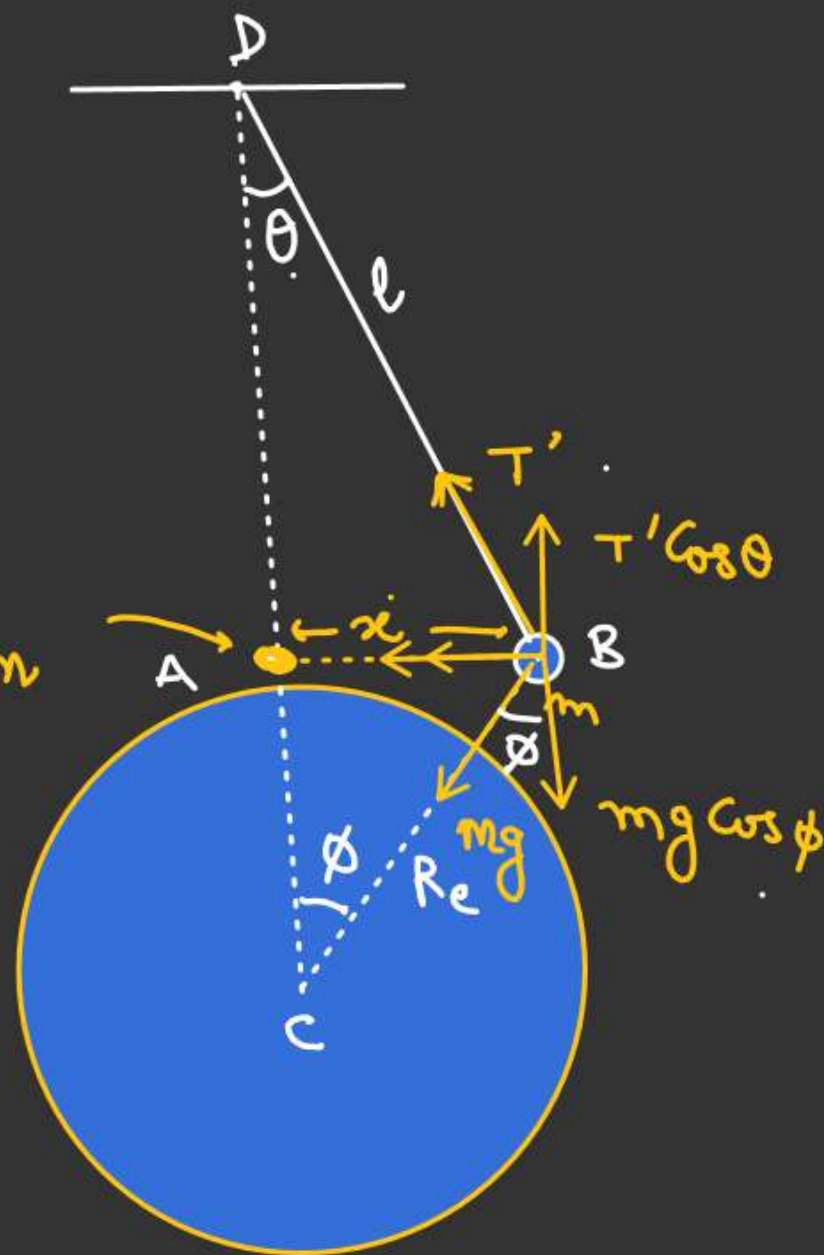
$$a = -g [\theta + \phi] \quad \underline{a \propto x}$$

$$a = -g \left[\frac{1}{l} + \frac{1}{R_e} \right] x$$

$$a = -\omega^2 x$$

$$\left[\begin{array}{l} \text{In } \triangle DAB \\ \sin \theta \approx \theta = \frac{x}{l} \\ \text{In } \triangle ABC \\ \sin \phi \approx \phi = \frac{x}{R_e} \end{array} \right]$$

Mean position



△△

$$a = -g \left[\frac{1}{l} + \frac{1}{R_e} \right] x$$

$$a = -\omega^2 x \quad \text{Compare}$$

$$\omega = \sqrt{g \left(\frac{1}{l} + \frac{1}{R_e} \right)}$$

$$T = \frac{2\pi}{\sqrt{g \left(\frac{1}{l} + \frac{1}{R_e} \right)}}$$

$$T = \frac{2\pi}{\sqrt{\frac{g}{l} \left(1 + \frac{l}{R_e} \right)}}$$

$$\Rightarrow T = \frac{2\pi \sqrt{l/g}}{\sqrt{1 + l/R_e}}$$

$$T = \left(\frac{T_0}{\sqrt{1 + l/R_e}} \right)$$

if $l \ll R_e$

$$\frac{l}{R_e} \rightarrow 0$$

$$T = T_0 \quad \checkmark$$



physical pendulum

Any Rigid body oscillating about any point of suspension.

$$\tau_r = -(mg \sin \theta) d$$

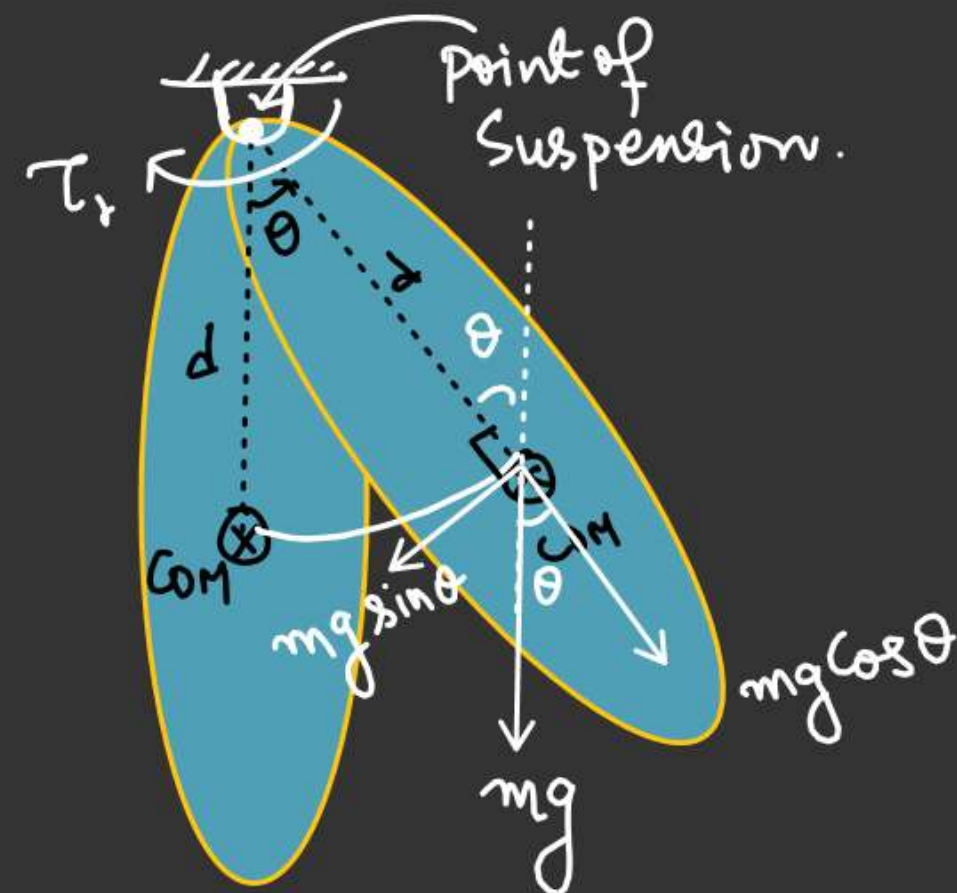
$$\theta = \text{very small}$$

$$\sin \theta \approx \theta$$

$$\alpha = \frac{\tau_r}{I} = - \left(\frac{mgd}{I} \right) \theta$$

$$\alpha = - \omega^2 \theta$$

$$\omega = \sqrt{\frac{mgd}{I}} \Rightarrow T = 2\pi \sqrt{\frac{I}{mgd}}$$



I = M.I of body about axis passing through point of suspension
 d = distance b/w COM & point of suspension.

* $T = ?$ M, L

$$T = 2\pi \sqrt{\frac{I}{mgd}}$$

$$I = I_{com} + M\left(\frac{L}{4}\right)^2$$

$$I = \left(\frac{ML^2}{12} + \frac{ML^2}{16}\right)$$

$$I = \left(\frac{7ML^2}{48}\right)$$

$$T = 2\pi \sqrt{\frac{\frac{7ML^2}{48} \times M \times g \times \frac{L}{4}}{}}$$

$$T = 2\pi \sqrt{\frac{7L}{12g}}$$

Hinged



$$\frac{12, 16}{3, 4}$$

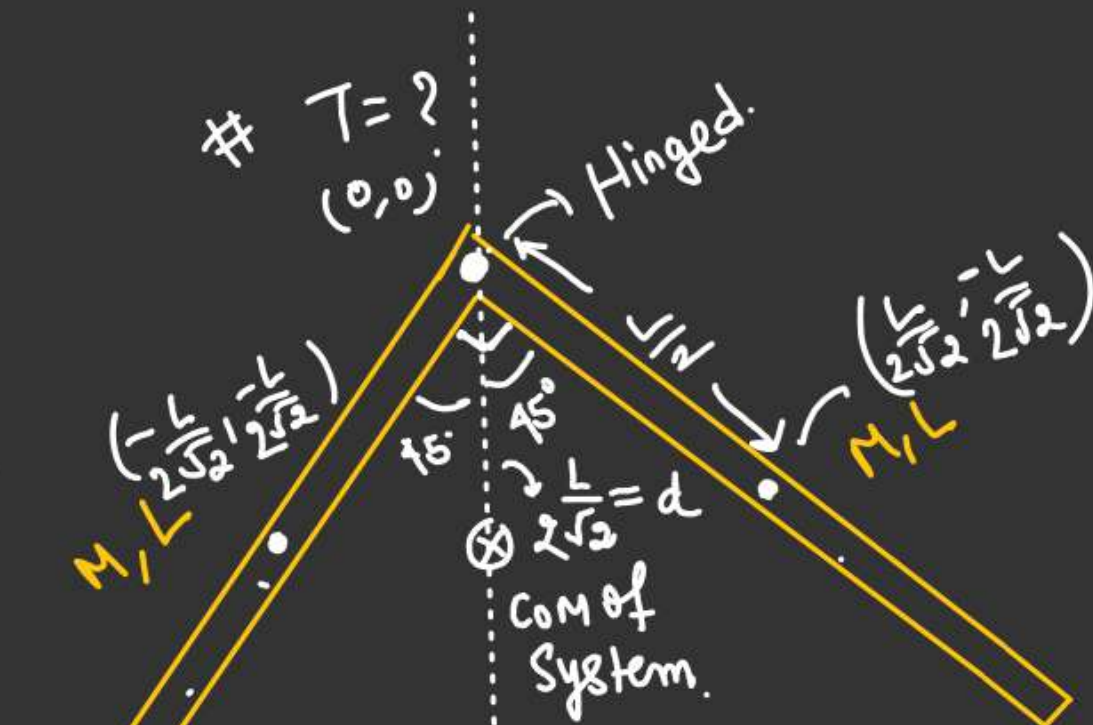
$$d = \frac{L}{2\sqrt{2}}$$

$$I = \frac{ML^2}{3} \times 2$$

$$I = \left(\frac{2ML^2}{3}\right)$$

$$T = 2\pi \sqrt{\frac{\frac{2ML^2}{3} \times (2M) \times g \times \frac{L}{2\sqrt{2}}{}}$$

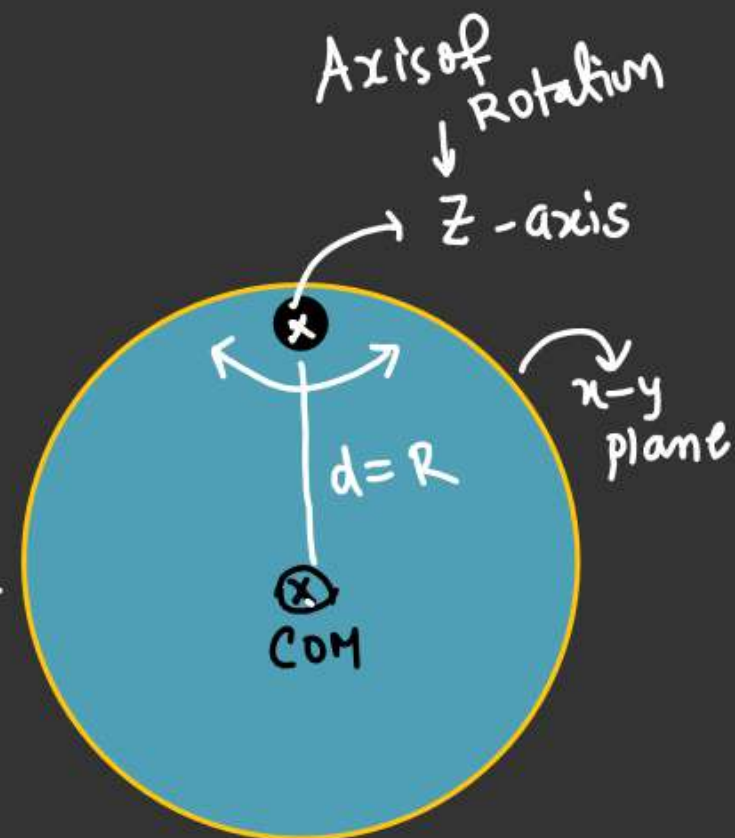
$$T = \left(2\pi \sqrt{\frac{2\sqrt{2}L}{3g}}\right) \checkmark$$



$$y_{com} = \frac{m\left(-\frac{L}{2\sqrt{2}}\right) - m\frac{L}{2\sqrt{2}}}{2m}$$

$$y_{com} = -\frac{2mL}{2\sqrt{2} \times 2m}$$

$$= \left(-\frac{L}{2\sqrt{2}}\right)$$



Find the ratio of time period of the uniform disc.

T_1 be the time period when disc oscillate in the plane of disc.

T_2 be the time period when disc oscillate perpendicular to the plane of disc

$$\frac{T_1}{T_2} = ?$$

$$I_1 = \frac{MR^2}{2} + MR^2 = \frac{3}{2}MR^2$$

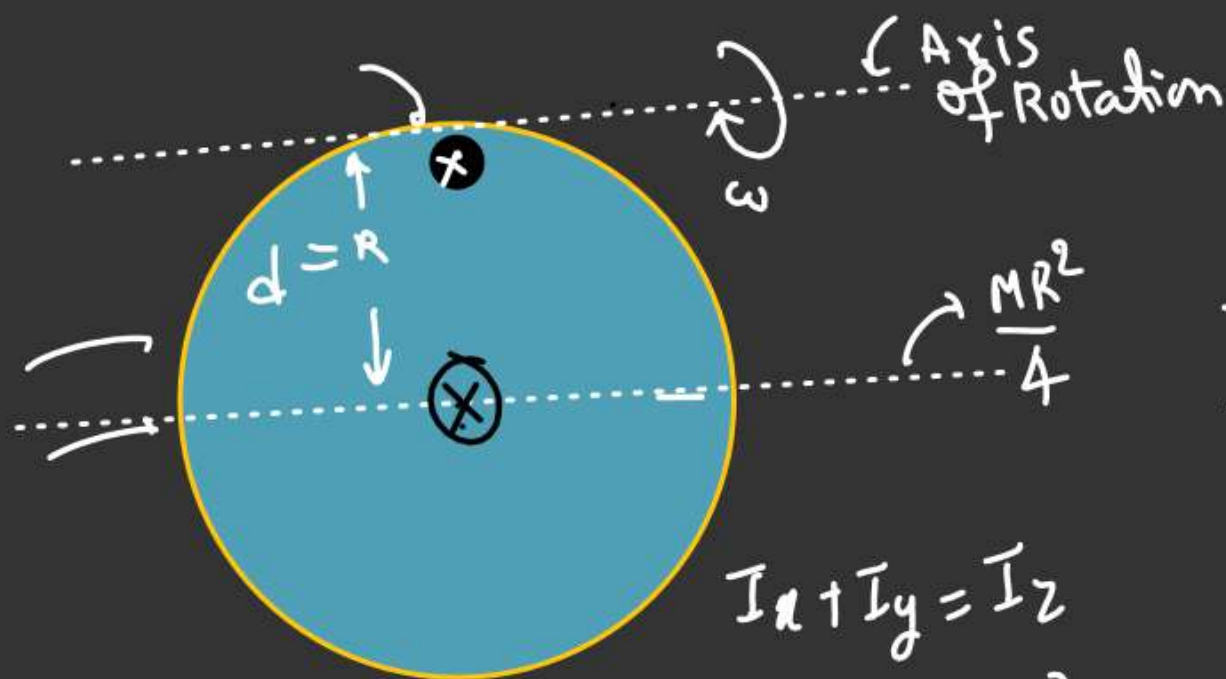
$$I_2 = \frac{MR^2}{4} + MR^2 = \frac{5}{4}MR^2$$

$$T_1 = 2\pi \sqrt{\frac{I_1}{mgR}}$$

$$T_2 = 2\pi \sqrt{\frac{I_2}{mgR}}$$

$$\frac{T_1}{T_2} = \sqrt{\frac{I_1}{I_2}}$$

$$\frac{T_1}{T_2} = \sqrt{\frac{3}{2} \times \frac{4}{5}} = \sqrt{\frac{6}{5}} \checkmark$$



$$I_x = I_y$$

$$I_x + I_y = I_z$$

$$2I_x = \frac{MR^2}{2}$$

$$I_x = \frac{MR^2}{4}$$

