



$$y=0$$

$$f(x) = f(0)f'(0) + f'(0)x$$

$$\frac{dy}{dx} = \frac{1}{2}x$$

$$(B) g(x) \neq \frac{e^x - 1}{x}$$

~~$x=0$~~     ~~$\frac{e^x - 1}{x}$~~     ~~$x=0$~~     ~~$x=0$~~

$$\frac{1}{2}f(x) = f'(0)$$

$$\int \frac{dy}{y} = \frac{1}{2} \int dx$$

$$f'(0) = \frac{1}{2}$$

$$\ln(y/x) = x + C \Rightarrow \int \frac{dy}{y/x} = \int dx$$

$$f(x) = e^x (x+1) (x^2 + \sin x) g(x) = 0$$

$$\lim_{x \rightarrow 0}$$

$$\ln y = \frac{1}{2}x + C$$

$$f'(x) = (f(x)+1) \left( \lim_{h \rightarrow 0} \frac{f(h)}{h} \right)$$

$$f'(0) = (f(0)+1) f'(0) = f(0)+1$$

$$f'(0) = \lim_{x \rightarrow 0} \frac{f(x)g(x)}{x} = 1$$

$$y = a \cos(\ln x) + b \sin(\ln x)$$

$$x^2 y_3 + 3xy_2 + 2y_1 = 0$$

$$xy_1 = -a \sin(\ln x) + b \cos(\ln x)$$

$$x(xy_2 + y_1) = -a \cos(\ln x) - b \sin(\ln x) = -y$$

$$x^2 y_2 + xy_1 = -y$$

$$2xy_2 + x^2 y_3 + xy_2 + y_1 = -y_1$$

$$y^{\frac{1}{m}} + y^{-\frac{1}{m}} = 2x$$

$$(x^2-1)y_3 + 3xy_2 + (1-m^2)y_1 = 0$$

$$t + \frac{1}{t} = 2x \Rightarrow t^2 - 2xt + 1 = 0, \quad t = x \pm \sqrt{x^2 - 1} = y^{\frac{1}{m}}$$

$$y = \left(x - \sqrt{x^2 - 1}\right)^m$$

$$y_1 = m \left(x - \sqrt{x^2 - 1}\right)^{m-1} \left(1 - \frac{x}{\sqrt{x^2 - 1}}\right) = \frac{-my}{\sqrt{x^2 - 1}}$$

$$(x^2-1)y_1^2 = m^2 y^2 \Rightarrow 2(x^2-1)y_1 y_2 + 2xy_1^2 = 2m^2 y y_1$$

$$(x^2-1)y_2 + xy_1 = m^2 y \Rightarrow (x^2-1)y_3 + 2xy_2 + xy_2 + y_1 = m^2 y_1$$

Q. Use the substitution  $x = \tan \theta$  to show that the equation

$$-\sin 2\theta \cos^2 \theta \frac{dy}{d\theta} + \cos^4 \theta \frac{d^2y}{d\theta^2} + \sin 2\theta \cos^3 \theta \frac{dy}{d\theta} + \cos^4 \theta \frac{d^2y}{d\theta^2} = 0$$

$\frac{dx}{d\theta} = \sec^2 \theta$

$$\frac{dy}{dx} = \frac{dy}{d\theta} \frac{d\theta}{dx} = \cos^2 \theta \frac{dy}{d\theta}$$

$$\cos^4 \theta \left( \frac{d^2y}{d\theta^2} + x \right) = 0$$

$$\frac{d^2y}{dx^2} = \frac{d}{dx} \left( \cos^2 \theta \frac{dy}{d\theta} \right) = \frac{d}{d\theta} \left( \cos^2 \theta \frac{dy}{d\theta} \right) \cdot \frac{d\theta}{dx} = \cos^2 \theta \left( -\sin 2\theta \frac{dy}{d\theta} + \cos^2 \theta \frac{d^2y}{d\theta^2} \right)$$

$$\frac{d^2y}{dx^2} = -\sin 2\theta \cos^2 \theta \frac{dy}{d\theta} + \cos^4 \theta \frac{d^2y}{d\theta^2}$$

Q. P.T.  $\frac{d^2x}{dy^2} = -\frac{\frac{d^2y}{dx^2}}{(dy/dx)^3} \Rightarrow \frac{d^3x}{dy^3} = -\frac{d}{dn}\left(\frac{\frac{d^2y}{dx^2}}{(dy/dx)^3}\right) \frac{dx}{dy}$

$$\frac{3(y'')^2 - y'y'''}{(y')^5} = -\frac{((y')^3 y''' - y'' 3(y')^2 y'')}{(y')^6} \cdot \frac{1}{y'}$$

$$\frac{dx}{dy} = \frac{1}{\left(\frac{dy}{dx}\right)} \quad \text{and} \quad \frac{d^2x}{dy^2} = \frac{1}{\left(\frac{dy}{dx}\right)^2} \frac{d^2y}{dx^2} \left(\frac{1}{\frac{dy}{dx}}\right) = -\frac{d^2y}{dx^2} \left(\frac{1}{\frac{dy}{dx}}\right)^3$$

$$\frac{d^2x}{dy^2} = \frac{d}{dy}\left(\frac{1}{\frac{dy}{dx}}\right) = \frac{d}{dx}\left(\frac{1}{\left(\frac{dy}{dx}\right)}\right) \frac{dx}{dy}$$

$$= \frac{\left(\frac{dy}{dx}\right)(0) - 1 \left(\frac{d^2y}{dx^2}\right)}{\left(\frac{dy}{dx}\right)^2} \left(\frac{1}{\frac{dy}{dx}}\right)$$

# Derivative of determinant

$$D(x) = \begin{vmatrix} f_1(x) & f_2(x) & f_3(x) \\ g_1(x) & g_2(x) & g_3(x) \\ h_1(x) & h_2(x) & h_3(x) \end{vmatrix} \quad D'(x) =$$

$$D'(x) = \begin{vmatrix} f'_1(x) & f'_2(x) & f'_3(x) \\ g_1(x) & g_2(x) & g_3(x) \\ h_1(x) & h_2(x) & h_3(x) \end{vmatrix} + \begin{vmatrix} f_1(x) & f_2(x) & f_3(x) \\ g'_1(x) & g'_2(x) & g'_3(x) \\ h_1(x) & h_2(x) & h_3(x) \end{vmatrix} + \begin{vmatrix} f_1(x) & f_2(x) & f_3(x) \\ g_1(x) & g_2(x) & g_3(x) \\ h'_1(x) & h'_2(x) & h'_3(x) \end{vmatrix}$$

$$\lim_{\Delta x \rightarrow 0} \frac{D(x + \Delta x) - D(x)}{\Delta x}$$

$\Delta x \rightarrow 0$

$$= \lim_{\Delta x \rightarrow 0} \frac{f_1(x + \Delta x) - f_1(x)}{\Delta x} + \lim_{\Delta x \rightarrow 0} \frac{f_2(x + \Delta x) - f_2(x)}{\Delta x} + \lim_{\Delta x \rightarrow 0} \frac{f_3(x + \Delta x) - f_3(x)}{\Delta x}$$

$$= \lim_{\Delta x \rightarrow 0} g_1(x + \Delta x) + \lim_{\Delta x \rightarrow 0} g_2(x + \Delta x) + \lim_{\Delta x \rightarrow 0} g_3(x + \Delta x)$$

$$= h_1(x + \Delta x) + h_2(x + \Delta x) + h_3(x + \Delta x)$$

$$+ \begin{vmatrix} f_1(x) & f_2(x) & f_3(x) \\ g_1(x) & g_2(x) & g_3(x) \\ \frac{f_1(x + \Delta x) - f_1(x)}{\Delta x} & \frac{f_2(x + \Delta x) - f_2(x)}{\Delta x} & \frac{f_3(x + \Delta x) - f_3(x)}{\Delta x} \\ -h_1(x) & -h_2(x) & -h_3(x) \end{vmatrix} = \begin{vmatrix} f'_1 & f'_2 & f'_3 \\ g_1 & g_2 & g_3 \\ h_1 & h_2 & h_3 \end{vmatrix} +$$

$P_{T-1} + P_{T-2}$

$$\lim_{\Delta x \rightarrow 0} f_1 g_2 h_3 - \dots$$