1. David: Buy brackets. 3 x robot kits bought.
2. David: Get another extension cord for Olin 269.
3. > 15 more chargers, plus 5 more adapters than chargers.

Or are they all somewhere? Check what I ordered?

1. Swap out parts so that current R25 goes back into service.
2. Try a voltmeter on an orange battery.
3. David: Load up-to-date Arduino code onto all robots.
4. Put black power cords onto robots that have the white thing. Confirm pin is cut.
5. David: Bring box with robots to Olin 269.
6. David and Ashley: 2 p.m. Saturday in Olin 269. Get 8+ robots in Olin 269 that work with all but Pixy and encoders.
   1. Make buzzers work.
   2. Repeat hardware tests.
   3. Test wireless.
7. Cable management for charging: 2 extension cords to reach the big cabinets and put the big power strips there. Or as Ashely sees fit.
8. Add pins for front bumpers as needed (solder).
9. Put Pixys onto new robots. Also other stuff as needed.
10. Get nuts and/or bolts for bumpers.
11. Determine how many adapters we need to buy to match power things, see if need more power things.
12. Buy adapters.
13. Determine anything else that we need to find or order.
14. Get twisty ties for servo wires. Make all wires OK onto robots that are in service.
15. Do various with the Python robot code, especially to make Pixy work.
16. David: Look at the Robot Procedure page.
17. David: Make a visual checklist for robots.
18. David: Make an electronic check for robots if possible without giving the show away.
19. Put masking tape over voltmeters to make them quieter.
20. Label all wires.
21. Glue washers back on encoders.
22. Eventually put white things on all robots with black power cords.
23. Model a bracket for new battery. Then have some made.
24. David: Way to report broken robots to you.
25. David: Procedure for getting broken robots repaired in a timely way.
26. David: Bring stuff from BIC to Olin 269.
27. Clear out / organize all the cabinets in Olin 269.
28. Investigate what happens if the A3 ground is not plugged in.