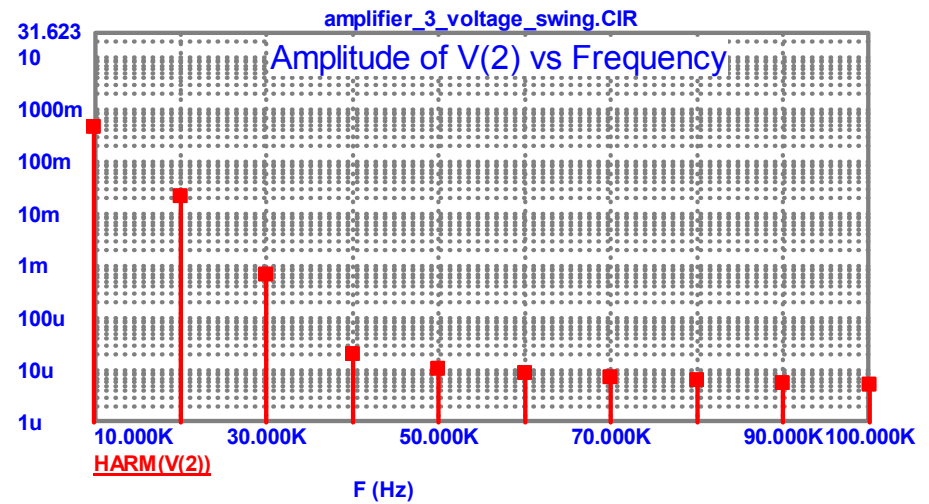
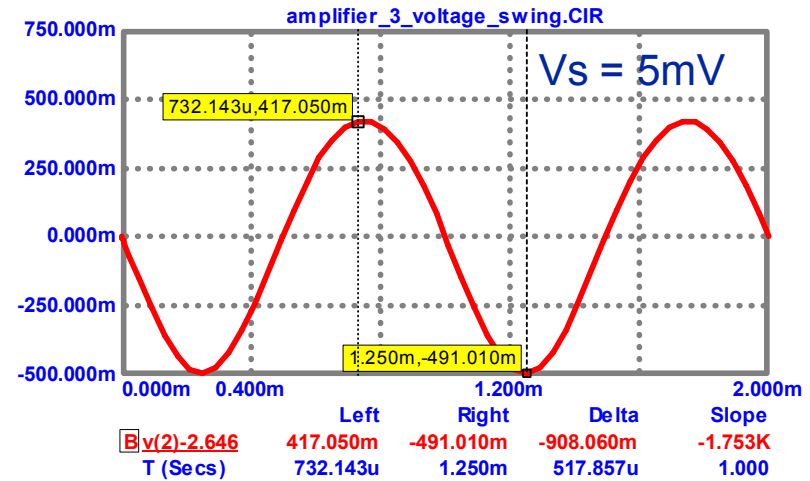
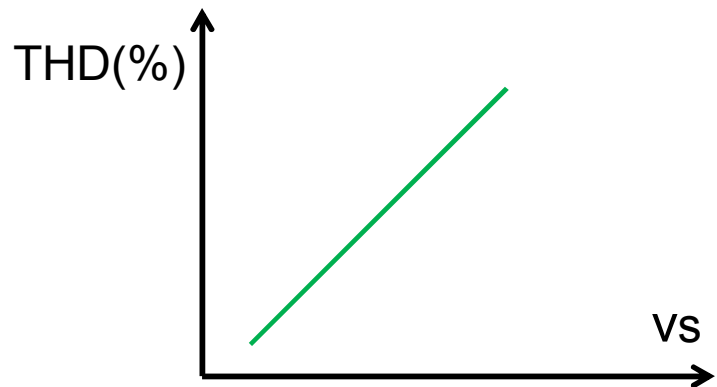
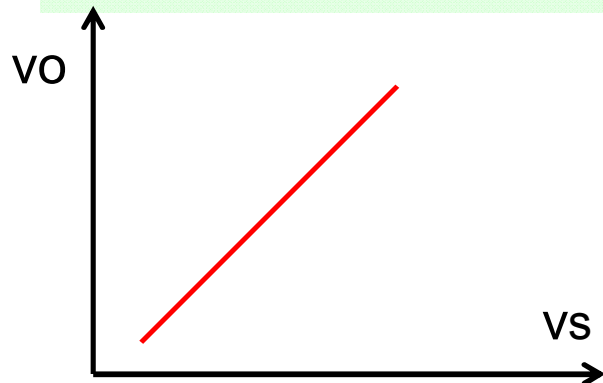
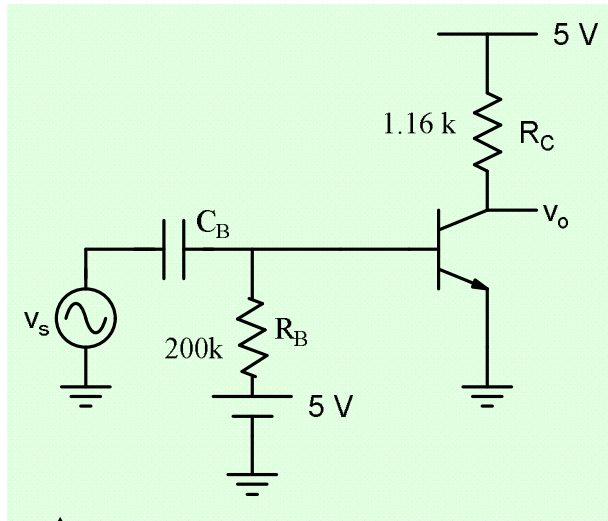


EE210: Microelectronics-I

Lecture-15 :BJT Amplifier-part-4

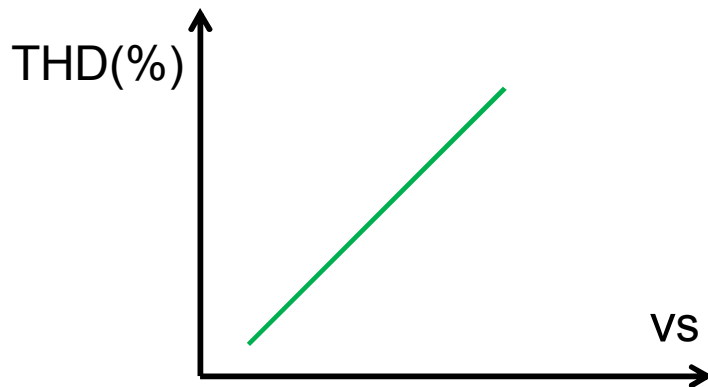
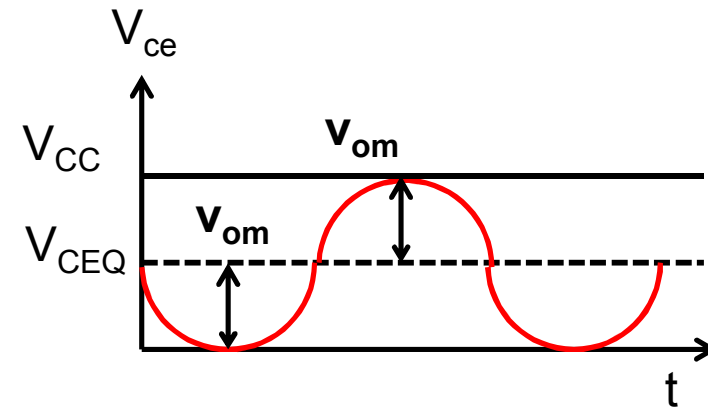
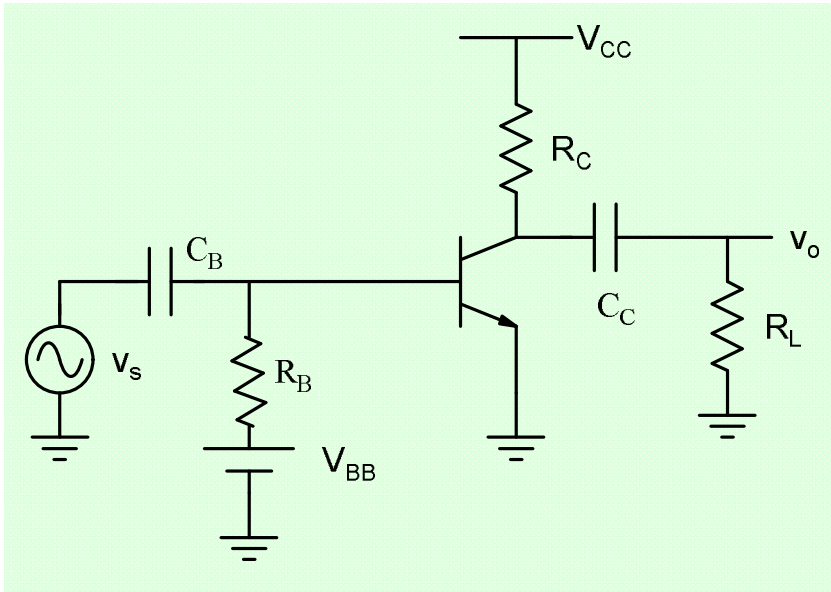
Instructor - Y. S. Chauhan

Slides from: B. Mazhari
Dept. of EE, IIT Kanpur



V_o (p-p) $\sim 0.91V$, THD $\sim 4.8\%$

Design for Maximum Output Voltage Swing

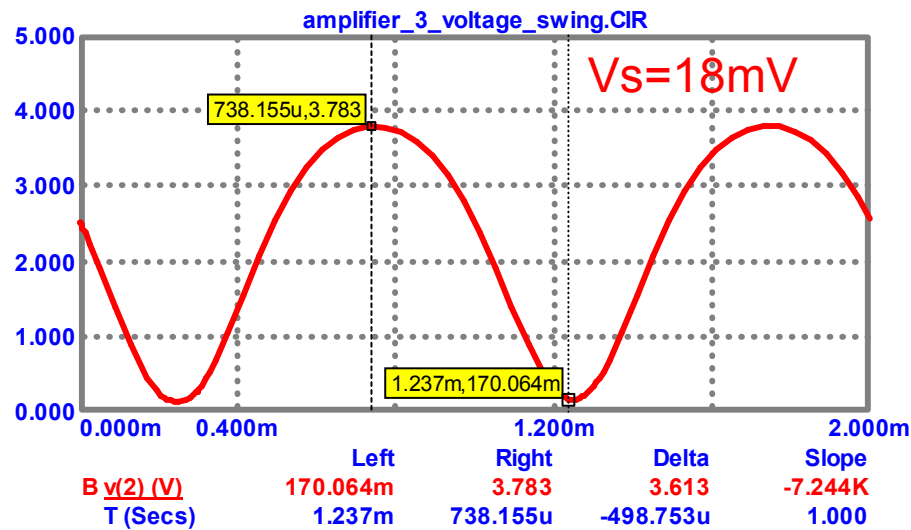
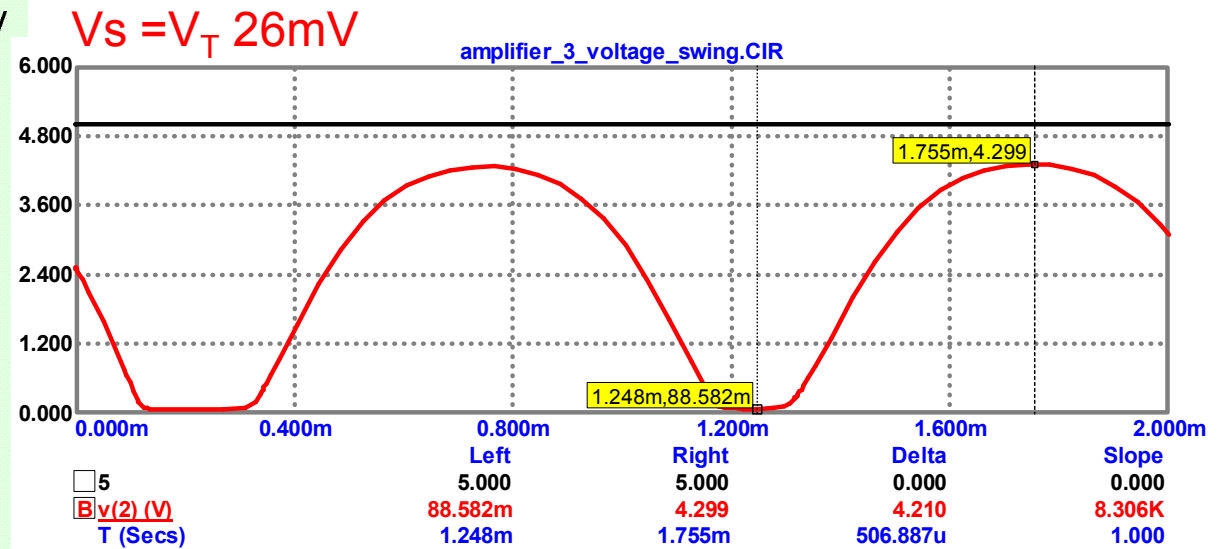
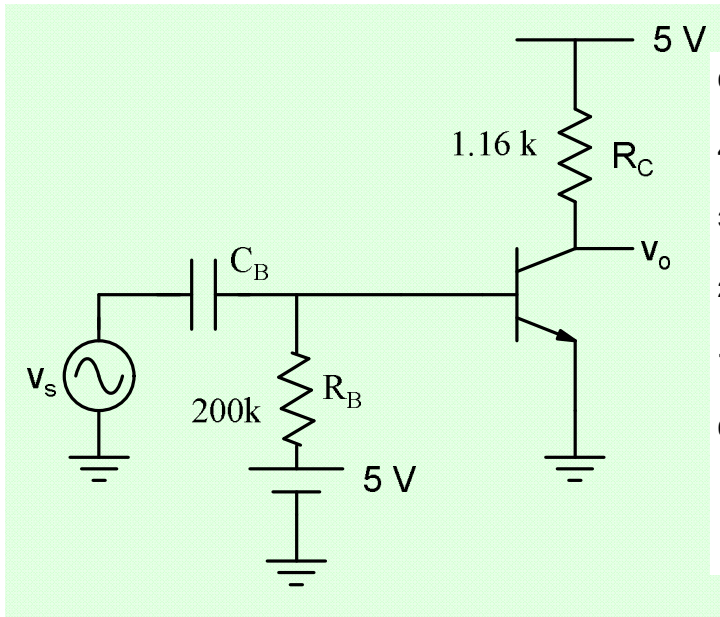


$$V_{CEQ} \sim \frac{V_{CC}}{2} \sim v_{om}$$

$$A_V = \frac{V_{CC} - V_{CEQ}}{V_T} \sim \frac{V_{CC}}{2V_T}$$

$$A_V = \frac{v_{om}}{v_s} \sim \frac{V_{CC}}{2V_T} \Rightarrow v_s = V_T$$

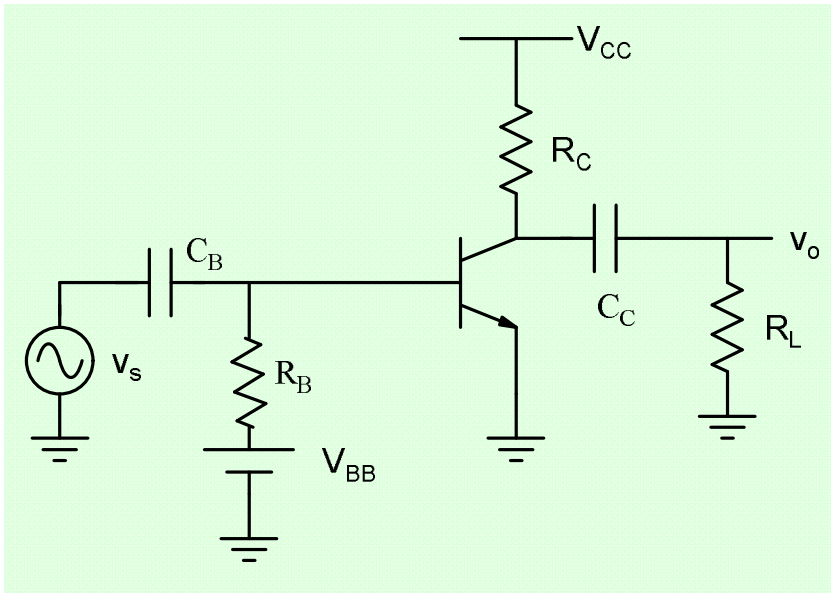
High Distortion begins to occur well before V_{ce} approaches V_{CC}



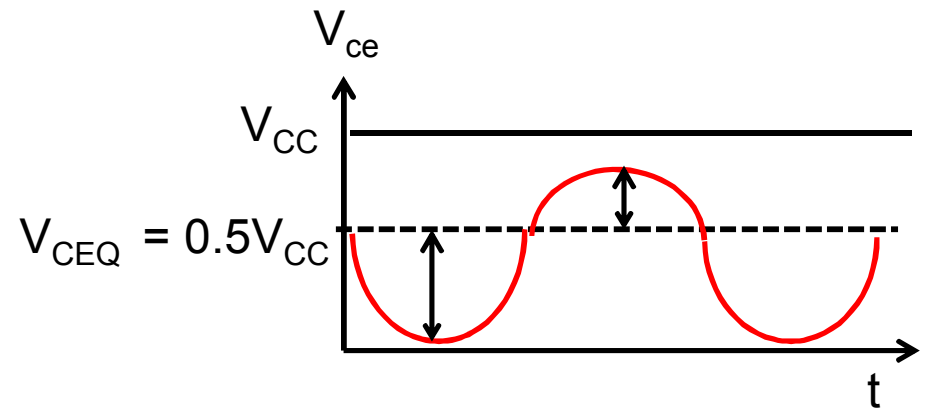
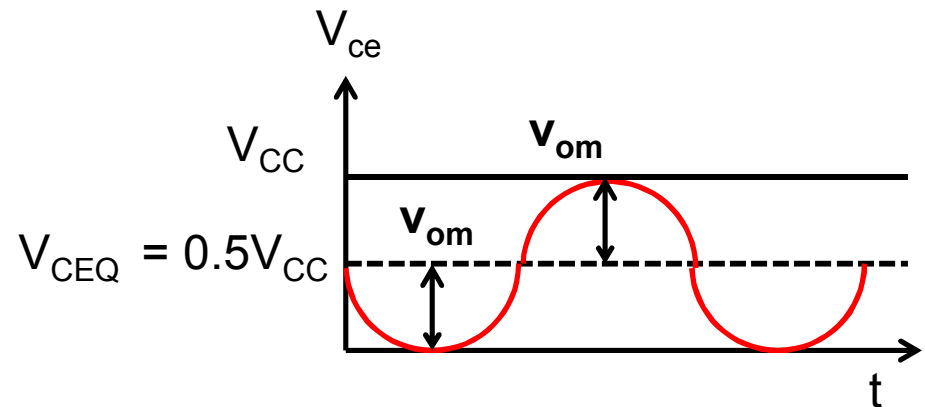
V_o (p-p) ~3.6V THD~16.9%

Must take harmonic distortion into account to calculate swing

Design for Maximum Output Voltage Swing

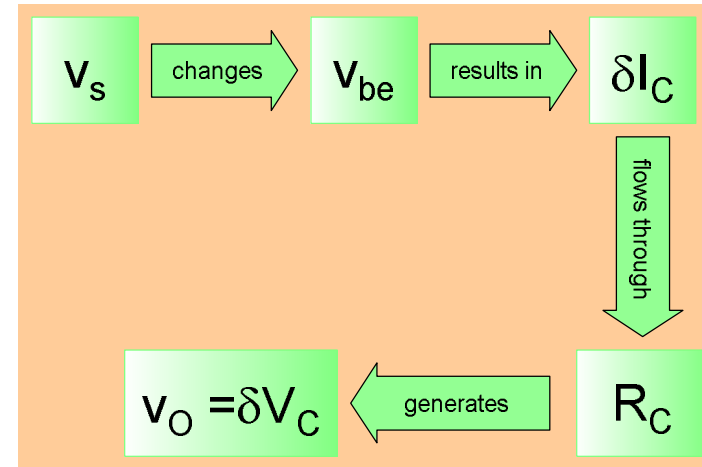
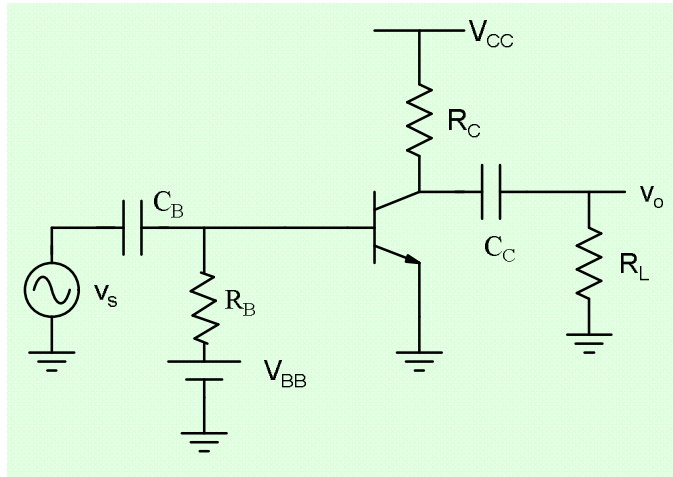


$$v_{om} = \text{Min} \left\{ V_{CEQ} - V_{CEsat}; V_{CC} - V_{CEQ} \right\}$$



Should $V_{CEQ} \sim \frac{V_{CC}}{2}$ for maximum output swing ?

Output Voltage Swing limited by Distortion



$$I_c = I_{CQ} + i_c = I_s \times \exp\left(\frac{V_{BEQ} + v_{be}}{V_T}\right) \quad i_c = I_{CQ} \times \exp\left(\frac{v_{be}}{V_T}\right) - I_{CQ}$$

$$v_s = v_{be} = v_{beo} \times \sin(\omega t)$$

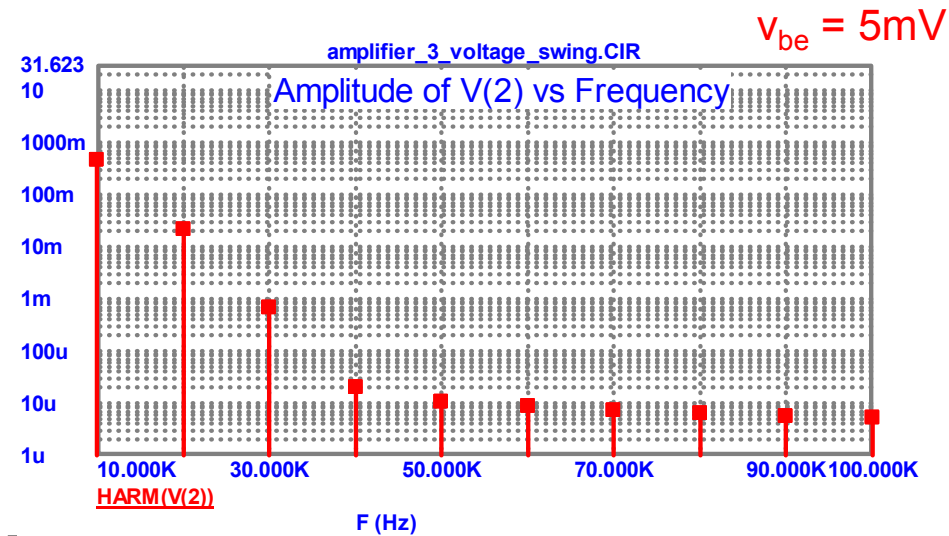
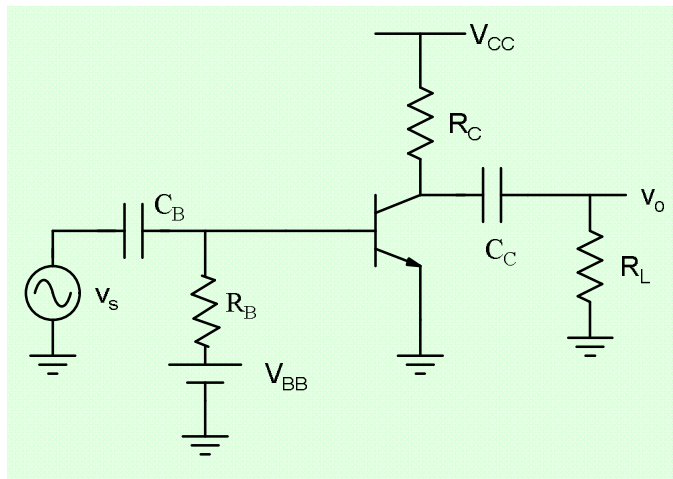
$$\frac{i_c}{I_{CQ}} = \exp\{m \times \sin(\omega t)\} - 1 \quad \frac{v_{beo}}{V_T} = m$$

$$\frac{i_c}{I_{CQ}} = m \times \sin(\omega t) + \frac{(m \times \sin(\omega t))^2}{2} + \dots$$

$$\frac{i_c}{I_{CQ}} = m \times \sin(\omega t) + \frac{(m \times \sin(\omega t))^2}{2} + \dots$$

$$\frac{v_{beo}}{V_T} = m$$

$$\frac{i_c}{I_{CQ}} = m \times \sin(\omega t) - \frac{m^2}{4} \cos(2\omega t) + \dots$$



Second Harmonic Distortion HD_2

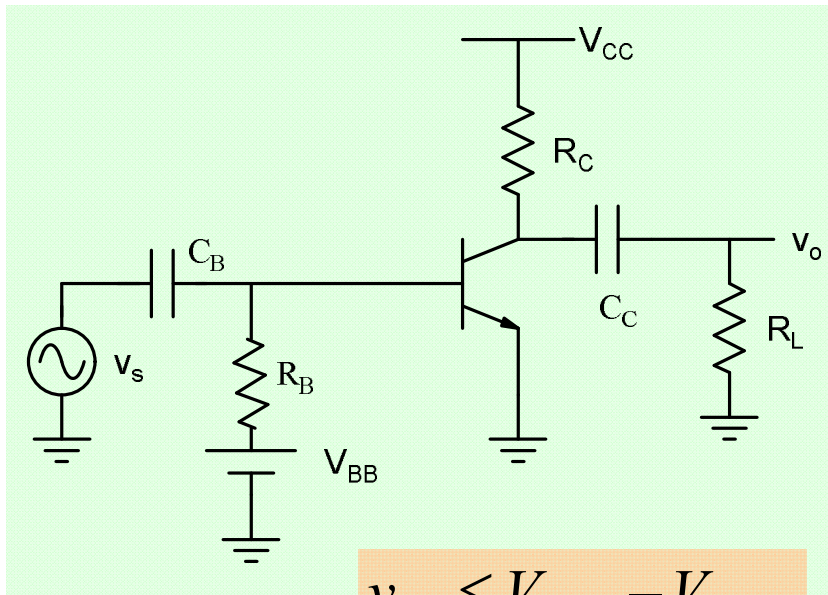
$$HD_2 \cong \frac{m}{4} = \frac{v_{beo}}{4 \times V_T}$$

$$HD_2(\%) = \frac{v_{beo}}{V_T} \times 25$$

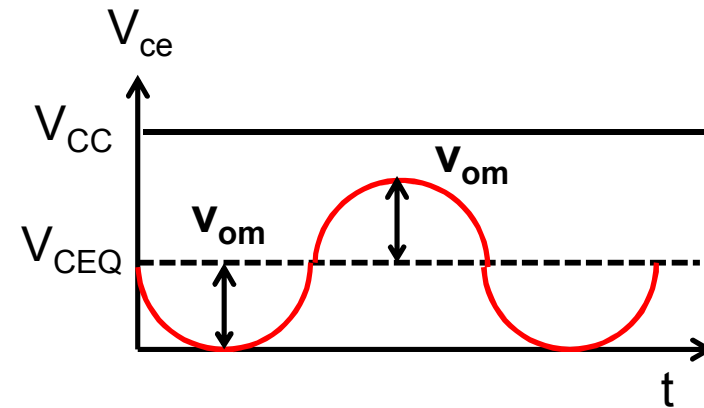
$$v_{om} \cong A_v \times v_{beo} \Rightarrow V_{om} \leq V_T \times \frac{HD_2}{25} \times A_v$$

$$V_{om} \leq (I_{CQ} \times R_C \parallel R_L) \times \left(\frac{HD_2}{25} \right)$$

Maximum Output voltage swing



$$v_{om} \leq V_{CEQ} - V_{CEsat}$$



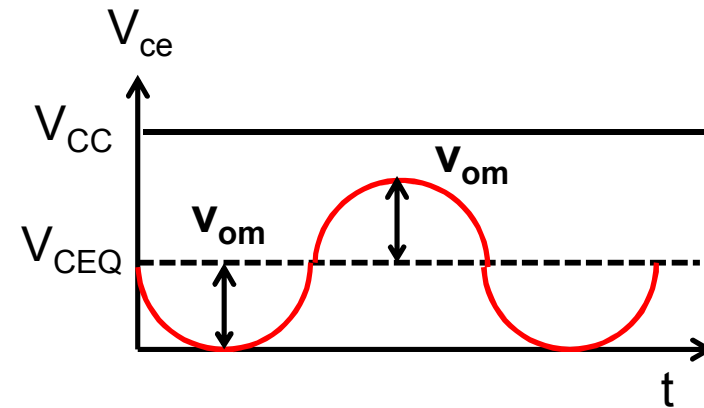
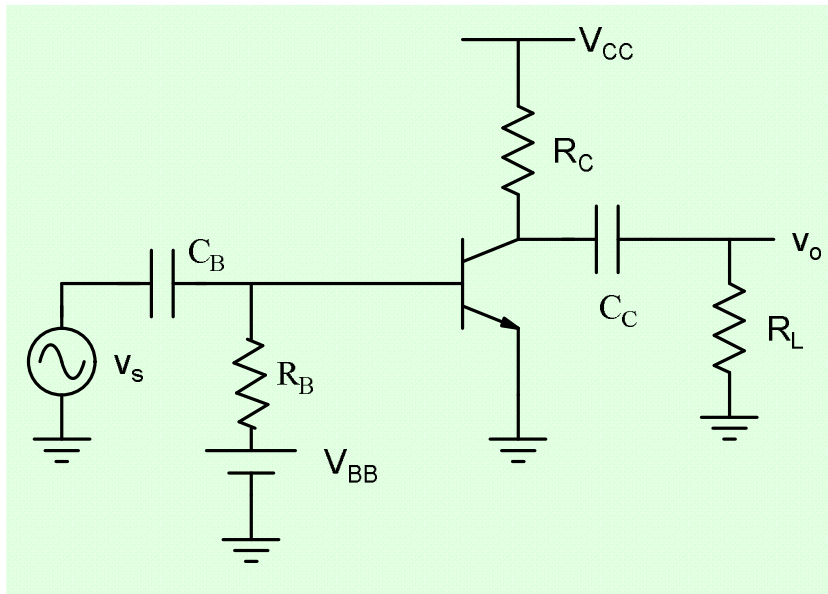
$$V_{om} \leq (I_{CQ} \times R_C \parallel R_L) \times \left(\frac{HD_2}{25} \right)$$

$$v_{om} = \text{Min} \left\{ V_{CEQ} - V_{CEsat}; \left(I_{CQ} \times R_C \parallel R_L \right) \times \left(\frac{HD_2}{25} \right) \right\}$$

$$V_{CEQ} - V_{CEsat} = \left(I_{CQ} \times R_C \parallel R_L \right) \times \left(\frac{HD_2}{25} \right)$$

$$v_{om} \cong V_{CEQ} \cong \frac{V_{CC}}{1 + \left(1 + \frac{R_C}{R_L} \right) \frac{25}{HD_2(\%)}}$$

Maximum Output voltage swing

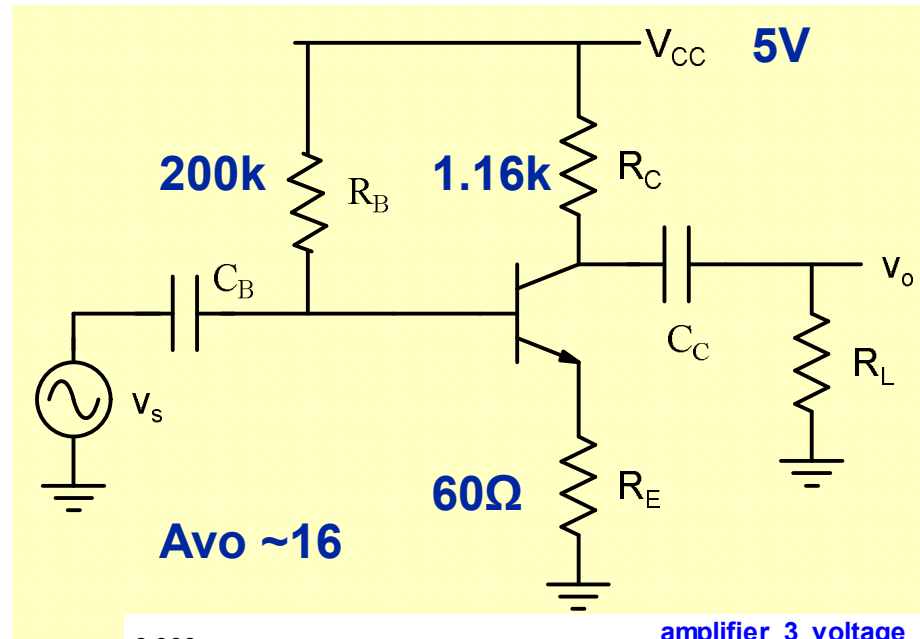


$$v_{om} \cong V_{CEQ} \cong \frac{V_{CC}}{1 + \left(1 + \frac{R_C}{R_L}\right) \frac{25}{HD_2(\%)}}$$

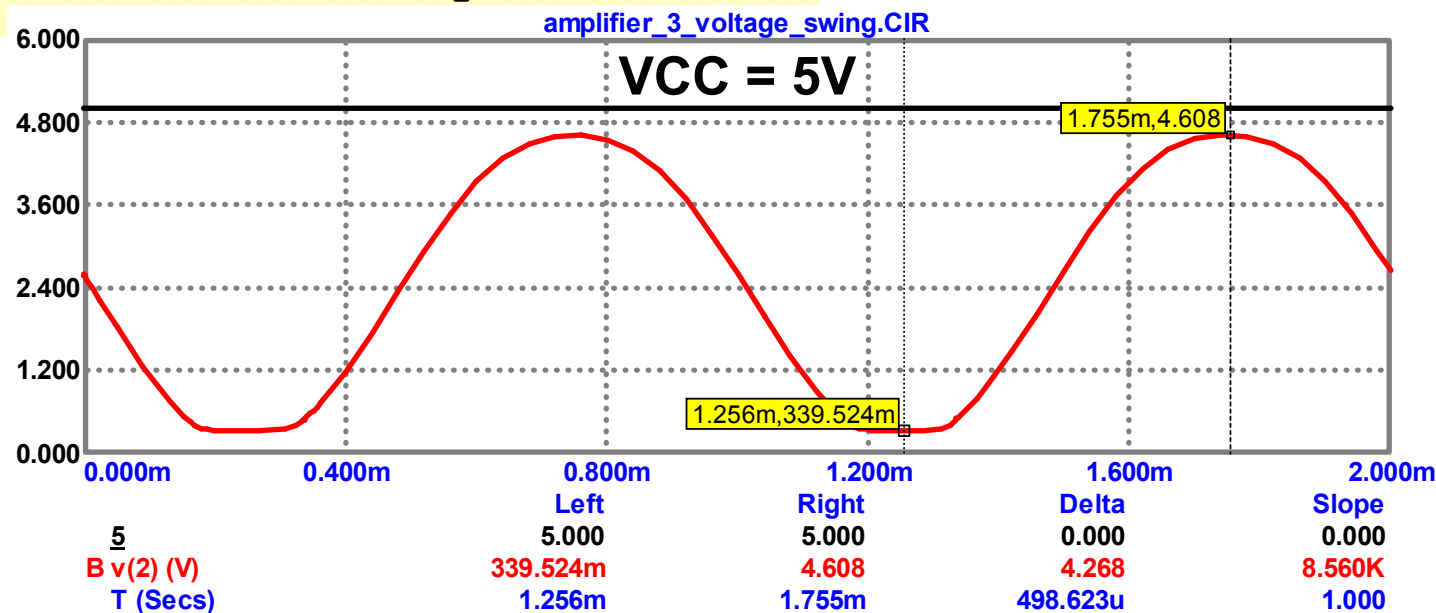
$$v_{om} \cong V_{CEQ} \cong \frac{V_{CC}}{1 + \frac{25}{HD_2(\%)}} \text{ for } R_L = \infty$$

$$v_{om} \cong V_{CEQ} \cong 1.43V \text{ for } HD_2 = 10\% \text{ for } V_{CC} = 5V$$

Use of emitter resistance reduces non-linear distortion

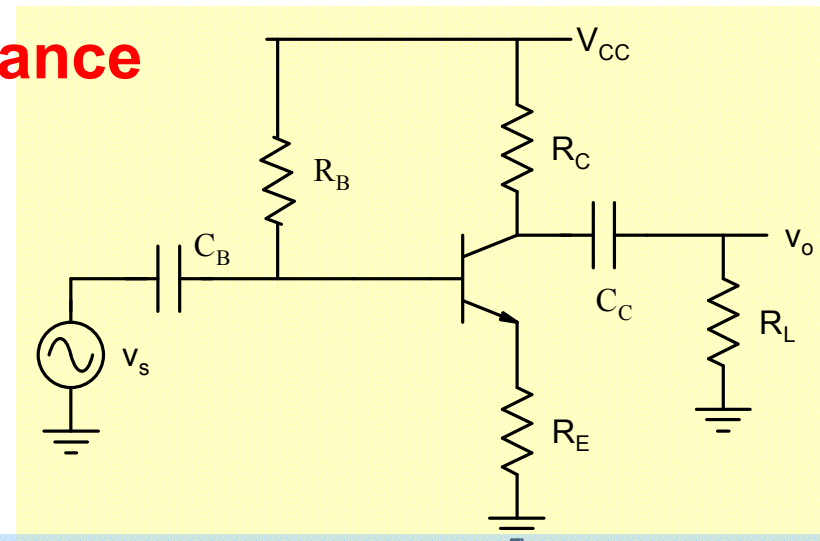
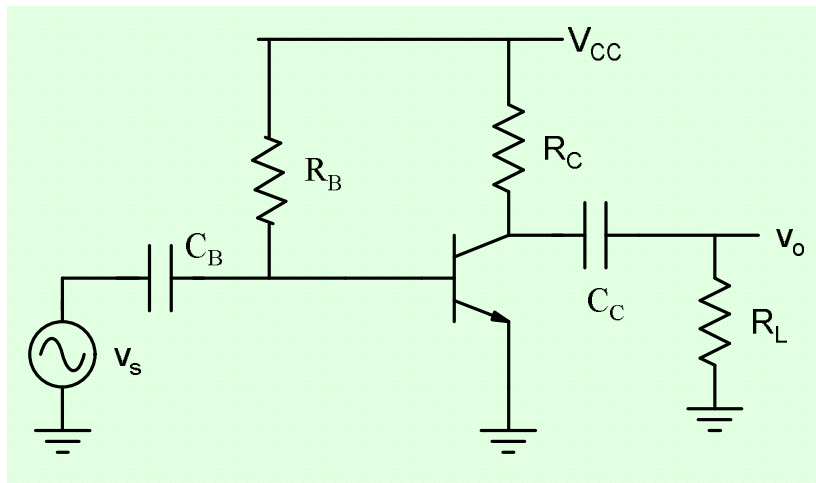


$V_{CEQ} \sim \frac{V_{CC}}{2}$ is a good bias point
for maximum output swing



THD~5%

CE Amplifier With Emitter Resistance

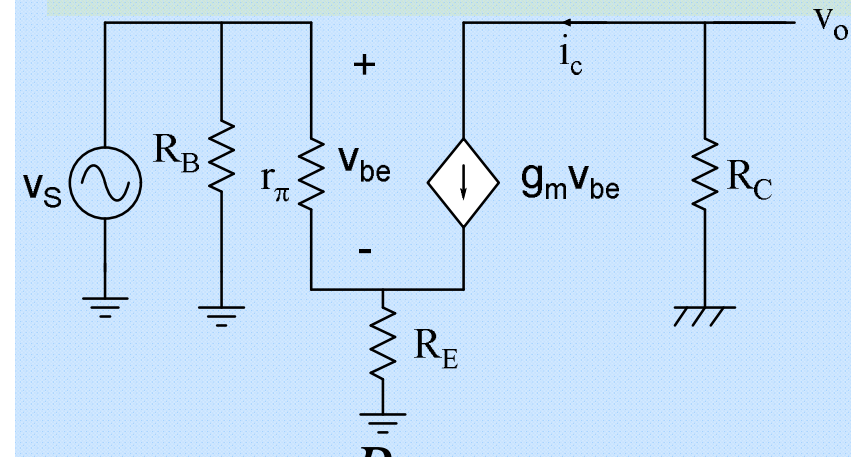


$$A_{VO} = -g_m R_C$$

$$R_{in} = R_B \parallel r_\pi \sim r_\pi = \frac{V_T}{I_{CQ}} \beta$$

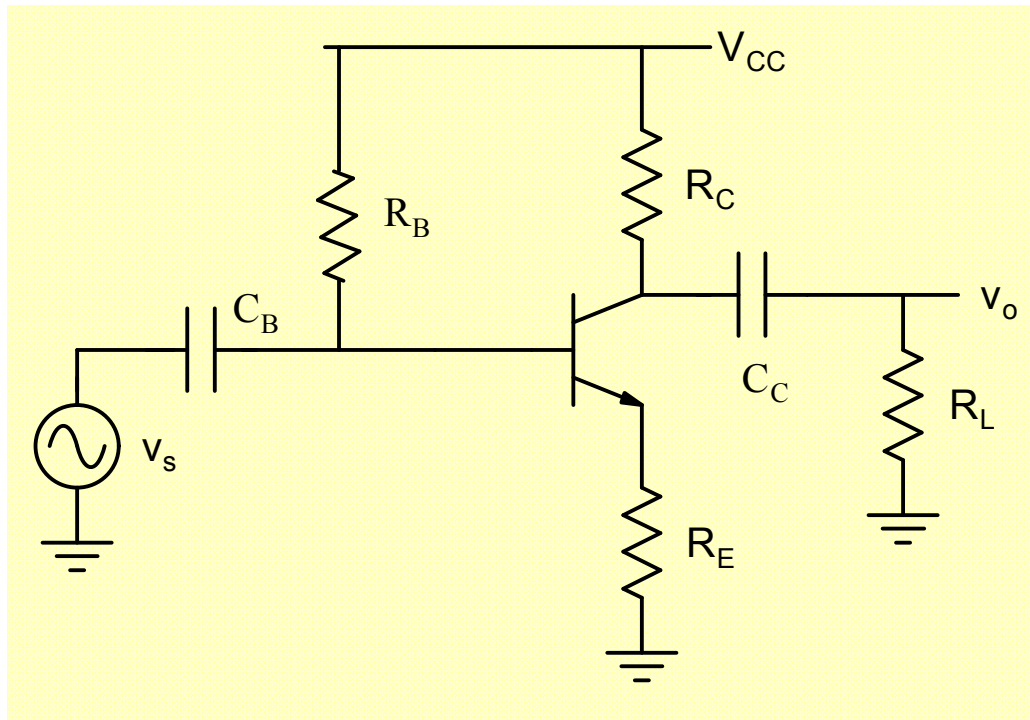
$$R_O \sim R_C$$

$$\frac{|A_{VO}| \times R_{in}}{R_O} \leq \beta$$



$$\left\{ \begin{aligned} A_{VO} &\cong -\frac{g_m R_C}{1 + g_m R_E} & R_O &\sim R_C \\ R_{in} &= R_B \parallel (r_\pi + (1 + \beta) R_E) \\ &\sim r_\pi (1 + g_m R_E) \end{aligned} \right.$$

Example



$$I_{CQ} = 1mA$$

$$g_m = \frac{I_{CQ}}{V_T} = 0.038 \Omega^{-1}$$

$$\text{For } R_E = 26 \Omega, g_m R_E = 1$$

$$A_{VO} \cong -\frac{g_m R_C}{2}$$

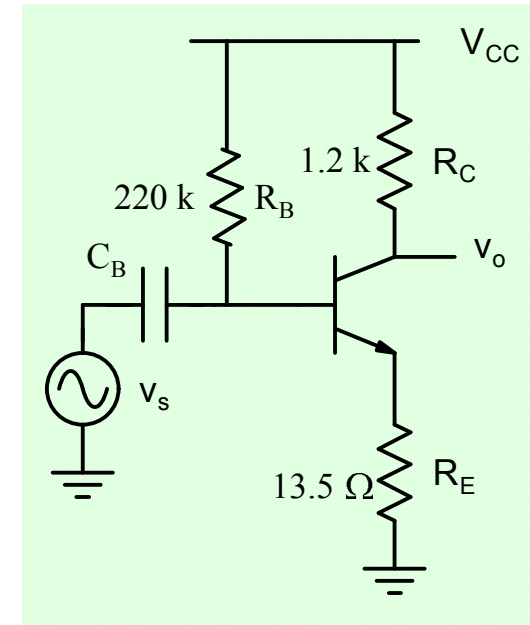
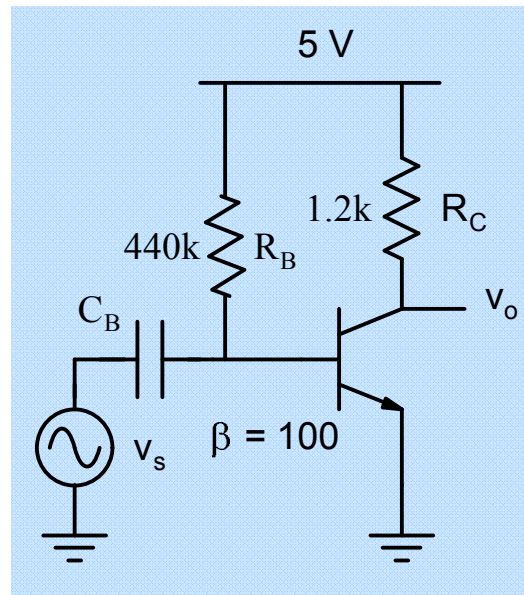
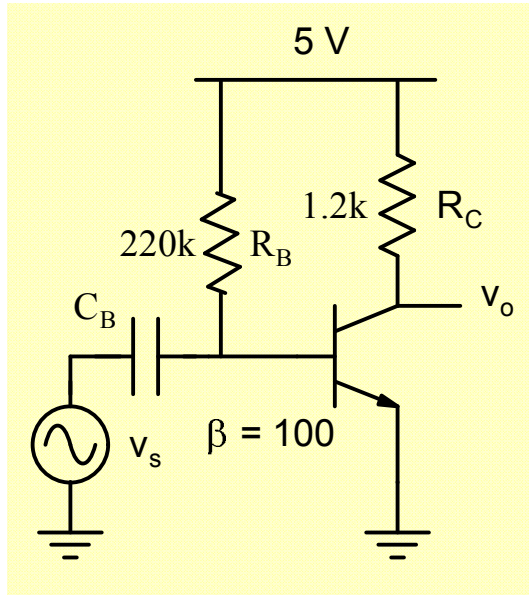
$$R_{in} \sim 2r_\pi$$

$$R_O \sim R_C$$

$$A_{VO} \cong -\frac{g_m R_C}{1 + g_m R_E} \quad R_O \sim R_C$$

$$R_{in} = R_B \parallel (r_\pi + (1 + \beta)R_E) \\ \sim r_\pi (1 + g_m R_E)$$

$$\frac{|A_{VO}| \times R_{in}}{R_O} \leq \beta$$



$$I_{CQ} = 1.95\text{ mA}$$

$$V_{CEQ} = 2.66\text{ V}$$

$$A_{V_o} = 90.2$$

$$R_{in} = 1.32\text{ k}\Omega$$

$$R_o = 1.2\text{ k}\Omega$$

$$I_{CQ} = 0.98\text{ mA}$$

$$V_{CEQ} = 3.8\text{ V}$$

$$A_{V_o} = 45.3$$

$$R_{in} = 2.6\text{ k}\Omega$$

$$R_o = 1.2\text{ k}\Omega$$

$$I_{CQ} = 1.93\text{ mA}$$

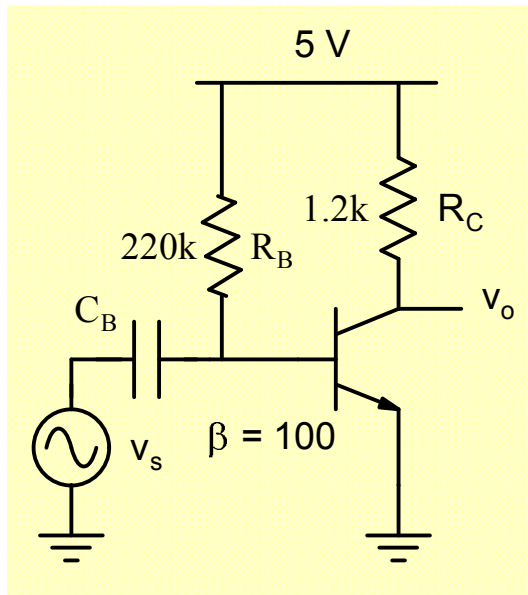
$$V_{CEQ} = 2.68\text{ V}$$

$$A_{V_o} = 44.3$$

$$R_{in} = 2.66\text{ k}\Omega$$

$$R_o = 1.2\text{ k}\Omega$$

Higher linearity at the cost of power dissipation



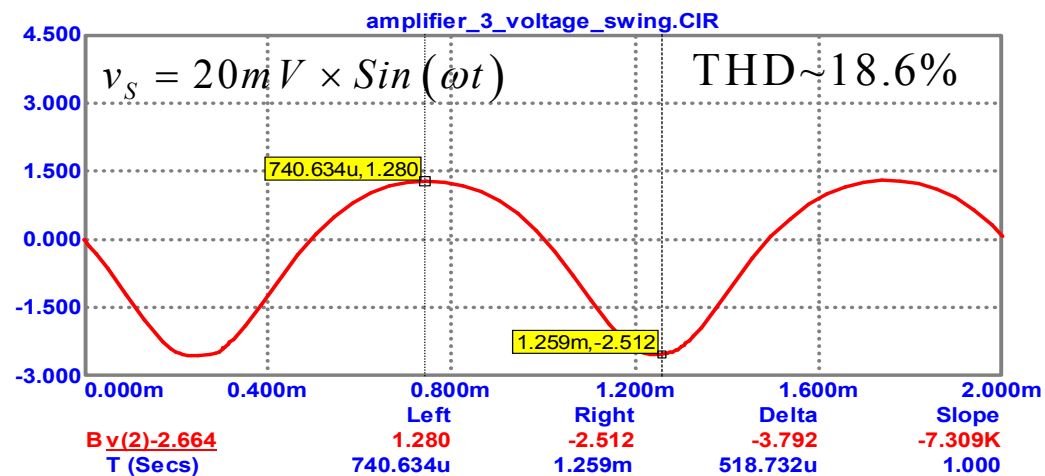
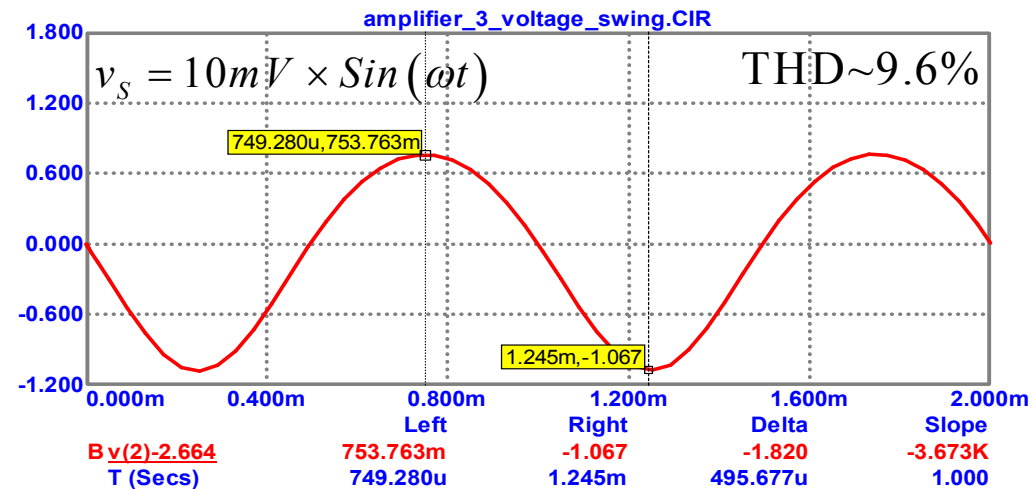
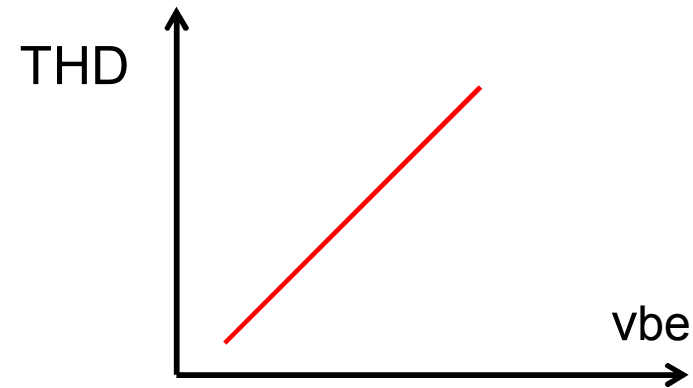
$$I_{CQ} = 1.95 \text{ mA}$$

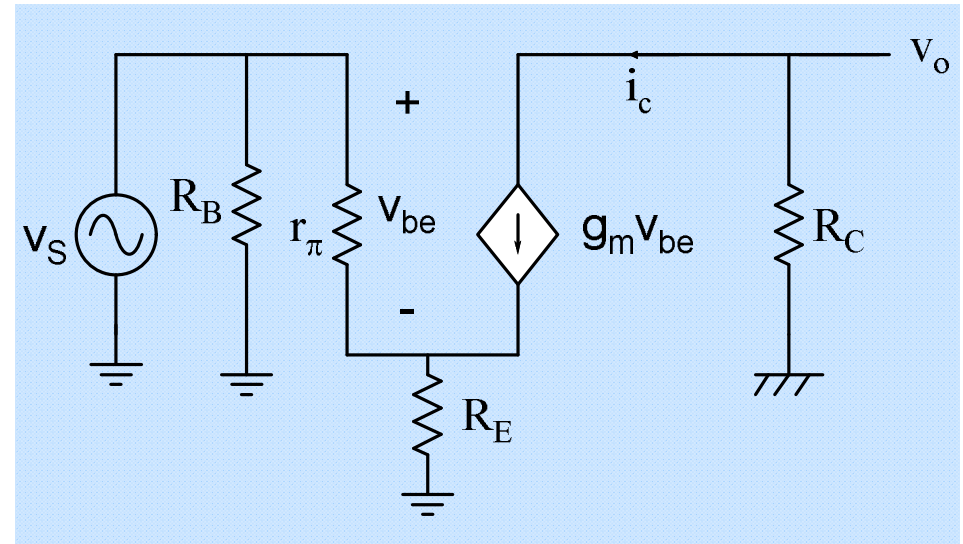
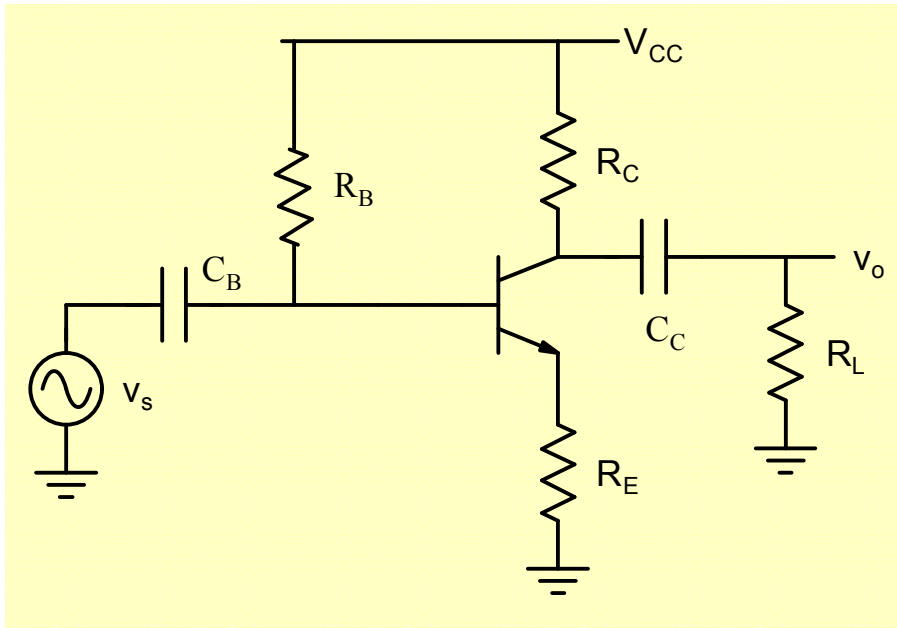
$$V_{CEQ} = 2.66 \text{ V}$$

$$A_{V_o} = 90.2$$

$$R_{in} = 1.32 \text{ k}\Omega$$

$$R_o = 1.2 \text{ k}\Omega$$





$$v_s = v_{be} \times (1 + g_m R_E)$$

Emitter resistance allows a higher input voltage to be used

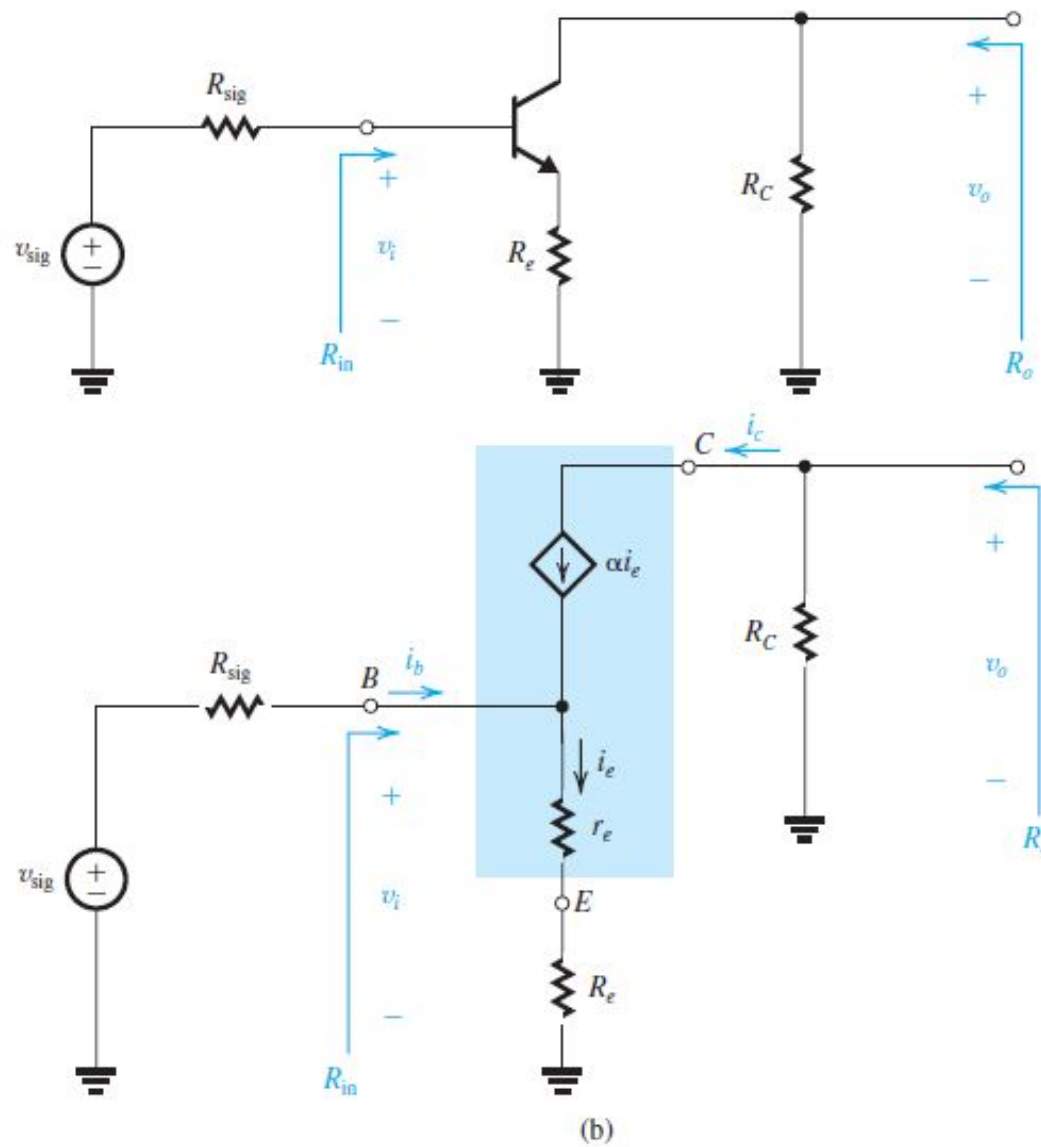



Figure 6.52 The CE amplifier with an emitter resistance R_e ; (a) Circuit without bias details; (b) Equivalent circuit with the BJT replaced with its T model.

Another important consequence of including the resistance R_e in the emitter is that it enables the amplifier to handle larger input signals without incurring nonlinear distortion. This is because only a fraction of the input signal at the base, v_i , appears between the base and the emitter. Specifically, from the circuit in Fig. 6.52(b), we see that

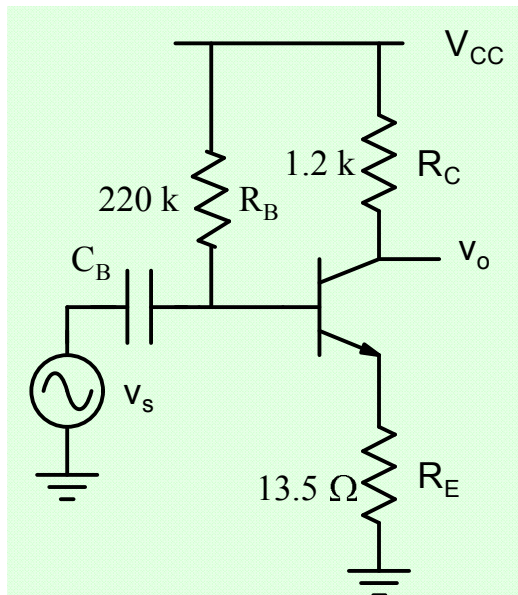
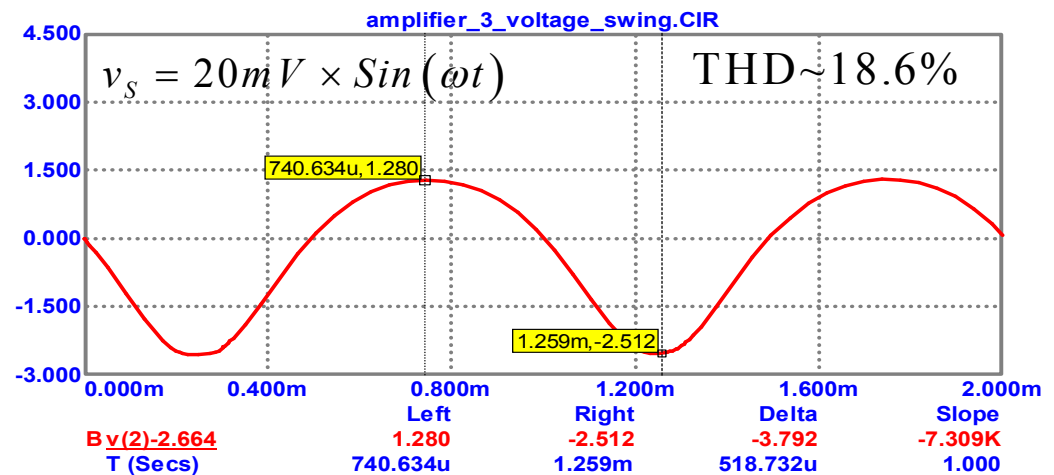
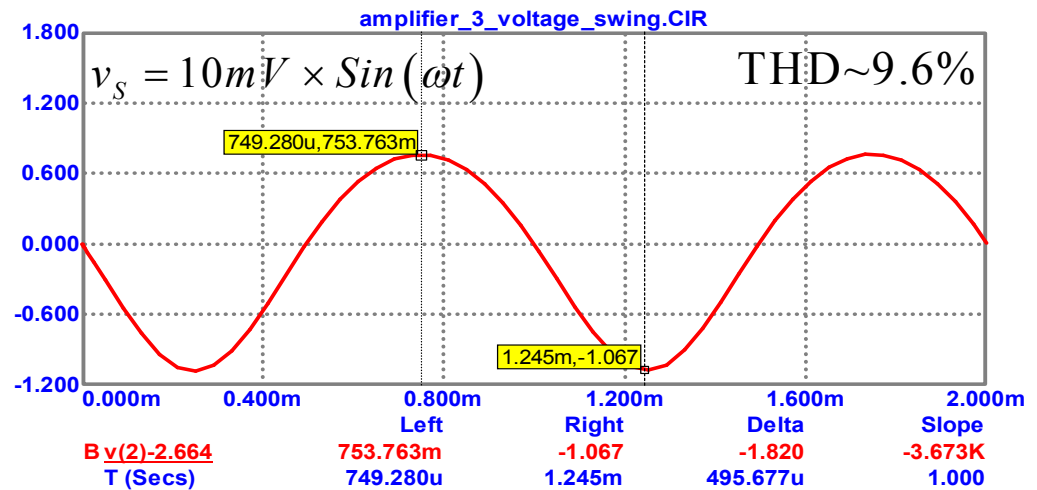
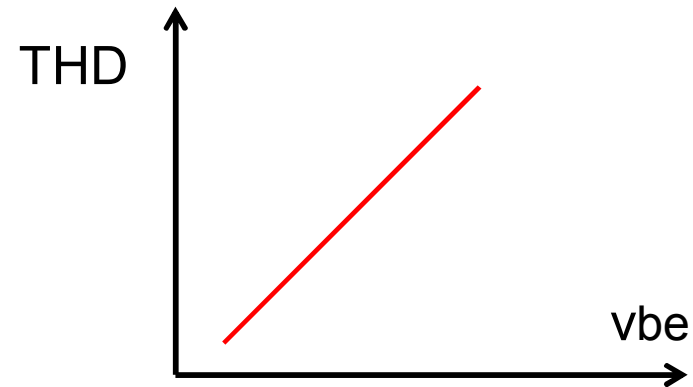
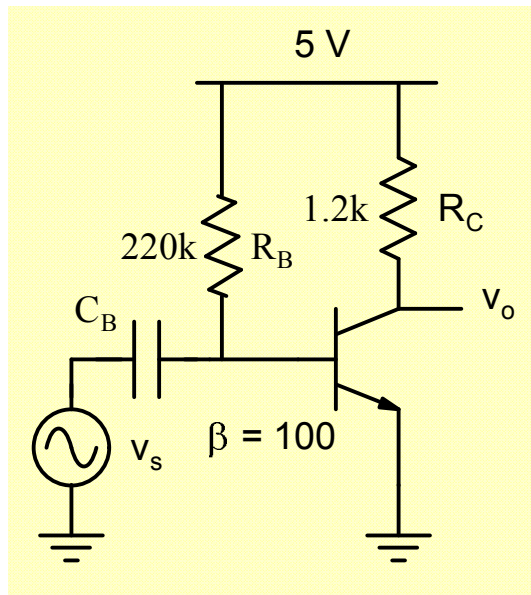

$$\frac{v_\pi}{v_i} = \frac{r_e}{r_e + R_e} \simeq \frac{1}{1 + g_m R_e} \quad (6.89)$$

Thus, for the same v_π , the signal at the input terminal of the amplifier, v_i , can be greater than for the CE amplifier by the factor $(1 + g_m R_e)$.

To summarize, including a resistance R_e in the emitter of the CE amplifier results in the following characteristics:

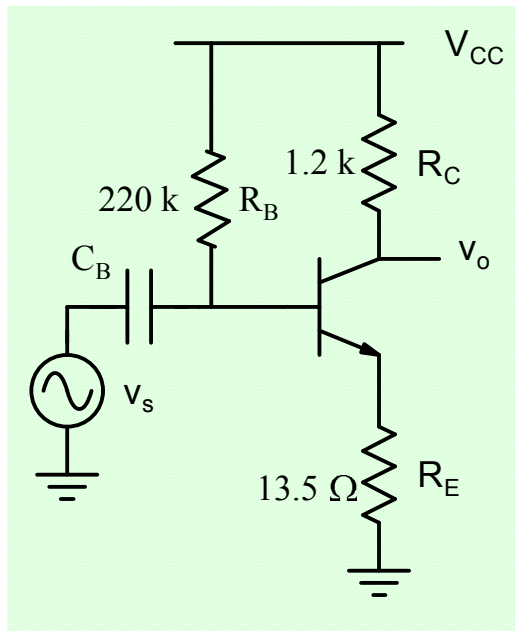
1. The input resistance R_{in} is increased by the factor $(1 + g_m R_e)$.
2. The voltage gain from base to collector, A_v , is reduced by the factor $(1 + g_m R_e)$.
3. For the same nonlinear distortion, the input signal v_i can be increased by the factor $(1 + g_m R_e)$.
4. The overall voltage gain is less dependent on the value of β .
5. The high-frequency response is significantly improved (as we shall see in Chapter 9).

Sedra and Smith



$$v_S = 20mV \times \sin(\omega t)$$

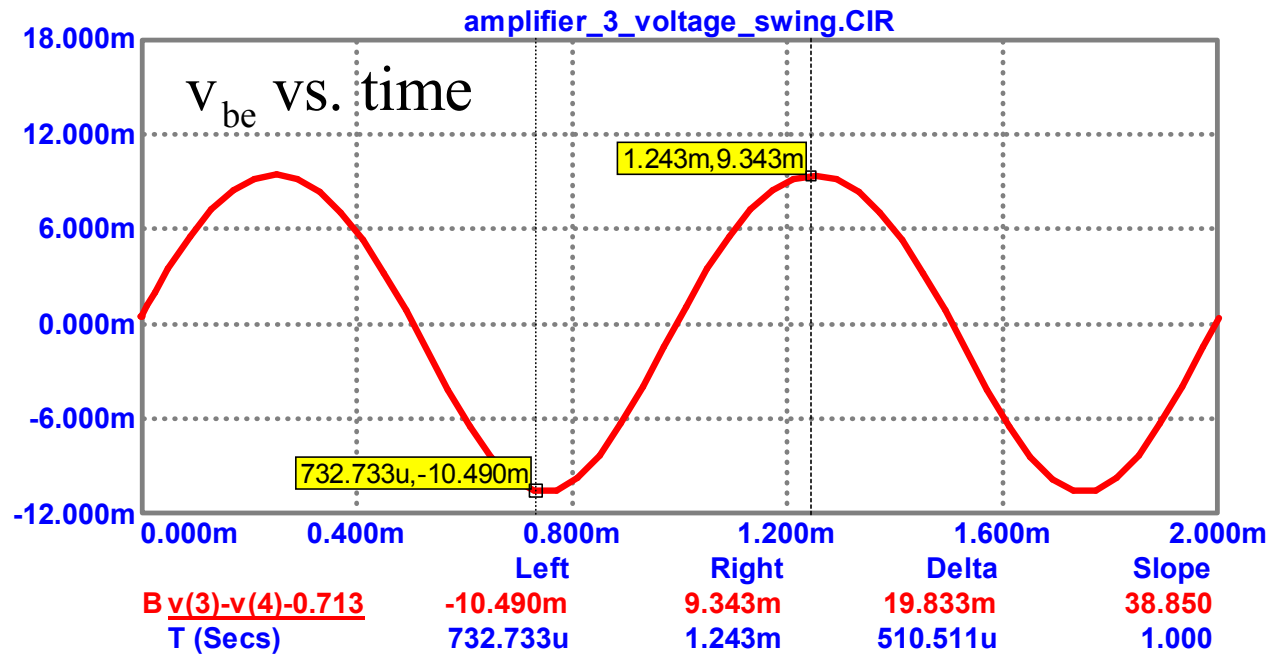
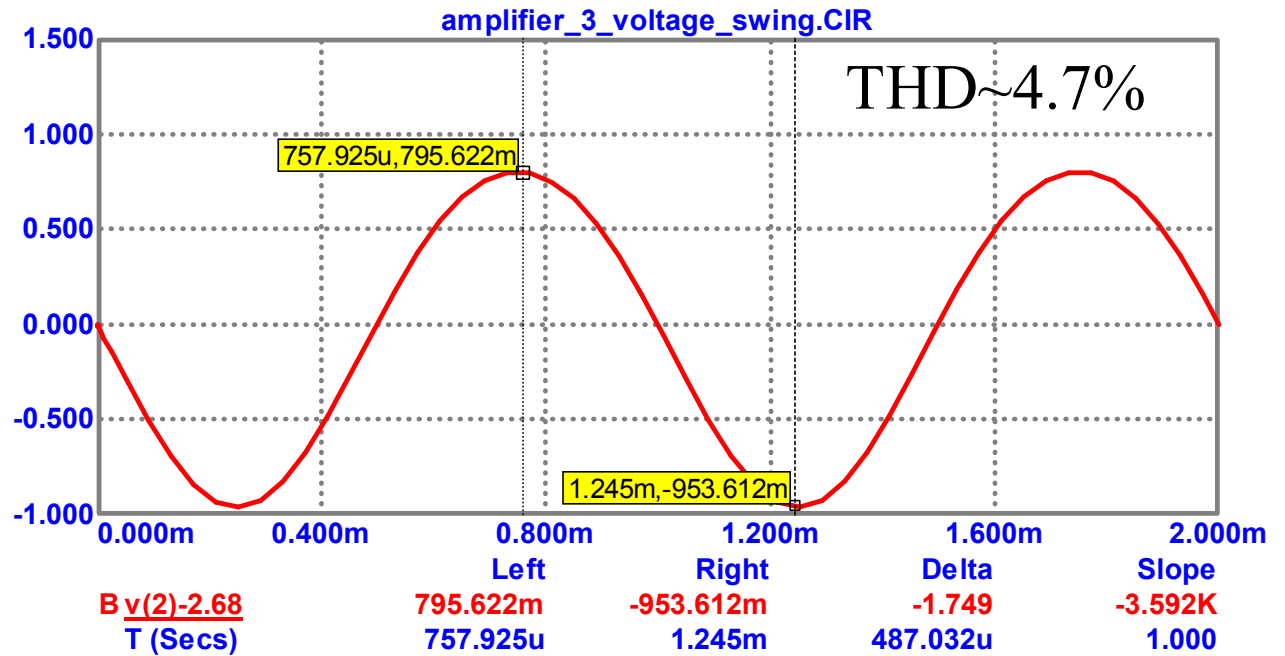
$$v_S = v_{be} \times (1 + g_m R_E) = 2v_{be}$$

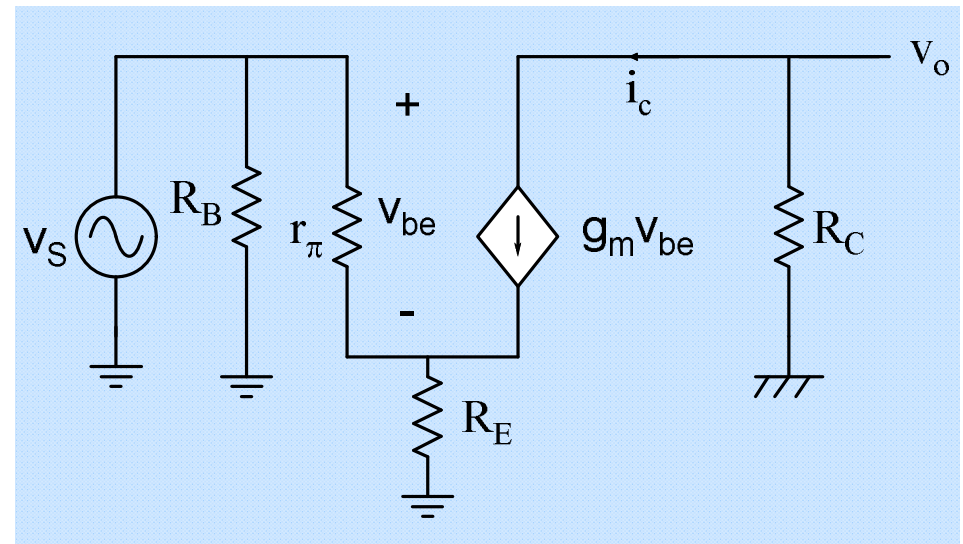
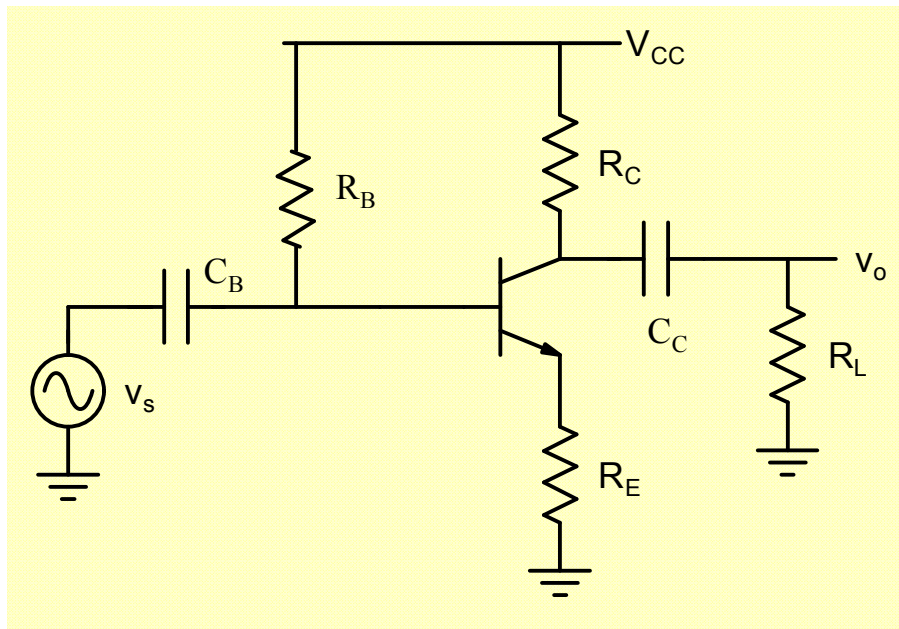


$$v_s = 20mV \times \sin(\omega t)$$

$$v_s = v_{be} \times (1 + g_m R_E)$$

$$= 2v_{be}$$

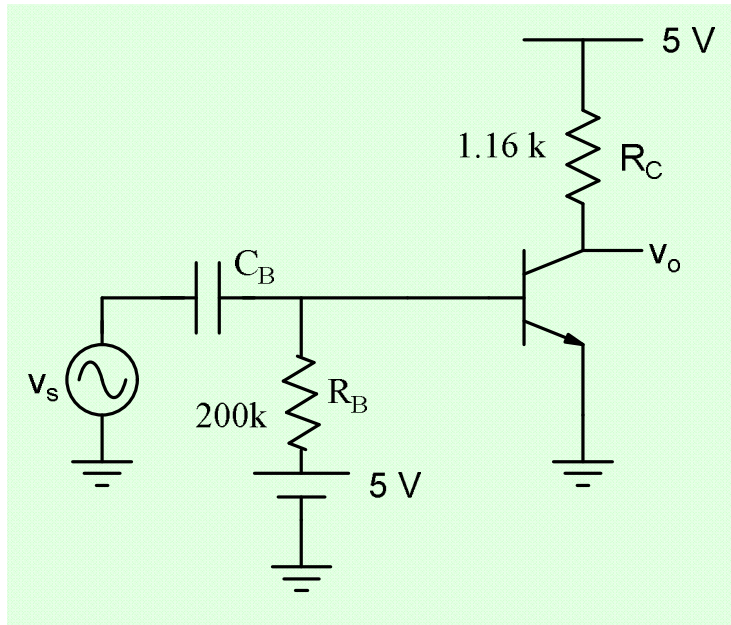




$$v_S = v_{be} \times (1 + g_m R_E)$$

3. For the same nonlinear distortion, the input signal v_i can be increased by the factor $(1 + g_m R_E)$.

Emitter resistance not only allows a higher input voltage to be used but for same v_{be} reduces harmonic distortion as well



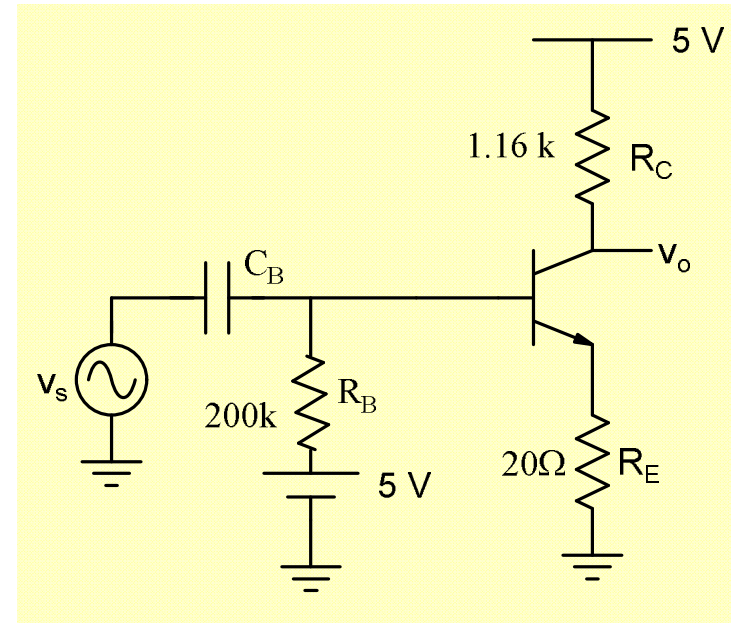
$$A_{v_o} = 95.75$$

$$R_{in} = 1.2 \text{ k}\Omega$$

$$R_o = 1.16 \text{ k}\Omega$$

$$v_{opp} = 1.93 \text{ V for THD} \sim 9.6\%$$

$$\frac{|A_{VO}| \times R_{in}}{R_o} = 99$$



$$A_{v_o} = 35.7$$

$$R_{in} = 3.18 \text{ k}\Omega$$

$$R_o = 1.16 \text{ k}\Omega$$

$$v_{opp} = 4.3 \text{ V for THD} \sim 9.6\%$$

$$\frac{|A_{VO}| \times R_{in}}{R_o} = 97.86$$