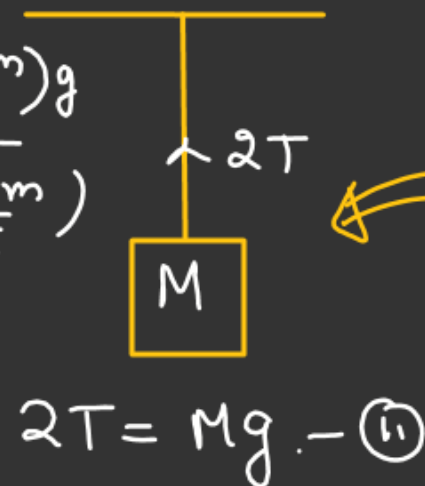


$$m_{eq} = \frac{4 \times 2m \times 3m}{5m}$$

$$m_{eq} = \frac{24m}{5}$$

$$T = \frac{2m \left(\frac{24m}{5} \right) g}{\left(m + \frac{24m}{5} \right)}$$

$$T = \frac{48mg}{29}$$



$$2T = Mg \quad \text{--- (i)}$$

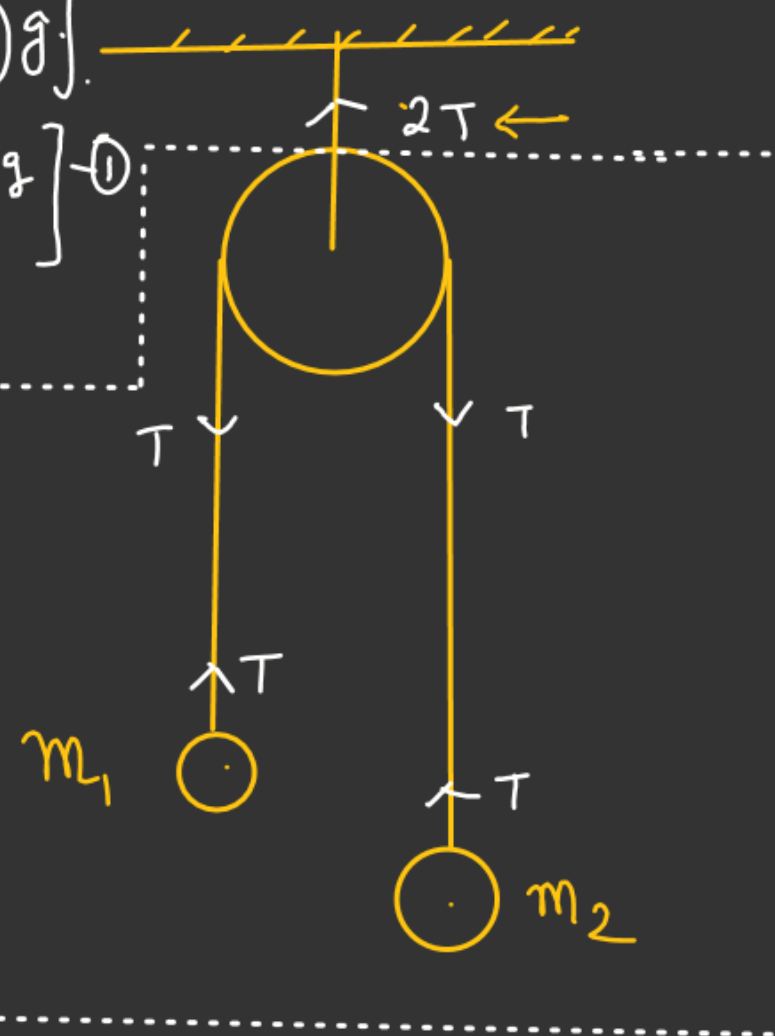
$$\frac{4m_1m_2g}{m_1+m_2} = Mg$$

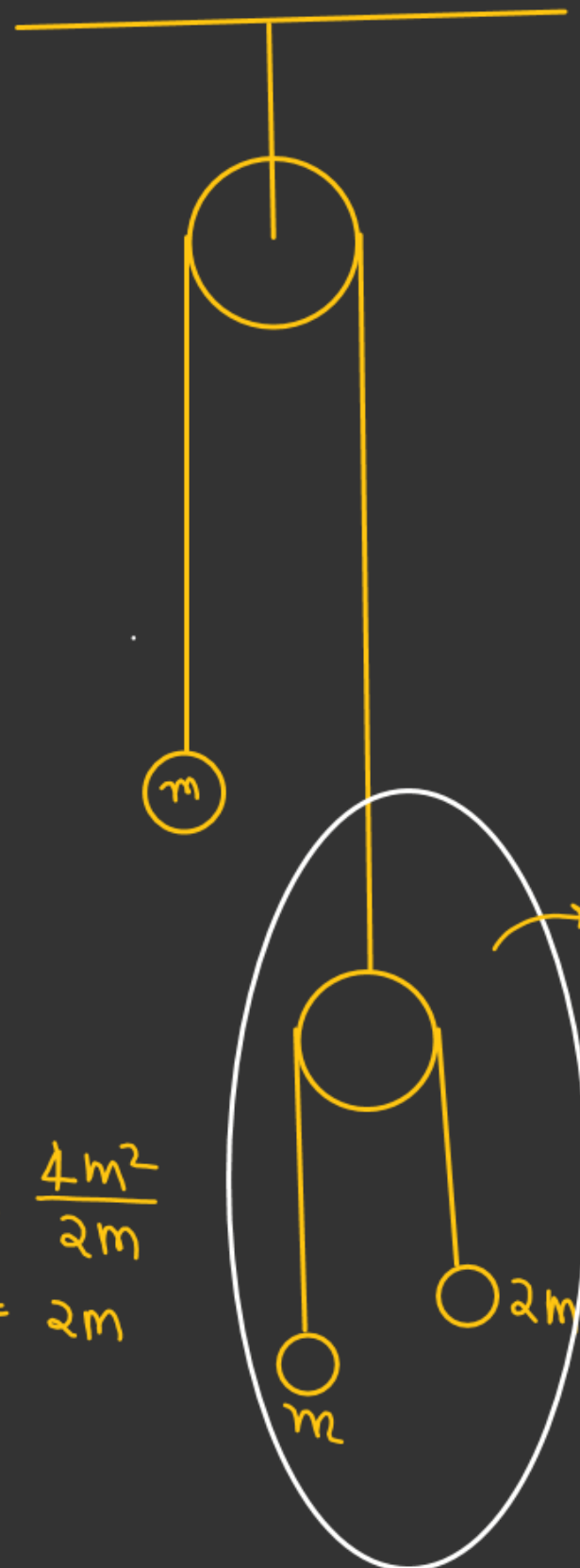
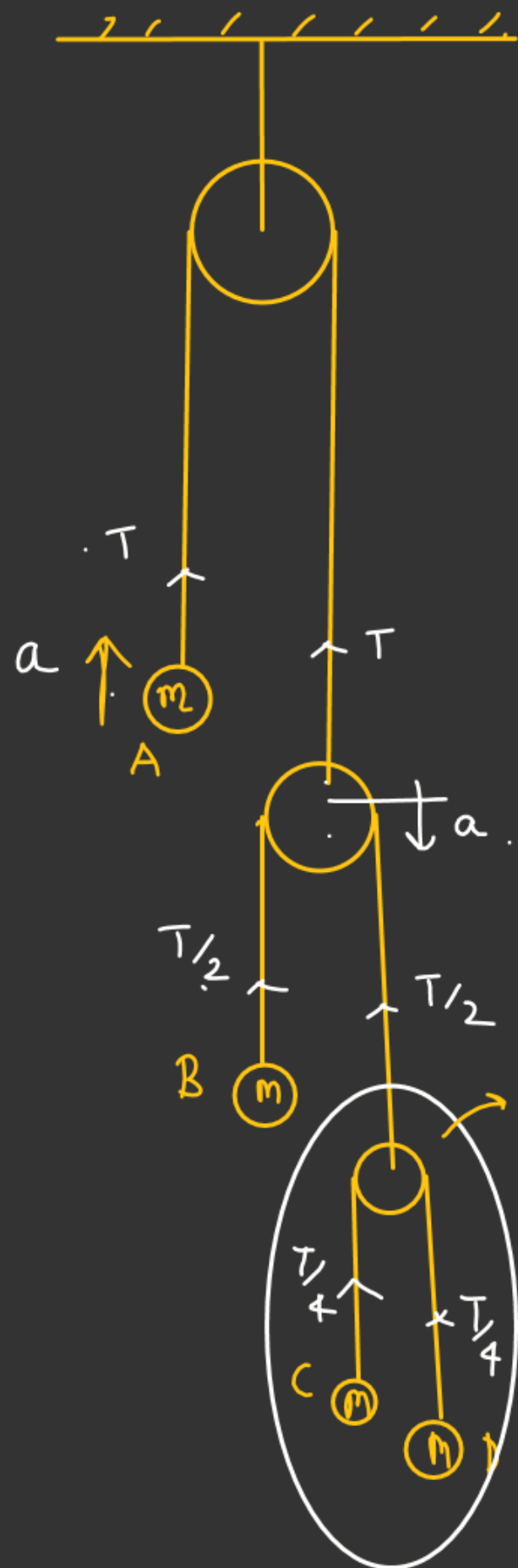
$$M = \frac{4m_1m_2}{m_1+m_2} \quad \checkmark$$

Equivalent mass.
which should be
replaced by atwood
Machine set-up.

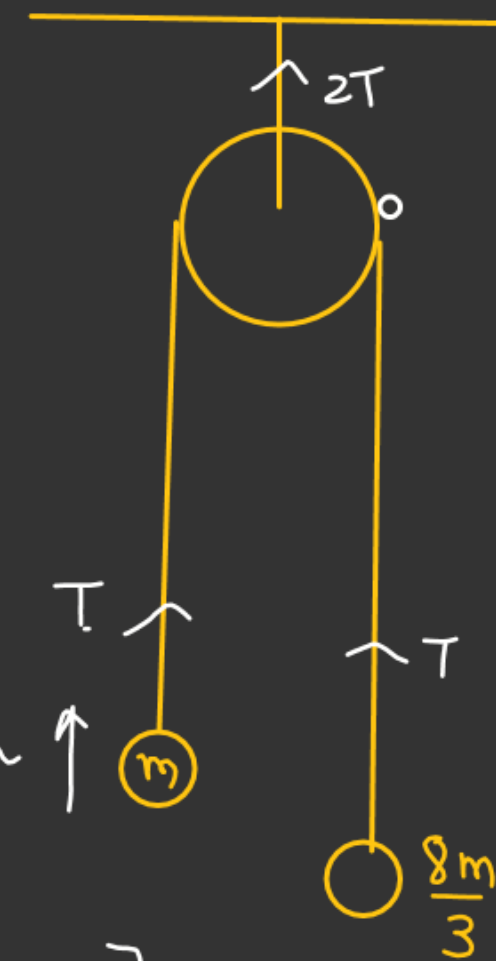
$$\left[a = \left(\frac{m_2 - m_1}{m_1 + m_2} \right) g \right]$$

$$T = \left[\frac{2m_1m_2g}{m_1+m_2} \right] \quad \text{--- (ii)}$$





$$m_{eq} = \left[\frac{4m \cdot (2m)}{m + 2m} \right] = \frac{8m}{3}$$

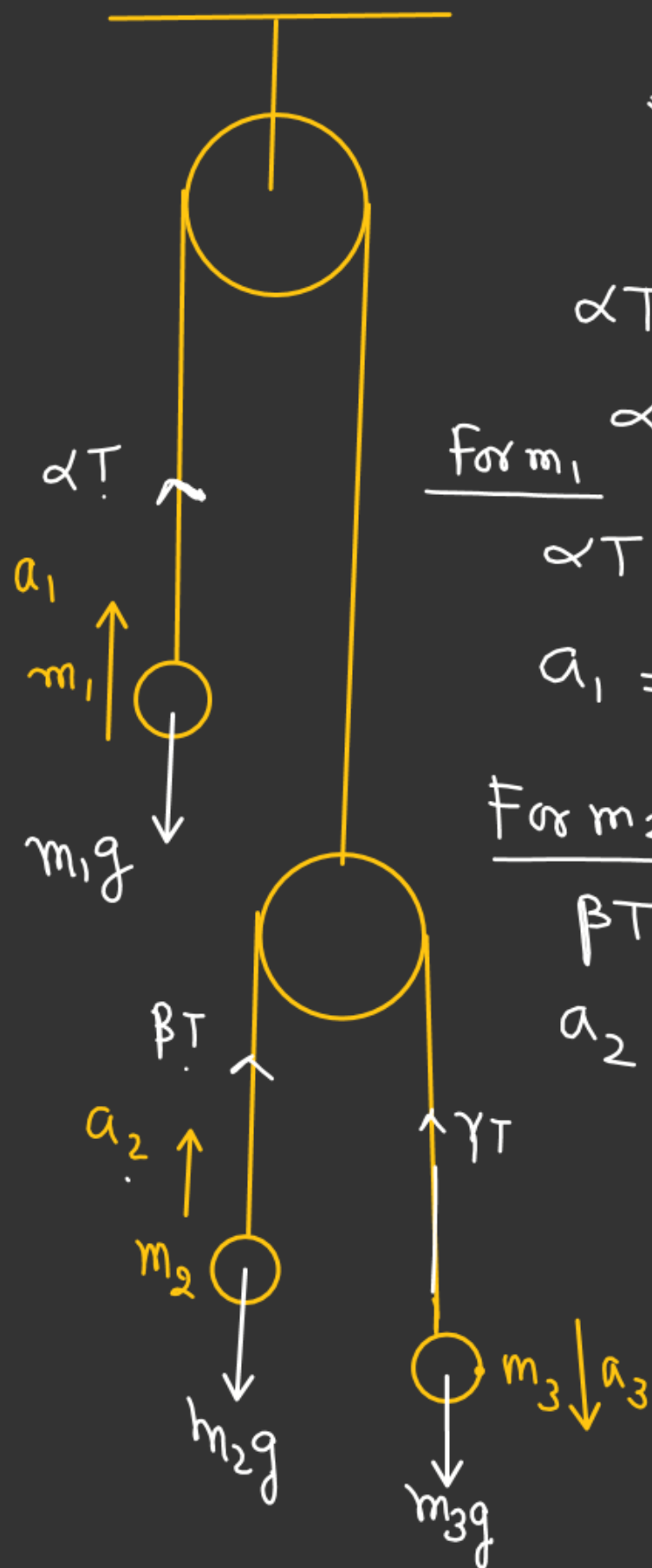


$$a = \left[\frac{\frac{8m}{3} - m}{\frac{8m}{3} + m} \right] g$$

$$a = \left(\frac{5g}{11} \right)$$

$$T = \frac{2m \left(\frac{8m}{3} \right) g}{\left(m + \frac{8m}{3} \right)}$$

$$T = \left(\frac{16mg}{11} \right)$$

Q.8

$$\sum \vec{T} \cdot \vec{a} = 0$$

$$\alpha T \cdot a_1 + \beta T a_2 - \gamma T a_3 = 0$$

For m_1

$$\alpha a_1 + \beta a_2 - \gamma a_3 = 0 \quad \text{--- (1)}$$

$$\alpha T - m_1 g = m_1 a_1$$

$$a_1 = \left[\frac{\alpha T}{m_1} - g \right] \checkmark$$

For m_2

$$\beta T - m_2 g = m_2 a_2$$

$$a_2 = \left(\frac{\beta T}{m_2} - g \right) \checkmark$$

Put value of $a_1, a_2 \leftarrow a_3$
in Eqⁿ (1)

$$\alpha \left[\frac{\alpha T}{m_1} - g \right] + \beta \left[\frac{\beta T}{m_2} - g \right] - \gamma \left[g - \frac{\gamma T}{m_3} \right] = 0$$

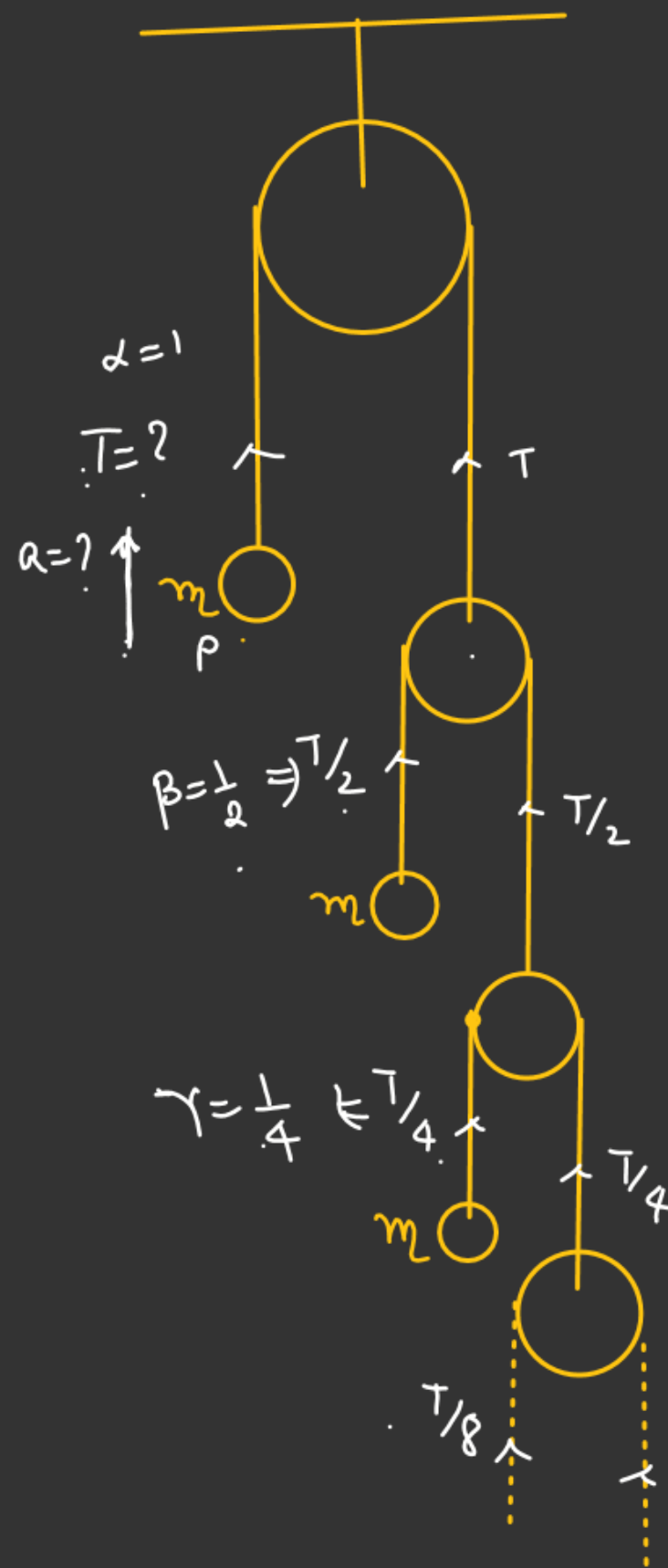
$$\left[\frac{\alpha^2}{m_1} + \frac{\beta^2}{m_2} + \frac{\gamma^2}{m_3} \right] T = (\alpha + \beta + \gamma) g$$

For m_3

$$m_3 g - \gamma T = m_3 a_3$$

$$a_3 = \left(g - \frac{\gamma T}{m_3} \right) \checkmark$$

$$T = \frac{(\alpha + \beta + \gamma) g}{\frac{\alpha^2}{m_1} + \frac{\beta^2}{m_2} + \frac{\gamma^2}{m_3}}$$



$$T = \frac{\left[1 + \frac{1}{2} + \frac{1}{4} + \frac{1}{8} + \dots + \infty\right]g}{\left[\frac{1}{m} + \left(\frac{1}{2}\right)^2 \cdot \frac{1}{m} + \left(\frac{1}{4}\right)^2 \cdot \frac{1}{m} + \dots + \infty\right]} \quad T = \frac{(\alpha + \beta + \gamma + \dots)g}{\left[\frac{\alpha^2}{m_1} + \frac{\beta^2}{m_2} + \frac{\gamma^2}{m_3} + \dots\right]} \checkmark$$

$$T = \frac{mg \left[1 + \frac{1}{2} + \frac{1}{4} + \frac{1}{8} + \dots + \infty\right]}{\left[1 + \left(\frac{1}{2}\right)^2 + \left(\frac{1}{2}\right)^4 + \left(\frac{1}{2}\right)^6 + \dots + \infty\right]}$$

$$T = \frac{mg \left[\frac{1}{1 - 1/2}\right]}{\left[\frac{1}{1 - (1/2)^2}\right]} \Rightarrow T = \frac{2mg}{\left(\frac{4}{3}\right)} = \frac{3mg}{2}$$

Free body diagram of a mass m with tension $T = \frac{3mg}{2}$ acting upwards and weight mg acting downwards. The acceleration is a .

$$\frac{3mg}{2} - mg = ma$$

$a = g/2$

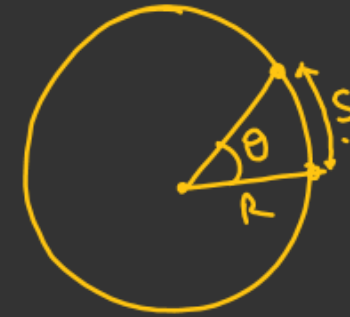
→ up to infinity

SS:

Angular velocity b/w two particles.

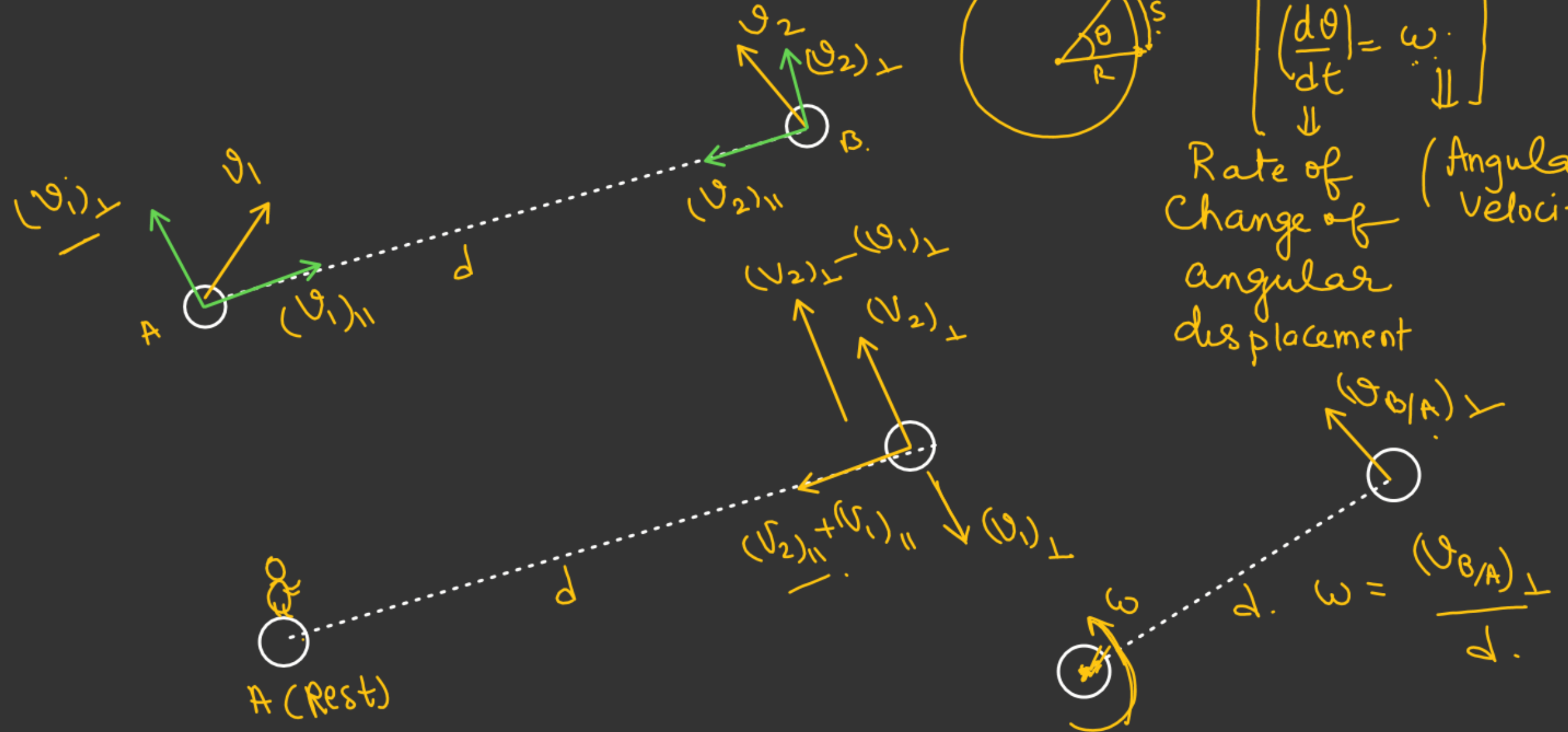
$$s = R\theta$$

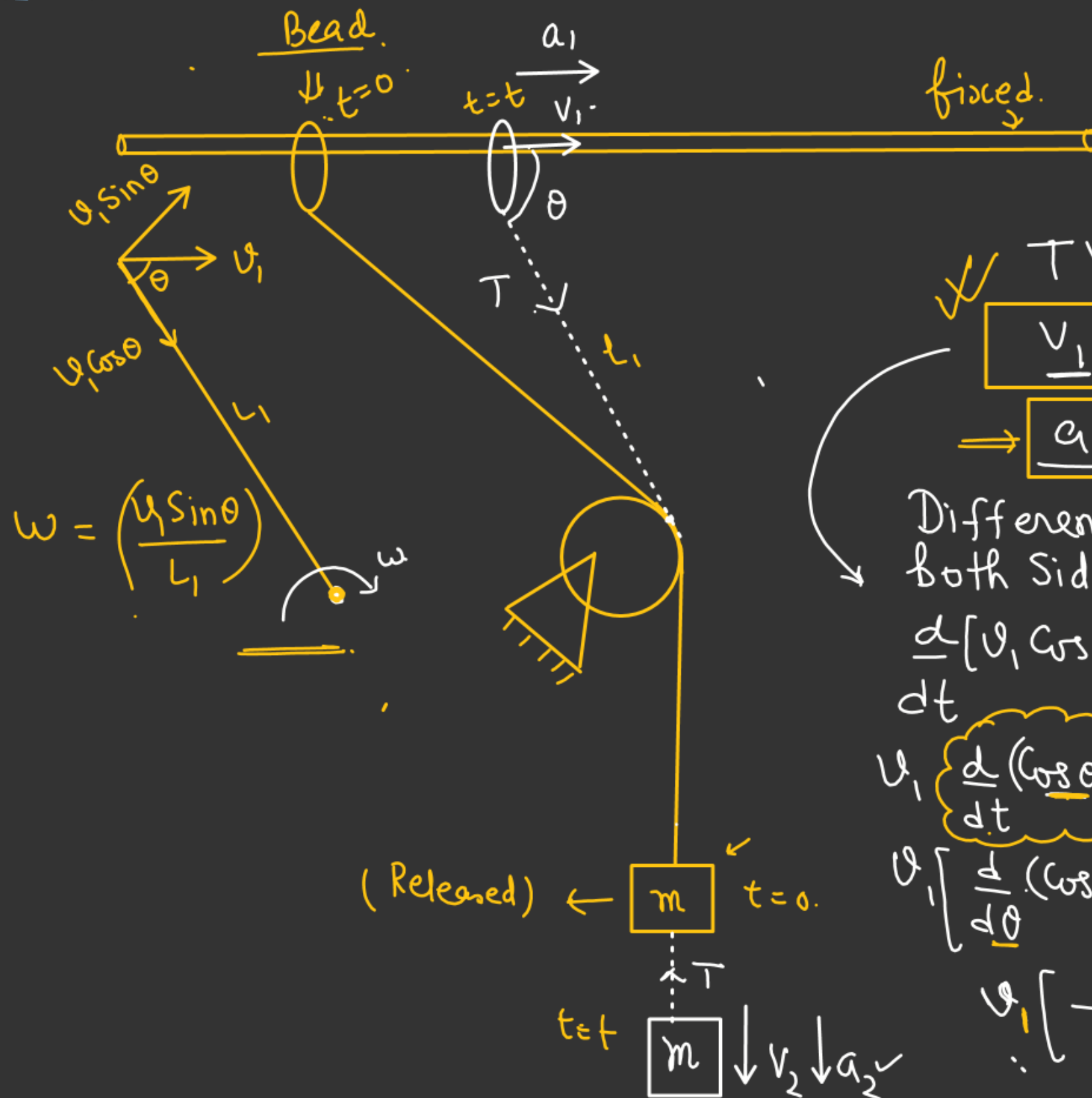
$$v = R\omega$$



$$\left[\begin{array}{l} \frac{dx}{dt} = v \\ \left(\frac{d\theta}{dt} \right) = \omega \\ \Downarrow \end{array} \right]$$

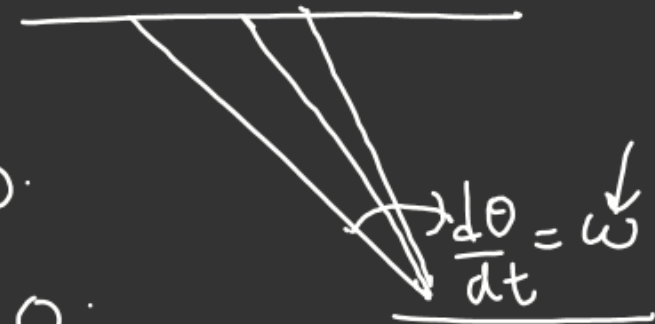
Rate of Change of angular displacement (Angular Velocity)





$$\frac{dy}{dt} \rightarrow \left(\frac{dy}{dx} \times \frac{dx}{dt} \right) \quad y=f(x)$$

$$\sum \vec{T} \cdot \vec{V} = 0$$



$$T v_1 \cos \theta - T v_2 = 0$$

$$\boxed{v_1 \cos \theta = v_2} \quad \times$$

$$\Rightarrow \boxed{a_1 \cos \theta = a_2} \quad \times \Rightarrow \theta \rightarrow \text{Changing}$$

Differentiating both side w.r.t time

$$\frac{d[v_1 \cos \theta]}{dt} = \left(\frac{dv_2}{dt} \right)$$

$$v_1 \left(\frac{d(\cos \theta)}{dt} \right) + \cos \theta \cdot \left(\frac{dv_1}{dt} \right) = a_2$$

$$v_1 \left[\frac{d}{d\theta} (\cos \theta) \cdot \left(\frac{d\theta}{dt} \right) + (\cos \theta) a_1 \right] = a_2$$

$$v_1 \left[-(\sin \theta) \omega \right] + a_1 \cos \theta = a_2$$

$$\sum \vec{T} \cdot \vec{a} \Rightarrow \text{Not applicable}$$

$$a_2 = a_1 \cos \theta - v_1 \omega \sin \theta$$

$$a_2 = \left(a_1 \cos \theta - \frac{v_1^2 \sin^2 \theta}{L_1} \right)$$

if $v_1 = 0$ i.e. at initial condition

$$\underline{a_2 = a_1 \cos \theta [t=0]}$$