

MAGNETIC FIELD

Motion of charge particle in a magnetic field

(*) Force acting on a charge particle placed in a uniform Magnetic field :-

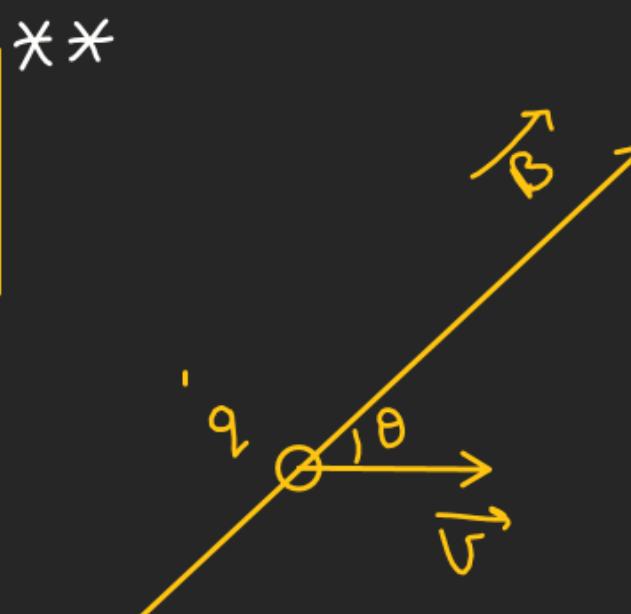
$$\vec{F} = q(\vec{v} \times \vec{B})$$

$$|\vec{F}| = [qvB \sin\theta]$$

$$\theta = \text{Angle b/w } (\vec{B} \text{ & } \vec{v})$$

Direction of \vec{F} :-

Always perpendicular to the plane containing both \vec{v} & \vec{B} .



Note

For e⁻

$$\vec{F} = -q(\vec{v} \times \vec{B})$$

Direction of Magnetic force is opposite w.r.t +ve charge direction

Magnetic field

Influence of a moving charge.

- +q → v = c [Electric field]
- +q → a = c [Magnetic field]
- Constant [Electromagnetic Radiation]

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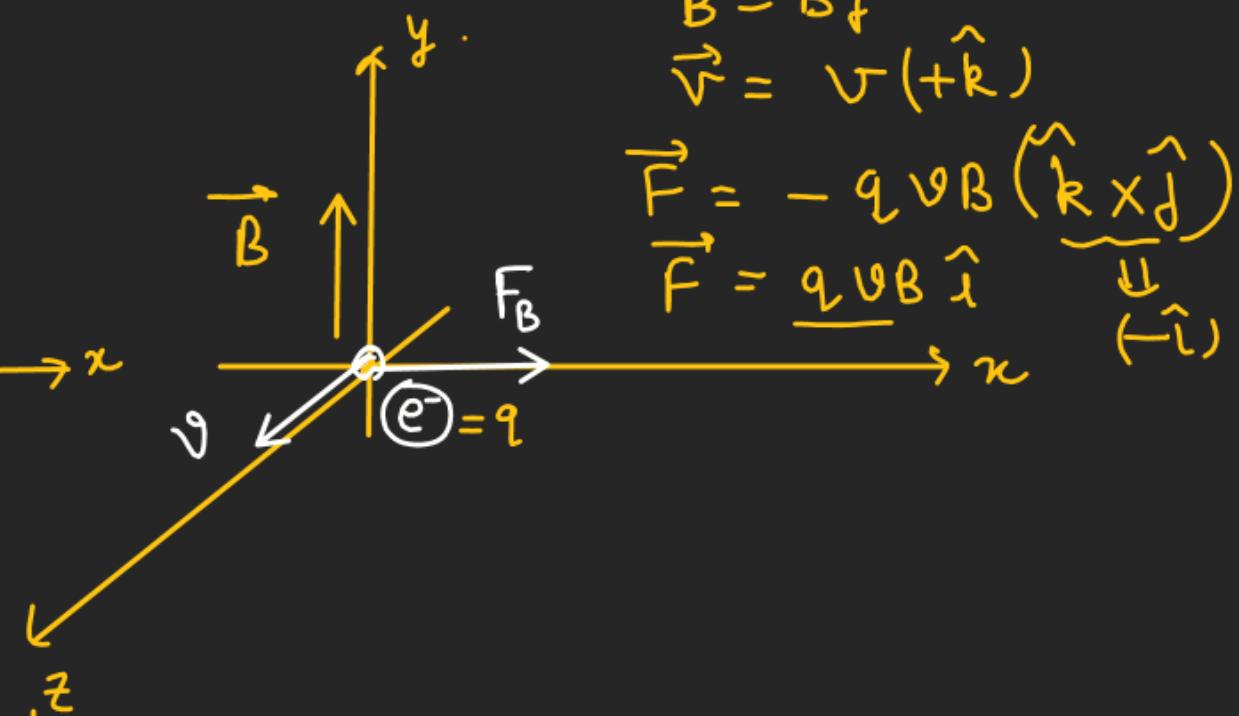
$$\vec{v} = v\hat{i}$$

$$\vec{B} = B\hat{k}$$

$$\vec{F} = q(\vec{v} \times \vec{B})$$

$$= qvB(\hat{i} \times \hat{k})$$

$$= (qvB)(-\hat{j})$$



Cross product

$$\vec{A} \times \vec{B} = [AB \sin \theta] \hat{n}$$

$\theta \rightarrow$ Angle b/w \vec{A} & \vec{B}

$$|\vec{A} \times \vec{B}| = \underbrace{AB \sin \theta}_{\text{Magnitude of } (\vec{A} \times \vec{B})}$$

\hat{n} = Unit Vector \perp to the plane containing both \vec{A} & \vec{B}

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Ex:- $\vec{F} = \underline{2\hat{i}} + \underline{3\hat{j}} + \underline{4\hat{k}}$

$$\vec{v} = -\hat{i} + \hat{j} + \hat{k}$$

\vec{F} is acting on a charge particle having magnitude $2c$ in a Uniform magnetic field. Find $|\vec{B}| = ?$

Sol \Rightarrow Let, $\vec{B} = B_x \hat{i} + B_y \hat{j} + B_z \hat{k}$

$$\vec{F} = q(\vec{v} \times \vec{B})$$

$$\underline{2\hat{i}} + \underline{3\hat{j}} + \underline{4\hat{k}} = \vec{F} = 2(B_z - B_y)\hat{i} + 2(B_z + B_x)\hat{j} - 2(B_y + B_x)\hat{k}$$

$$2(B_z - B_y) = 2 \Rightarrow B_z - B_y = 1 \quad \textcircled{1}$$

$$2(B_z + B_x) = 3 \Rightarrow B_z + B_x = \frac{3}{2} \quad \textcircled{2}$$

$$\vec{v} \times \vec{B} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ -1 & 1 & 1 \\ B_x & B_y & B_z \end{vmatrix}$$

$$\vec{v} \times \vec{B} = \hat{i}(B_z - B_y) - \hat{j}(-B_z - B_x) + \hat{k}(-B_y - B_x)$$

$$-2(B_y + B_x) = 4 \quad \textcircled{3}$$

$$\begin{cases} B_x = \\ B_y = \\ B_z = \end{cases} \quad \checkmark$$

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AA

Magnetic force

It changes the direction of charge particle not the speed of the charge particle.
 as it always acts perpendicular to \vec{v} so it doesn't perform any work. So kinetic energy of charge particle remain same.

$$(F_B)_{\max} = ? ?$$

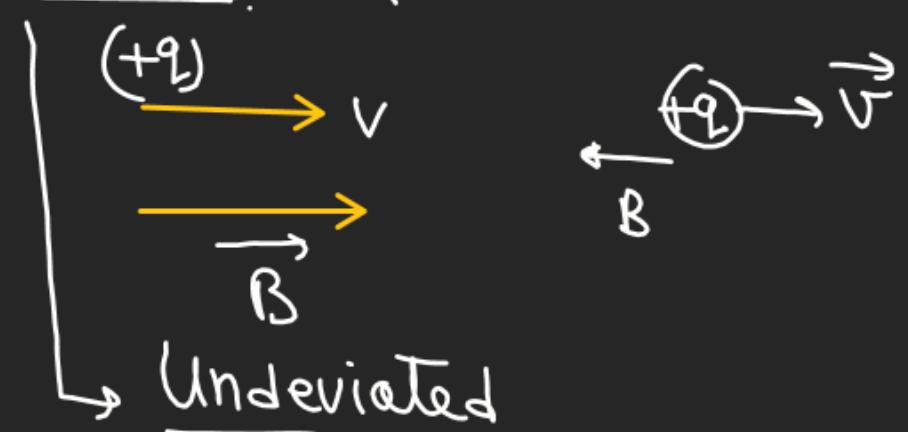
$\vec{v} \perp \vec{B}$

$$F_B = qvB \sin \theta$$

$$(F_B)_{\max} = qvB$$

$$\theta = 90^\circ$$

$$(F_B)_{\min} = 0 \text{ or } (\vec{v} \parallel \vec{B}), (\vec{v} \perp \vec{B})$$



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Case-1 [$\vec{v} \perp \vec{B}$]

↳ Locus is a uniform Circular Motion.

⇒ F_B acts as a Centripetal force.

$$F_B = \frac{mv^2}{R}$$

$$(\vec{v} \perp \vec{B}) \\ \theta = 90^\circ$$

$$qvB = \frac{mv^2}{R} \Rightarrow R = \frac{mv}{qB} \quad **$$

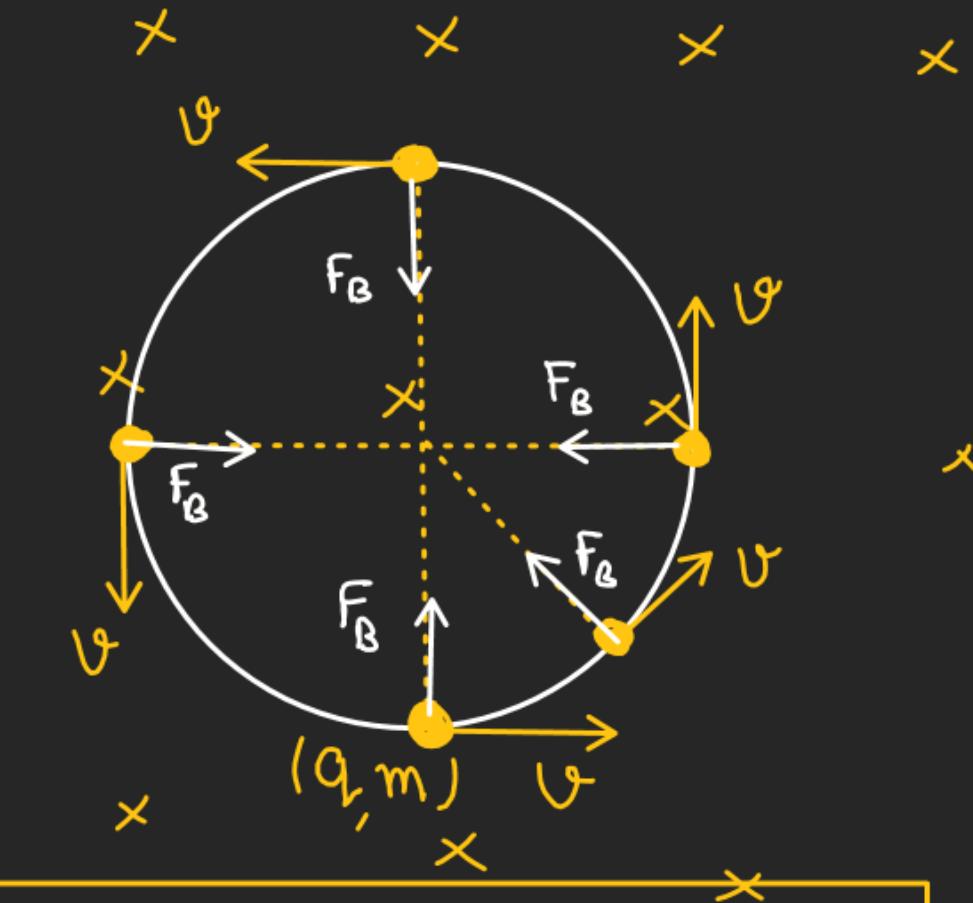
$$T = \frac{2\pi R}{v}$$

$$T = \frac{2\pi}{v} \times \frac{mv}{qB} \Rightarrow T = \frac{2\pi m}{qB}$$

$$**$$

$\text{X} \rightarrow \perp \text{ to plane and inward.}$

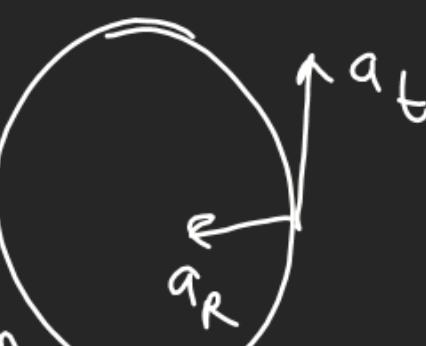
X



$$a_t = \frac{d(v)}{dt}$$

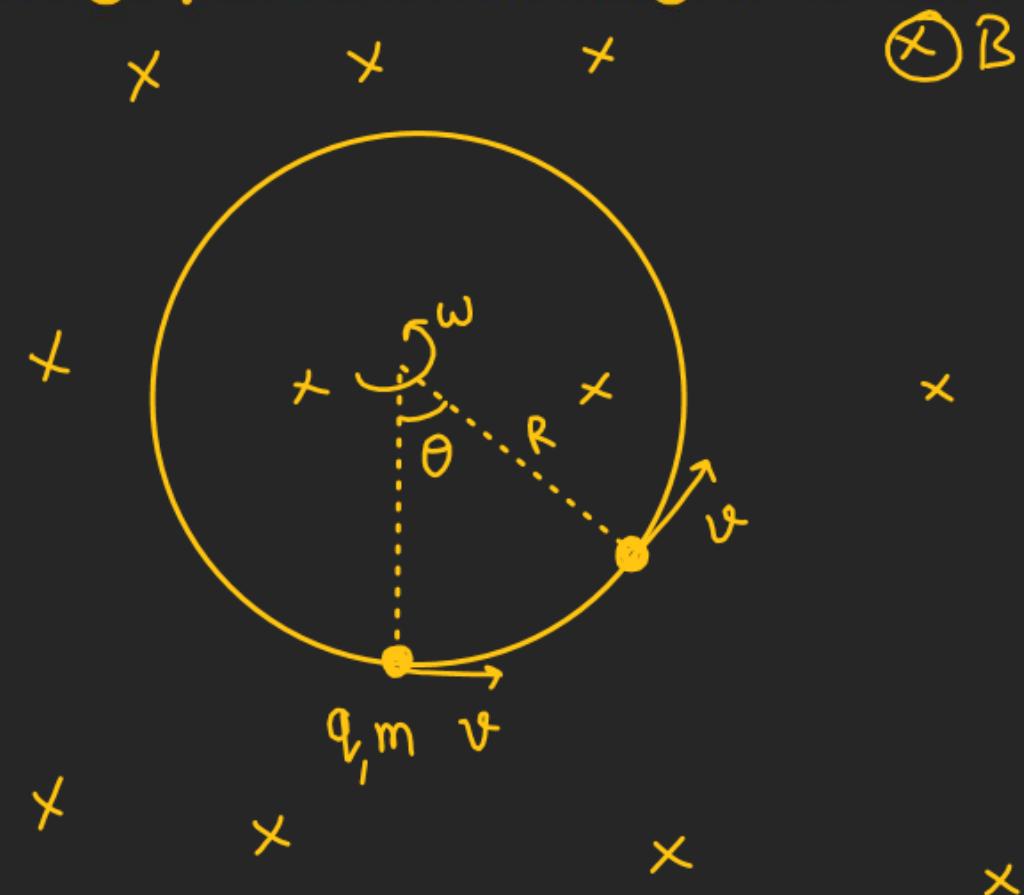
$$a_R = \frac{v^2}{R} = \omega^2 R$$

If $a_t = 0$
 $a_R = \frac{v^2}{R} \Rightarrow \text{Uniform circular motion}$



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$$V = R\omega$$

$$\omega = \left(\frac{v}{R} \right)$$

$$\omega = \frac{2\pi}{T} = \left(\frac{2\pi m}{q_B} \right)$$

$$\omega = \frac{q\beta}{m}$$

$$\times \quad \omega = \frac{2\pi}{T} . = 2\pi f$$

$$f = \frac{1}{T}$$

(frequency)

$$\theta = \omega t$$

$$\theta = \frac{qB}{m}t$$

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(*) general velocity vector and position vector of the charged particle
when $\vec{v} \perp \vec{B}$.

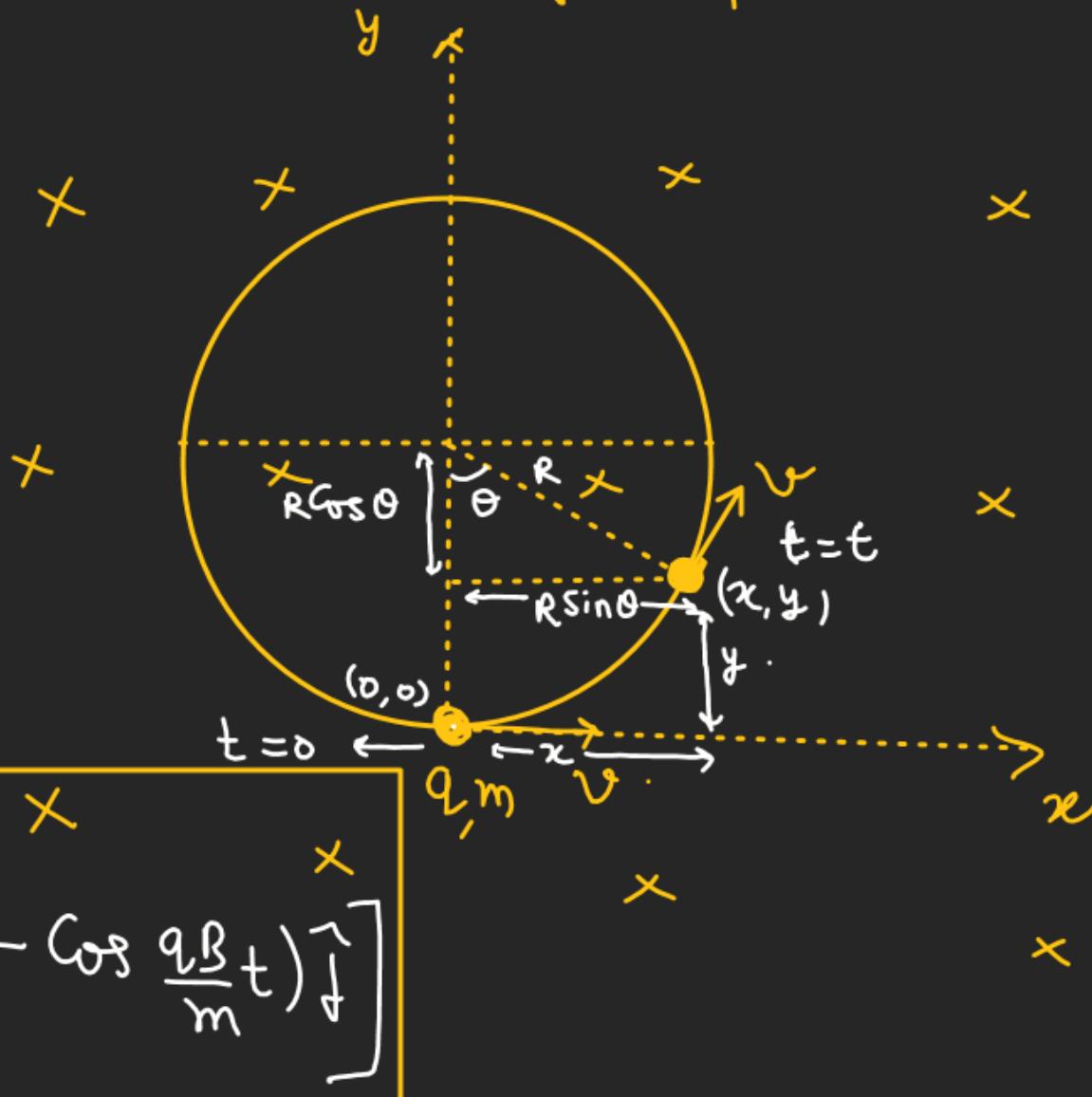
$$x = R \sin \theta.$$

$$x = \frac{mv}{qB} \sin \omega t$$

$$x = \frac{mv}{qB} \sin\left(\frac{qB}{m}t\right)$$

$$y = R(1 - \cos \theta) = \frac{mv}{qB} \left[1 - \cos\left(\frac{qB}{m}t\right) \right]$$

$$\boxed{\vec{r} = x\hat{i} + y\hat{j} = \frac{mv}{qB} \left[\sin\left(\frac{qB}{m}t\right)\hat{i} + (1 - \cos\frac{qB}{m}t)\hat{j} \right]}$$



general Velocity vector

$$\vec{v} = v \cos \theta \hat{i} + v \sin \theta \hat{j}$$

$$\vec{v} = v \cos\left(\frac{qB}{m}t\right) \hat{i} + v \sin\left(\frac{qB}{m}t\right) \hat{j}$$

$$\vec{a} = \frac{d\vec{v}}{dt} = -v \sin\left(\frac{qB}{m}t\right) \left(\frac{qB}{m}\right) \hat{i} + v \cos\left(\frac{qB}{m}t\right) \left(\frac{qB}{m}\right) \hat{j}$$

$$\vec{a} = \left(v \times \frac{qB}{m}\right) \left[-\sin\left(\frac{qB}{m}t\right) \hat{i} + \cos\left(\frac{qB}{m}t\right) \hat{j} \right]$$

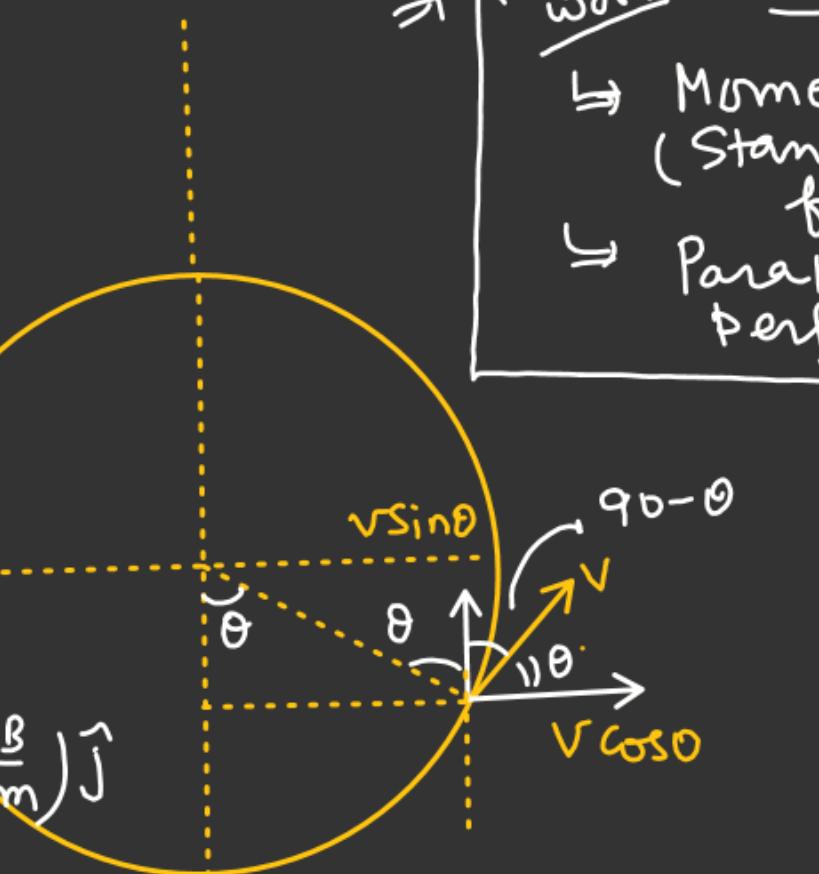
$$\vec{a} = v \times \frac{v}{R} \left[-\sin\left(\frac{qB}{m}t\right) \hat{i} + \cos\left(\frac{qB}{m}t\right) \hat{j} \right]$$

$$\vec{a} = \left(\frac{v^2}{R}\right) \left[-\sin\left(\frac{qB}{m}t\right) \hat{i} + \cos\left(\frac{qB}{m}t\right) \hat{j} \right]$$

$$\theta = \omega t$$

$$\theta = \frac{qB}{m}t$$

⇒ Home work ↳ Torque
 ↳ Moment of Inertia
 (Standard body formula)
 ↳ Parallel axis and perpendicular axis



$$a_R = a_{net} = \omega^2 R = v^2/R$$

$$a_R = -a_R \sin \theta \hat{i} + a_R \cos \theta \hat{j}$$

$$a_R = \frac{v^2}{R} \left[-\sin\left(\frac{qB}{m}t\right) \hat{i} + \cos\left(\frac{qB}{m}t\right) \hat{j} \right]$$

