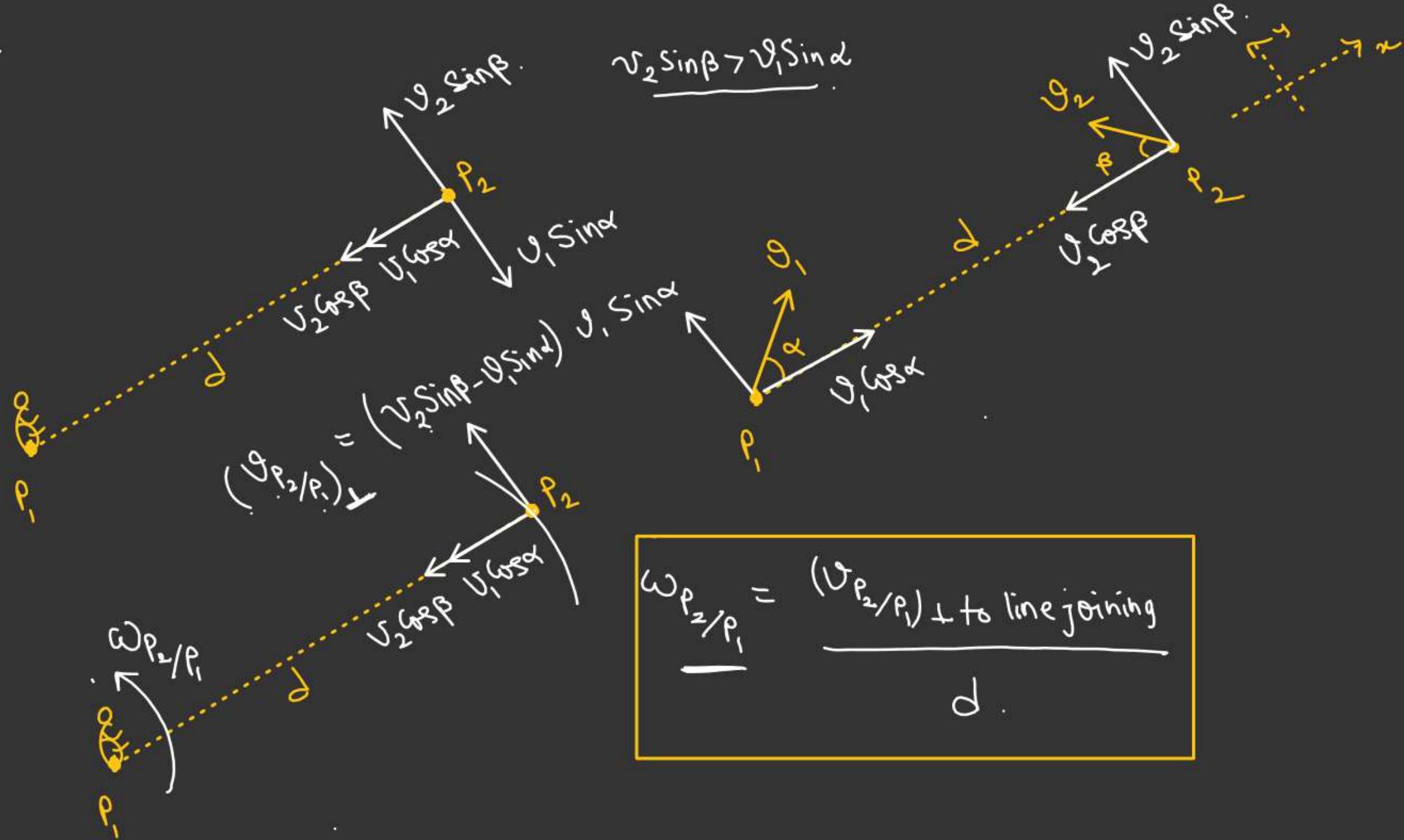


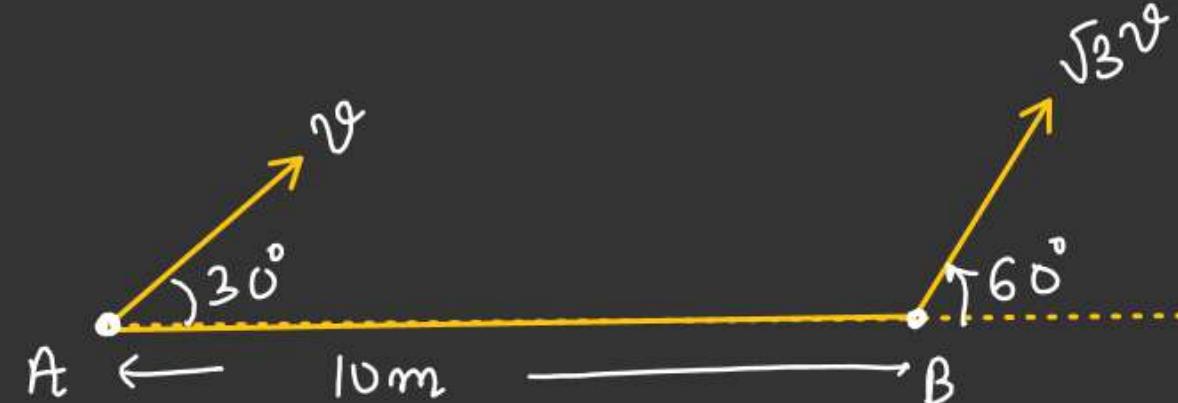
Relative angular velocity

Relative angular velocity b/w two points moving in a plane



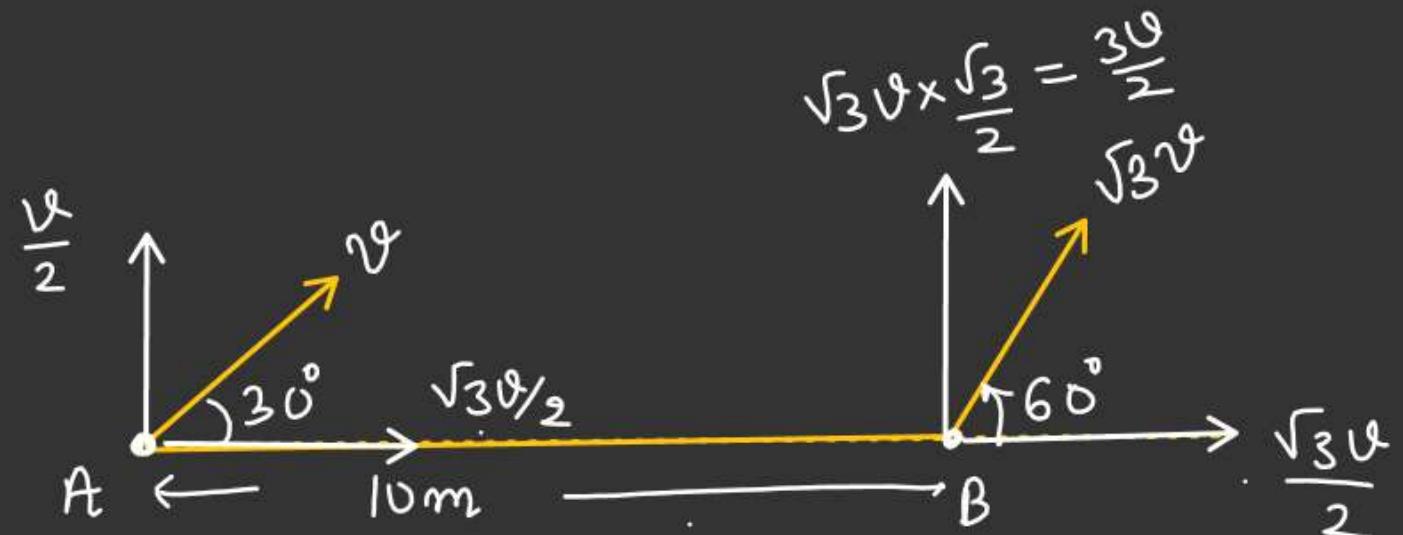
$$\omega_{B/A} = ??$$

$$\begin{aligned}\vec{v}_{B/A} &= \vec{v}_{B/E} - \vec{v}_{A/E} \\ &= \left(\frac{\sqrt{3}v}{2} \hat{i} + \frac{3v}{2} \hat{j} \right) - \left(\frac{\sqrt{3}v}{2} \hat{i} + \frac{v}{2} \hat{j} \right) \\ &= v \hat{j}\end{aligned}$$



$$\omega_{B/A} = \frac{v}{10} \text{ Ans.}$$

$$\left(\begin{array}{l} v = R\omega \\ \omega = v/R \end{array} \right)$$



~~* *~~
Relative Angular velocity b/w two points Moving
in a Circle of radius R with velocity $v_1 \& v_2$

$v_1 \& v_2$ constant

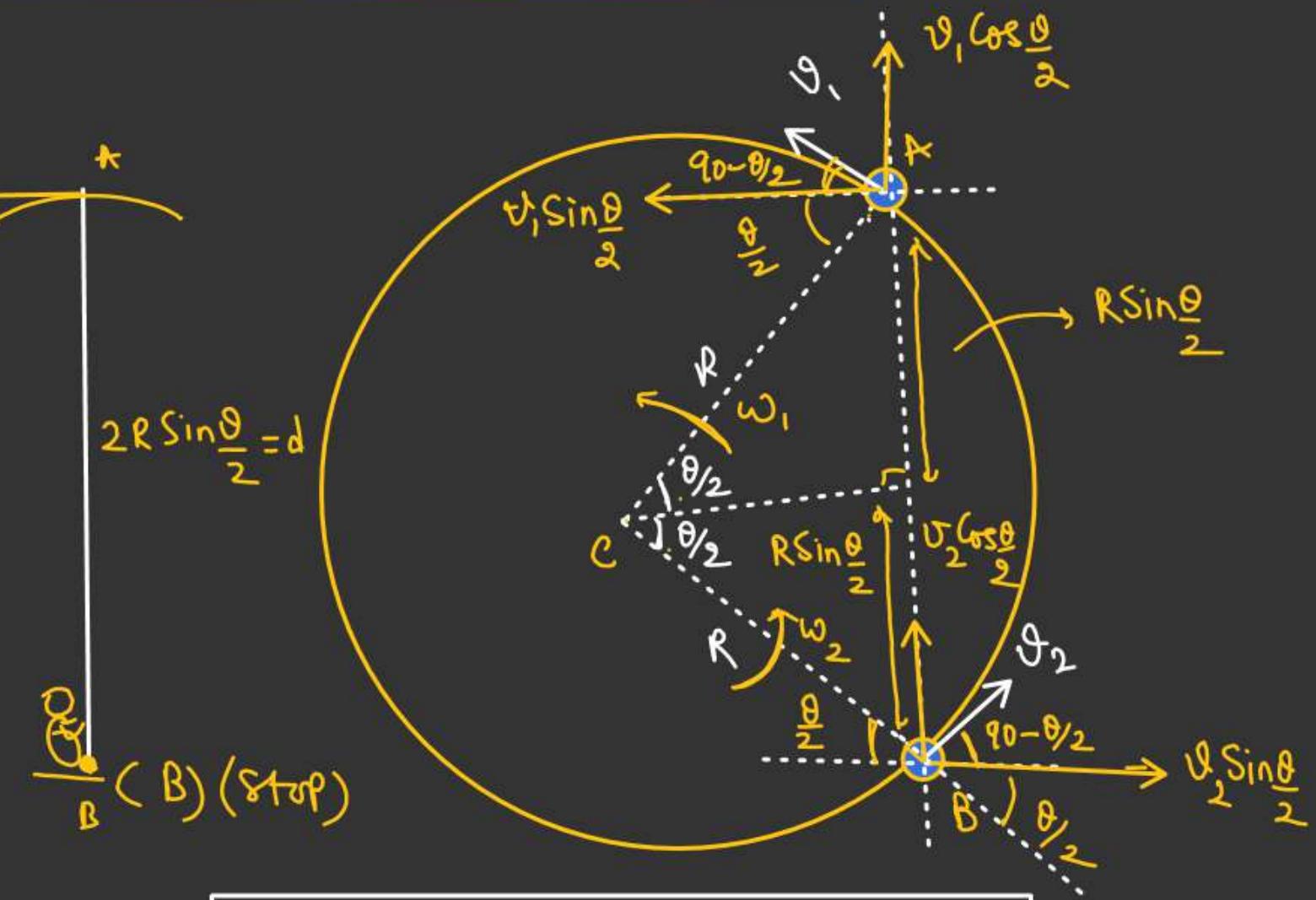
$$\omega_{A/B} = \frac{(v_{A/B})_\perp}{d_{AB}}$$

$$(v_{A/B})_\perp = (v_1 + v_2) \sin \frac{\theta}{2}$$

$$\omega_{A/B} = \frac{(v_1 + v_2) \sin(\theta/2)}{2 R \sin(\theta/2)}$$

$$\omega_{A/B} = \left(\frac{v_1 + v_2}{2 R} \right)$$

$$\omega_{A/B} = \frac{(v_1/R) + (v_2/R)}{2} = \frac{\omega_1 + \omega_2}{2}$$



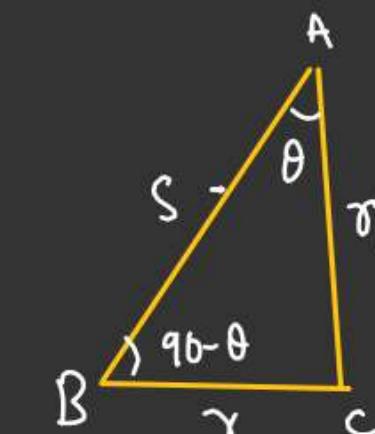
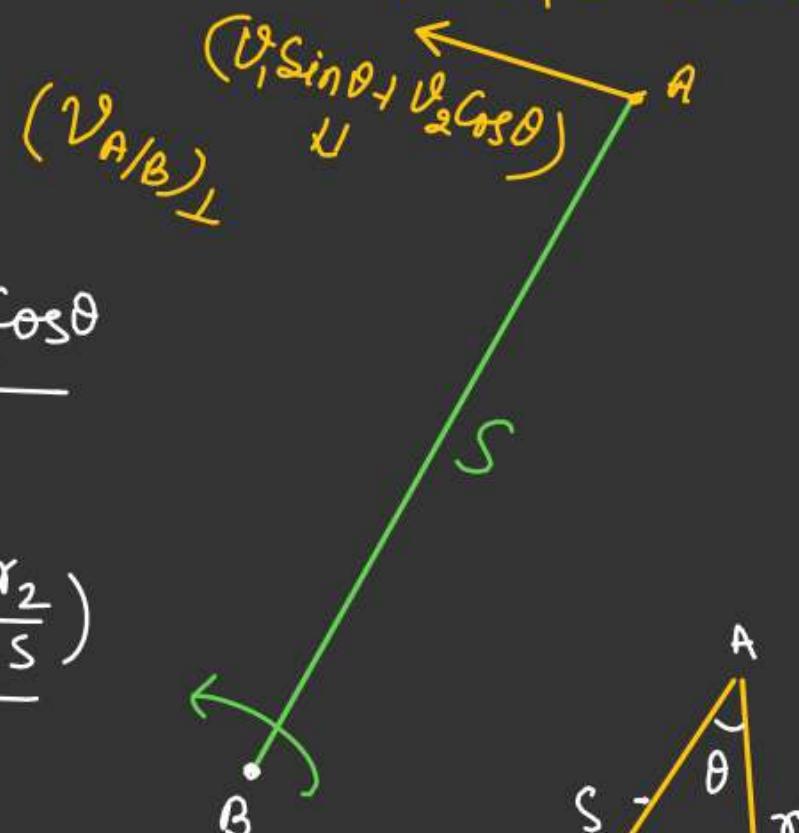
$$\omega_{A/B} = \frac{\omega_1 + \omega_2}{2} \Rightarrow \text{Rotating in Same sense}$$

Relative Angular velocity b/w two points moving in a concentric circle when their radius vector are perpendicular to each other.

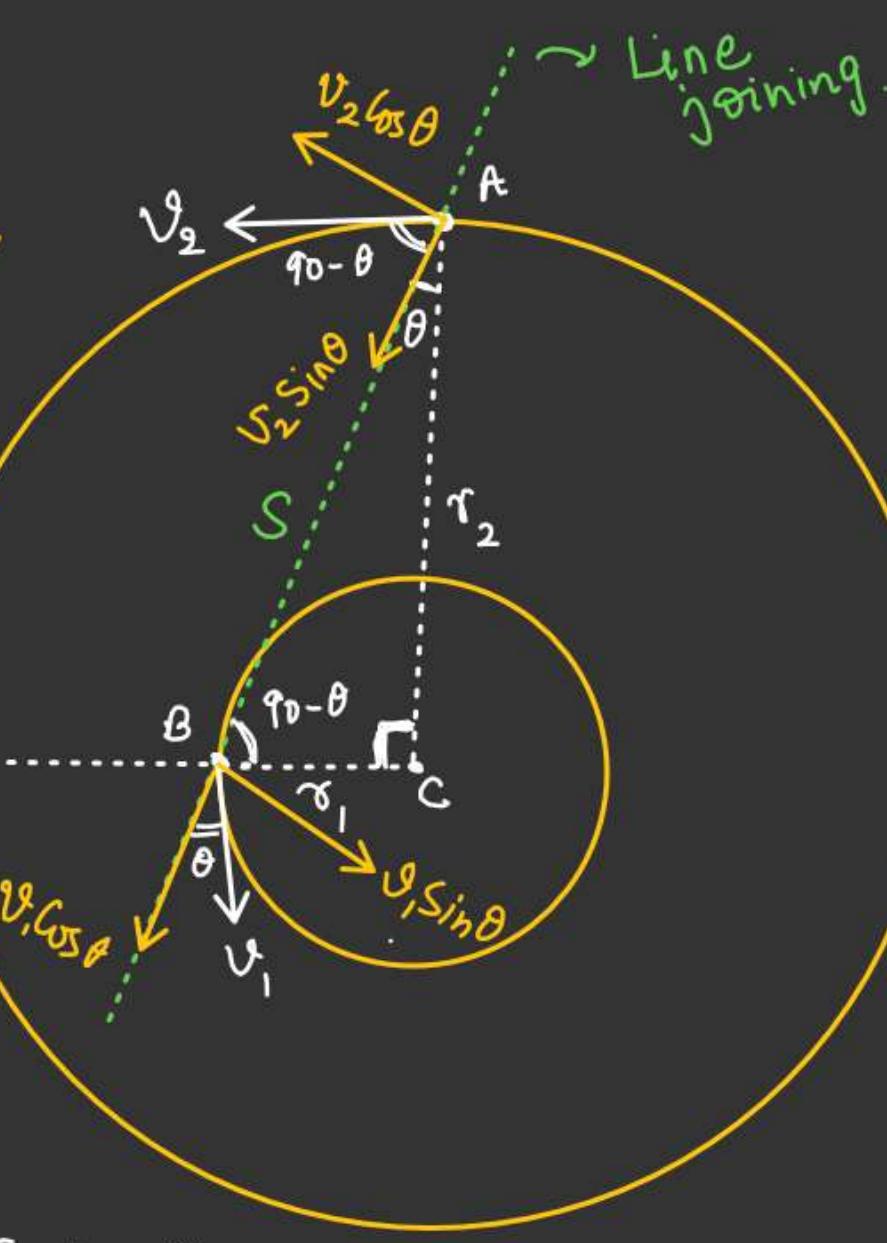
$$\omega_{A/B} = \frac{v_1 \sin \theta + v_2 \cos \theta}{S}$$

$$\begin{aligned}\omega_{A/B} &= \frac{v_1 \left(\frac{r_1}{S} \right) + v_2 \left(\frac{r_2}{S} \right)}{S} \\ &= \frac{v_1 r_1 + v_2 r_2}{S^2}\end{aligned}$$

$$\boxed{\omega_{A/B} = \left(\frac{v_1 r_1 + v_2 r_2}{r_1^2 + r_2^2} \right)}$$



$$\begin{aligned}\sin \theta &= \frac{r_1}{S} \\ \cos \theta &= \frac{r_2}{S} \\ S &= \sqrt{(r_1^2 + r_2^2)}\end{aligned}$$



~ Line joining.

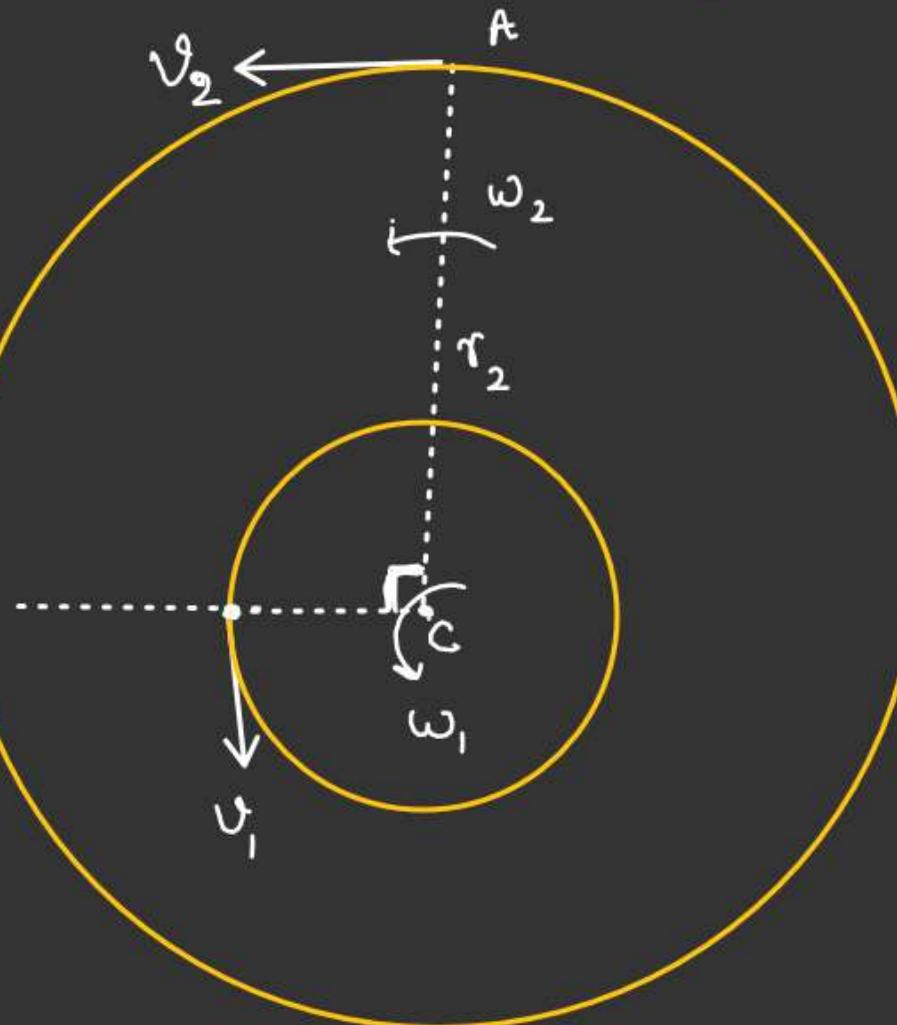
~ Line
joining.

$$\omega_{A/B} = \left(\frac{v_1 r_1 + v_2 r_2}{r_1^2 + r_2^2} \right)$$

$$\left(\begin{array}{l} \omega_2 = \frac{v_2}{r_2} \\ \omega_1 = \frac{v_1}{r_1} \end{array} \right)$$

~~AA~~:

$$\omega_{A/B} = \frac{\omega_1 r_1^2 + \omega_2 r_2^2}{r_1^2 + r_2^2}$$

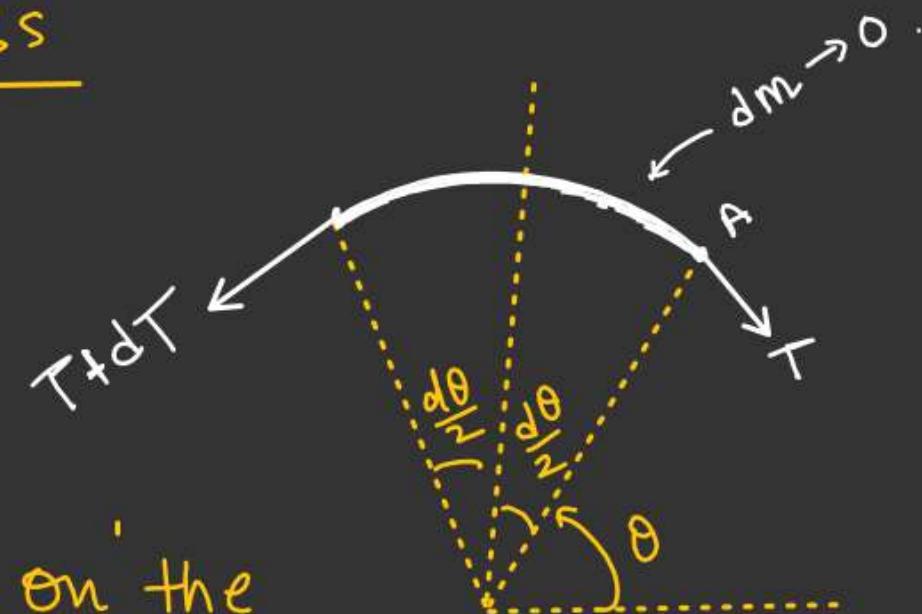




String Massless and pulley is
friction less

$$T - (T + dT) = dm a$$

$$\frac{dT = 0}{}$$



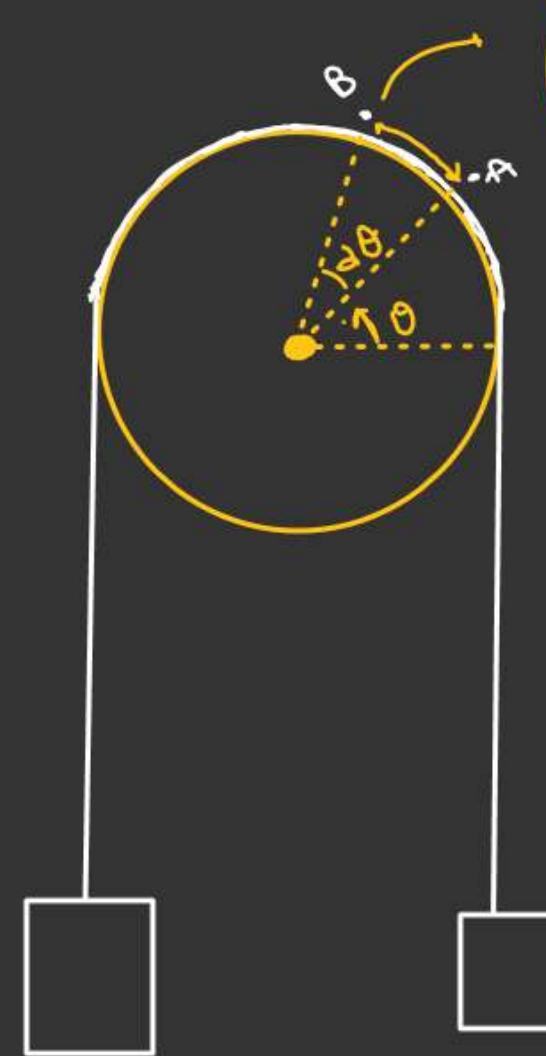
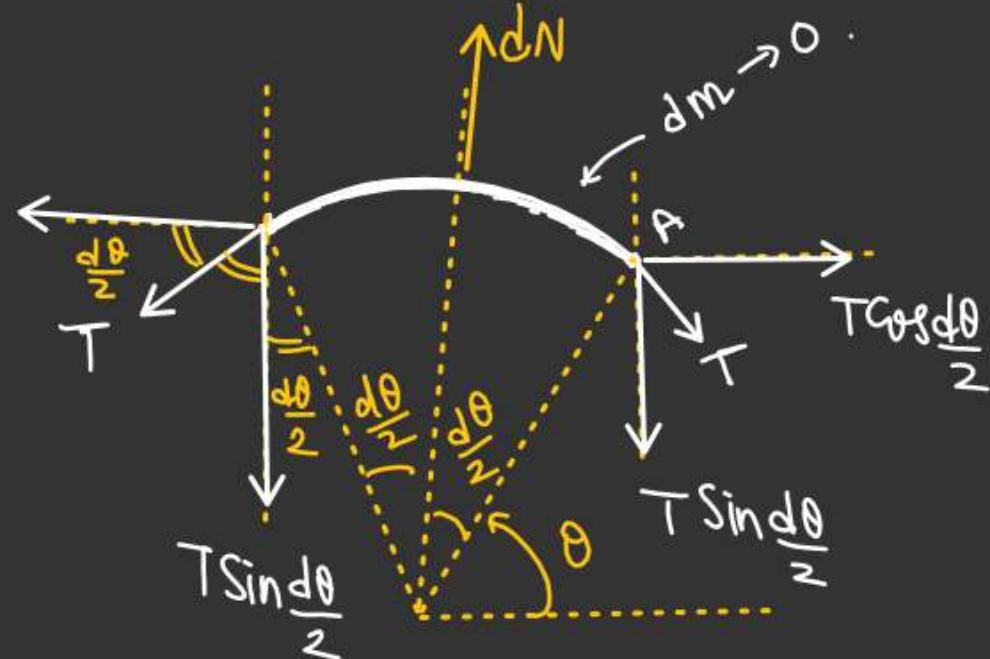
(Fixed
Pully)

Normal reaction on the
pully.

$$dN = 2T \sin\left(\frac{d\theta}{2}\right)$$

$$dN = 2T\left(\frac{d\theta}{2}\right)$$

$$dN = T d\theta$$



If θ is very small
 $\sin \theta \approx \theta$

When pulley is Rough

String massless.

$$T = T + dT + df$$

$$dT = -df$$

For string just about to slip.

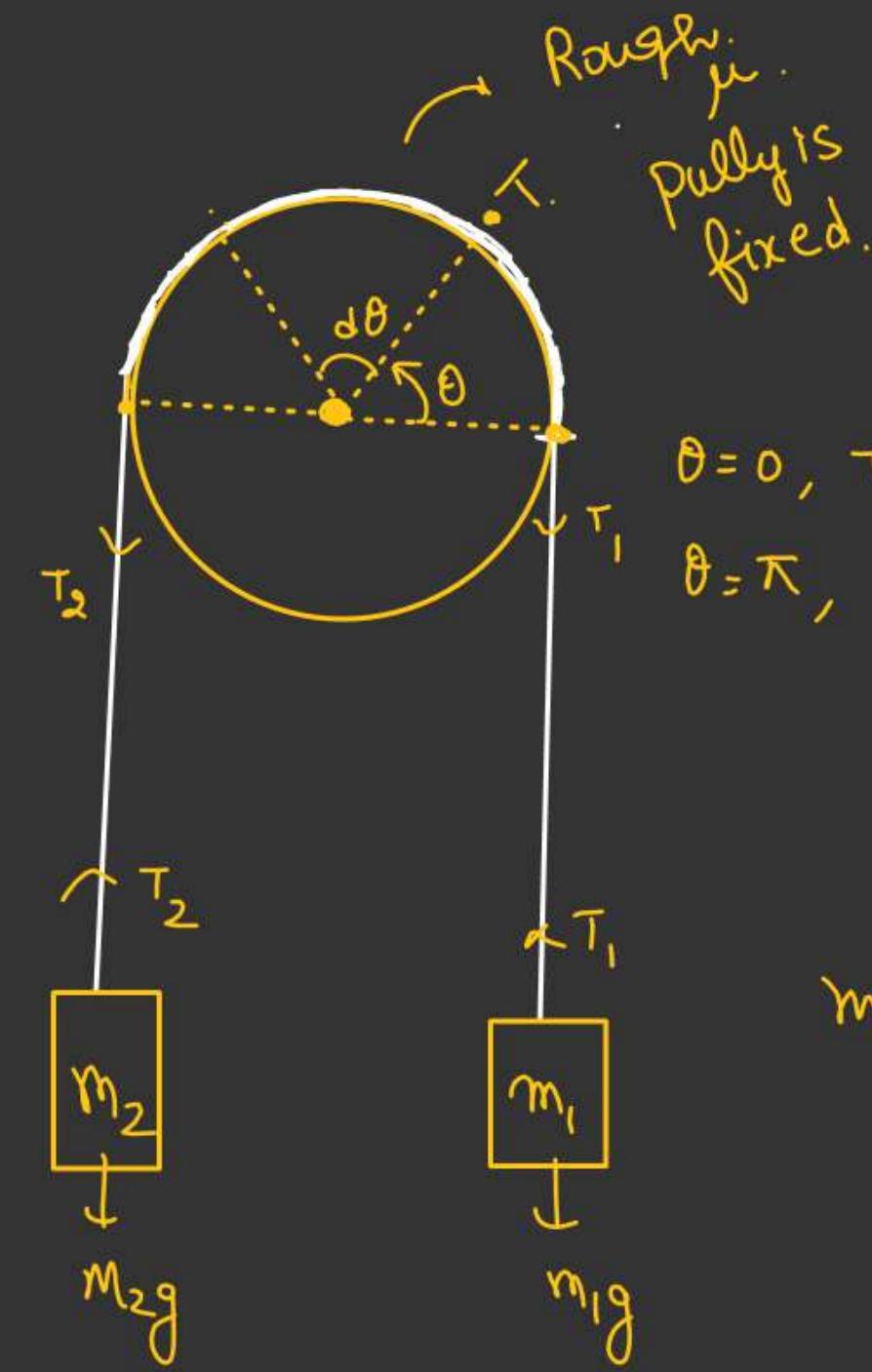
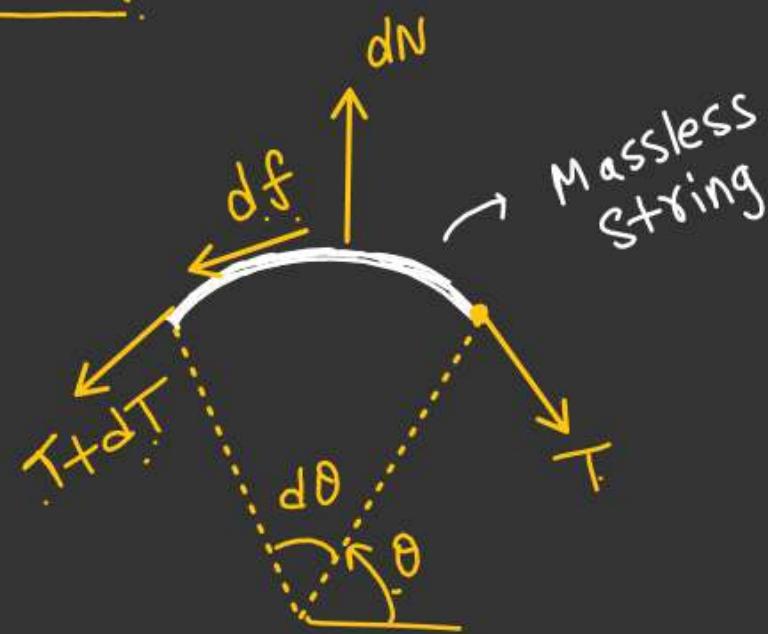
$$df = \mu dN$$

$$dT = -\mu dN$$

$$dT = -\mu T d\theta$$

$$\ln\left(\frac{T}{T_1}\right) = -\mu\theta$$

$$T = T_1 e^{-\mu\theta}$$



$$\theta = 0, T = T_1 = m_1 g$$

$$\theta = \pi, T = T_2 = m_2 g$$

$$m_1 > m_2$$

$$T = T_1 e^{-\mu \theta} \quad \text{---}$$

When $\theta = \pi$, $T = T_2$

$$T_2 = T_1 e^{-\mu \pi}$$

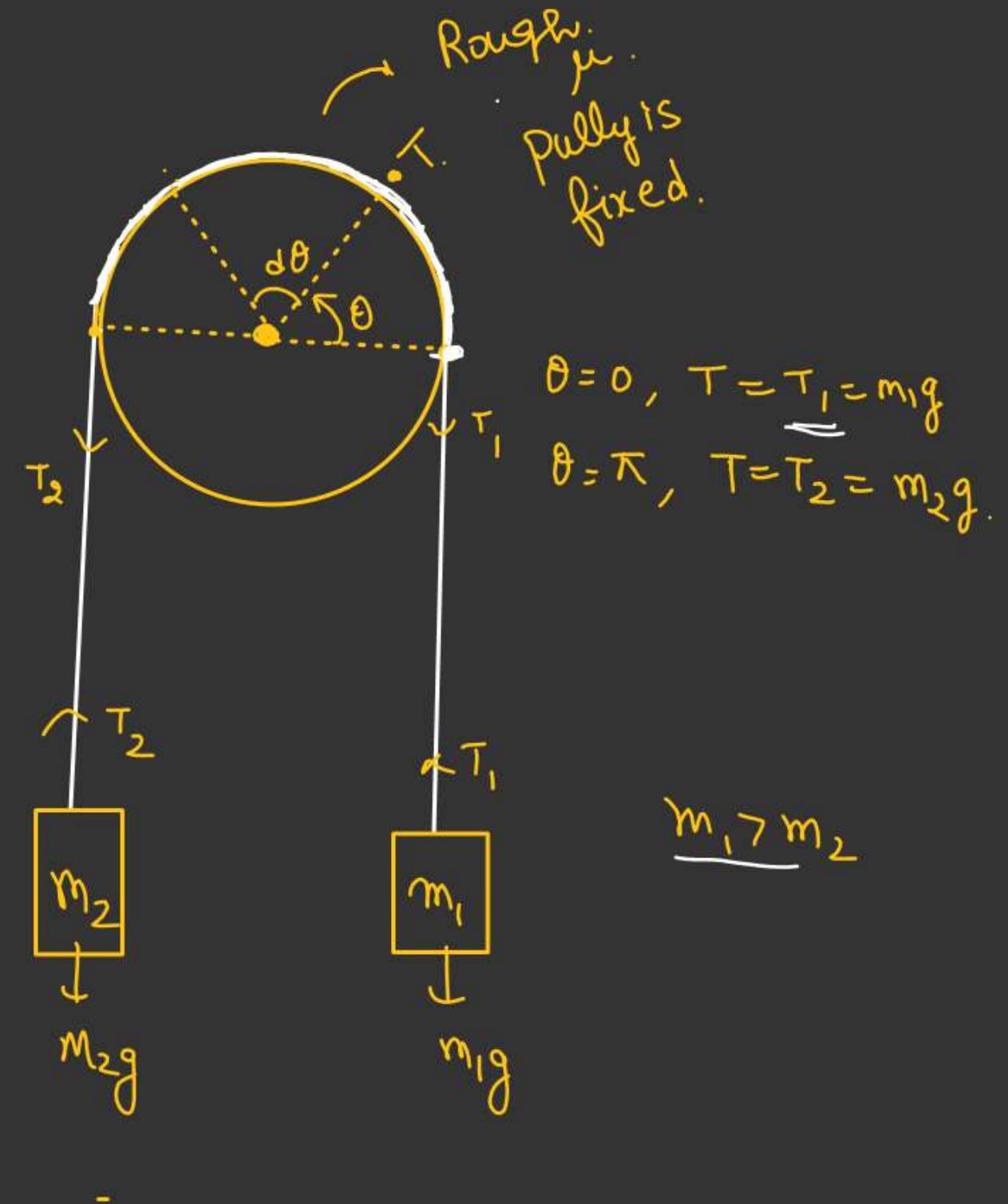
$$\underline{T_1} = T_2 e^{\mu \pi}$$

↓

$$T_{\max} = T_{\min} e^{\mu \pi}$$

$$\left(\frac{m_1}{m_2}\right) = \frac{T_{\max}}{T_{\min}} = e^{\mu \pi}$$

$$\mu \pi = \ln\left(\frac{m_1}{m_2}\right) \Rightarrow \mu = \frac{1}{\pi} \ln\left(\frac{m_1}{m_2}\right)$$



Fin μ b/w string
and cylinder so that
blocks just about to slip.

