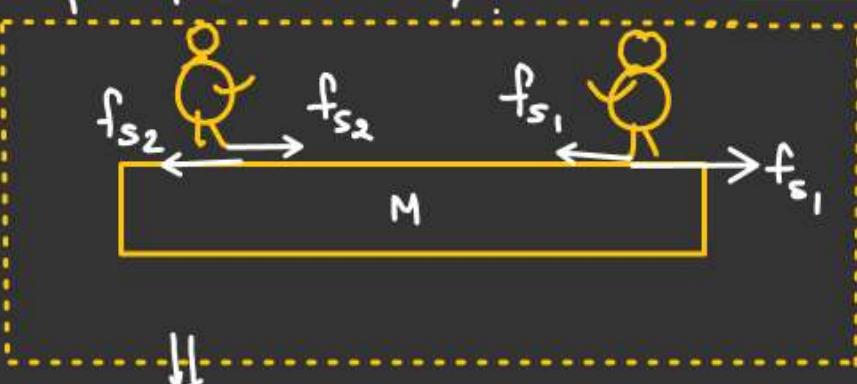


MOTION OF COMCase. $\Delta X_{com} = 0$ Two Men + Plank System

x_1 & x_2 be the displacement
of person A and B w.r.t plank.
then displacement of plank = ??

Note:-

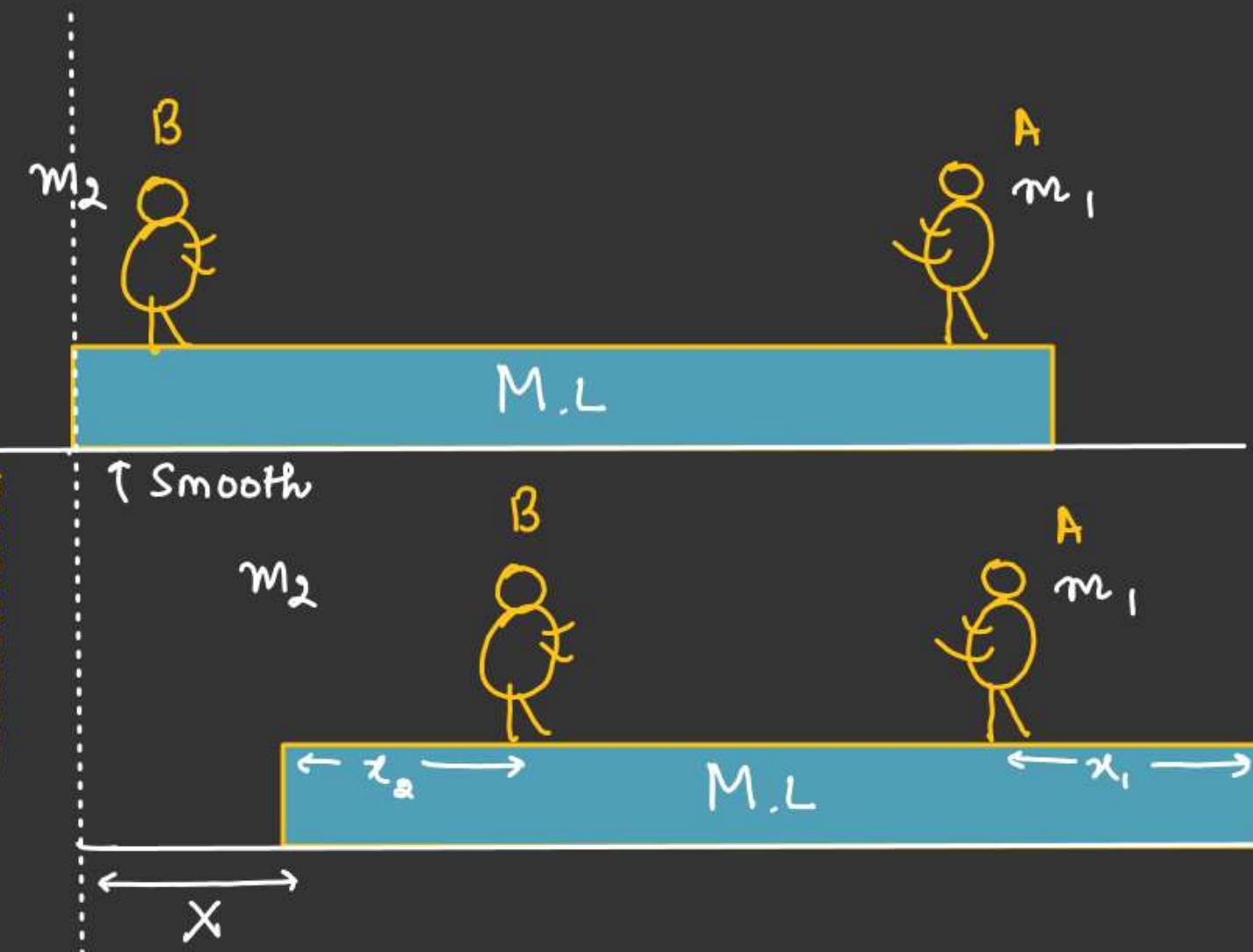
While using $\Delta X_{com} = 0$
all the displacements
must be w.r.t
earth



• Taking both the men
and plank as system
net external force in
 x -direction is zero

\Rightarrow Since $(V_{com})_i = 0$.

$$\underline{(\Delta X_{com})_i = 0}.$$



MOTION OF COMCase. $[\Delta X_{\text{com}} = 0]$

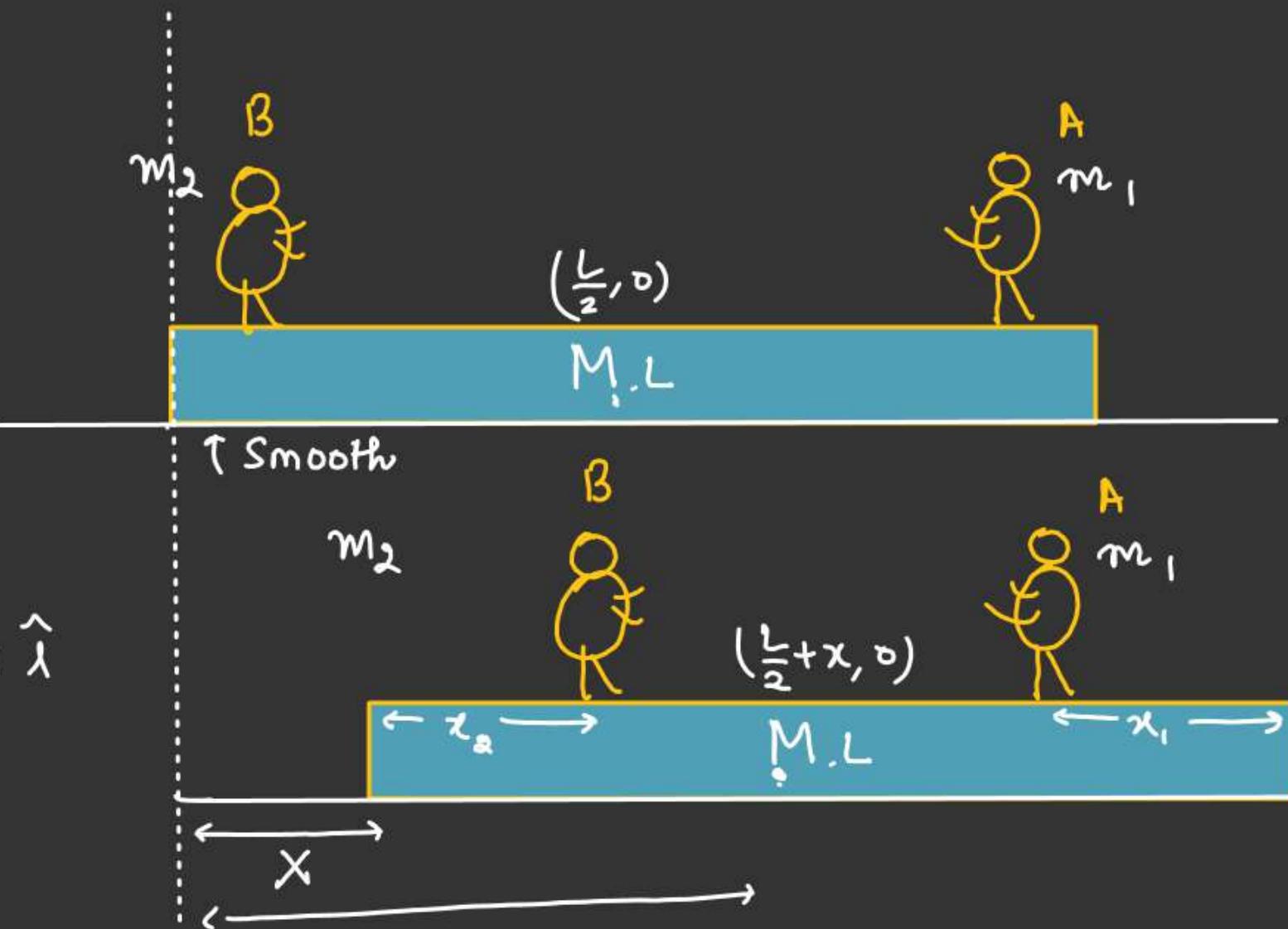
$$\vec{x}_{A/\text{E}} = \vec{x}_{A/\text{plank}} + \vec{x}_{\text{plank/E}}$$

Displacement
of A w.r.t.
earth. = $-x_1 \hat{i} + x \hat{i}$
 $= (x - x_1) \hat{i}$

$$\begin{aligned}\vec{x}_{B/\text{E}} &= \vec{x}_{B/\text{plank}} + \vec{x}_{\text{plank/E}} \\ &= x_2 \hat{i} + x \hat{i} \quad \Delta \vec{x}_{\text{plank}} = x \hat{i} \\ &= (x_2 + x) \hat{i}\end{aligned}$$

$$0 = \Delta X_{\text{com}} = \frac{m_1 x_{A/\text{E}} + m_2 (x_{B/\text{E}}) + M x}{m_1 + m_2}$$

$$0 = m_1 (x - x_1) + m_2 (x + x_2) + M x$$



$$x = \frac{m_1 x_1 - m_2 x_2}{m_1 + m_2 + M}$$

MOTION OF COMCase. $\Delta X_{\text{com}} = 0$

$$\cancel{M \cdot 2} \checkmark$$

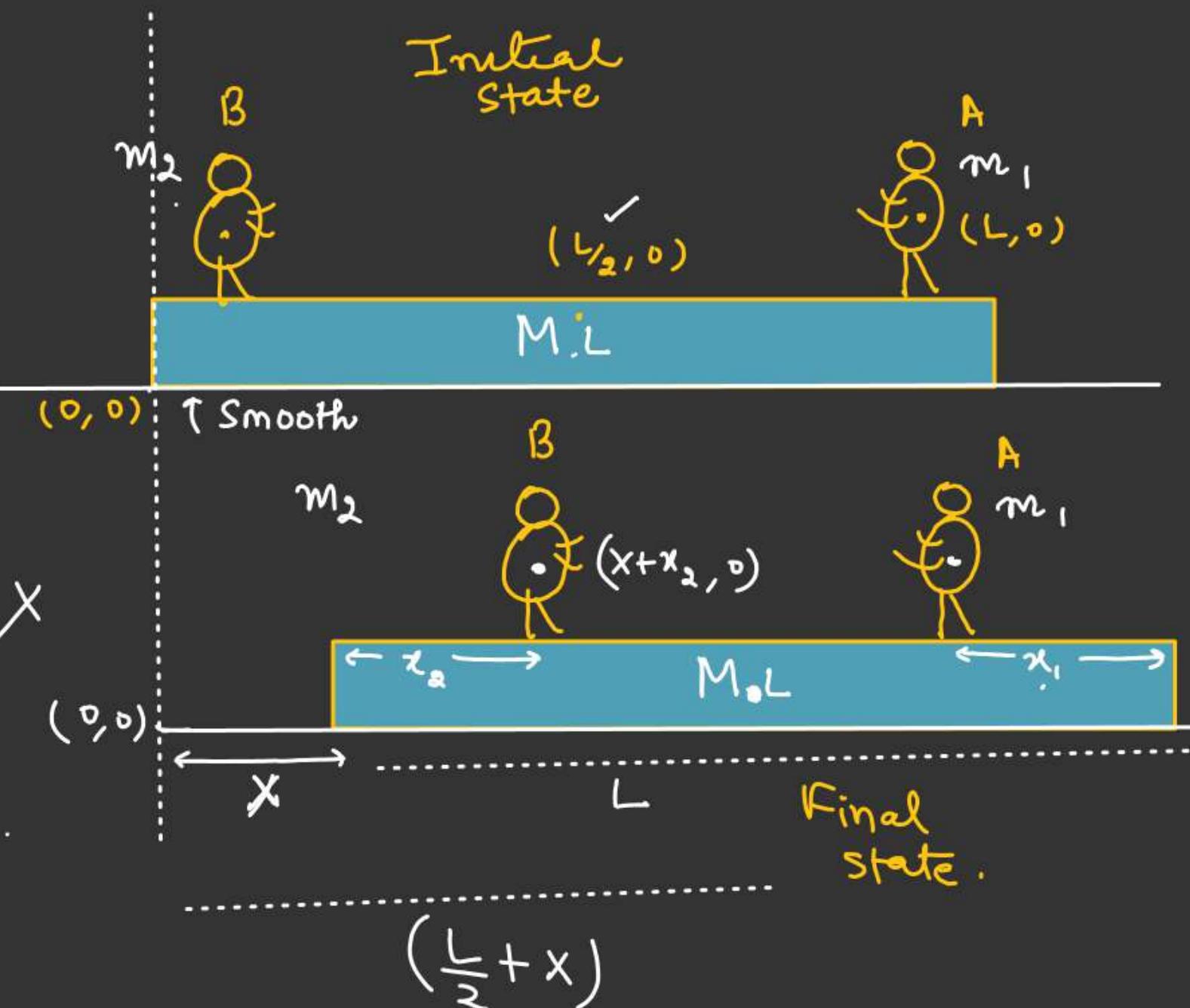
$$(X_{\text{com}})_i = (X_{\text{com}})_f$$

$$\frac{m_2(0) + m_1 L + M(\frac{L}{2})}{m_1 + m_2 + M} = \frac{m_2(x + x_2) + m_1(L - x_1 + x)}{m_1 + m_2 + M}$$

$$\cancel{m_1 L} = (m_2 x_2 - m_1 x_1) + (m_2 + m_1 + M)x$$

$$+ m_1 L$$

$$x = \left(\frac{m_1 x_1 - m_2 x_2}{m_1 + m_2 + M} \right) \checkmark$$



MOTION OF COMCase. $\Delta X_{\text{com}} = 0$

All the contact surfaces are smooth.

Block is released from the position shown in the fig.

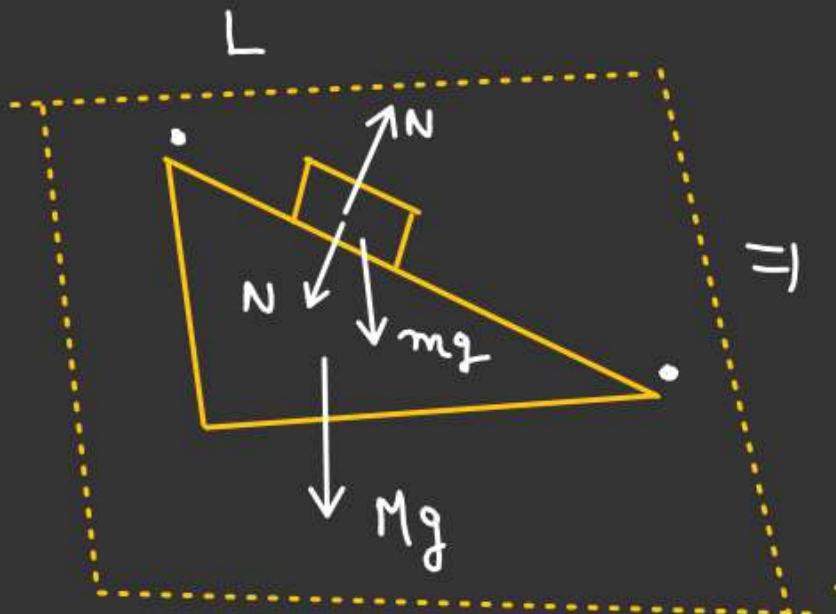
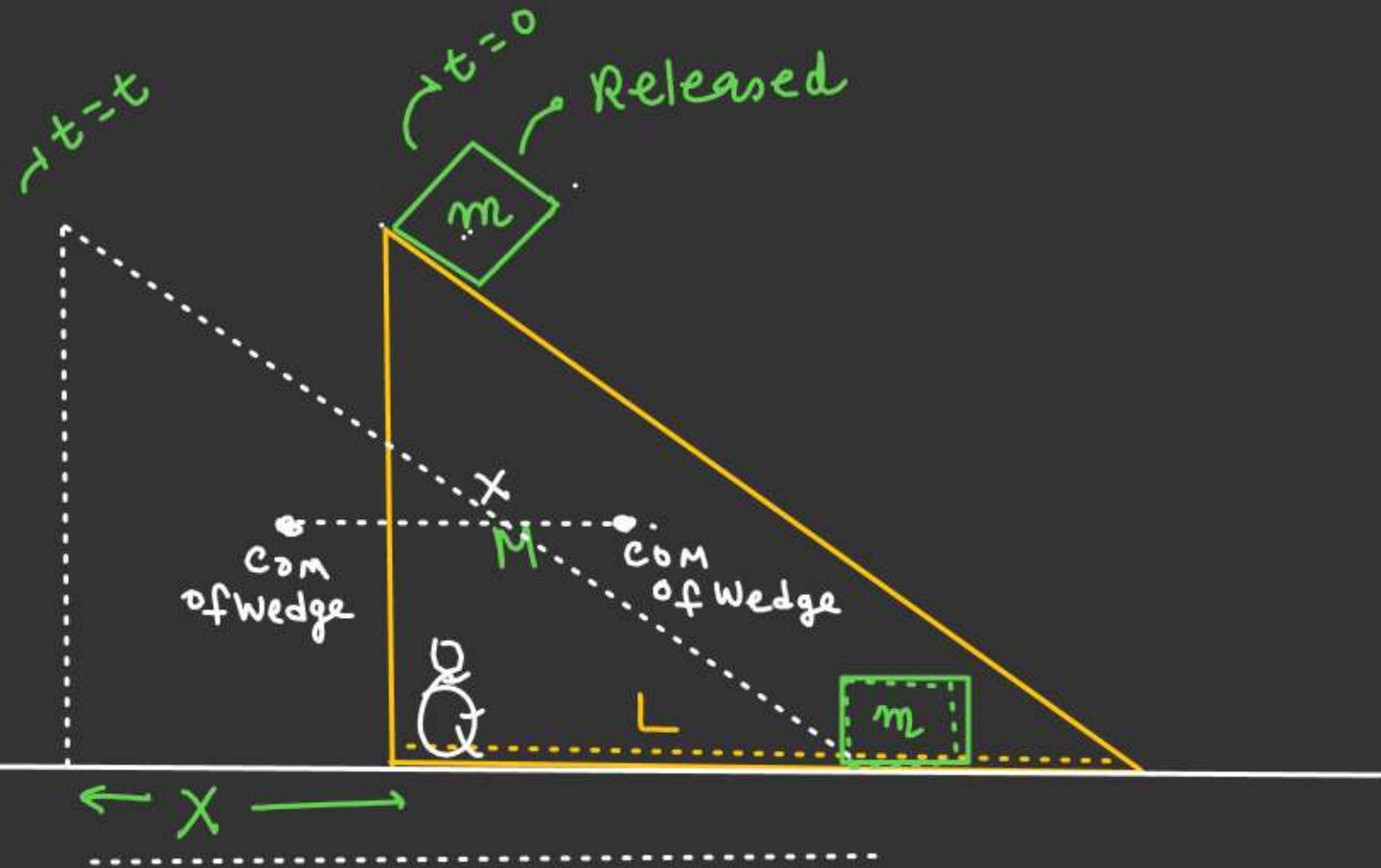
Find displacement of wedge when block just reach the ground.

$$\begin{aligned}\vec{x}_{\text{block}/\mathbb{E}} &= \vec{x}_{\text{block/wedge}} + \vec{x}_{\text{wedge}/\mathbb{E}} \\ &= (L\hat{i} - x\hat{i}) \\ &= (\underline{L-x})\hat{i}\end{aligned}$$

$$\Delta X_{\text{com}} = 0$$

$$m(\Delta \vec{x}_{\text{block}/\mathbb{E}}) + M(\Delta \vec{x}_{\text{wedge}/\mathbb{E}}) = 0$$

$$m(L-x)\hat{i} + Mx\hat{i} = 0 \Rightarrow \boxed{x = -\frac{mL}{M+m}\hat{i}}$$



$$\begin{aligned}(F_{\text{ext}})_x &= 0 \\ \Rightarrow (\Delta X_{\text{com}})_x &= 0\end{aligned}$$

MOTION OF COMCase. $[\Delta X_{\text{com}} = 0]$

* String breakers and ball of mass finally drop in the slot.

Find displacement of trolley.

$$\Delta X_{\text{com}} = 0. \quad (F_{\text{ext}})_x = 0.$$

$$(V_{\text{com}})_i = 0.$$

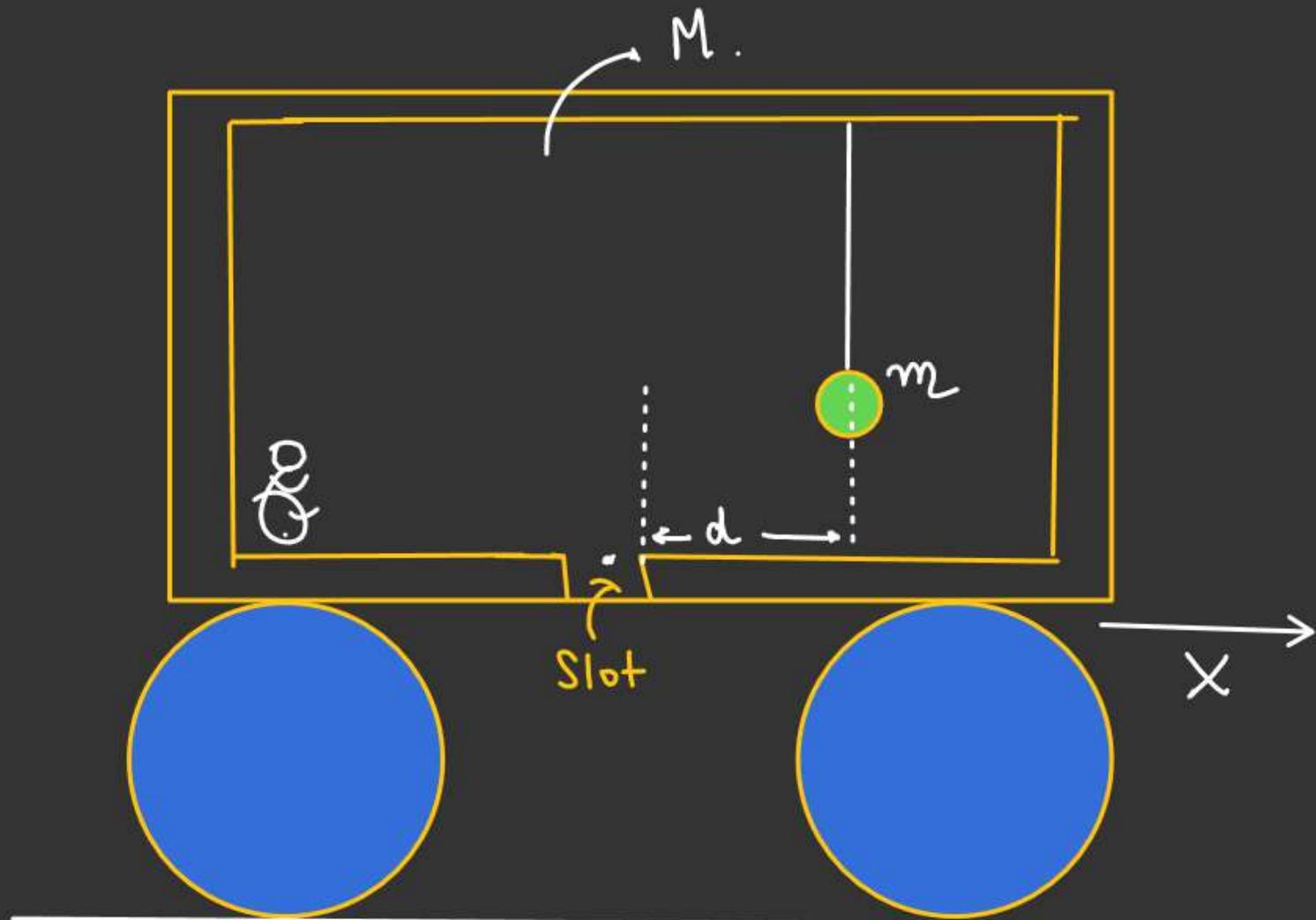
$$\vec{x}_{\text{ball}/\mathcal{E}} = \vec{x}_{\text{ball/trolley}} + \vec{x}_{\text{trolley}/\mathcal{E}}$$

$$= -d\hat{i} + x\hat{i}$$

$$= \underbrace{(x-d)\hat{i}}.$$

$$\Delta X_{\text{com}} = 0$$

$$\frac{M\hat{x} + m(x-d)\hat{i}}{(M+m)} = 0 \quad x(M+m) = md \quad x = \left(\frac{md}{M+m}\right)$$



MOTION OF COMCase. $\Delta X_{\text{com}} = 0$

All the contact surfaces are smooth.

System is released from rest.

Find displacement of wedge if d be the displacement of blocks w.r.t wedge

$$\text{Sol}^n \quad \vec{x}_{m_1/\varepsilon} = \vec{x}_{m_1/\text{wedge}} + \vec{x}_{\text{wedge}/\varepsilon}$$

$$= (d \cos \alpha) \hat{i} + x \hat{i}$$

$$= (d \cos \alpha + x) \hat{i}$$

$$\vec{x}_{m_2/\varepsilon} = \vec{x}_{m_2/\text{wedge}} + \vec{x}_{\text{wedge}/\varepsilon}$$

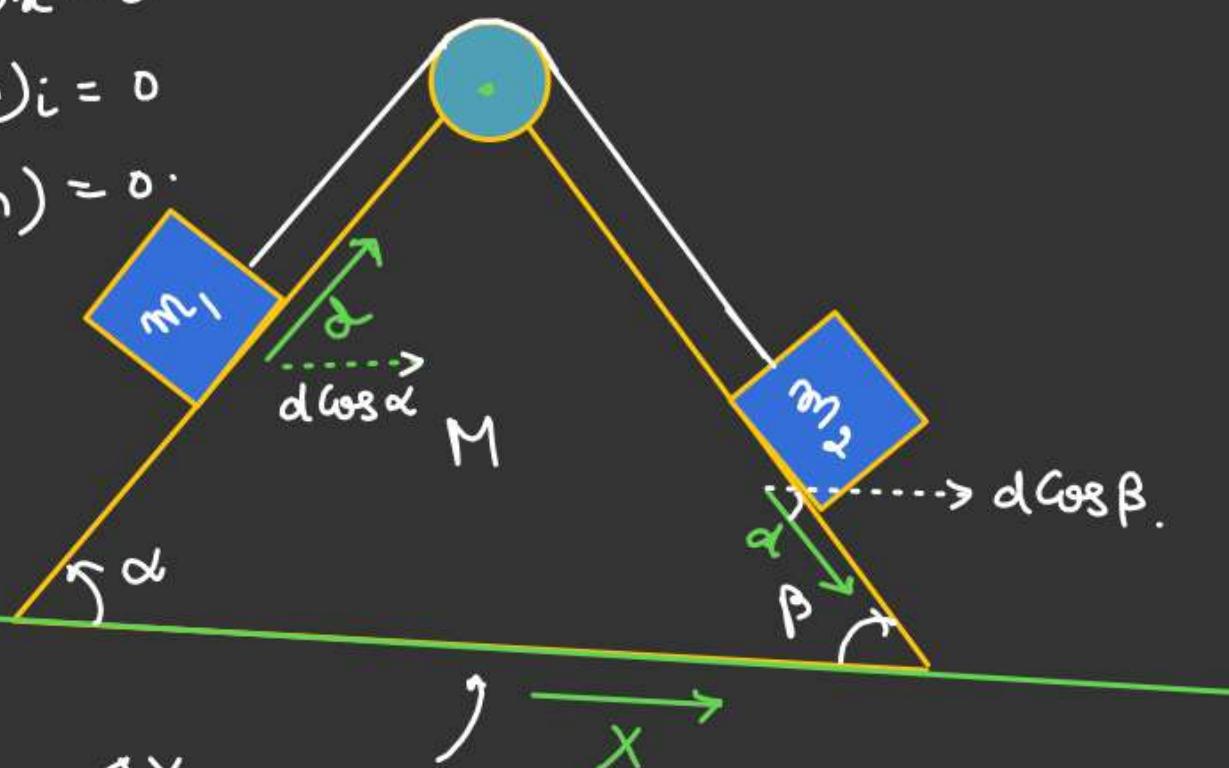
$$= d \cos \beta \hat{i} + x \hat{i}$$

$$= (d \cos \beta + x) \hat{i}$$

$$(F_{\text{ext}})_x = 0$$

$$(V_{\text{com}})_i = 0$$

$$(\Delta X_{\text{com}}) = 0$$



$$\Delta X_{\text{com}} = 0$$

$$\underbrace{m_1(d \cos \alpha + x) \hat{i} + m_2(d \cos \beta + x) \hat{i} + Mx \hat{i}}_{(m_1+m_2+M)} = 0$$

$$(m_1 + m_2 + M)x = d(m_2 \cos \beta - m_1 \cos \alpha)$$

$$x = \frac{(m_2 \cos \beta - m_1 \cos \alpha)d}{m_1 + m_2 + M}$$

MOTION OF COMCase. $[\Delta X_{\text{com}} = 0]$ Find $X = ??$ 