Assignment 7

- 1 Prove that convolution has the following properties.
 - (a) associativity
 - (b) commutativity
 - (c) distribution over +
 - $(d) \ y(t) = x(t) * h(t) \Rightarrow \dot{x}(t) * h(t) = x(t) * \dot{h}(t) = \dot{y}(t) \ (\dot{x}(t), \dot{h}(t) \text{ cont.}, \dot{f}(t)) = df(t)/dt$

 - $\begin{array}{l} (e) \ y(t) = x(t)*h(t) \Rightarrow \dot{x}(t)*\dot{h}(t) = \ddot{x}(t)*h(t) = x(t)*\ddot{h}(t) = \ddot{y}(t) \ (\ddot{x}(t),\ddot{h}(t) \ \text{cont.}, \ \ddot{f}(t)) = d^2f(t)/dt^2) \\ (f) \ \text{Let} \ A(f) = \int_{-\infty}^{+\infty} f(t)dt. \ \text{Show that} \ y(t) = x(t)*h(t) \Rightarrow A(y) = A(x)A(h). \ \text{State and prove the discrete} \end{array}$ version of this result.
- A different interpretation of the convolution operation from the one discussed in the class is that y(t) = x(t) * h(t) is the inner product of the convolver $x(\tau)$ with the convolvend $h(\tau)$ after the latter is time reversed and centered about t, viz, $h(t-\tau)$, where the inner product of any 2 functions f(t), g(t) is given by $\int_{t=-\infty}^{t=+\infty} f(t)g(t)dt$. Write out the corresponding interpretation for the case of discrete convolution. Verify for the example solved in the lecture that this yields the same result.
- We define the support of any signal x(t) or x[n] as the smallest interval outside which the signal is zero. Thus, the support of $\sin t$ is $(-\infty, \infty)$ and the support of $\delta[n+1] - 2\delta[n-3]$ is [-1,3]. Let us denote the support of x(t) by (t_{xL}, t_{xR}) or $(t_{xL}, t_{xR}]$ or $[t_{xL}, t_{xR}]$ or $[t_{xL}, t_{xR}]$ as applicable, and that of x[n] by $[n_{xL}, n_{xR}]$. The support time of x(t) is denoted as $t_{xR} - t_{xL}$ and of x[n] by $n_{xR} - n_{xL}$. Show that the convolution of two signals x(t), x'(t) with finite support intervals T, T' has a finite support interval of T + T'. Similarly, prove the corresponding result for discrete signals: the convolution of two discrete signals having finite supports N, N' is N + N' - 1.
- Develop relations between the boundary points t_{xL} , t_{xR} , t_{hL} , t_{hR} and t_{yL} , t_{yR} . Similarly, develop the corresponding relations between n_{xL} , n_{xR} , n_{hL} , n_{hR} and n_{yL} , n_{yR} for discrete convolution.
- Under the new interpretation of convolution, the value of y(t) is equal to the area under $x(\tau)h(t-\tau)$. Use this to construct two examples of y(t) = x(t) * h(t) which is finite but not bounded, though x(t), h(t) are both bounded. Find constraints on x(t), h(t) that will ensure that y(t) remains finite for all t. Find a sufficient constraint to be applied upon x(t), h(t) to ensure that y(t) remains bounded, and not just finite. Compare these constraints with those obtained above to keep y(t) finite.
- After the above problems, can you comment on y(t) when x(t) is periodic and h(t) is finitely supported and both are bounded? What will happen when both x(t), h(t) are non negative, periodic and bounded?
- Following the consequences of the above, we seek a way out for the specific case of convolving periodic signals. The periodic convolution of two signals x(t), y(t) of period T is defined as $x(t) \circledast y(t) = \int_{t=-T/2}^{t=T/2} x(\tau)y(t-\tau)d\tau$. The convolution is now bounded because the integration limits have been restricted to exactly one period. What if the indicated integration interval (-T/2, T/2] is replaced by any other contiguous T-length time interval of the form $(\Delta, T + \Delta)$? Use this definition to convolve a T-periodic signal x(t) with a constant $y(t) = y_0$, using T as the convolution interval. Next, use any finite convolution interval T to convolve two constant signals $x(t) = x_0$ and $y(t) = y_0$. Express your result in terms of T in both cases.
- Let $x_i(t)$; i=1,2 be periodic signals of the same period T, and let each cycle of $x_i(t)$; i=1,2 be nonzero only over $t \leq T/2$ and zero over the remaining part of width $T/2 < t \leq T$ of the cycle. Define $x_i'(t) =$ $\int x_i(t); t \leq T$ $t \ge 1 \ t < 0, t > T$; i = 1, 2. Show that $x_1(t) \circledast x_2(t) = x_1'(t) * x_2'(t); t \le T$.