EAST-ADL

An Architecture Description Language for Automotive Software-Intensive Systems

Introduction

 EAST-ADL represents an Architecture Description Language (ADL) to describe automotive systems

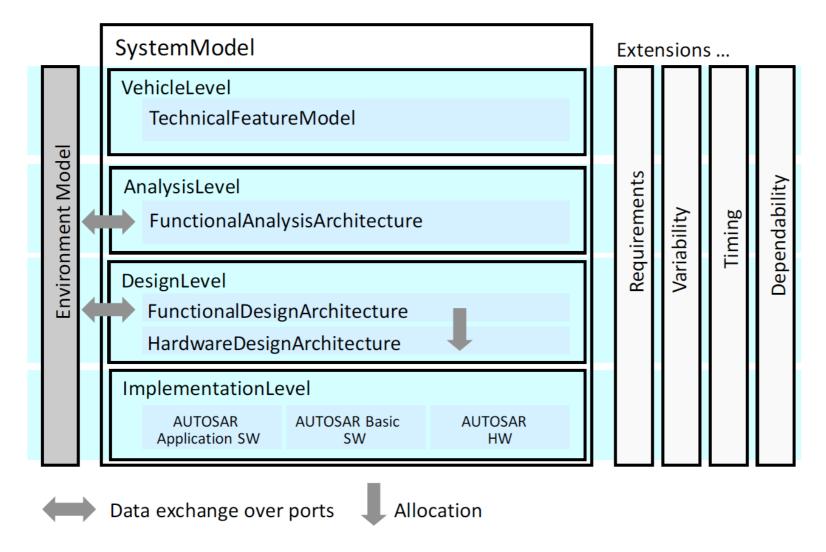


Figure 1: The EAST-ADL's breakdown in abstraction levels (vertically) and in core system model, environment and extensions (horizontally).

The four abstraction levels

Vehicle Level

Feature trees characterizing the vehicle content as it is perceived externally.

Analysis Level

An abstract functional architecture defining systems from a functional point of view.

Design Level

The detailed functional architecture allocated to a hardware architecture.

Implementation Level

The implementation of the embedded system represented using AUTOSAR elements

Example Model—BBW

Brake By Wire System

Vehicle Level

TechnicalFeatureModel <FeatureModel>

Analysis Level

BBWAL: BBW_FAA <AnalysisFunction>

Design Level

BBWDL: BBW_FDA < DesignFunction>

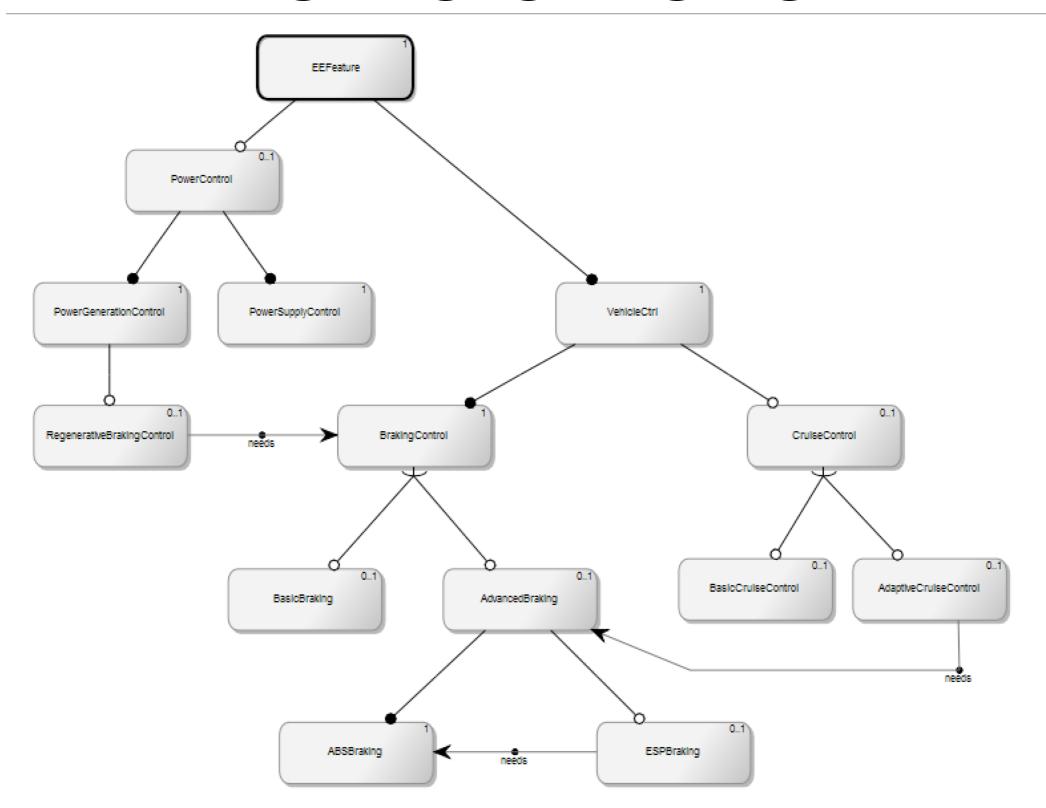
Design Level

HW_BBW: HDA <HardwareComponent>

Design Level

BBWAllocation: AllocationMatrix

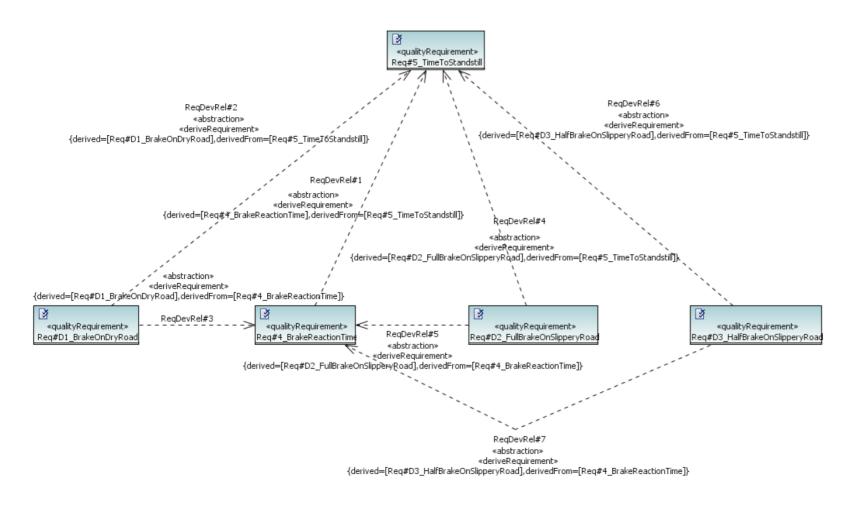
Vehicle Level



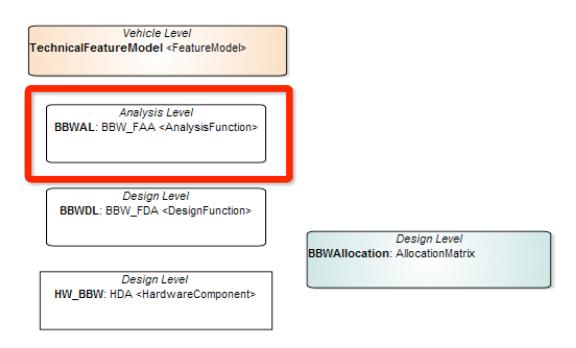
Vehicle Level

- The Technical Feature tree of the target braking system
- Requirements at the Vehicle Level are directly based on system use cases and allocated to vehicle Features denoting the expected system functions.

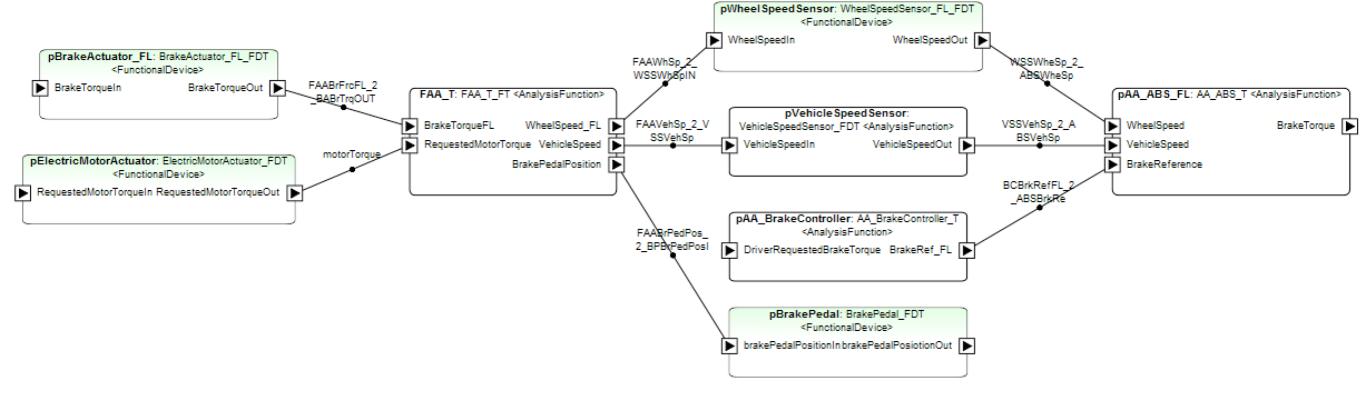
ID	Description
Req#1_BaseBraking	"The system shall provide a base brake functionality where the driver indicates that he/she wants to reduce speed and the braking system starts decelerating the vehicle"
Req#2_DriverBrakeRequest	"The driver shall be able to request braking"
Req#3_Anti-LockBraking	"The system shall be an anti-lock braking system (ABS) by preventing the wheels from locking while braking"
Req#4_BrakeReactionTime	"The time from the driver's brake request until the actual start of the deceleration shall be \leq 300ms.(Value derived from expert judgment)"
Req#5_TimeToStandstill	"The time to stadstill shall follow the recommendations in EU braking systems Directive 71/320 EEC. The Swdish Road Administration claims that a factor of 3 (on braking distance) is acceptable for ice"
Req#6_OperationofBrakePedal	"The Operator shall be able to vary the desired braking force using the brake pedal. A fully pressed pedal means maximum brake force."
Req#7_BrakeRelease	"When the brake pedal is not pressed, the brake shall not be active."



Analysis Level



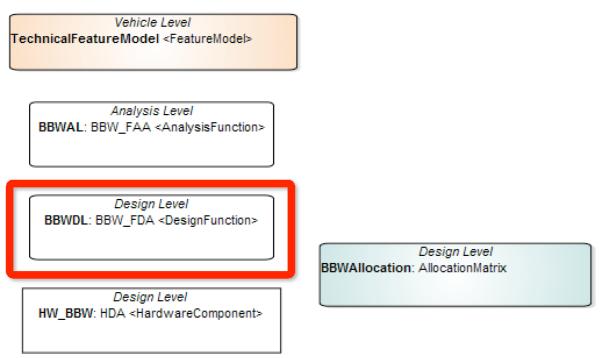
Functional Analysis Architecture (FAA)



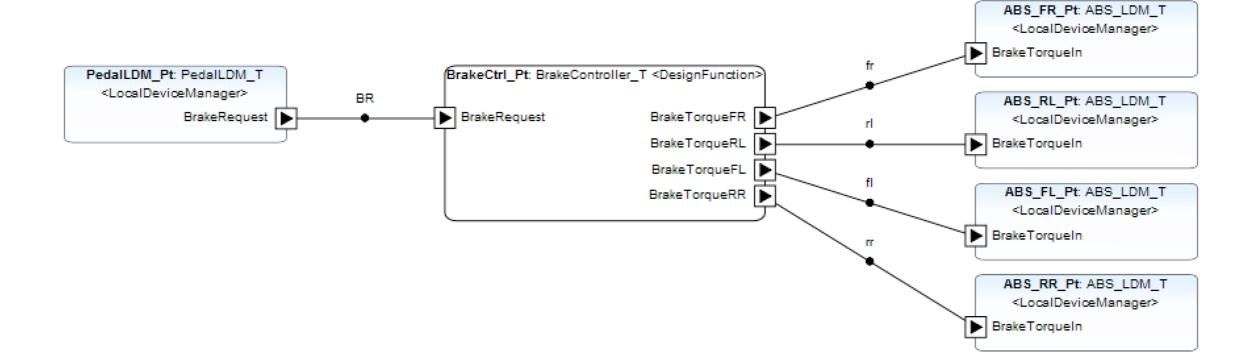
Analysis Level

- The Vehicle Level Features are realied by some interconnected abstract functions at the Analysis Level
- Functional Device: Sensor or Actuator. Through Functional Devices, an Analysis Function interacts with the physical environment.
- Analysis Functional Prototype: Calculation or Control Logic

Design Level



Functional Design Architecture



Design Level

 The Design Level architecture further details the Analysis Level design by taking the software and hardware resources into consideration.

Implementation Level

- AUTOSAR model
- C\C++, Java, Matlab Code