

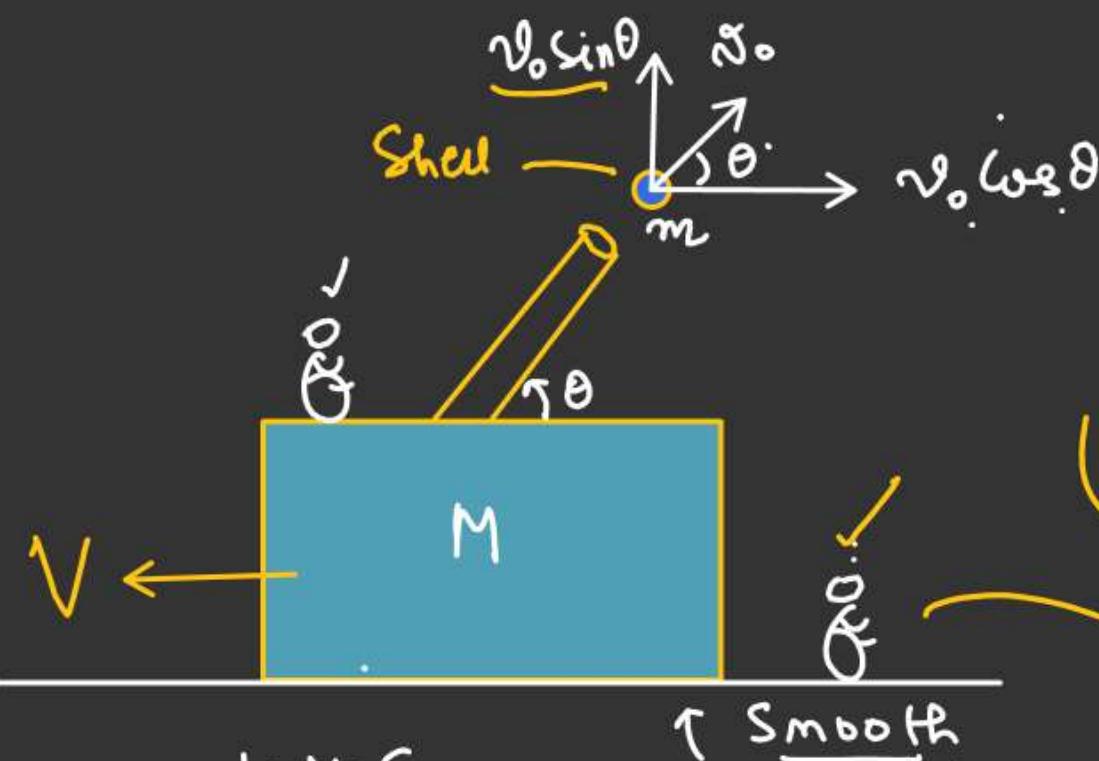
Case of firing of Shell through a Cannon

v_0 = velocity of shell w.r.t
Cannon ✓

$$(\vec{v}_{\text{shell}/\text{E}})_x = (\vec{v}_{\text{shell/cannon}})_x + (\vec{v}_{\text{cannon/E}})_x$$

$$(\vec{v}_{\text{shell/E}})_x = (v_0 \cos \theta \hat{i} - v \hat{i}) \quad \text{L.M.C.}$$

$$(\vec{v}_{\text{shell/E}})_y = v_0 \sin \theta \hat{j}$$



$$(\vec{F}_i)_x = (\vec{F}_f)_x$$

$$0 = m(v_0 \cos \theta - v) - Mv \quad \beta = ??$$

$$(M+m)v = m v_0 \cos \theta$$

$$V = \left(\frac{m v_0 \cos \theta}{M+m} \right)$$

$\omega \cdot r \cdot t$ earth

Angle made by
Shell with horizontal

$(\vec{v}_{\text{shell/E}})_x$

$(\vec{v}_{\text{shell/E}})_y$

$\tan \beta = \left(\frac{v_0 \sin \theta}{v_0 \cos \theta - V} \right)$



L.M.C IN COM FRAME

By Δ Law.

$$\vec{r}_{P/\mathcal{E}} = \vec{r}_{P/COM} + \vec{r}_{COM/\mathcal{E}}$$

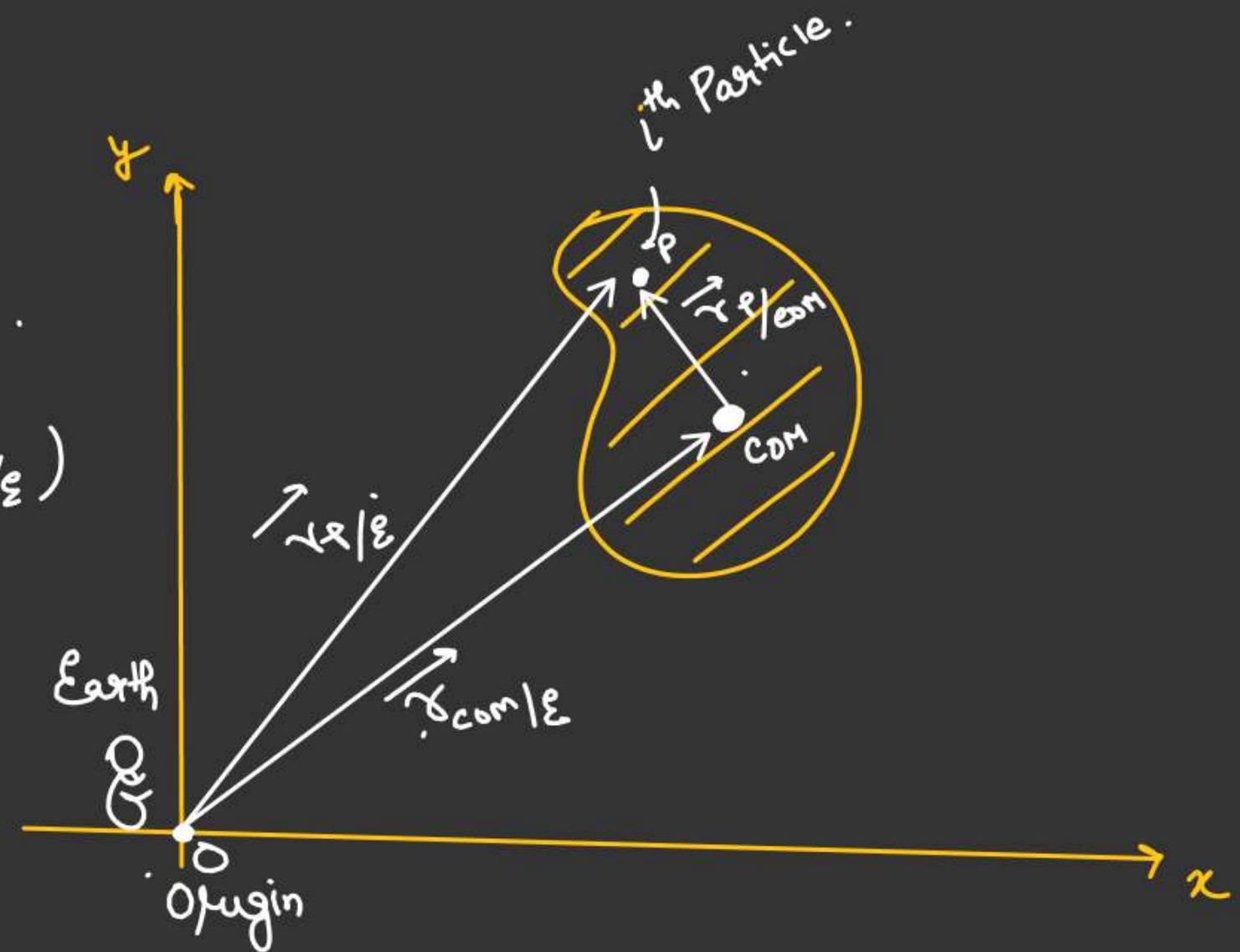
Differentiating both side w.r.t time.

$$\frac{d}{dt}(\vec{r}_{P/\mathcal{E}}) = \frac{d}{dt}(\vec{r}_{P/COM}) + \frac{d}{dt}(\vec{r}_{COM/\mathcal{E}})$$

\Downarrow

$$\vec{v}_{P/\mathcal{E}} = \underbrace{\vec{v}_{P/COM}}_{\Downarrow} + \vec{v}_{COM/\mathcal{E}}$$

Relative velocity
of P w.r.t COM



L.M.C IN COM FRAME

$$\vec{v}_{P/E} = \vec{v}_{P/COM} + \vec{v}_{COM/E}$$

Relative velocity
of P w.r.t COM

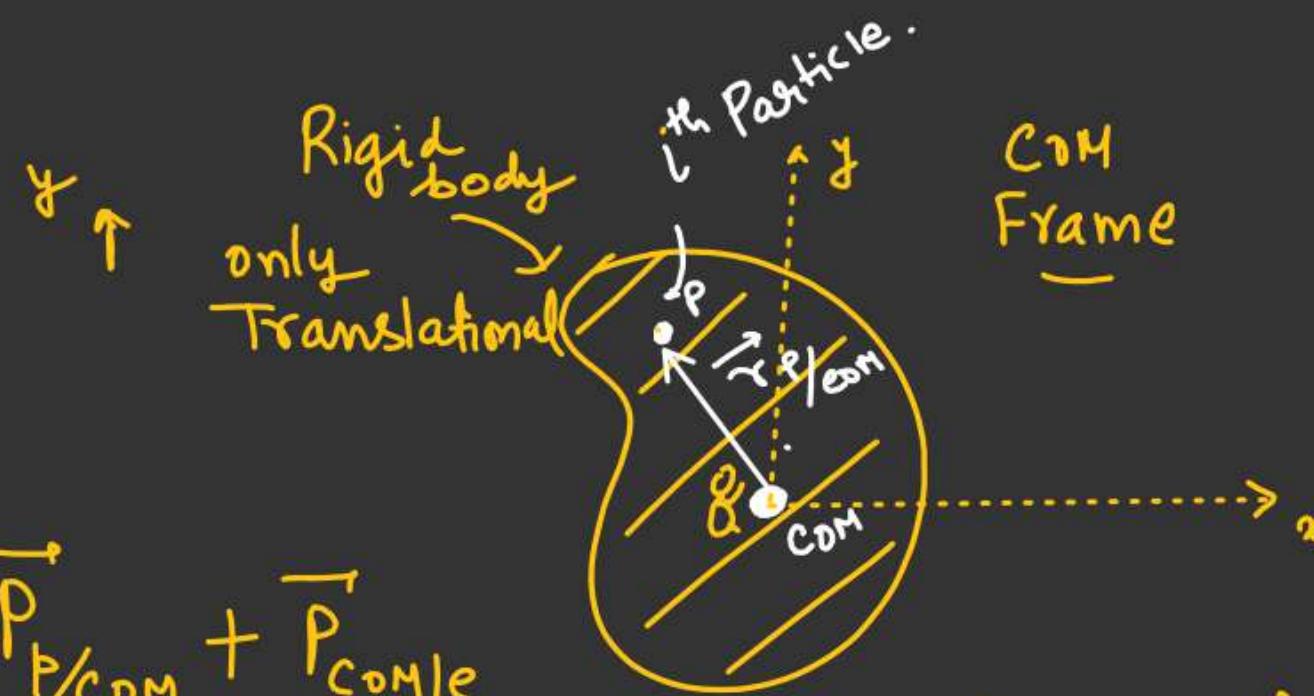
w.r.t COM frame.

$$\vec{v}_{P/COM} = 0 \checkmark$$

$$\vec{v}_{P/E} = \vec{v}_{COM/E}$$

$$\vec{P}_{P/E} = \vec{P}_{P/COM} + \vec{P}_{COM/E}$$

$$\vec{P}_{P/E} = \vec{P}_{COM/E} \quad \checkmark$$



$$\vec{v}_P = \vec{v}_{COM} \quad \checkmark$$

When particle P at rest
w.r.t COM frame OR
both particle & COM move with
same velocity w.r.t Earth frame

~~FR~~:L.M.C of two mass system in COM FRAME

$$\vec{v}_{\text{com}} = \frac{m_2 v_2 \hat{i} + m_1 v_1 \hat{i}}{(m_1 + m_2)}$$

$$\vec{v}_{\text{com}} = \left(\frac{m_2 v_2 + m_1 v_1}{m_1 + m_2} \right) \hat{i}$$

$$\begin{aligned}\vec{v}_{m_1/\text{com}} &= \vec{v}_{m_1/\infty} - \vec{v}_{\text{com}/\infty} \\ &= \left[v_1 - \left(\frac{m_2 v_2 + m_1 v_1}{m_1 + m_2} \right) \right] \hat{i} \\ &= \left(\frac{m_2 v_1 - m_1 v_2}{m_1 + m_2} \right) \hat{i}\end{aligned}$$

$$\vec{v}_{m_1/\text{com}} = \frac{m_2 (v_1 - v_2)}{m_1 + m_2} \hat{i}$$

$$\vec{v}_{m_1/\text{com}} = \left(\frac{m_2}{m_1 + m_2} \right) (\vec{v}_{m_1/m_2})$$



ω · r + COM

Rest



$$\vec{p}_{m_1/\text{com}} = m_1 \vec{v}_{m_1/\text{com}}$$

$$= \left(\frac{m_1 m_2}{m_1 + m_2} \right) (\vec{v}_{m_1/m_2})$$

\Downarrow
 μ

$$\vec{p}_{m_1/\text{com}} = \mu \vec{v}_{\text{rel}}$$

~~Ex:~~L.M.C of two mass system in COM FRAME

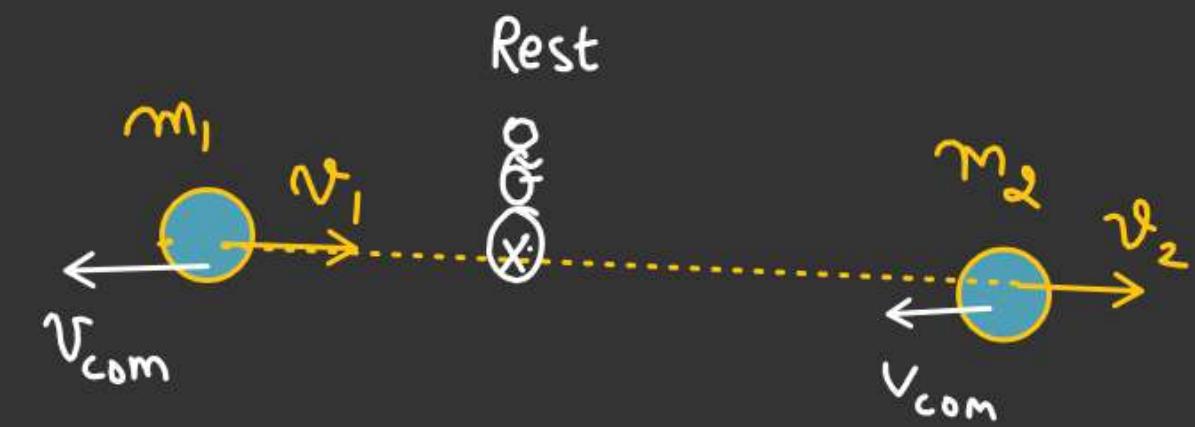
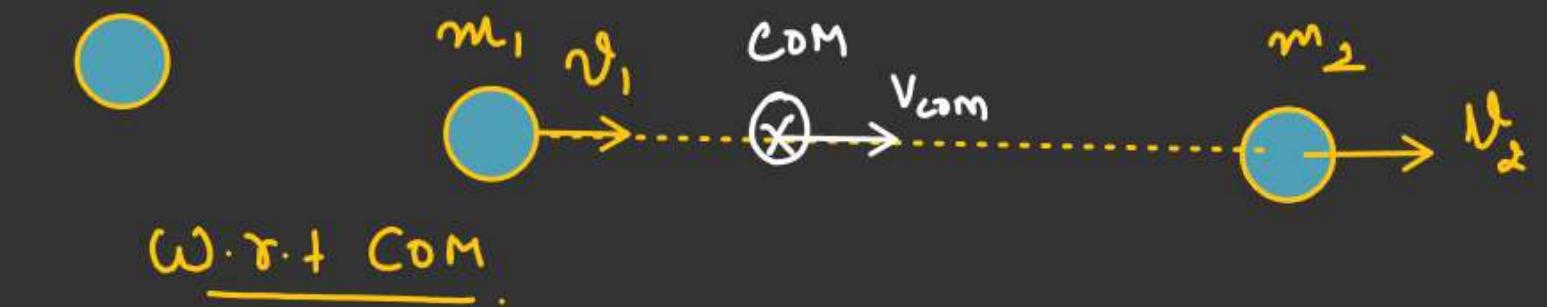
$$\vec{v}_{\text{com}} = \frac{m_2 v_2 \hat{i} + m_1 v_1 \hat{i}}{(m_1 + m_2)}$$

$$\vec{v}_{\text{com}} = \left(\frac{m_2 v_2 + m_1 v_1}{m_1 + m_2} \right) \hat{i}$$

$$\begin{aligned} \vec{v}_{m_2/\text{COM}} &= \vec{v}_{m_2/\epsilon} - \vec{v}_{\text{com}/\epsilon} \\ &= v_2 \hat{i} - \left(\frac{m_2 v_2 + m_1 v_1}{m_1 + m_2} \right) \hat{i} \\ &= \frac{m_1}{m_1 + m_2} (v_2 - v_1) \hat{i} \end{aligned}$$

$$\vec{p}_{m_2/\text{COM}} = m_2 \vec{v}_{m_2/\text{COM}} = \left(\frac{m_1 m_2}{m_1 + m_2} \right) (\vec{v}_{m_2/m_1}) = (\mu \vec{v}_{m_2/m_1})$$

\Downarrow
 μ



TRICK

For two point mass system.

$$\vec{P}_{m_1/\text{COM}} = \mu \vec{v}_{\text{rel}}$$



$$\vec{P}_{m_2/\text{COM}} = -\mu \vec{v}_{\text{rel}}$$

$$\vec{v}_{\text{rel}} = \underline{(v_1 - v_2)} \hat{i}$$

$$\boxed{\mu = \frac{m_1 m_2}{m_1 + m_2}} \quad \stackrel{\text{Def}}{=}$$



$$\mu \rightarrow v_{\text{rel}} = (v_1 - v_2)$$

(Reduced Mass)

$$\boxed{|\vec{P}_{m_1/\text{COM}}| = |\vec{P}_{m_2/\text{COM}}| = \mu (v_{\text{rel}})} \quad \stackrel{\text{Def}}{=}$$

K.E in COM frame

$$|V_{rel}| = |v_{m_1/m_2}| = |v_{m_2/m_1}|$$

K.E of m_1 w.r.t COM =

$$\frac{1}{2} m_1 (v_{m_1/\text{COM}})^2$$

$$= \frac{1}{2} m_1 \left[\frac{m_2 (v_1 - v_2)}{m_1 + m_2} \right]^2$$

$$= \frac{1}{2} \frac{m_1^2}{m_1} \times \frac{m_2^2}{(m_1 + m_2)^2} \times (v_{rel})^2$$

$$= \frac{1}{2m_1} \left(\frac{m_1 m_2}{m_1 + m_2} \right)^2 \cdot v_{rel}^2$$

$$= \frac{1}{2m_1} M^2 V_{rel}^2$$

K.E of m_2 w.r.t COM

$$\frac{1}{2} m_2 (v_{m_2/\text{COM}})^2$$

$$= \frac{1}{2m_2} M^2 V_{rel}^2$$

$$K.E_{\text{System/COM}} = \underbrace{\frac{1}{2} m_1 (v_{m_1/\text{COM}})^2}_{K.E_{m_1}} + \underbrace{\frac{1}{2} m_2 (v_{m_2/\text{COM}})^2}_{K.E_{m_2}}$$

$$= \frac{M^2 V_{rel}^2}{2} \left(\frac{1}{m_1} + \frac{1}{m_2} \right)$$

$$= \left(\frac{m_1 m_2}{m_1 + m_2} \right)^2 \times \frac{m_1 + m_2}{m_1 m_2} \times \frac{1}{2} V_{rel}^2$$

$$K.E_{\text{System/COM}} = \frac{1}{2} M V_{rel}^2$$

$$h_{\max} = ??$$

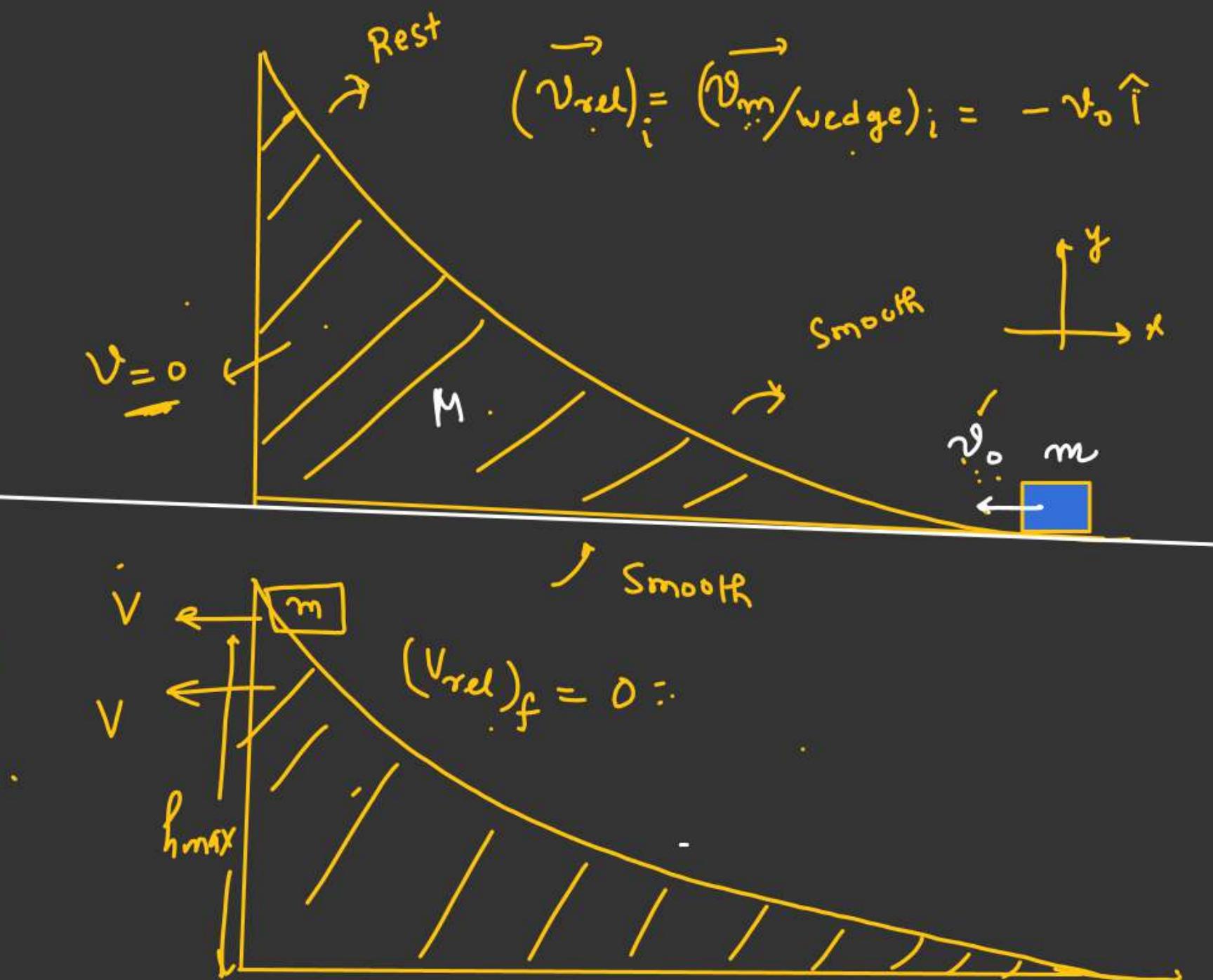
$$\frac{1}{2} \mu \underline{v_{\text{rel}}^2} = mg h_{\max}$$

$$\mu = \left(\frac{Mm}{M+m} \right)$$

$$\frac{1}{2} \left(\frac{Mm}{M+m} \right) v_0^2 = mg h_{\max}$$

$$h_{\max} =$$

$$\frac{v_0^2}{2g} \left(\frac{M}{M+m} \right)$$



L.M.C IN SPRING BLOCK SYSTEMMaximum Compression in theSpring

For two blocks and spring as system Kx is an internal force so no net external force in X -direction

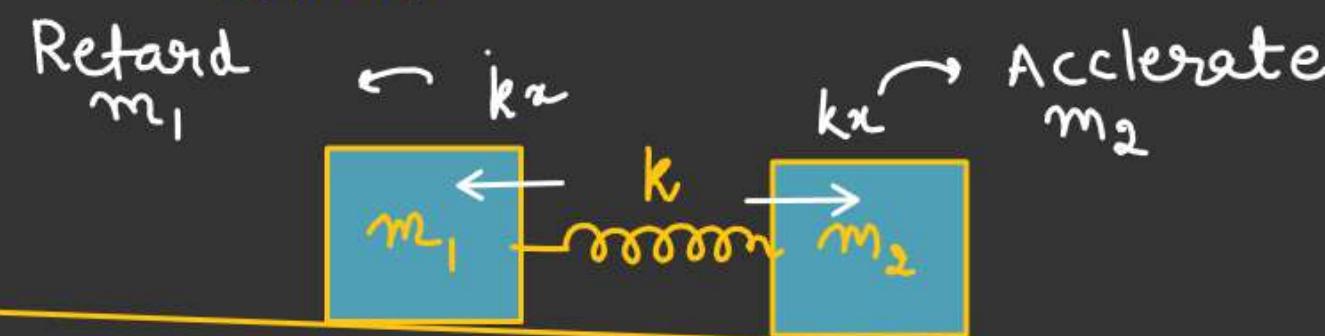
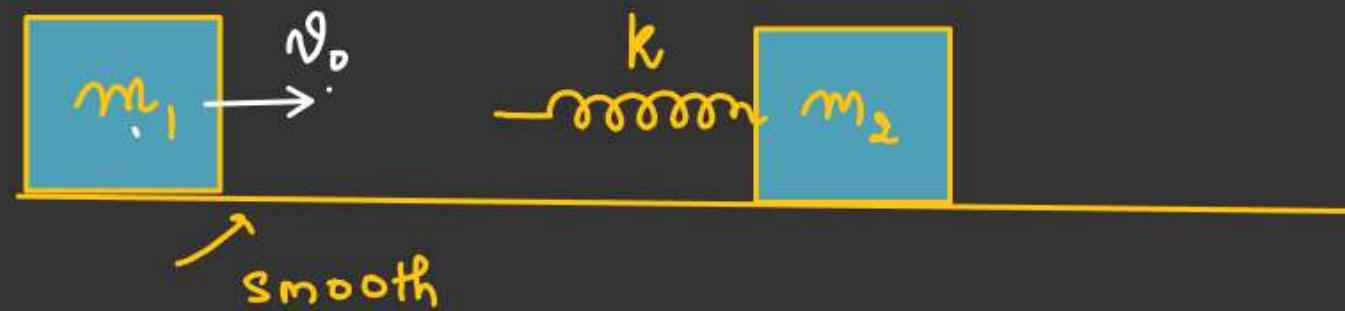
L.M.C

$$m_1 v_0 = (m_1 + m_2) v_c$$

$$v_c = \left(\frac{m_1 v_0}{m_1 + m_2} \right) \checkmark \quad ①$$

Energy Conservation

$$\frac{1}{2} m_1 v_0^2 = \frac{1}{2} (m_1 + m_2) v_c^2 + \frac{1}{2} k x_{\max}^2 \quad ②$$

Initial State

At the time
of Maximum compression



Final
state

$$v_c = \frac{m_1 v_0}{m_1 + m_2} \quad \text{--- (1)}$$

$$\frac{1}{2} m_1 v_0^2 = \frac{1}{2} (m_1 + m_2) v_c^2 + \frac{1}{2} k x_{\max}^2 \quad \text{--- (2)}$$

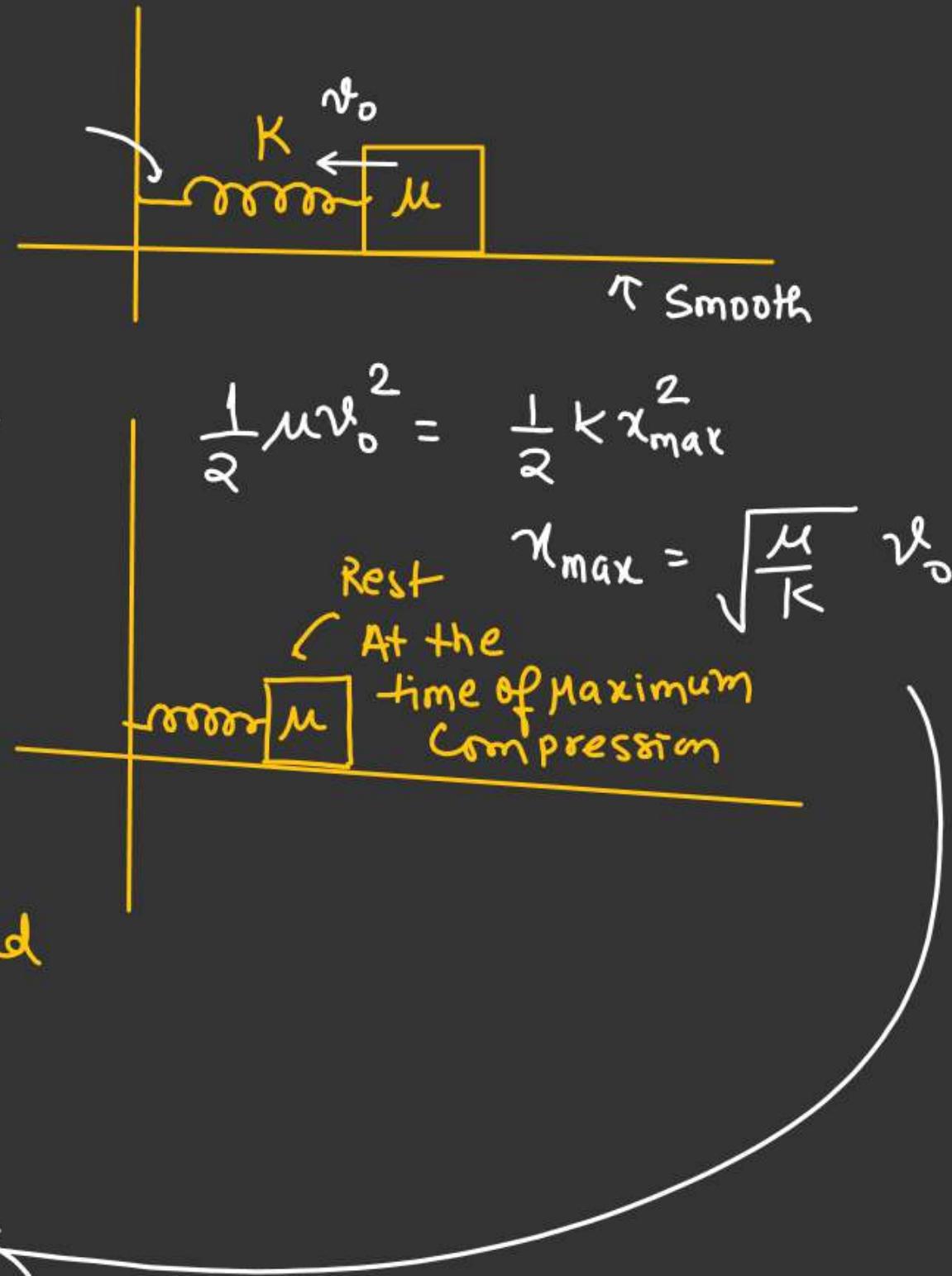
$$\frac{1}{2} k x_{\max}^2 = \frac{1}{2} m_1 v_0^2 - \cancel{\frac{1}{2} (m_1 + m_2) \frac{m_1^2 v_0^2}{(m_1 + m_2)^2}}$$

$$\frac{1}{2} k x_{\max}^2 = \frac{1}{2} m_1 v_0^2 \left[1 - \frac{m_1}{m_1 + m_2} \right]$$

$$\cancel{\frac{1}{2} k x_{\max}^2} = \frac{1}{2} \left(\frac{m_1 m_2}{m_1 + m_2} \right) v_0^2$$

$\mu = \text{Reduced Mass}$

$$x_{\max} = \sqrt{\frac{\left(\frac{m_1 m_2}{m_1 + m_2} \right)}{k}} v_0^2 \Rightarrow \boxed{x_{\max} = \sqrt{\frac{\mu}{k}} v_0}$$



$$v_c = \frac{m_1 v_0}{m_1 + m_2} \quad \text{--- (1)}$$

$$\frac{1}{2} m_1 v_0^2 = \frac{1}{2} (m_1 + m_2) v_c^2 + \frac{1}{2} k x_{\max}^2 \quad \text{--- (2)}$$

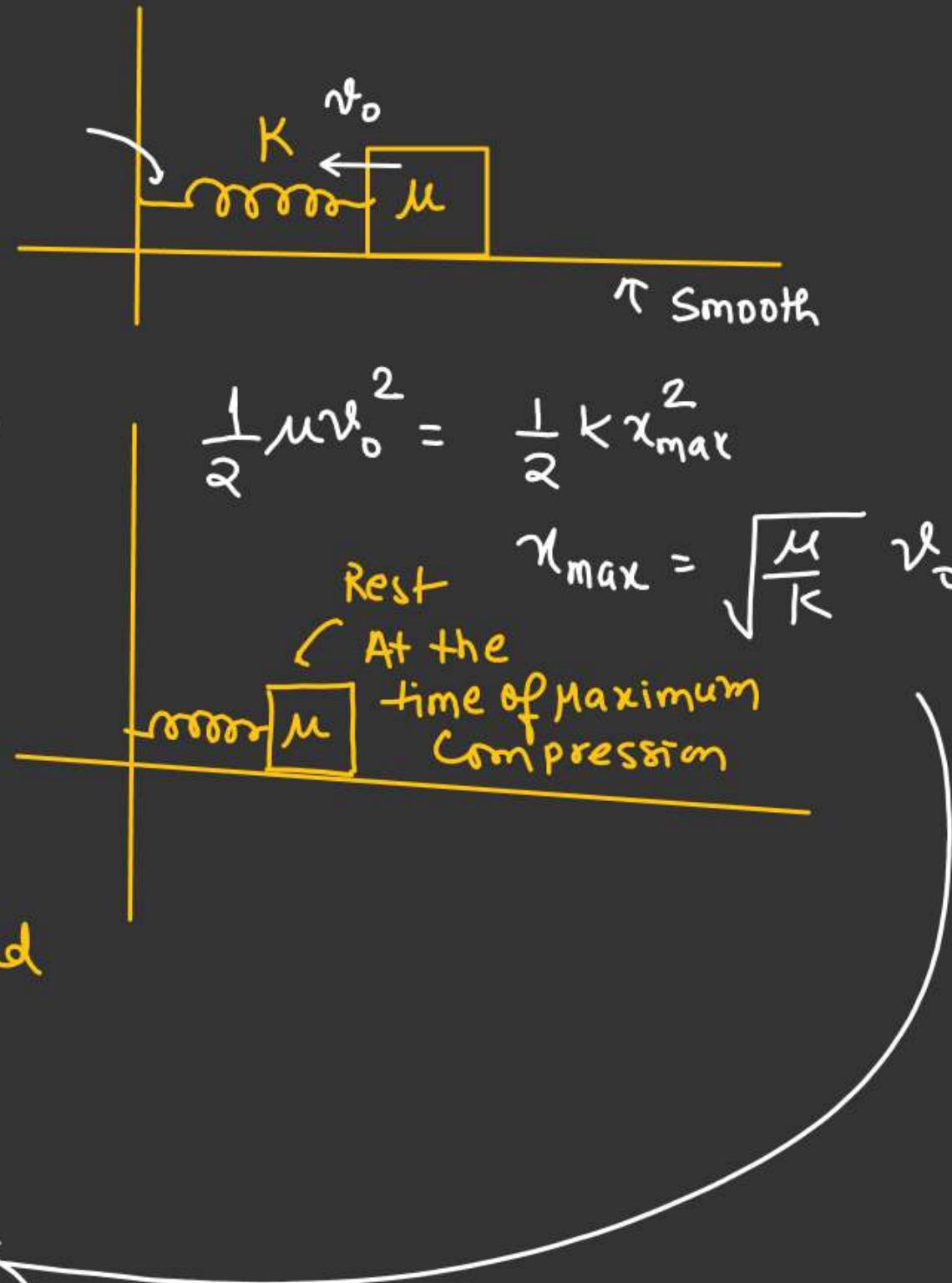
$$\frac{1}{2} k x_{\max}^2 = \frac{1}{2} m_1 v_0^2 - \frac{1}{2} (m_1 + m_2) \cancel{\frac{m_1^2 v_0^2}{(m_1 + m_2)^2}}$$

$$\frac{1}{2} k x_{\max}^2 = \frac{1}{2} m_1 v_0^2 \left[1 - \frac{m_1}{m_1 + m_2} \right]$$

$$\cancel{\frac{1}{2} k x_{\max}^2} = \frac{1}{2} \left(\frac{m_1 m_2}{m_1 + m_2} \right) v_0^2$$

$\mu = \text{Reduced Mass}$

$$x_{\max} = \sqrt{\frac{\left(\frac{m_1 m_2}{m_1 + m_2} \right)}{k}} v_0^2 \Rightarrow \boxed{x_{\max} = \sqrt{\frac{\mu}{k}} v_0}$$



Find $\chi_{\max} = ??$ H.W
Solve w.r.t
Earth frame.

M-1 W.r.t. COM ✓

$$\frac{1}{2} \mu v_{\text{rel}}^2 = \frac{1}{2} K X_{\max}^2$$

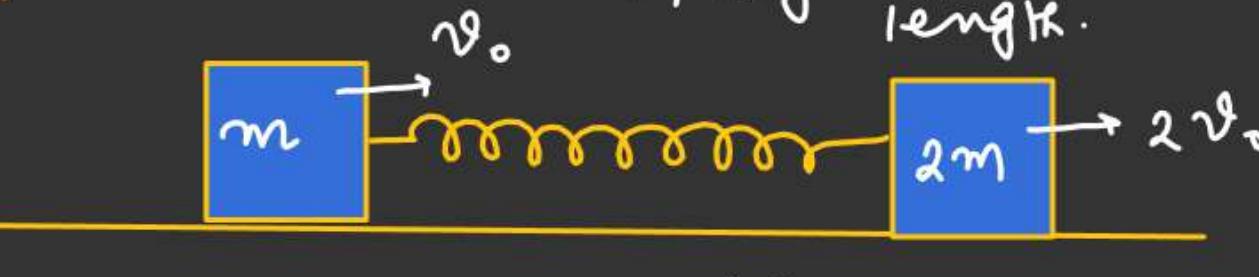
(V_{rel})_i

$$\frac{1}{2} \mu (v_{\text{rel}})_i^2 + \frac{1}{2} \mu (v_{\text{rel}})_f^2 = \frac{1}{2} K X_{\max}^2$$

$$\frac{1}{2} \left(\frac{2m \cdot m}{2m+m} \right) v_0^2 = \frac{1}{2} K X_{\max}^2$$

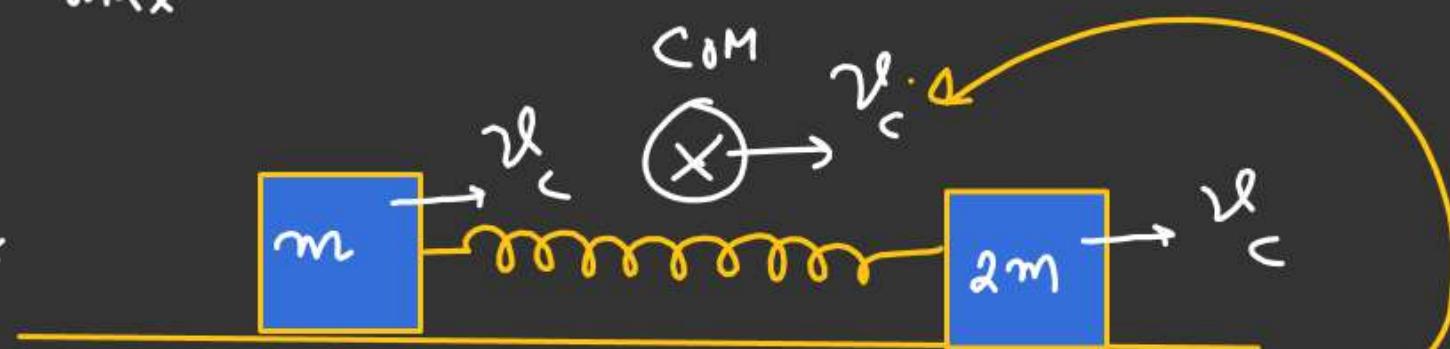
$$\frac{m}{3} v_0^2 = \frac{1}{2} K X_{\max}^2$$

$$X_{\max} = \sqrt{\frac{2m}{3K}} v_0$$



At $t=0$.
Spring at its Natural length.

At the time of Maximum elongation both move with common velocity.



$$v_{\text{COM}} = \frac{2m v_c + m v_c}{(2m+m)} = v_c$$