

## **IEEE ROBOTICS AND AUTOMATION SOCIETY**

## **Outstanding Navigation Paper Award - Finalist**

IEEE International Conference on Robotics and Automation – ICRA 2023 is hereby presented to

## Yunfan Ren

For the paper co-authored with Siqi Liang, Fangcheng Zhu, Guozheng Lu, and Fu Zhang

"Online Whole-body Motion Planning for Quadrotor using Multiresolution Search"



FePmh

Frank Park
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Maren Bennewitz
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