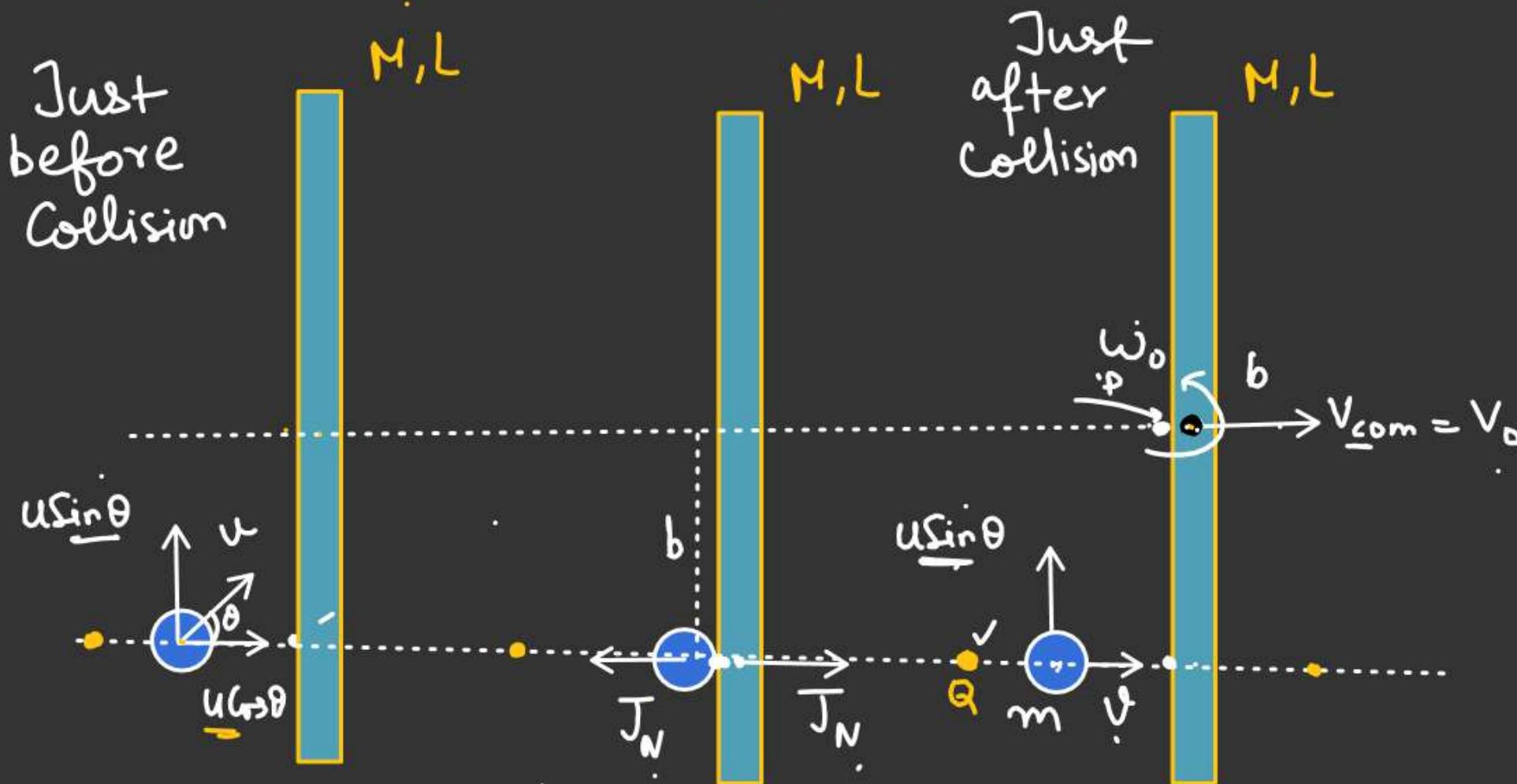


## Case of collision of ball with free Rod

The whole System on a Smooth horizontal Surface.



Taking (Rod + ball) as System  
L.M.C.

$$mu \cos \theta = Mv_0 + mv \Rightarrow ①$$

A.M.C about P

$$(mu \cos \theta)b = mvb + \frac{ML^2}{12}\omega_0 - ②$$

L =  $I_{com}\omega + MVR_L$

About P

$\gamma_L = 0$

$V \rightarrow V_{com}$

Case of collision of ball with free Rod

The whole System on a Smooth horizontal S

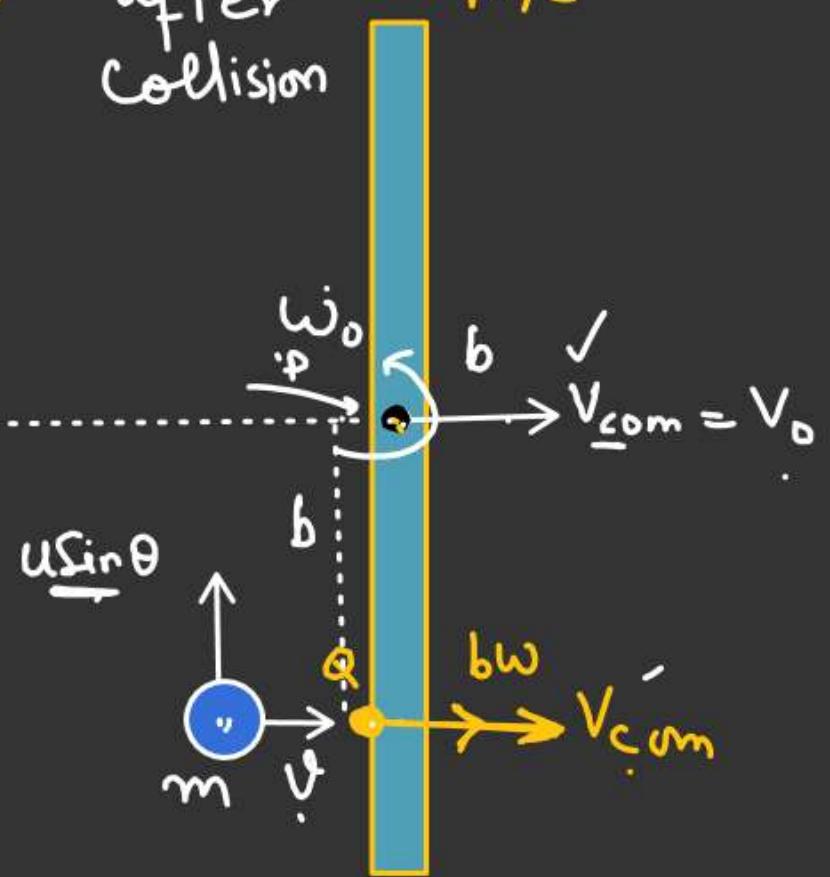
M,L

Just before Collision



M,L

Just after Collision



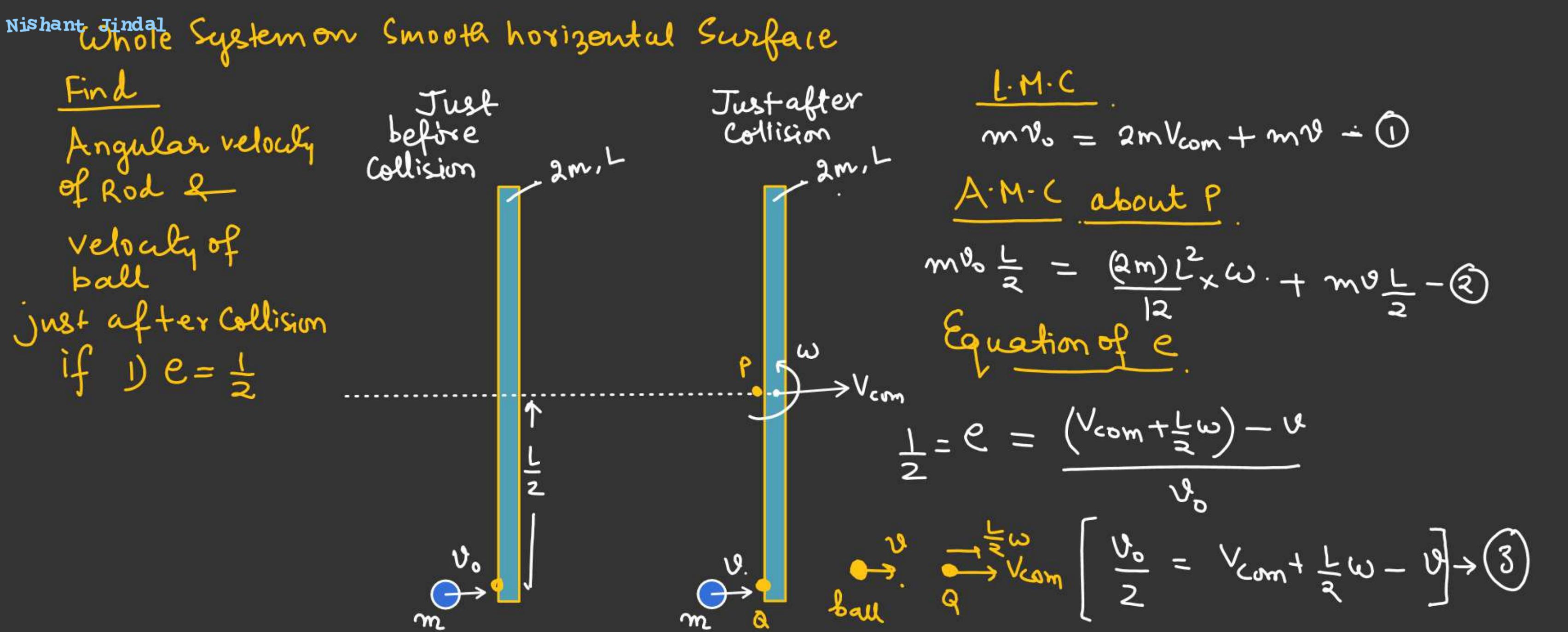
M,L

Equation of e

$$e = \frac{(V_{com} + b\omega) - v}{u \cos \theta}$$

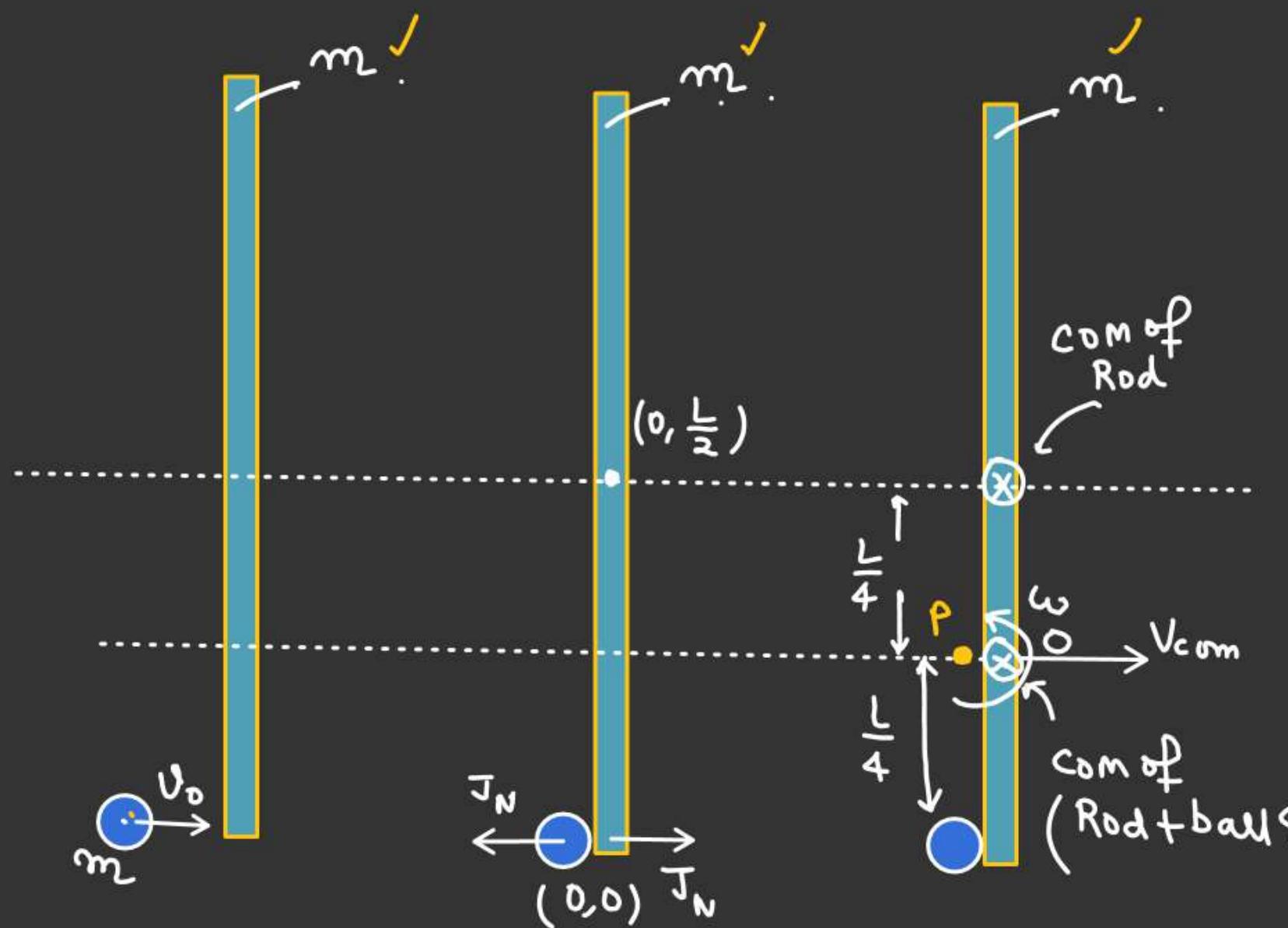
$$[e u \cos \theta = (V_{com} + b\omega) - v] - \textcircled{3}$$

$$\begin{aligned} \vec{V}_Q &= \vec{V}_{Q/COM} + \vec{V}_{COM \text{ of Rod}}/e \\ &= (b\omega \hat{i} + V_{com} \hat{i}) \end{aligned}$$



~~W.A.~~Perfectly Inelastic Collision of a ball with a free rod

$$[e=0]$$



$$y = \frac{m(L/2)}{m+m} = \frac{L}{4}$$

L.M.C.

$$mv_0 = (m+m)v_{com}$$

$$v_{com} = \frac{v_0}{2}$$

A.M.C about P

$$mv_0 \frac{L}{4} = (I_{com})_0 \omega$$

$$= (I_{Rod} + I_{ball})_0 \omega$$

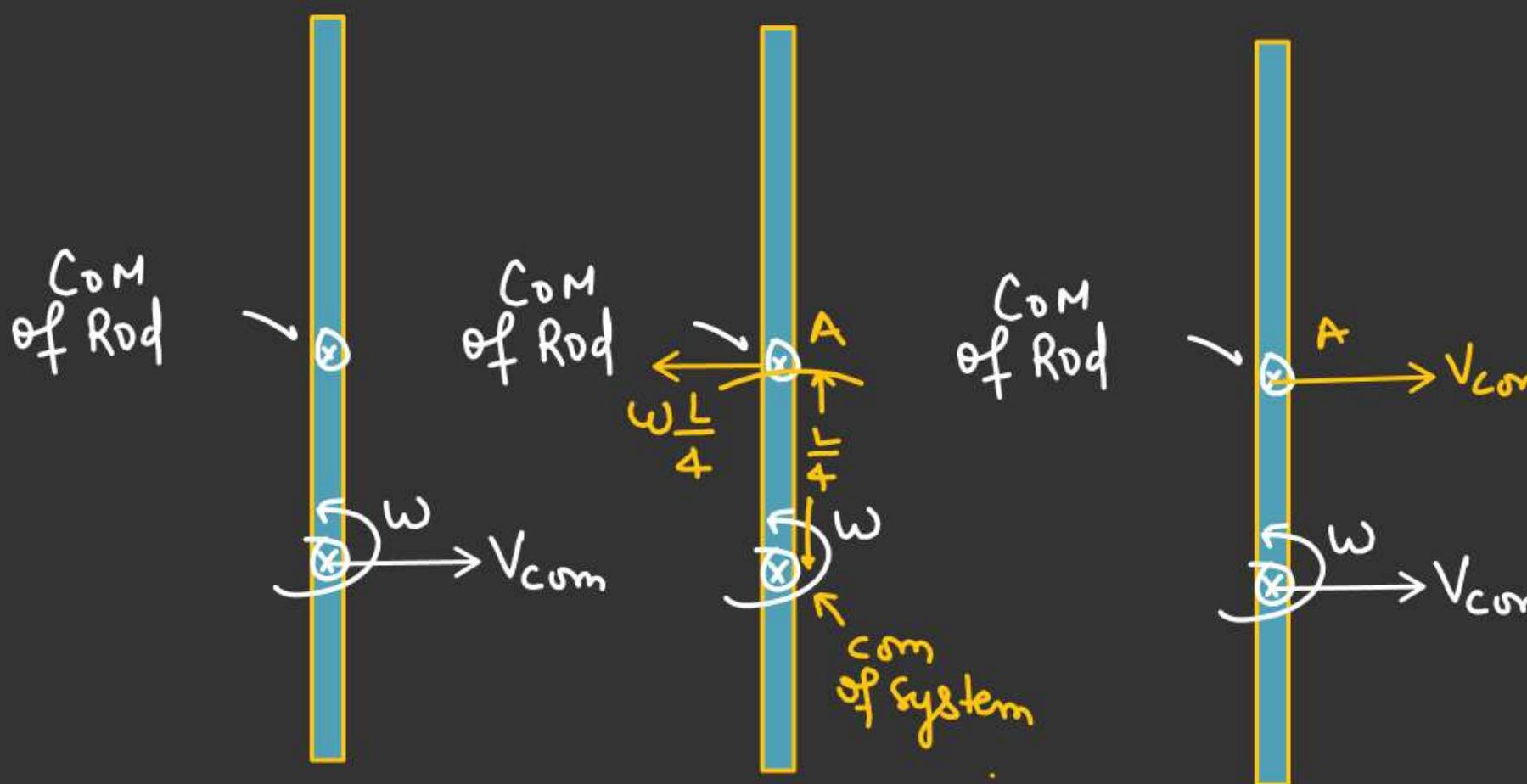
$$= \left[ \frac{mL^2}{12} + m\left(\frac{L}{4}\right)^2 + m\left(\frac{L}{4}\right)^2 \right] \omega$$

$$\frac{v_0 L}{4} = \left[ \frac{L^2}{12} + \frac{L^2}{8} \right] \omega$$

$$\frac{v_0 L}{4} = \frac{5L^2}{24} \omega$$

$$\omega = \left( \frac{6v_0}{5L} \right)$$

# Speed of center of Rod after Collision

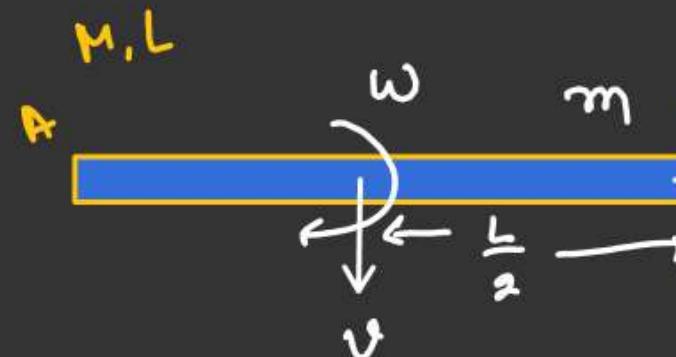


$$\begin{aligned}
 \vec{v}_A &= \vec{v}_{A/com} + \vec{v}_{com/\infty} \\
 &= -\frac{\omega L}{4} \hat{i} + V_{com} \hat{i} \\
 &= \left( V_{com} - \frac{\omega L}{4} \right) \hat{i}
 \end{aligned}$$

$$\begin{aligned}
 &= \left( \frac{V_0}{2} - \frac{L}{4} \times \frac{6V_0}{5L} \right) \hat{i} \\
 &= \left( \frac{V_0}{2} - \frac{6V_0}{20} \right) \hat{i} \\
 &= \frac{4V_0}{20} = \boxed{\frac{V_0}{5}} \quad \text{Ans.}
 \end{aligned}$$



Just before Collision.



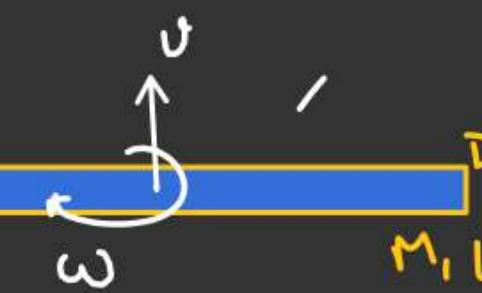
$$L = I_{\text{com}}\omega + Mv\tau_1 - k \quad k$$

After Collision both the.

Rod Stick together.

Find angular velocity of

both the rod just after collision.

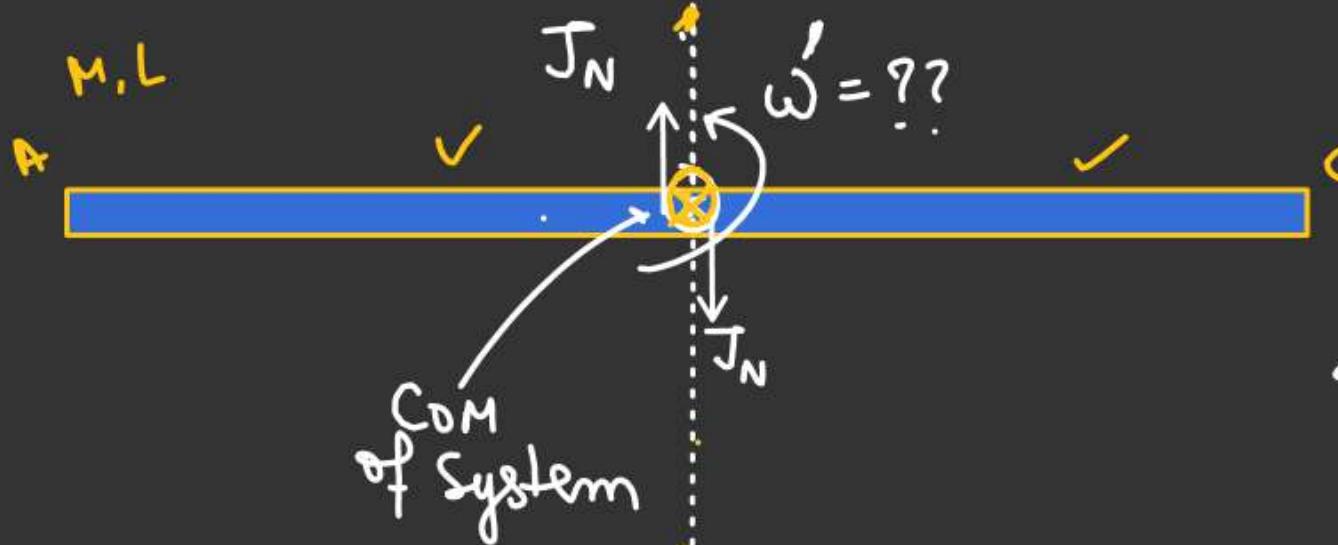


$$I \cdot M \cdot C$$

$$-mv + mv = (m+m)v_{\text{com}}$$

$$\underline{v_{\text{com}} = 0}$$

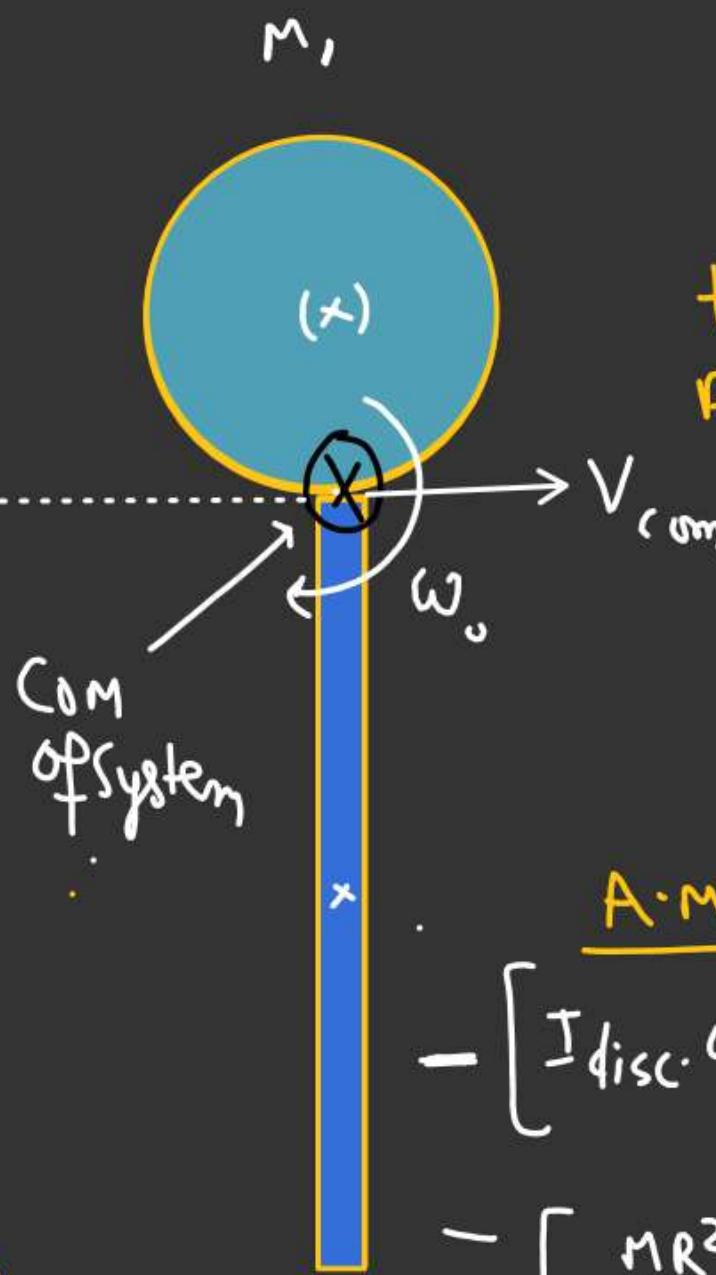
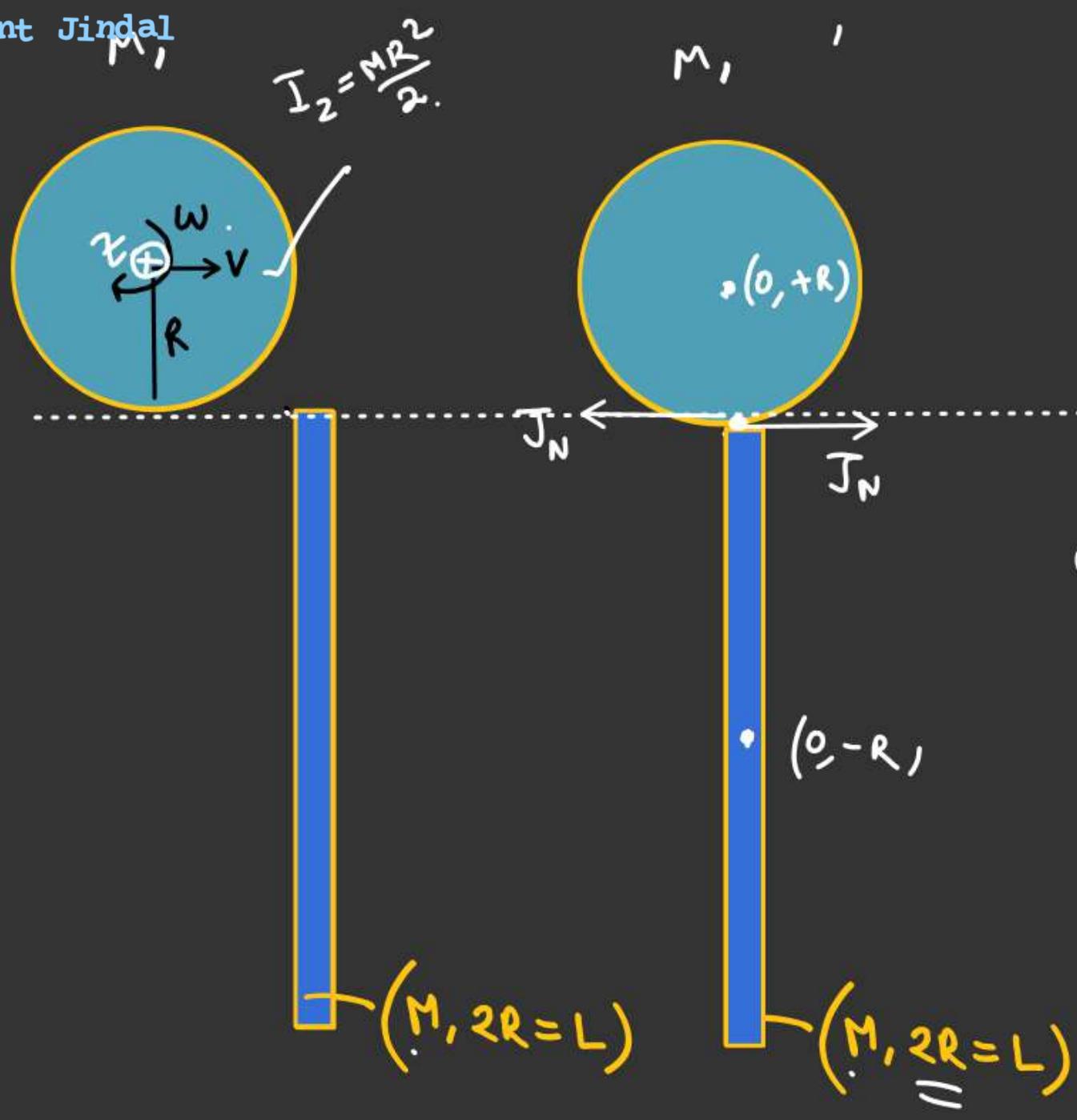
A.M.C about COM of System



$$I_i = I_f$$

$$2 \times \left[ \underbrace{m v \frac{L}{2} - \frac{M L^2}{12} \omega}_{J_N} \right] = \left( \frac{M L^2}{3} \omega' \right) \times \frac{L}{2}$$

$$\omega' = \left( \frac{3v}{2L} - \frac{\omega}{4} \right) \left( \frac{m v L}{2} - \frac{M L^2}{12} \omega \right) = \frac{M L^2}{3} \omega'$$



Whole System  
on a smooth horizontal  
surface. disc stick  
to the rod after collision.  
Find  $\omega_{\text{system}}$  just after collision.  
 $(v = R\omega \text{ given})$

$$\frac{L \cdot M \cdot C}{A \cdot M \cdot C}$$

$$Mv = 2M V_{\text{com}}$$

$$V_{\text{com}} = \frac{v}{2}$$

$$-\left[ I_{\text{disc}} \cdot \omega + MvR \right] = \left[ \frac{MR^2}{2} + MR^2 + \frac{M(2R)^2}{3} \right] \omega_0$$

$$-\left[ \frac{MR^2}{2} \times \frac{v}{R} + MvR \right] = \left[ \frac{3}{2}MR^2 + \frac{4MR^2}{3} \right] \omega_0$$

$$-\left[ \frac{3}{2}M(vR) \right] = \frac{17MR^2}{6} \omega_0$$

$$-\frac{9v}{17R} = \omega_0 \quad \text{or} \quad \left( \frac{9v}{17R} = \omega_0 \right)$$