

# Linear Models Lecture 12: MLE

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## Testing "Restrictions"

- Consider the following model of incumbent support:

$$\text{incumbent support} = \beta_1 + \beta_2 \text{war dead} + \beta_3 \text{economic growth} + \beta_4 \text{inflation} + e$$

- An alternative (non-testable) theory says that voters care about real growth (net of inflation).

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- A testable theory could be that voters care about \*only\* about real growth (net of inflation).

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- We can specify joint hypotheses by specifying them as a matrix equation:

$$\underbrace{R}_{q \times K} \beta = \underbrace{r}_{q \times 1}$$

- The null hypothesis  $H_0: \beta_3 = 0$  is presented as:

$$[0 \ 0 \ 1 \ 0 \dots 0] \beta = [0]$$

- The null hypothesis  $H_0: \beta_2 = \beta_3$  and  $\beta_4 + \beta_5 = 1$  is:

$$\begin{bmatrix} 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} \beta = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

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## Test Statistic for Restrictions in Normal Regression

$$F = (\mathbf{R}\hat{\beta} - \mathbf{r})'(\mathbf{R}(Var(\hat{\beta}))\mathbf{R}')^{-1}(\mathbf{R}\hat{\beta} - \mathbf{r})/q \sim F(q, N - K)$$

or equivalently

$$F = \frac{(\mathbf{e}'_r \mathbf{e}_r - \mathbf{e}' \mathbf{e})/q}{\mathbf{e}' \mathbf{e}/(N - K)} \sim F(q, N - K)$$

Where  $\mathbf{e}$  is the residual from the regression,  $\mathbf{e}_r$  is the residual from the regression with restrictions.

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```
library(car)
set.seed(10)
x1 <- rnorm(100)
x2 <- rnorm(100)
x3 <- rnorm(100)
y <- 5*x1 + 0.5*x2 - 0.5*x3 + rnorm(100)
m1 <- lm(y~x1+x2+x3)
linearHypothesis(m1, c("x2 = 0.5", "x3 = -0.5"), test="F")
```

## Prediction versus forecasts

Prediction: The best point estimate for  $\bar{y}_0$  given  $\mathbf{x}_0$  is  $\hat{y}_0 = \mathbf{x}'_0 \hat{\beta}$ .

$$\bar{e}_0 = \bar{y}_0 - \hat{y}_0 = \mathbf{x}'_0 \beta - \mathbf{x}'_0 \hat{\beta} = -\mathbf{x}'_0 (\beta - \hat{\beta})$$

$$\begin{aligned} \text{Var}(\bar{e}_0) &= \text{Var}(\mathbf{x}'_0 \hat{\beta}) = \mathbf{x}'_0 \text{Var}(\hat{\beta}) \mathbf{x}_0 \\ &= \sigma_e^2 (\mathbf{x}'_0 (\mathbf{X}' \mathbf{X})^{-1} \mathbf{x}_0) \end{aligned}$$

Forecast: The best point estimate for a future value  $y_{n+1}$  given  $\mathbf{x}$  is also  $\mathbf{x}' \hat{\beta}$ .

$$\begin{aligned} \hat{e}_{n+1} &= y_{n+1} - \mathbf{x}' \hat{\beta} = (\mathbf{x}' \beta + e) - \mathbf{x}' \hat{\beta} \\ &= e - \mathbf{x}' (\beta - \hat{\beta}) \end{aligned}$$

$$\text{Var}(\hat{e}_{n+1}) = \text{Var}(e - \mathbf{x}' (\beta - \hat{\beta})) = \sigma_e^2 + \mathbf{x}' \text{Var}(\hat{\beta}) \mathbf{x}$$

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## Predictions and Forecasts in R

- You can get the confidence interval for the prediction of the mean of  $y$  in R (for each value of  $x$  specified in a data frame called `dtax`) with  
`predict(mod, interval= "confidence", newdata=dtax)`
- You can get the forecast for a value of  $y$  for some points  $x$  with:  
`predict(mod, interval= "prediction", newdata=dtax)`

## Likelihood of Probit Regression

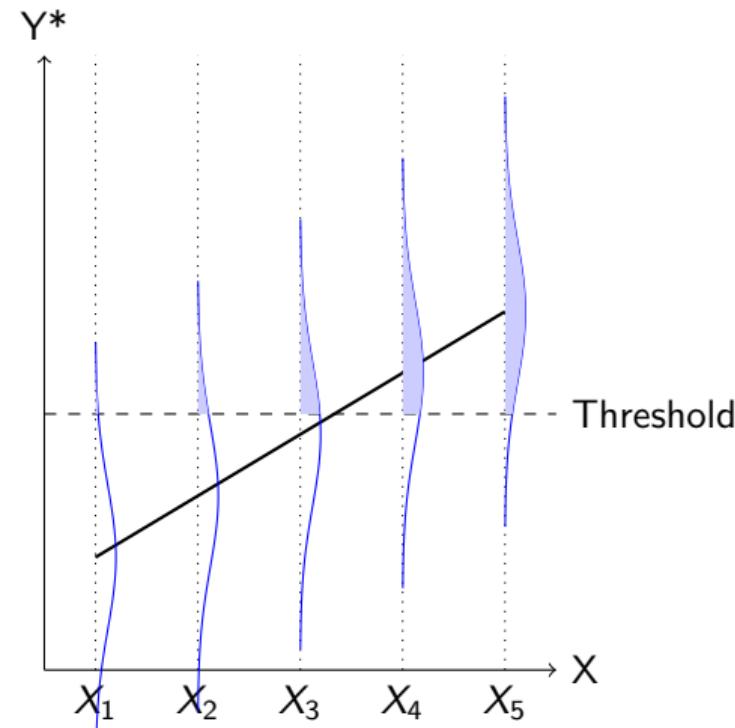
- Suppose we only observe binary manifestations of a *latent*  $Y^*$ :

$$Y = \begin{cases} 1 & Y^* > 0 \\ 0 & \text{otherwise} \end{cases} = \begin{cases} 1 & \mathbf{x}'\beta + e > 0 \\ 0 & \text{otherwise} \end{cases}$$

- If  $e \sim N(0, 1)$ , then  $P(Y = 1|X) = \Phi(\mathbf{x}'\beta)$ .
- The likelihood of a single observation  $(y_i, x_i)$  is then:

$$\mathcal{L}(\beta; y_i, x_i) = \Phi(\mathbf{x}'\beta)^{y_i} [1 - \Phi(\mathbf{x}'\beta)]^{(1-y_i)}$$

## Visualization of Probit Regression



## Score Function in Probit Regression

- The score function for a single observation  $(y_i, x_i)$  is:

$$\frac{\partial \log \mathcal{L}(\beta; y_i, x_i)}{\partial \beta} = (y_i - \Phi(x_i' \beta)) \frac{\phi(x_i' \beta)}{\Phi(x_i' \beta)(1 - \Phi(x_i' \beta))} x_i$$

- In GLMs (including probit), the score simplifies to:

$$\text{score} = (\text{residual}) \times (\text{covariate})$$

- The model says  $P(Y = 1|X) = g^{-1}(X'\beta)$ , where  $g^{-1}$  is a CDF (link inverse).
- the derivative of  $\Phi$  is  $\phi$  and chain rule applies).
- $\text{score} = (y_i - \Phi(X_i' \beta)) \times \left( \frac{\phi(X_i' \beta)}{\Phi(X_i' \beta)(1 - \Phi(X_i' \beta))} \right) X_i$
- Take the residual, weight it by the local slope, and multiply by the covariates.

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- Take the residual, weight it by the local slope, and multiply by the covariates.

```
probitmodel <- glm( y ~ x,  
                     family= binomial(link = "probit") ,  
                     data = df)  
summary(probitmodel)  
predict(probitmodel)
```

The probit slope estimates can be divided by 2.5 to make them comparable to the linear probability model estimates.

## Variance and Standard Errors in Probit Regression

- The asymptotic variance of  $\hat{\beta}$  is based on the Fisher Information Matrix:

$$\mathcal{I}(\beta) = \mathbb{E} \left[ \left( \frac{\partial \log \mathcal{L}(\beta; y, x)}{\partial \beta} \right) \left( \frac{\partial \log \mathcal{L}(\beta; y, x)}{\partial \beta} \right)' \right]$$

- In practice, we estimate  $\mathcal{I}(\hat{\beta})$  with the observed information:

$$\widehat{\mathcal{I}}(\hat{\beta}) = \sum_{i=1}^n \left( \frac{\phi(x_i' \hat{\beta})^2}{\Phi(x_i' \hat{\beta})(1 - \Phi(x_i' \hat{\beta}))} x_i x_i' \right)$$

- Then:

$$\widehat{\text{Var}}(\hat{\beta}) = (\widehat{\mathcal{I}}(\hat{\beta}))^{-1}$$

- The **standard errors** are the square roots of the diagonal elements of  $\widehat{\text{Var}}(\hat{\beta})$ .

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- In practice, we estimate  $\mathcal{I}(\hat{\beta})$  with the observed information:

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## Variance and Standard Errors in Probit Regression

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## Interpreting Probit Coefficients

- In probit regression,  $\beta_j$  does not directly measure the marginal effect on  $P(Y = 1|X)$ .
- The marginal effect of  $x_j$  is:

$$\frac{\partial P(Y = 1|X)}{\partial x_j} = \phi(X'\beta)\beta_j$$

where  $\phi(\cdot)$  is the standard normal PDF.

- Interpretation:
  - $\beta_j$  indicates the *direction* (positive or negative) of the effect.
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  - Effects are largest when  $X'\beta$  is near 0 (where  $\phi$  is largest).
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## Warnings about nonlinear models

- In linear models, heteroskedasticity is a nuisance, but doesn't affect the estimates and can be addressed (partially) with robust standard errors.
- In nonlinear models, heteroskedasticity can produce inconsistent estimates.
- Including fixed effects is also more complicated, as they don't have a de-meaning interpretation.