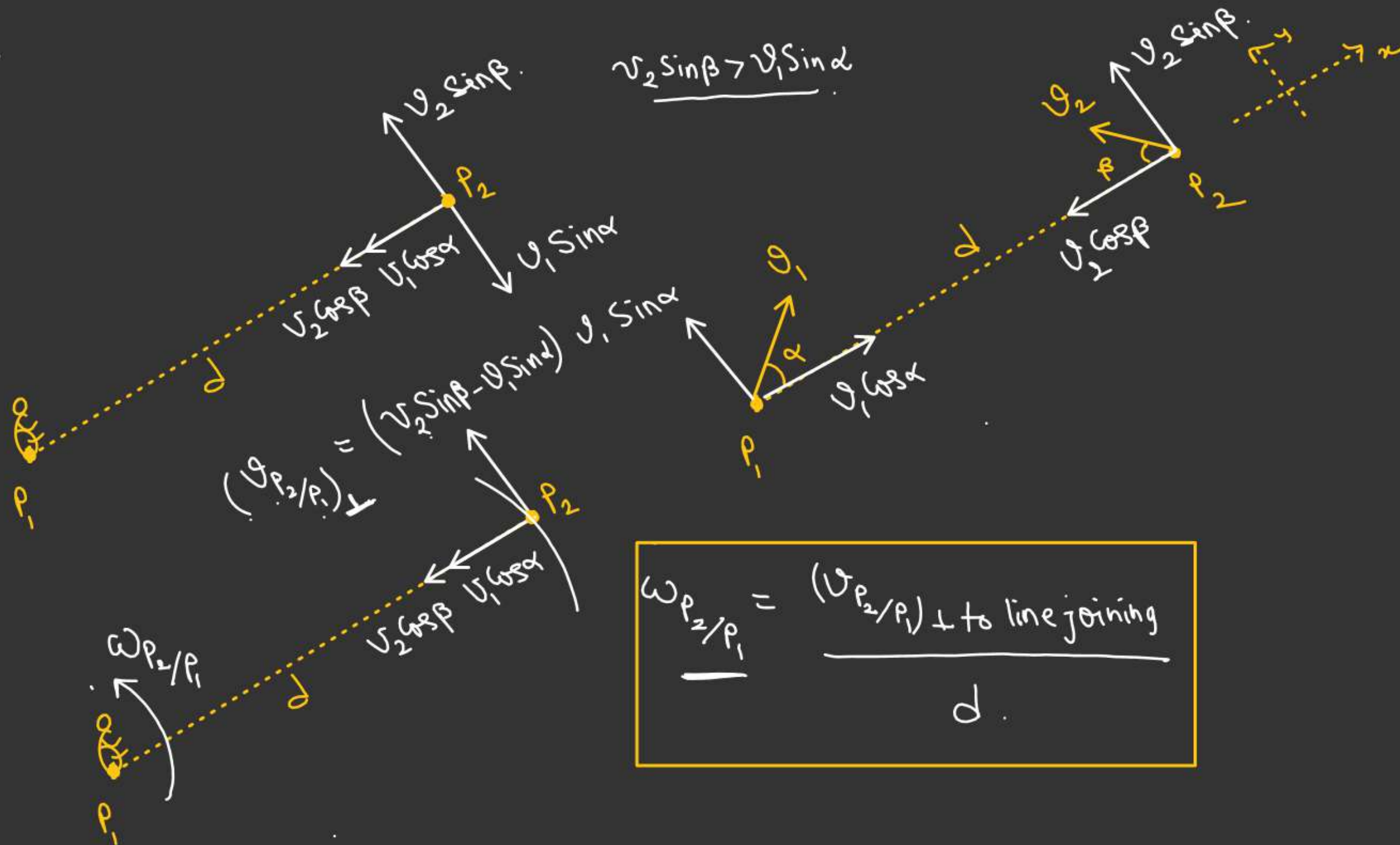


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Relative angular velocity

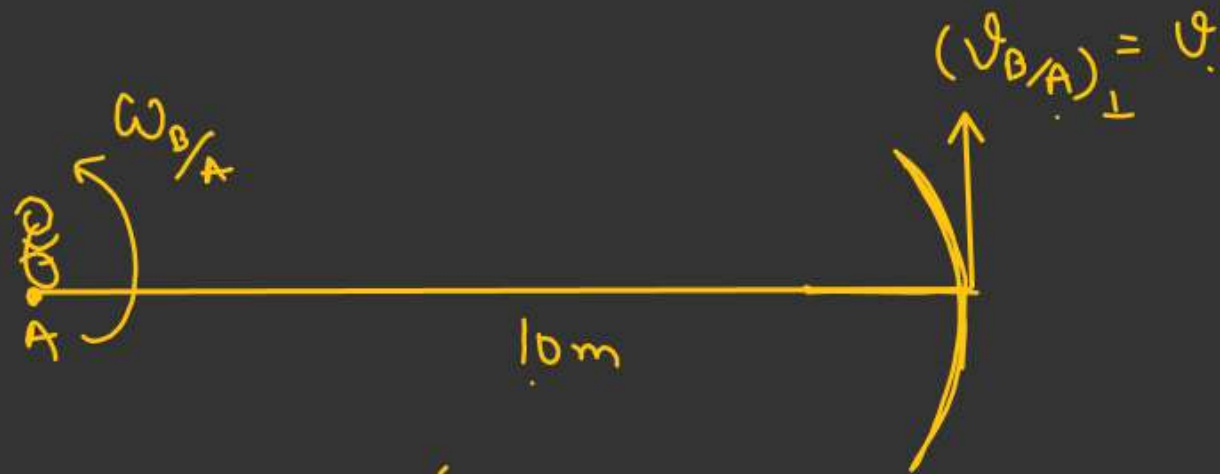
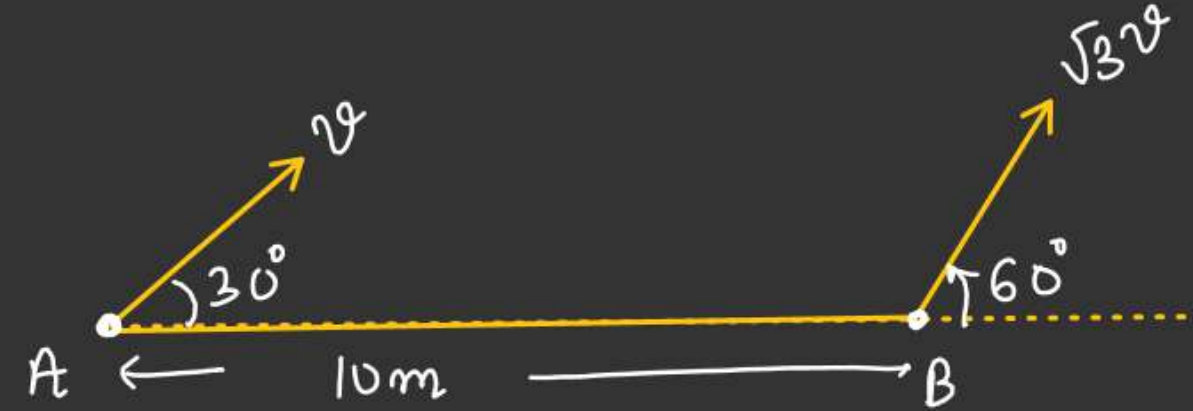
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Relative angular velocity b/w two points moving in a plane

$$\omega_{P_2/P_1} = \frac{(V_{P_2/P_1})_{\perp} \text{ to line joining}}{d}$$

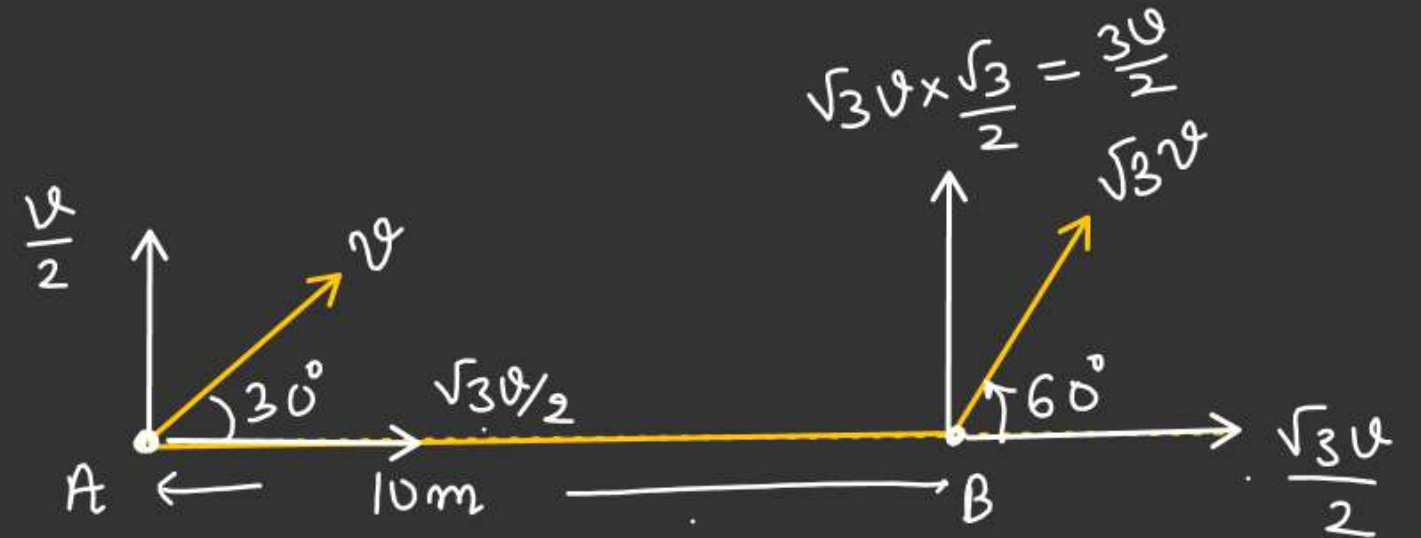
$$\omega_{B/A} = ??$$

$$\begin{aligned}\vec{v}_{B/A} &= \vec{v}_{B/E} - \vec{v}_{A/E} \\ &= \left(\frac{\sqrt{3}v}{2} \hat{i} + \frac{3v}{2} \hat{j} \right) - \left(\frac{\sqrt{3}v}{2} \hat{i} + \frac{v}{2} \hat{j} \right) \\ &= v \hat{j}\end{aligned}$$



$$\omega_{B/A} = \frac{v}{10} \text{ Ans}$$

$$\begin{pmatrix} v = R\omega \\ \omega = \frac{v}{R} \end{pmatrix}$$



Relative Angular velocity b/w two points moving in a circle of radius R with velocity v_1 & v_2

v_1 & v_2 constant

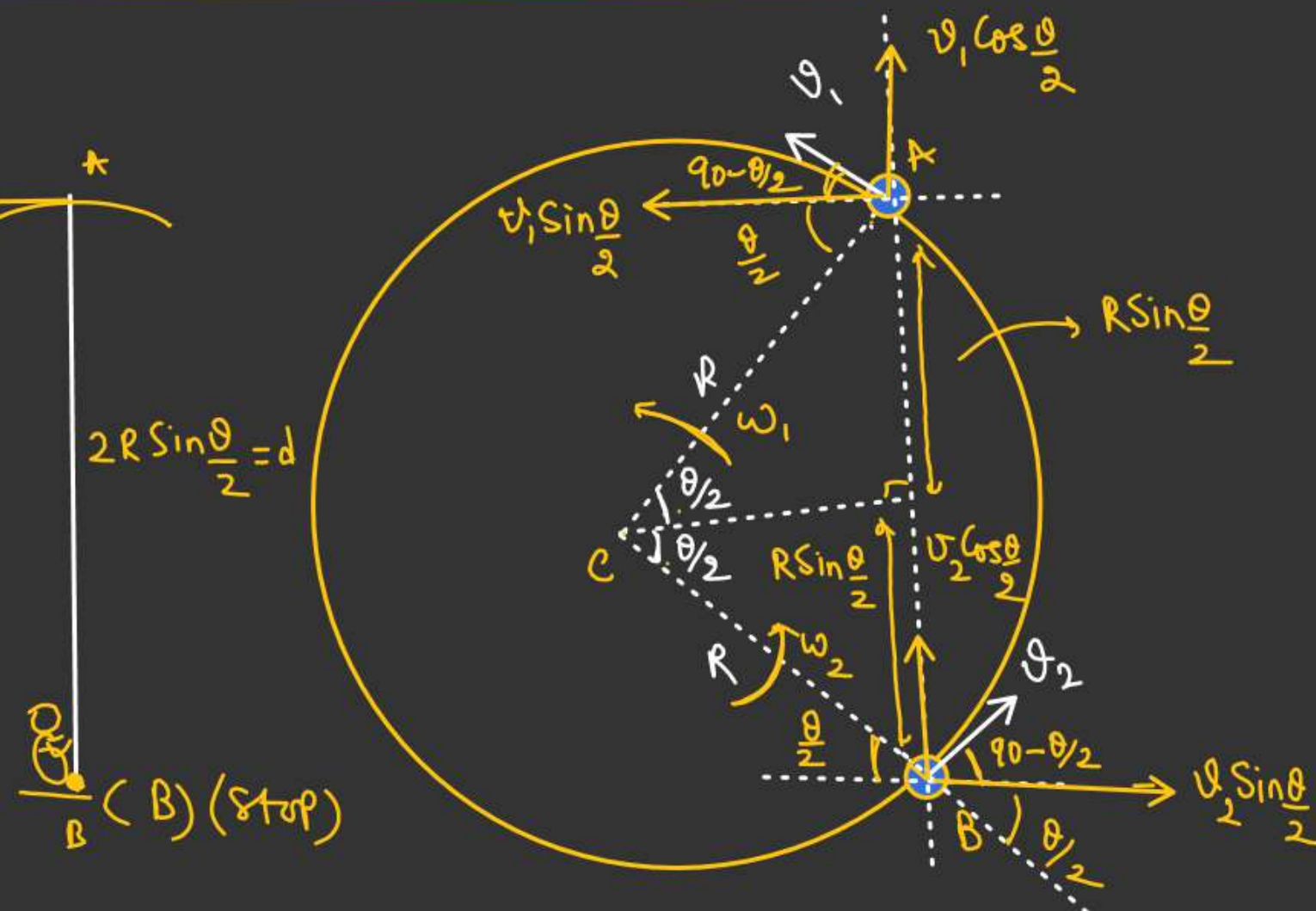
$$\omega_{A/B} = \frac{(v_{A/B})_{\perp}}{d_{AB}}$$

$$\begin{aligned} & (v_1 + v_2) \sin \frac{\theta}{2} \\ & \Downarrow \\ & (v_{A/B})_{\perp} \end{aligned}$$

$$\omega_{A/B} = \frac{(v_1 + v_2) \sin(\theta/2)}{2R \sin(\theta/2)}$$

$$\omega_{A/B} = \left(\frac{v_1 + v_2}{2R} \right)$$

$$\omega_{A/B} = \frac{(v_1/R) + (v_2/R)}{2} = \frac{\omega_1 + \omega_2}{2}$$



$$\omega_{A/B} = \frac{\omega_1 + \omega_2}{2} \Rightarrow \text{Rotating in Same sense}$$

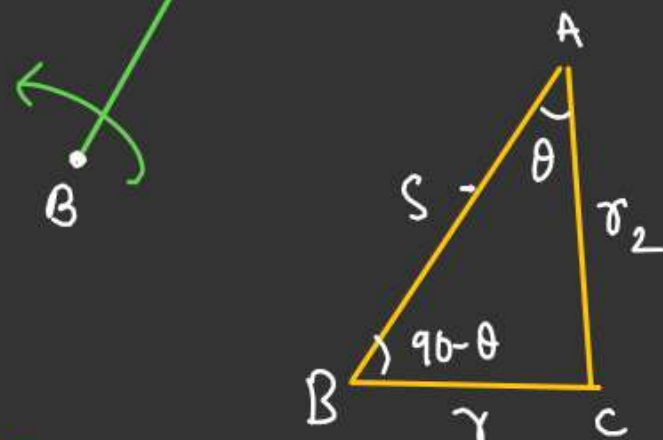
Q.8: Relative Angular velocity b/w two points moving in a concentric circle when their radius vector are perpendicular to each other.

$$\omega_{A/B} = \frac{v_1 \sin \theta + v_2 \cos \theta}{S}$$

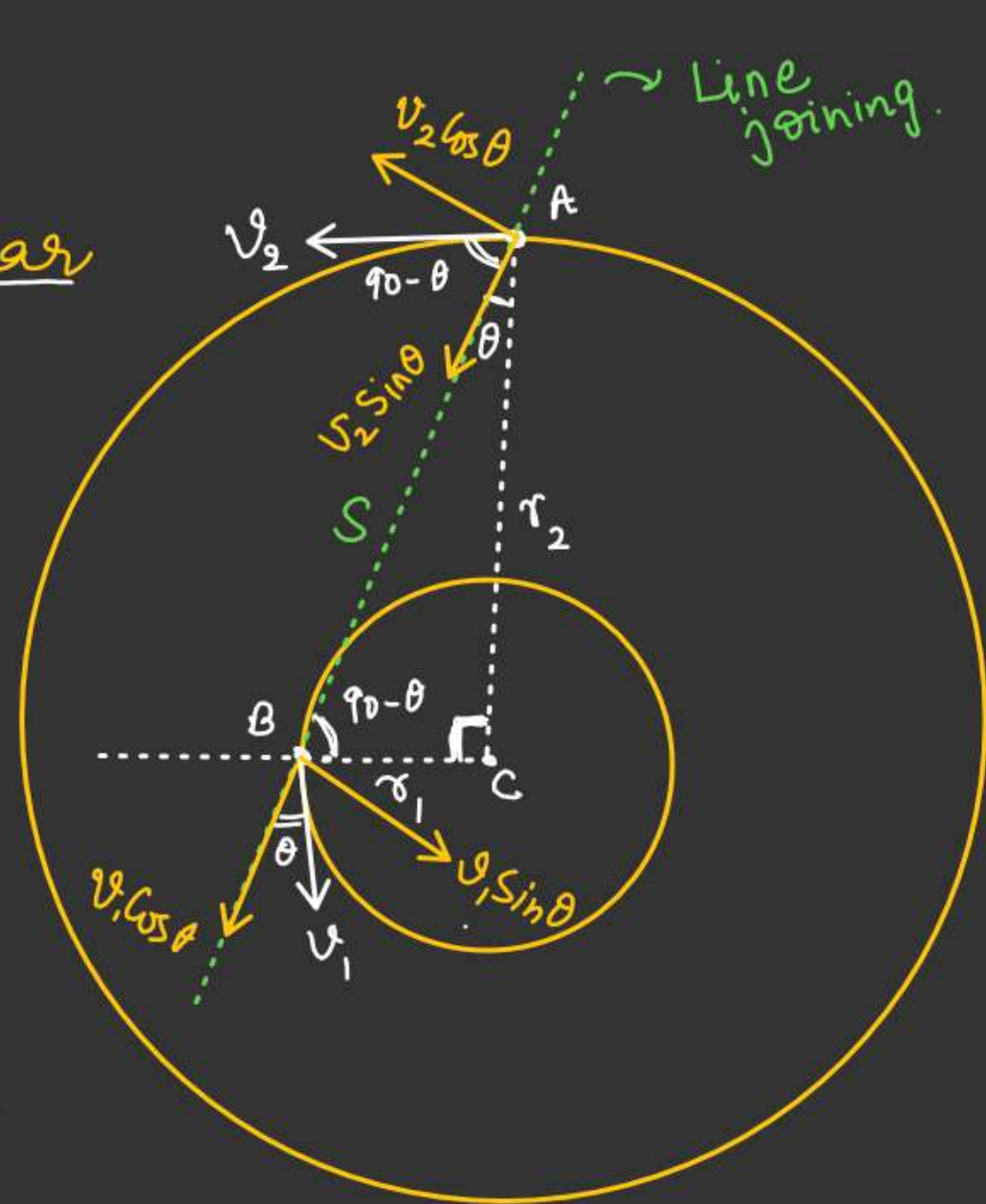
$$\begin{aligned} \omega_{A/B} &= \frac{v_1 \left(\frac{r_1}{S} \right) + v_2 \left(\frac{r_2}{S} \right)}{S} \\ &= \frac{v_1 r_1 + v_2 r_2}{S^2} \end{aligned}$$

$$\omega_{A/B} = \left(\frac{v_1 r_1 + v_2 r_2}{r_1^2 + r_2^2} \right)$$

$$(v_{A/B})_{\perp} = (v_1 \sin \theta + v_2 \cos \theta)$$



$$\begin{aligned} \sin \theta &= \frac{r_1}{S} \\ \cos \theta &= \frac{r_2}{S} \\ S &= \sqrt{r_1^2 + r_2^2} \end{aligned}$$

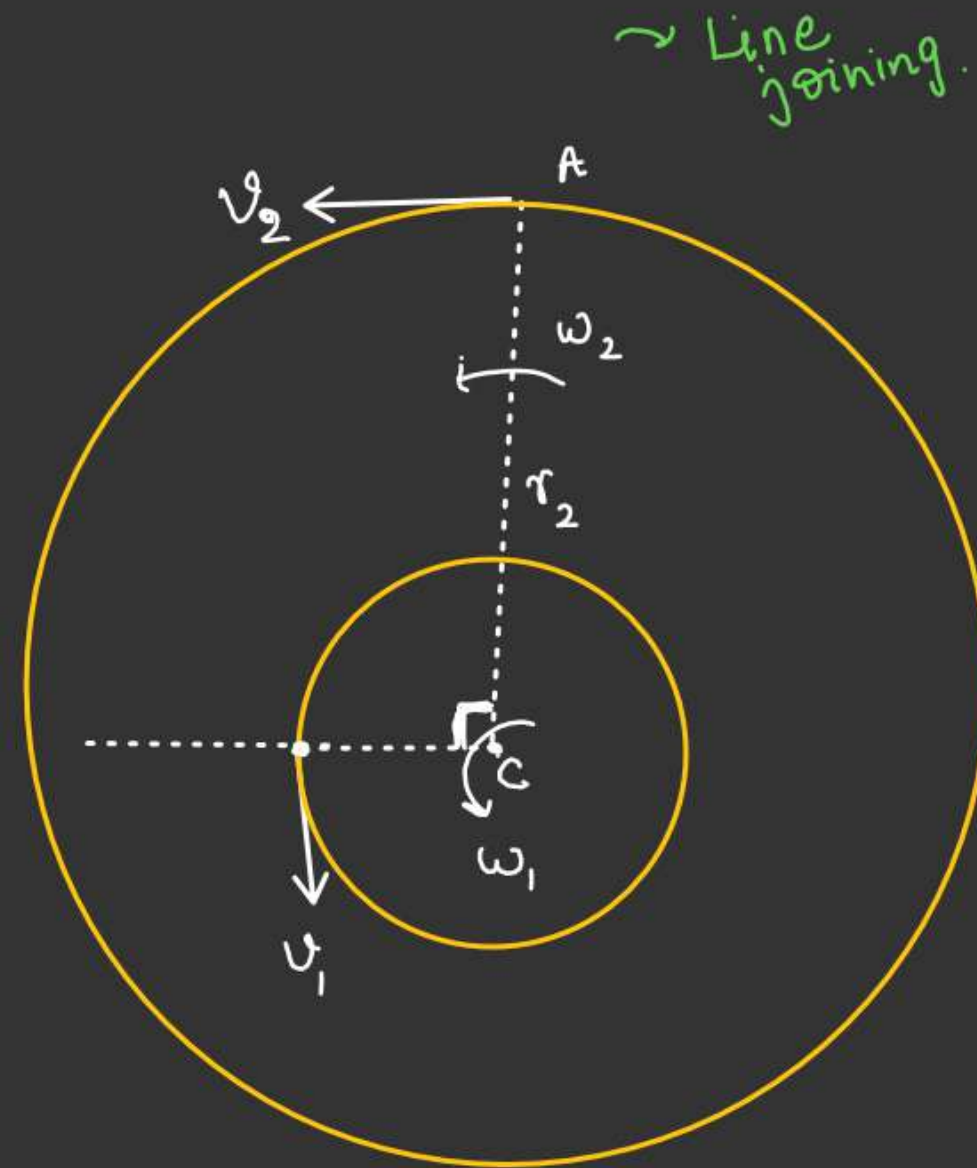


$$\omega_{A/B} = \left(\frac{v_1 r_1 + v_2 r_2}{r_1^2 + r_2^2} \right)$$

$$\omega_{A/B} = \frac{\omega_1 r_1^2 + \omega_2 r_2^2}{r_1^2 + r_2^2}$$

$$\left(\begin{array}{l} \omega_2 = \frac{v_2}{r_2} \\ \omega_1 = \frac{v_1}{r_1} \end{array} \right)$$

QA:



✖✖:

String Massless and pulley is frictionless

$$T - (T + dT) = dm \cdot a$$

\Downarrow
 0

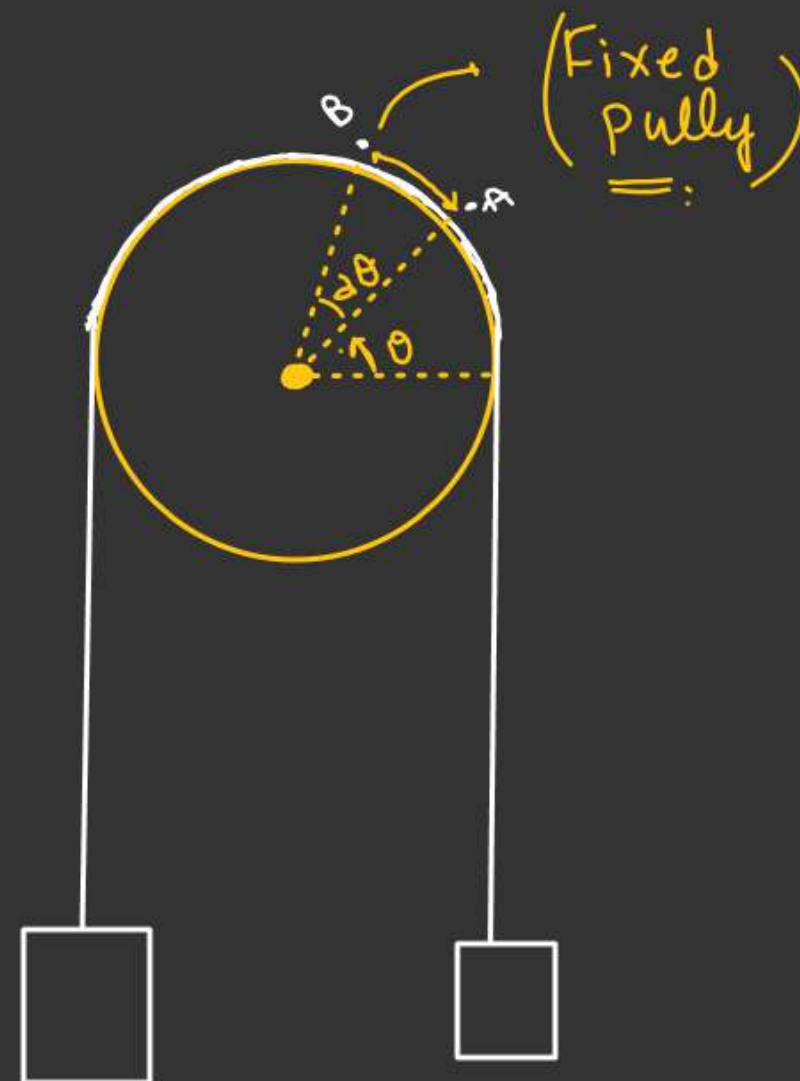
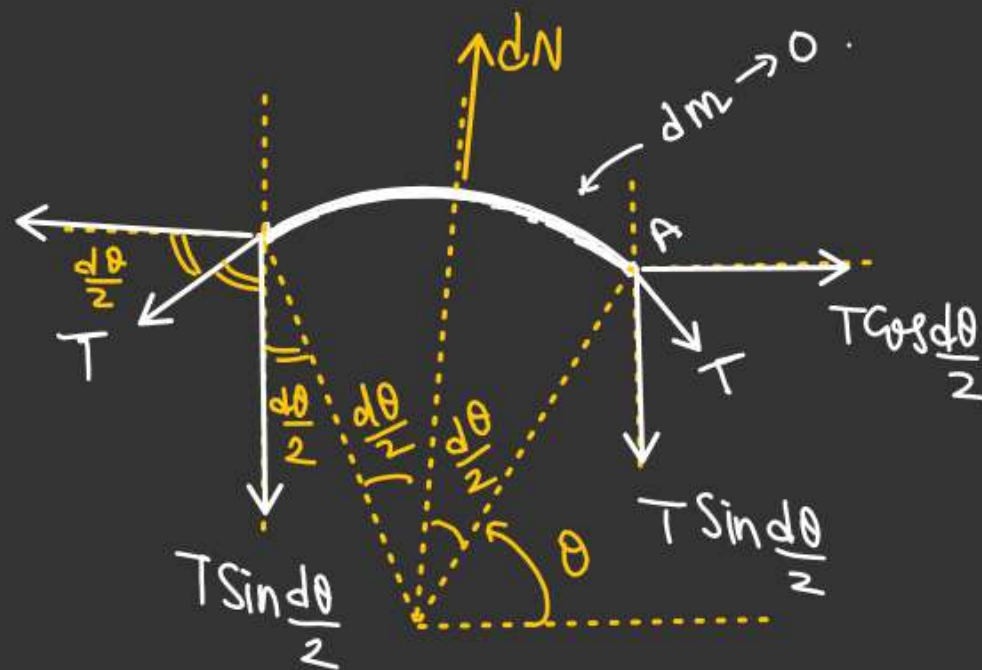
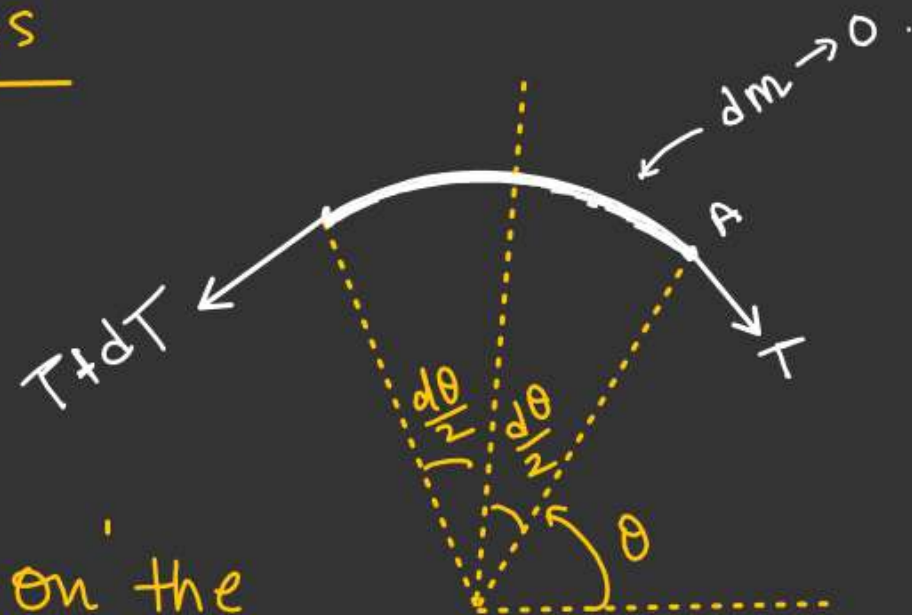
$$\underline{dT = 0}$$

Normal reaction on the pulley.

$$dN = 2T \sin\left(\frac{d\theta}{2}\right)$$

$$dN = 2T \left(\frac{d\theta}{2}\right)$$

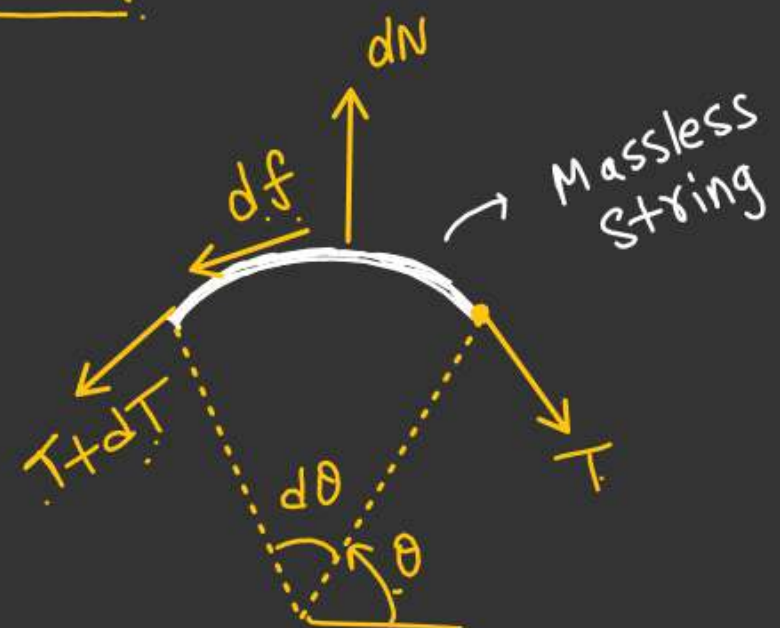
$$\boxed{dN = T d\theta}$$



If θ is very small
 $\sin \theta \approx \theta$

Q.8: When pulley is Rough.

String massless.



$$T = T + dT + df$$

$$dT = -df$$

For string just about to slip.

$$df = \mu dN$$

$$dT = -\mu dN$$

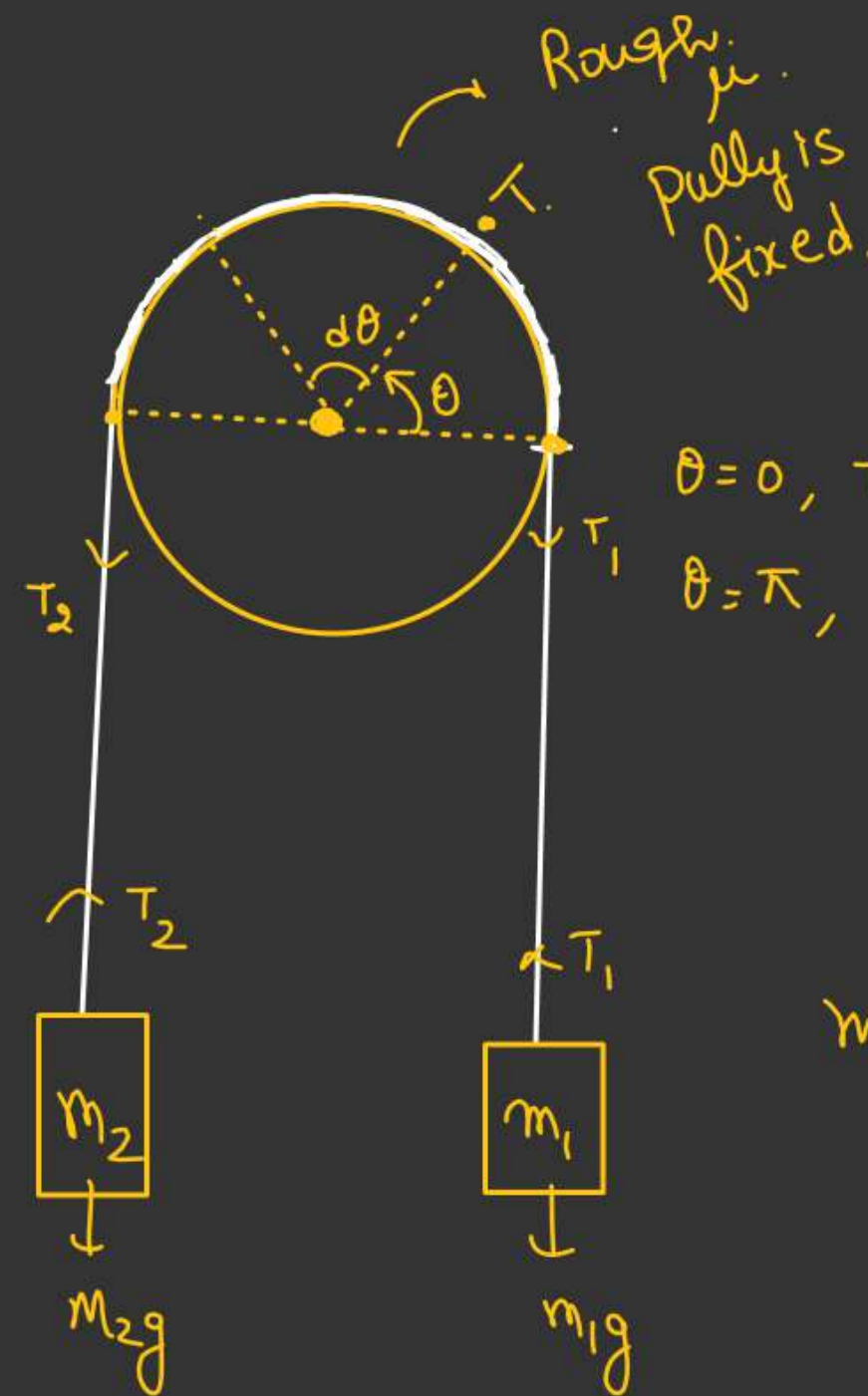
$$dT = -\mu T d\theta$$

$$dN = (T d\theta)$$

$$\int_{T_1}^T \frac{dT}{T} = -\mu \int_0^\theta d\theta$$

$$\ln\left(\frac{T}{T_1}\right) = -\mu\theta$$

$$T = T_1 e^{-\mu\theta}$$



$$\theta = 0, T = T_1 = m_1 g$$

$$\theta = \pi, T = T_2 = m_2 g$$

$$m_1 > m_2$$

$$T = T_1 e^{-\mu\theta}$$

When $\theta = \pi$, $T = T_2$

$$T_2 = T_1 e^{-\mu\pi}$$

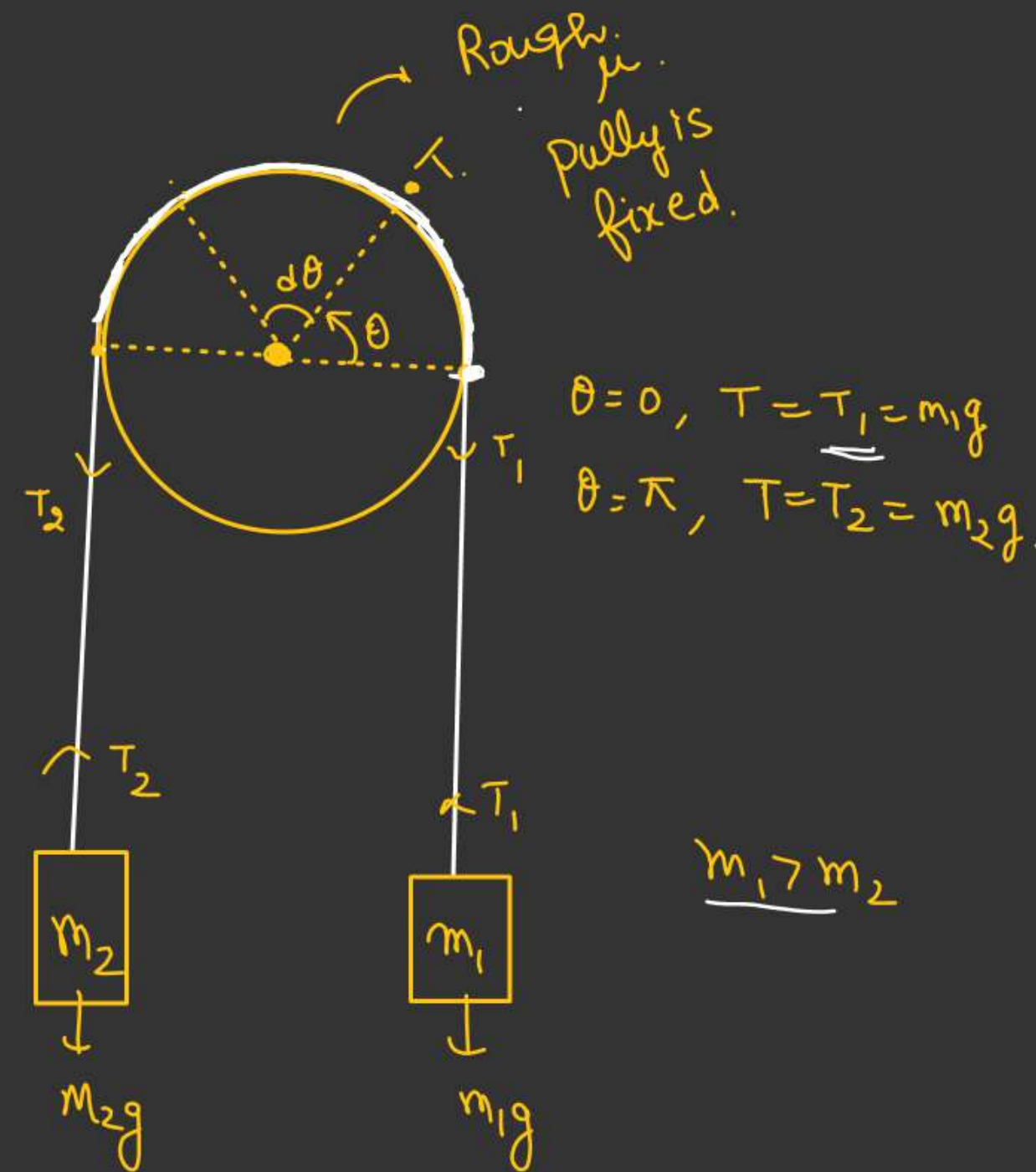
$$T_1 = T_2 e^{\mu\pi}$$

$$T_{\max} = T_{\min} e^{\mu\pi}$$

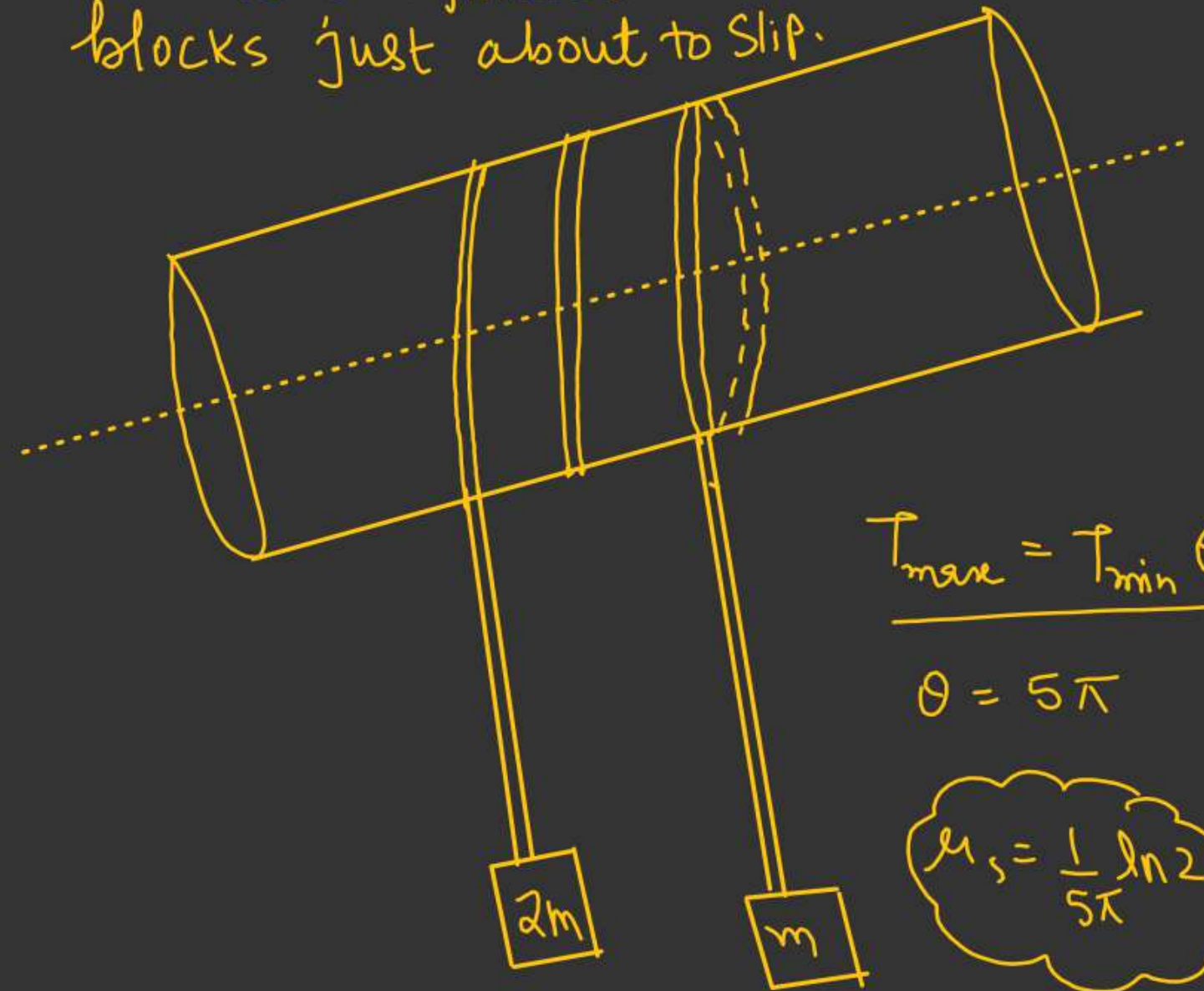
$$\left(\frac{m_1}{m_2}\right) = \frac{T_{\max}}{T_{\min}} = e^{\mu\pi}$$

$$\mu\pi = \ln\left(\frac{m_1}{m_2}\right) \Rightarrow \mu = \frac{1}{\pi} \ln\left(\frac{m_1}{m_2}\right)$$

$$\begin{pmatrix} T_2 = m_2 g \\ T_1 = m_1 g \end{pmatrix}$$



Find μ b/w string
and cylinder so that
blocks just about to slip.



$$T_{\max} = T_{\min} e^{\mu \theta}$$

$$\theta = 5\pi$$

$$\mu_s = \frac{1}{5\pi} \ln 2 \quad \text{Ans}$$