

Dynamic optimisation in solar power tower plants

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Outline

- 1 Introduction
- 2 Optimisation Problem
- 3 Algorithms
 - Penalisation
 - Augmented Lagrangian
 - Gradient Ascent
- 4 Numerical approximation
- 5 Illustrative Example

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Introduction

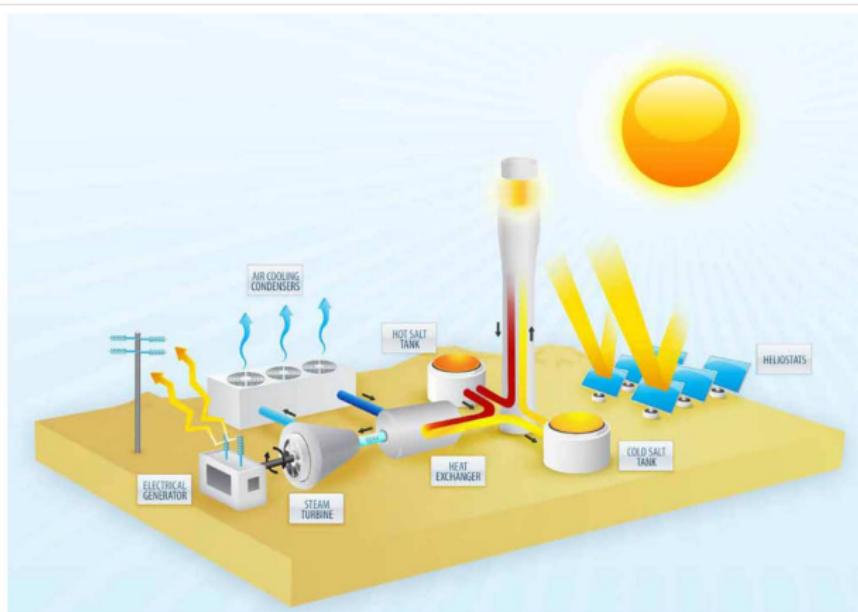
Partners



Solar Power Tower (SPT) Plant



Solar Power Tower (SPT) Plant



Aiming Strategy

Publications:

"Optimisation of aiming strategies in Solar Power Tower plants". Ashley T., Carrizosa E., Fernández-Cara E.. Energy, 137C, pp. 285–291 (2017).

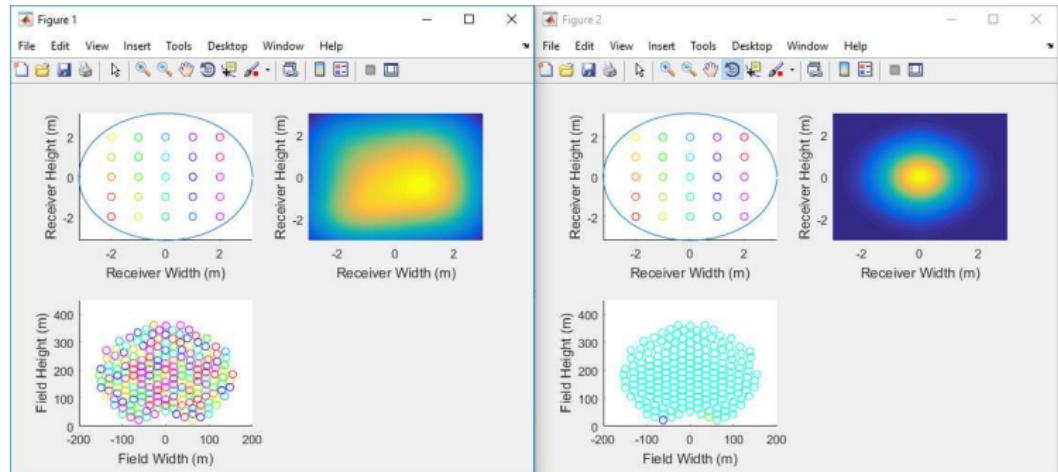
"Continuous Optimisation Techniques for Optimal Aiming Strategies in Solar Power Tower plants". Ashley T., Carrizosa E., Fernández-Cara E.. (Submitted)

"Dynamic Continuous Optimisation Applied to Aiming Strategies in Solar Power Tower plants". Ashley T., Carrizosa E., Fernández-Cara E.. (Not yet submitted)



Aiming Strategy

Target Distribution



```
TotalInitial_E =  
1.12301846313501e+07  
  
TotalOptEnergy =  
1.339351695305695e+07  
  
Max  
ans =  
2.498875343796182e+06  
  
Min  
ans =  
2.503208031699102e+04  
  
Range  
ans =  
2.383843263479191e+06
```

Aiming Strategy

Heliostat Rotation

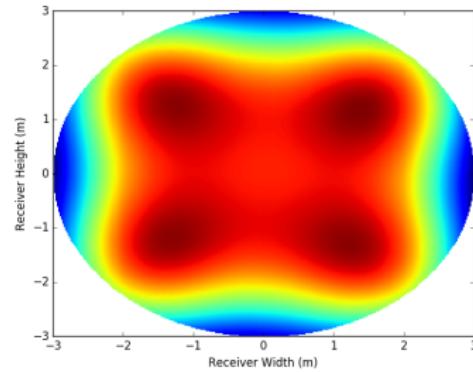
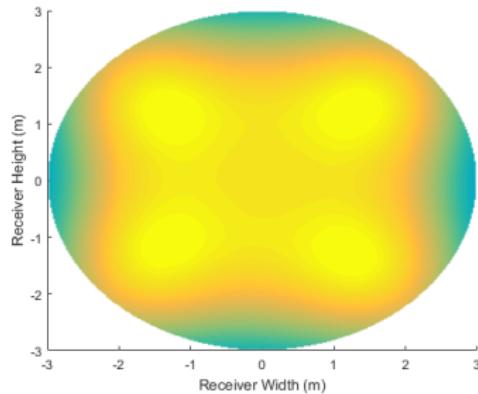


Source:

<http://theleadsouthaustralia.com.au/industries/resources-energy/solar-park-drive-plastic-heliostat-development/>

Aiming Strategy

Radiation Change



Aiming Strategy

Summary

- Optimise aiming strategy of heliostats
- Maximise radiation
- Minimise deviation from target distribution
- Constrain heliostat rotation speed
- Constrain radiation change on receiver

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Optimisation Problem

Model

The proportion of energy reaching the receiver for each heliostat within the field, given:

- Physical location (x, y)
- Aim point $(\rho \cos \phi, \rho \sin \phi)$

$$f_{sp}(x, y, \Theta) = f_1(x, y, \Theta) \iint_S \exp\left(\frac{-f_2(u, v, x, y)}{2f_3^2(x, y, \Theta)}\right) du dv ,$$

$$\sum_{h \in H} f_{sp}(h, p, t).$$

Optimisation Problem

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$$\sum_{h \in H} f_{sp}(h, p, t).$$

Optimisation Problem

Objective

Maximise Energy

$$\int_0^T \left(\iint_R \sum_{h \in H} f(h, \mathbf{p}, t) dudv \right) dt$$

Minimise target distribution deviation

$$\int_0^T \iint_R \left(\sum_{h \in H} F^{u,v}(h, \mathbf{p}, t) - E_{tar}^{u,v,t}(t) \right)^2 dudvdt$$

Optimisation Problem

Objective

Penalised weighted objective

$$\begin{aligned} \text{Maximise } & A \int_0^T \left(\iint_R \sum_{h \in H} f(h, \mathbf{p}, t) dudv \right) dt - \\ & (1 - A) \int_0^T \iint_R \left(\sum_{h \in H} F^{u,v}(h, \mathbf{p}, t) - E_{tar}^{u,v,t}(t) \right)^2 dudvdt \end{aligned}$$

with $A \in [0, 1]$.

Optimisation Problem

Constraints

Limit heliostat turn rate $\dot{p}_h(t)$

$$\int_0^T (||\dot{p}_h(t)|| - V_p)_+^2 dt \leq \tau_1 \quad \forall h \in H$$

Limit radiation change over time $\frac{\partial}{\partial t} F^{u,v}(h, \mathbf{p}, t)$

$$\int_0^T \iint_R \left(\sum_{h \in H} \frac{\partial}{\partial t} F^{u,v}(h, \mathbf{p}, t) \right) du dv dt \leq \tau_2$$

Optimisation Problem

$$\begin{aligned} \text{Maximise } & A \int_0^T \left(\iint_R \sum_{h \in H} f(h, \mathbf{p}, t) dudv \right) dt - \\ & (1 - A) \int_0^T \iint_R \left(\sum_{h \in H} F^{u,v}(h, \mathbf{p}, t) - E_{tar}^{u,v,t}(t) \right)^2 dudvdt \end{aligned}$$

with $A \in [0, 1]$.

Subject to:

$$\int_0^T (||\dot{p}_h(t)|| - V_p)_+^2 dt \leq \tau_1 \quad \forall h \in H$$

$$\int_0^T \iint_R \left(\sum_{h \in H} \frac{\partial}{\partial t} F^{u,v}(h, \mathbf{p}, t) \right) dudvdt \leq \tau_2$$



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Penalisation

$$\begin{aligned} \text{Maximise} \quad & A_1 \int_0^T \left(\iint_R \sum_{h \in H} f(h, \mathbf{p}, t) dudv \right) dt \\ & - A_2 \int_0^T \iint_R \left(\sum_{h \in H} F^{u,v}(h, \mathbf{p}, t) - E_{tar}^{u,v,t}(t) \right)^2 dudvdt \\ & - A_3 \int_0^T (||\dot{\mathbf{p}}_h(t)|| - V_p)_+^2 dt - \tau_1 \\ & - A_4 \int_0^T \iint_R \left(\sum_{h \in H} \frac{\partial}{\partial t} F^{u,v}(h, \mathbf{p}, t) \right) dudvdt - \tau_2 \end{aligned}$$

Augmented Lagrangian

$$\mathcal{L}_\mu(\mathbf{p}; \lambda) := J(\mathbf{p}) + \psi(M(\mathbf{p}) - \sigma, \lambda; \mu),$$

$$\psi(z, \lambda; \mu) := \begin{cases} -z \cdot \lambda + \frac{1}{2\mu} |z|^2 & \text{if } z + \mu\lambda \leq 0 \\ -\frac{\mu}{2} |\lambda|^2 & \text{otherwise} \end{cases}$$

$\mu > 0$ small

Take $\lambda^{n+1} = (\lambda^n - \frac{1}{\mu}(M_i(p_N^n) - \sigma))_+$.

Gradient Ascent

Aiming points \mathbf{p}_N^{n+1} found by gradient ascent:

$$\mathbf{p}_N^{n+1} = \mathbf{p}_N^n + \gamma_h^k \nabla G_N(\mathbf{p}_N^n).$$

Step size with *Armijo's Rule*

$$\gamma_h^k = \gamma_h^{k-1} \cdot \epsilon$$

with $\epsilon \in (0, 1)$

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Numerical approximation

Objective

Maximise radiation

$$\int_0^T \iint_R \left(\sum_{h=1}^H F^{(u,v)}(h, p_h(t), t) \right) du dv dt \approx \sum_{n=1}^T \sum_{i=1}^I \sum_{h=1}^H F^{(u_i, v_i)}(h, p_h(t^n), t^n)$$

Minimise target distribution deviation

$$\int_0^T \iint_R \left(\sum_{h=1}^H F^{u,v}(h, \mathbf{p}, t) - E_{tar}^{u,v}(t) \right)^2 du dv dt \approx \sum_{n=1}^T \sum_{i=1}^I \left(\sum_{h=1}^H F^{u_i, v_i}(h, \mathbf{p}, t^n) - E_{tar}^{u_i, v_i}(t^n) \right)^2$$

Numerical approximation

Constraints

Limit heliostat turn rate

$$\int_0^T \|(\dot{\mathbf{p}}(t) - \mathbf{v}_p)_+\|^2 dt \approx \int_0^T \sum_{n=1}^N (|\mathbf{P}^n - \mathbf{P}^{n-1}| - V_p)_+^2 dt,$$

Limit radiation change on receiver

$$\begin{aligned} & \int_0^T \left(\iint_R \left(\sum_{h=1}^H \frac{d}{dt} F^{u,v}(h, \mathbf{p}(t), t) \right)^2 du dv \right) dt \\ & \approx \int_0^T \sum_{i=1}^I \left| \sum_{h=1}^H F^{u_i, v_i}(h, \mathbf{P}_h^n, t^n) - F^{u_i, v_i}(h, \mathbf{P}_h^{n-1}, t^{n-1}) \right|^2 dt. \end{aligned}$$

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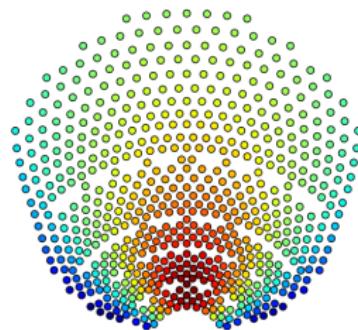
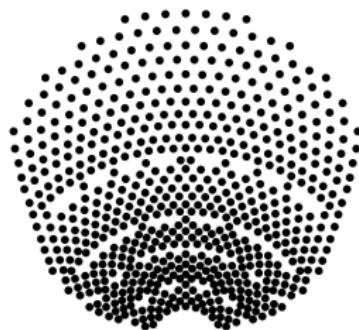
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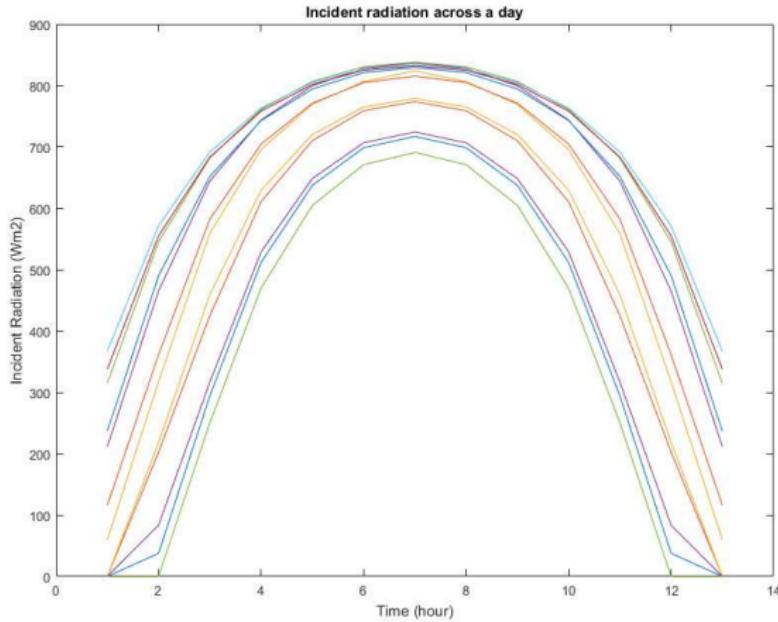
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Illustrative Example

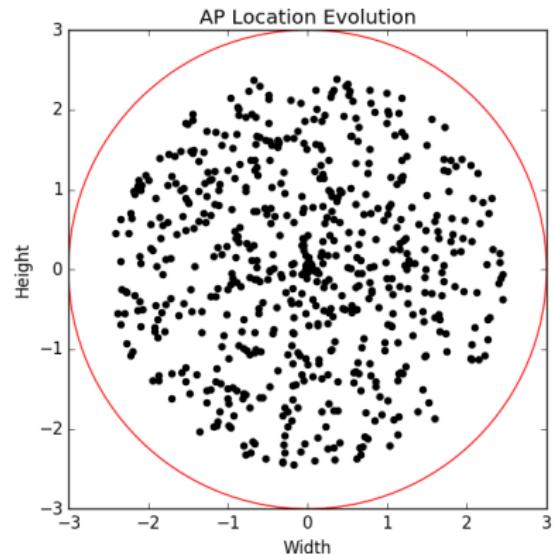
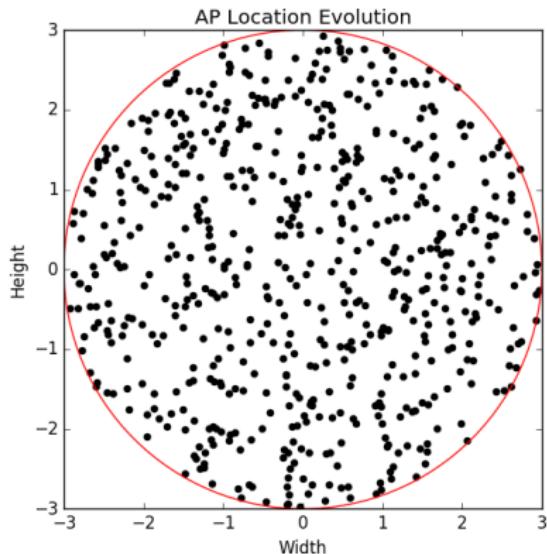
- Results - *PS10, Sanlúcar la Mayor*



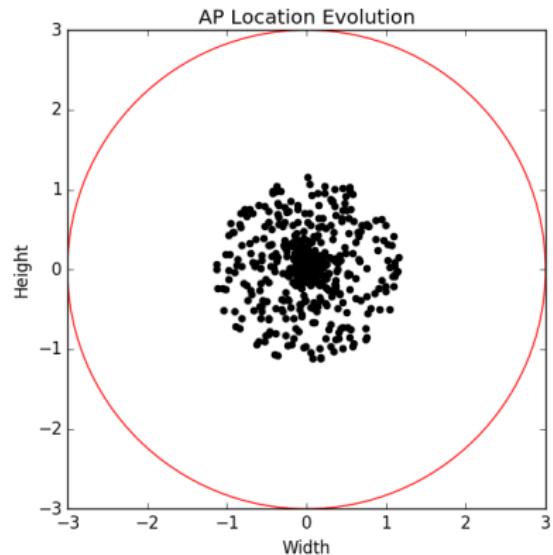
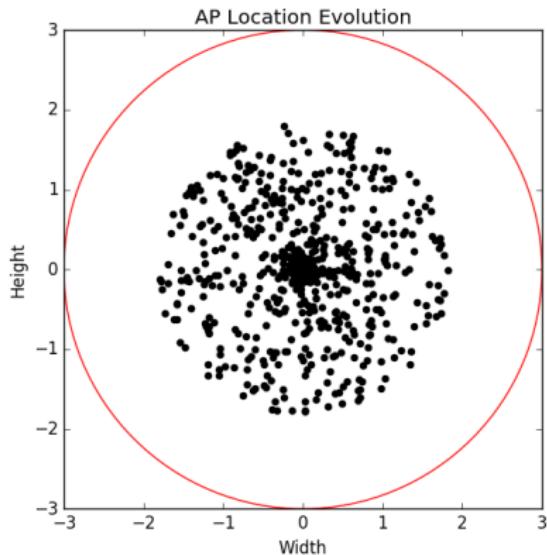
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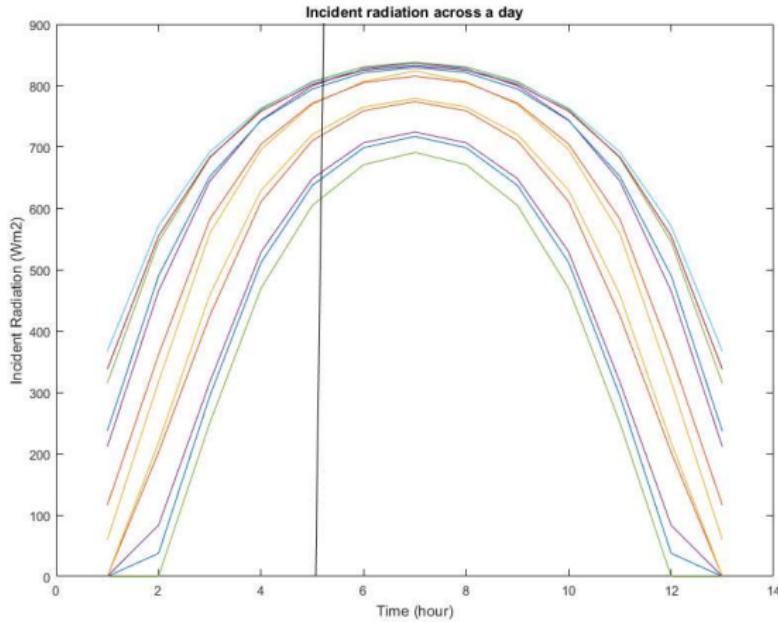
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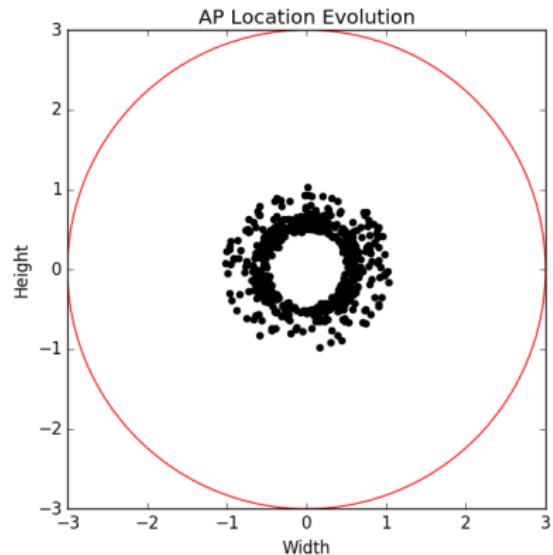
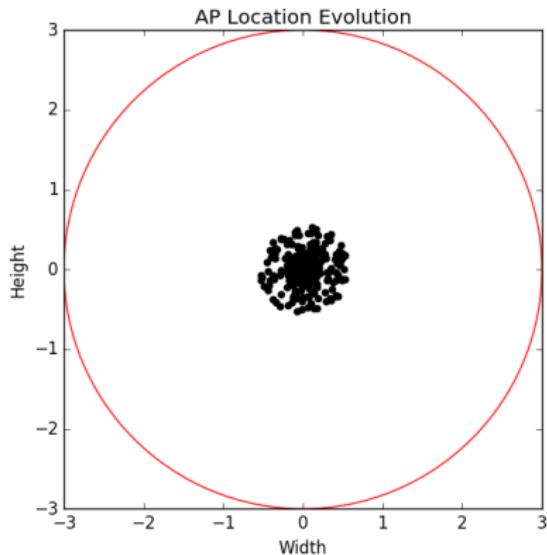
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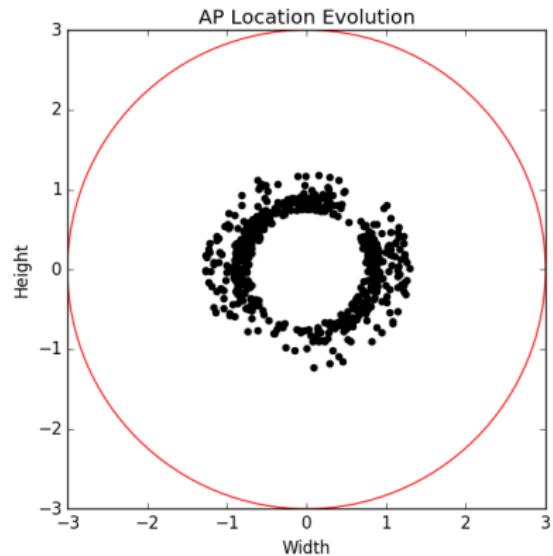
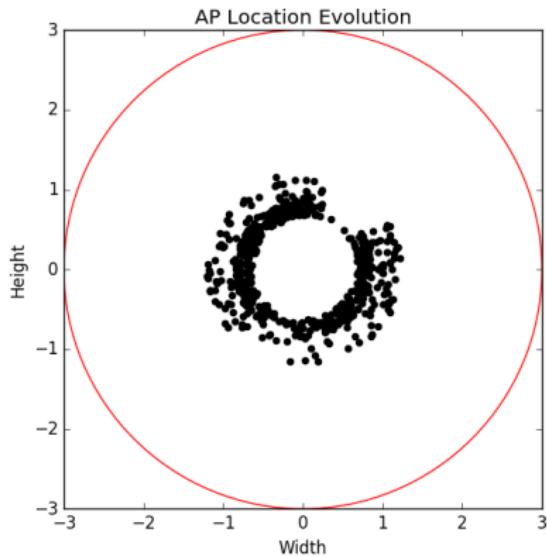
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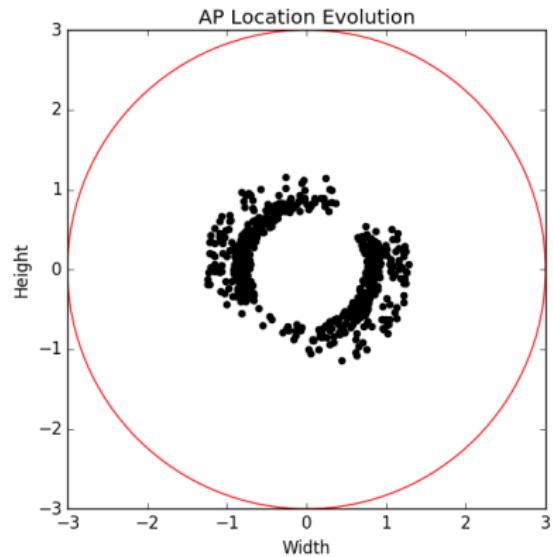
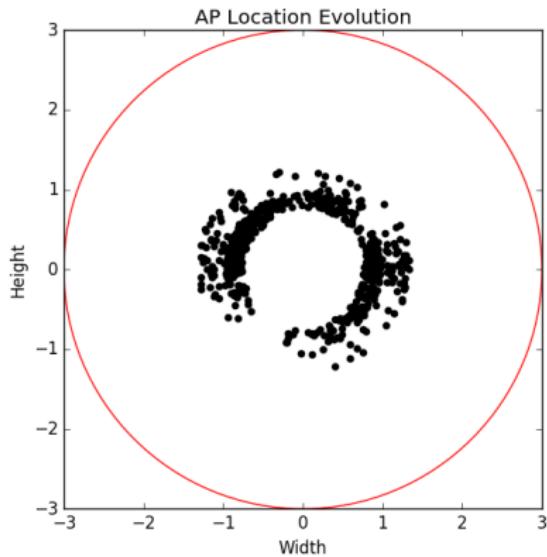
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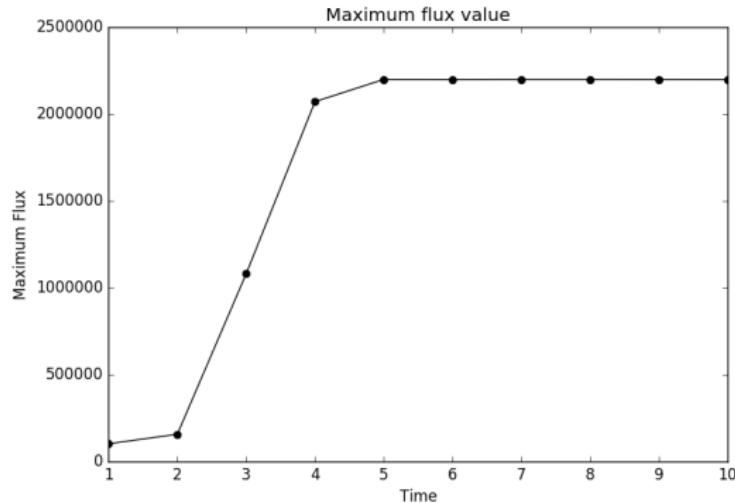


Figure: Maximum flux on receiver over time

Questions

Questions?

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