



DPP - 1

Solution

1. moment of inertia of the ring where axis is in plane of the ring $I_1 = MR^2$

moment of inertia of 2nd ring about axis passing through the center of the 1st ring

$$I_2 = \frac{MR^2}{2} \text{ (By perpendicular Theorem)}$$

$$I = I_1 + I_2 = MR^2 + \frac{MR^2}{2} = \frac{3}{2}MR^2$$

$$\text{so } p + q = 3 + 2 = 5$$

2. Moment of Inertia of two spheres lying on the axis is $2 \times \frac{2}{5}ma^2 = \frac{4}{5}ma^2$

moment of Inertia of two sphere lying on the edge parallel to the axis at a distance of b :

$$= 2 \left[\frac{2}{5}ma^2 + mb^2 \right] = \frac{4}{5}ma^2 + 2mb^2.$$

$$\text{So Total moment of Inertia} = \frac{4}{5}ma^2 + 2mb^2 + \frac{4}{5}ma^2 = \frac{8}{5}ma^2 + 2mb^2$$

$$\therefore \frac{\alpha + \gamma}{\beta} = \frac{8+2}{5} = 2$$

3. Moment of inertia can be calculated by principle of superposition

$$MI = \frac{1}{2} \times 9MR^2 - \left(\frac{MR^2}{18} + M \times \frac{4R^2}{9} \right)$$

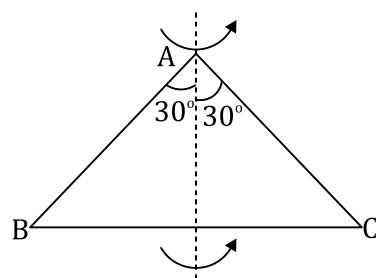
$$= \frac{72MR^2}{18} = 4MR^2$$

4. $I = I_{AB} + I_{BC} + I_{AC}$

$$I_{AC} = \frac{ml^2}{3} \sin^2 \theta$$

$$= \frac{mb^2}{3} \frac{1}{4}$$

$$= \frac{mb^2}{12} = I_{AB}$$



$$I = 2 \left(\frac{mb^2}{12} \right) + \frac{mb^2}{12}$$

$$I = \frac{mb^2}{4}$$

$$\text{ie } \frac{a}{16} = \frac{1}{4}$$

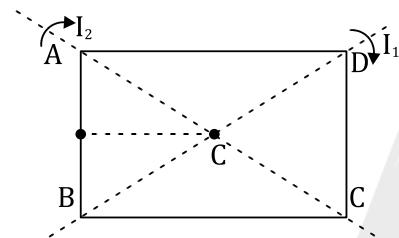
$$a = 4$$

5. As given in Question

$$\sqrt{2}L = b$$

$$\therefore L = \frac{b}{\sqrt{2}}$$

$$L^2 = \frac{b^2}{2}$$



Moment of Inertia of AB = $\frac{mL^2}{12}$ about C (MI)

$$I' = \frac{mL^2}{12} + m\left(\frac{L}{2}\right)^2$$

$$I' = \frac{1}{3}ML^2 \text{ parallel axis}$$

$$\text{for } < 114\text{rod} = 4\left(\frac{1}{3}mL^2\right) = \frac{4}{3}mL^2 = I$$

By perpendicular axis Theorem

$\because I_1 = I_2$ (because frame is symmetrical)

$$I = I_1 + I_2 = 2I_1$$

$$I_1 = I/2 = \frac{2mL^2}{3}$$

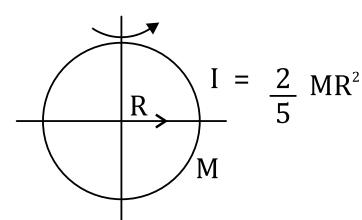
$$I_1 = \frac{2mb^2}{3 \times 2} = \frac{mb^2}{3}$$

$$\text{ie } \cdot P = 6.$$

6. case 1

Let

Aluminum density = 0





$$M = \rho V = \rho \left(\frac{4}{3} \pi R^3 \right) \rightarrow (1)$$

$$I' = \frac{2}{5} M' R'^2$$

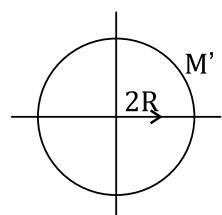
$$= \frac{2}{5} 8M(2R)^2 = 32 \left(\frac{2}{5} \right) MR^2$$

$$I' = 32 \left[\frac{2}{5} MR^2 \right] = 32I$$

$$\therefore I' = 32I$$

Thus option (E)

Case 2



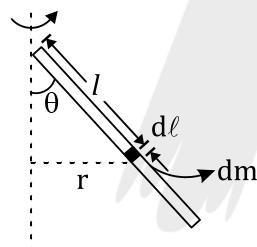
$$M' = \rho \left(\frac{4}{3} \pi (2R)^3 \right)$$

$$M' = 8 \cdot \frac{4}{3} \pi R^3 \rightarrow (2)$$

$$M' = 8M [\text{From 0}]$$

7. We can observe that each and every element of rod is rotating with different radius about the axis of rotation

Take an elementary mass dm of the rod



$$dm = \frac{m}{l_0} dl$$

The moment of inertia of the elementary mass is given as $dI = (dm)r^2$

The moment of inertia of the rod

$$= I = \int dI \Rightarrow I = \int r^2 dm$$

Substituting $r = l \sin \theta$; $dm = \frac{m}{l_0} dl$ we obtain

$$I = \int (l^2 \sin^2 \theta) \frac{m}{l_0} dl = \frac{m \sin^2 \theta}{l_0} \int_0^{l_0} l^2 dl = \frac{ml_0^3}{3l_0} \sin^2 \theta$$

$$\Rightarrow I = \frac{ml_0^2 \sin^2 \theta}{3}$$

8. In the given diagrams, when the small piece Q is removed and glued to the centre of the plate, the mass comes closer to the z-axis; hence, moment of inertia decreases.
9. Divide the ring into infinitely small lengths of mass dm_i . Even though mass distribution is non-uniform, each mass dm_i is at the same distance R from origin.

10. $I_{yy'} = \frac{2}{5} M \left(\frac{R}{2}\right)^2 + M(2R)^2 + \frac{2}{5} M \left(\frac{R}{2}\right)^2$

$$= \frac{2}{5} \frac{MR^2}{4} + M(4R)^2 + \frac{2}{5} M \frac{R^2}{4}$$

$$= MR^2 \left[\frac{1}{5} + 4 \right]$$

$$I_{yy'} = \frac{21}{5} MR^2$$

11. When body is hinged at a distance x, then moment of inertia is given by:-

$$\Rightarrow I = x^2 - 2x + 99$$

As we know Moment of Inertia (I) about Centre of mass (com) is minimum

$$\Rightarrow \frac{dI}{dx} = \text{minimum about COM}$$

$$\Rightarrow \frac{dI}{dx} = 2x - 2 = 0 \Rightarrow x = 1$$

Hence, Coordinate of Centre of mass is 1 unit.

12. Moment of Inertia about AB $\Rightarrow I_p$

Moment of Inertia about AC $\Rightarrow I_B$

Moment of Inertia about BC $= I_H$

Moment of Inertia about an axis perpendicular to point c $\Rightarrow I_c$

We know that,

Moment of Inertia is More when mass is farther from the axis. ($M \cdot O \cdot I \Rightarrow MR^2$)

i.e BC

And Less when mass distribution is closest to it i.e AB.

So, the order will be.

$$I_{AB} > I_{AC} > I_{BC}/I_p > I_B > I_H$$

Now, I_c

Let the distance of point c from COM of the plate be $\rightarrow y$

And of point A from CoM of the plate by $\rightarrow x$

$$I_c \Rightarrow I_{COM} + M_y^2 \text{ (Parallel Axis Theorem)-(1)}$$



$$I_A \Rightarrow I_{COM} + M_x^2 - (2)$$

From (1) & (2)

$$I_C \Rightarrow I_A - mx^2 + my^2$$

$$I_C \Rightarrow I_A + m(y^2 - x^2)$$

$I_A = I_p + I_B$ (Perpendicular Axis Theorem)

$$I_C = I_p + I_B + m(y^2 - x^2)$$

so, I_c will be the greatest one.

$$I_C > I_p > I_B > I_H$$

Hence the correct option is (A.)