10 – Processes

Modern operating systems are usually *multitasking*, meaning they create the illusion of doing more than one thing at once by rapidly switching from one executing program to another. The Linux kernel manages this through the use of *processes*. Processes are how Linux organizes the different programs waiting for their turn at the CPU.

Sometimes a computer will become sluggish or an application will stop responding. In this chapter, we will look at some of the tools available at the command line that let us examine what programs are doing and how to terminate processes that are misbehaving.

This chapter will introduce the following commands:

- `ps` – Report a snapshot of current processes
- `top` – Display tasks
- `jobs` – List active jobs
- `bg` – Place a job in the background
- `fg` – Place a job in the foreground
- `kill` – Send a signal to a process
- `killall` – Kill processes by name
- `shutdown` – Shutdown or reboot the system

How a Process Works

When a system starts up, the kernel initiates a few of its own activities as processes and launches a program called `init`. `init`, in turn, runs a series of shell scripts (located in `/etc`) called *init scripts*, which start all the system services. Many of these services are implemented as *daemon programs*, programs that just sit in the background and do their thing without having any user interface. So, even if we are not logged in, the system is at least a little busy performing routine stuff.

The fact that a program can launch other programs is expressed in the process scheme as a *parent process* producing a *child process*.

The kernel maintains information about each process to help keep things organized. For example, each process is assigned a number called a *process ID* (*PID*). PIDs are assigned in ascending order, with `init` always getting PID 1. The kernel also keeps track of the memory assigned to each process, as well as the processes' readiness to resume execution. Like files, processes also have owners and user IDs, effective user IDs, etc.

Viewing Processes

The most commonly used command to view processes (there are several) is `ps`. The `ps` program has a lot of options, but in its simplest form it is used like this:

```
[me@linuxbox ~]$ ps
  PID TTY          TIME CMD
 5198 pts/1    00:00:00 bash
10129 pts/1    00:00:00 ps
```

The result in this example lists two processes, process 5198 and process 10129, which are `bash` and `ps` respectively. As we can see, by default, `ps` doesn't show us very much, just the processes associated with the current terminal session. To see more, we need to add some options, but before we do that, let's look at the other fields produced by `ps`. `TTY` is short for “teletype,” and refers to the *controlling terminal* for the process. Unix is showing its age here. The `TIME` field is the amount of CPU time consumed by the process. As we can see, neither process makes the computer work very hard.

If we add an option, we can get a bigger picture of what the system is doing.

```
[me@linuxbox ~]$ ps x
  PID TTY      STAT   TIME COMMAND
 2799 ?        Ssl    0:00 /usr/libexec/bonobo-activation-server –ac
 2820 ?        Sl     0:01 /usr/libexec/evolution-data-server-1.10 --
15647 ?        Ss     0:00 /bin/sh /usr/bin/startkde
15751 ?        Ss     0:00 /usr/bin/ssh-agent /usr/bin/dbus-launch --
15754 ?        S      0:00 /usr/bin/dbus-launch --exit-with-session
15755 ?        Ss     0:01 /bin/dbus-daemon --fork --print-pid 4 –pr
15774 ?        Ss     0:02 /usr/bin/gpg-agent -s –daemon
15793 ?        S      0:00 start_kdeinit --new-startup +kcminit_start
15794 ?        Ss     0:00 kdeinit Running...
15797 ?        S      0:00 dcopserver –nosid
and many more...
```

Adding the “x” option (note that there is no leading dash) tells `ps` to show all of our pro-

cesses regardless of what terminal (if any) they are controlled by. The presence of a “?” in the TTY column indicates no controlling terminal. Using this option, we see a list of every process that we own.

Since the system is running a lot of processes, ps produces a long list. It is often helpful to pipe the output from ps into less for easier viewing. Some option combinations also produce long lines of output, so maximizing the terminal emulator window may be a good idea, too.

A new column titled STAT has been added to the output. STAT is short for “state” and reveals the current status of the process, as shown in Table 10-1.

Table 10-1: Process States

State	Meaning
R	Running. This means that the process is running or ready to run.
S	Sleeping. The process is not running; rather, it is waiting for an event, such as a keystroke or network packet.
D	Uninterruptible sleep. The process is waiting for I/O such as a disk drive.
T	Stopped. The process has been instructed to stop. More on this later in the chapter.
Z	A defunct or “zombie” process. This is a child process that has terminated but has not been cleaned up by its parent.
<	A high-priority process. It's possible to grant more importance to a process, giving it more time on the CPU. This property of a process is called *niceness*. A process with high priority is said to be less *nice* because it's taking more of the CPU's time, which leaves less for everybody else.
N	A low-priority process. A process with low priority (a “nice” process) will get processor time only after other processes with higher priority have been serviced.

The process state may be followed by other characters. These indicate various exotic process characteristics. See the ps man page for more detail.

Another popular set of options is “aux” (without a leading dash). This gives us even more information.

```
[me@linuxbox ~]$ ps aux
USER    PID %CPU %MEM    VSZ   RSS TTY      STAT START   TIME COMMAND
root      1  0.0  0.0   2136   644 ?        Ss   Mar05   0:31 init
root      2  0.0  0.0      0     0 ?        S<   Mar05   0:00 [kt]
root      3  0.0  0.0      0     0 ?        S<   Mar05   0:00 [mi]
root      4  0.0  0.0      0     0 ?        S<   Mar05   0:00 [ks]
root      5  0.0  0.0      0     0 ?        S<   Mar05   0:06 [wa]
root      6  0.0  0.0      0     0 ?        S<   Mar05   0:36 [ev]
root      7  0.0  0.0      0     0 ?        S<   Mar05   0:00 [kh]
and many more...
```

This set of options displays the processes belonging to every user. Using the options without the leading dash invokes the command with “BSD style” behavior. The Linux version of `ps` can emulate the behavior of the `ps` program found in several different Unix implementations. With these options, we get the additional columns shown in Table 10-2.

Table 10-2: BSD Style `ps` Column Headers

Header	Meaning
`USER`	User ID. This is the owner of the process.
`%CPU`	CPU usage in percent.
`%MEM`	Memory usage in percent.
`VSZ`	Virtual memory size.
`RSS`	Resident set size. This is the amount of physical memory (RAM) the process is using in kilobytes.
`START`	Time when the process started. For values over 24 hours, a date is used.

Viewing Processes Dynamically with `top`

While the `ps` command can reveal a lot about what the machine is doing, it provides only a snapshot of the machine's state at the moment the `ps` command is executed. To see a more dynamic view of the machine's activity, we use the `top` command:

```
[me@linuxbox ~]$ top
```

The `top` program displays a continuously updating (by default, every three seconds) display of the system processes listed in order of process activity. The name *top* comes from the fact that the `top` program is used to see the "top" processes on the system. The `top` display consists of two parts: a system summary at the top of the display, followed by a table of processes sorted by CPU activity:

```
top - 14:59:20 up  6:30,  2 users,  load average: 0.07, 0.02, 0.00
Tasks: 109 total,   1 running, 106 sleeping,   0 stopped,   2 zombie
Cpu(s):  0.7%us,  1.0%sy,  0.0%ni, 98.3%id,  0.0%wa,  0.0%hi,  0.0%si
Mem:    319496k total,   314860k used,     4636k free,    19392k buff
Swap:   875500k total,   149128k used,   726372k free,   114676k cach

  PID USER      PR  NI  VIRT  RES  SHR S %CPU %MEM    TIME+  COMMAND
 6244 me        39  19 31752 3124 2188 S  6.3  1.0  16:24.42 trackerd
11071 me        20   0  2304 1092  840 R  1.3  0.3   0:00.14 top
 6180 me        20   0  2700 1100  772 S  0.7  0.3   0:03.66 dbus-dae
 6321 me        20   0 20944 7248 6560 S  0.7  2.3   2:51.38 multiloa
 4955 root      20   0  104m 9668 5776 S  0.3  3.0   2:19.39 Xorg
    1 root      20   0  2976  528  476 S  0.0  0.2   0:03.14 init
    2 root      15  -5     0    0    0 S  0.0  0.0   0:00.00 kthreadd
    3 root      RT  -5     0    0    0 S  0.0  0.0   0:00.00 migratio
    4 root      15  -5     0    0    0 S  0.0  0.0   0:00.72 ksoftirq
    5 root      RT  -5     0    0    0 S  0.0  0.0   0:00.04 watchdog
    6 root      15  -5     0    0    0 S  0.0  0.0   0:00.42 events/0
    7 root      15  -5     0    0    0 S  0.0  0.0   0:00.06 khelper
   41 root      15  -5     0    0    0 S  0.0  0.0   0:01.08 kblockd/
   67 root      15  -5     0    0    0 S  0.0  0.0   0:00.00 kseriod
  114 root      20   0     0    0    0 S  0.0  0.0   0:01.62 pdflush
  116 root      15  -5     0    0    0 S  0.0  0.0   0:02.44 kswapd0
```

The system summary contains a lot of good stuff. Here's a rundown:

Table 10-3: `top` Information Fields

Row	Field	Meaning
1	`top`	The name of the program.
	`14:59:20`	The current time of day.
	`up 6:30`	This is called *uptime*. It is the amount of time since the machine was last booted. In this example, the system has been up for six-and-a-half hours.

	`2 users`	There are two users logged in.
	`load average:`	*Load average* refers to the number of processes that are waiting to run, that is, the number of processes that are in a runnable state and are sharing the CPU. Three values are shown, each for a different period of time. The first is the average for the last 60 seconds, the next the previous 5 minutes, and finally the previous 15 minutes. Values less than 1.0 indicate that the machine is not busy.
2	`Tasks:`	This summarizes the number of processes and their various process states.
3	`Cpu(s):`	This row describes the character of the activities that the CPU is performing.
	`0.7%us`	0.7 percent of the CPU is being used for *user processes*. This means processes outside the kernel.
	`1.0%sy`	1.0 percent of the CPU is being used for *system* (kernel) processes.
	`0.0%ni`	0.0 percent of the CPU is being used by “nice” (low-priority) processes.
	`98.3%id`	98.3 percent of the CPU is idle.
	`0.0%wa`	0.0 percent of the CPU is waiting for I/O.
4	`Mem:`	This shows how physical RAM is being used.
5	`Swap:`	This shows how swap space (virtual memory) is being used.

The `top` program accepts a number of keyboard commands. The two most interesting are `h`, which displays the program's help screen, and `q`, which quits `top`.

Both major desktop environments provide graphical applications that display information similar to `top` (in much the same way that Task Manager in Windows works), but `top` is better than the graphical versions because it is faster and it consumes far fewer system resources. After all, our system monitor program shouldn't be the source of the system slowdown that we are trying to track.

Controlling Processes

Now that we can see and monitor processes, let's gain some control over them. For our experiments, we're going to use a little program called `xlogo` as our guinea pig. The `xlogo` program is a sample program supplied with the X Window System (the underlying engine that makes the graphics on our display go), which simply displays a re-sizable window containing the X logo. First, we'll get to know our test subject.

```
[me@linuxbox ~]$ xlogo
```

After entering the command, a small window containing the logo should appear somewhere on the screen. On some systems, `xlogo` may print a warning message, but it may be safely ignored.

> **Tip:** If your system does not include the `xlogo` program, try using `gedit` or `kwrite` instead.

We can verify that `xlogo` is running by resizing its window. If the logo is redrawn in the new size, the program is running.

Notice how our shell prompt has not returned? This is because the shell is waiting for the program to finish, just like all the other programs we have used so far. If we close the `xlogo` window, the prompt returns.

Figure 4: The xlogo program

Interrupting a Process

Let's observe what happens when we run `xlogo` again. First, enter the `xlogo` command

and verify that the program is running. Next, return to the terminal window and press `Ctrl-c`.

```
[me@linuxbox ~]$ xlogo
[me@linuxbox ~]$
```

In a terminal, pressing `Ctrl-c`, *interrupts* a program. This means we are politely asking the program to terminate. After we pressed `Ctrl-c`, the `xlogo` window closed and the shell prompt returned.

Many (but not all) command-line programs can be interrupted by using this technique.

Putting a Process in the Background

Let's say we wanted to get the shell prompt back without terminating the `xlogo` program. We can do this by placing the program in the *background*. Think of the terminal as having a *foreground* (with stuff visible on the surface like the shell prompt) and a background (with stuff hidden behind the surface). To launch a program so that it is immediately placed in the background, we follow the command with an ampersand (&) character.

```
[me@linuxbox ~]$ xlogo &
[1] 28236
[me@linuxbox ~]$
```

After entering the command, the `xlogo` window appeared and the shell prompt returned, but some funny numbers were printed too. This message is part of a shell feature called *job control*. With this message, the shell is telling us that we have started job number 1 (`[1]`) and that it has PID 28236. If we run `ps`, we can see our process.

```
[me@linuxbox ~]$ ps
 PID TTY          TIME CMD
10603 pts/1    00:00:00 bash
28236 pts/1    00:00:00 xlogo
28239 pts/1    00:00:00 ps
```

The shell's job control facility also gives us a way to list the jobs that have been launched from our terminal. Using the `jobs` command, we can see this list:

```
[me@linuxbox ~]$ jobs
[1]+  Running                 xlogo &
```

The results show that we have one job, numbered 1, that it is running, and that the command was `xlogo &`.

Returning a Process to the Foreground

A process in the background is immune from terminal keyboard input, including any attempt to interrupt it with `Ctrl-c`. To return a process to the foreground, use the `fg` command in this way:

```
[me@linuxbox ~]$ jobs
[1]+  Running                 xlogo &
[me@linuxbox ~]$ fg %1
xlogo
```

The `fg` command followed by a percent sign and the job number (called a *jobspec*) does the trick. If we only have one background job, the jobspec is optional. To terminate `xlogo`, press `Ctrl-c`.

Stopping (Pausing) a Process

Sometimes we'll want to stop a process without terminating it. This is often done to allow a foreground process to be moved to the background. To stop a foreground process and place it in the background, press `Ctrl-z`. Let's try it. At the command prompt, type `xlogo`, press the `Enter` key, and then press `Ctrl-z`:

```
[me@linuxbox ~]$ xlogo
[1]+  Stopped                 xlogo
[me@linuxbox ~]$
```

After stopping `xlogo`, we can verify that the program has stopped by attempting to resize the `xlogo` window. We will see that it appears quite dead. We can either continue the program's execution in the foreground, using the `fg` command, or resume the program's execution in the background with the `bg` command:

```
[me@linuxbox ~]$ bg %1
```

```
[1]+ xlogo &
[me@linuxbox ~]$
```

As with the `fg` command, the jobspec is optional if there is only one job.

Moving a process from the foreground to the background is handy if we launch a graphical program from the command line, but forget to place it in the background by appending the trailing `&`.

Why would we want to launch a graphical program from the command line? There are two reasons.

- The program we want to run might not be listed on the window manager's menus (such as `xlogo`).
- By launching a program from the command line, we might be able to see error messages that would otherwise be invisible if the program were launched graphically. Sometimes, a program will fail to start up when launched from the graphical menu. By launching it from the command line instead, we may see an error message that will reveal the problem. Also, some graphical programs have interesting and useful command line options.

Signals

The `kill` command is used to "kill" processes. This allows us to terminate programs that need killing (that is, some kind of pausing or termination). Here's an example:

```
[me@linuxbox ~]$ xlogo &
[1] 28401
[me@linuxbox ~]$ kill 28401
[1]+  Terminated              xlogo
```

We first launch `xlogo` in the background. The shell prints the jobspec and the PID of the background process. Next, we use the `kill` command and specify the PID of the process we want to terminate. We could have also specified the process using a jobspec (for example, `%1`) instead of a PID.

While this is all very straightforward, there is more to it than that. The `kill` command doesn't exactly "kill" processes: rather it sends them *signals*. Signals are one of several ways that the operating system communicates with programs. We have already seen signals in action with the use of `Ctrl-c` and `Ctrl-z`. When the terminal receives one of these keystrokes, it sends a signal to the program in the foreground. In the case of `Ctrl-c`, a signal called `INT` (interrupt) is sent; with `Ctrl-z`, a signal called `TSTP` (terminal

stop) is sent. Programs, in turn, “listen” for signals and may act upon them as they are received. The fact that a program can listen and act upon signals allows a program to do things such as save work in progress when it is sent a termination signal.

Sending Signals to Processes with `kill`

The `kill` command is used to send signals to programs. Its most common syntax looks like this:

```
kill [-signal] PID...
```

If no signal is specified on the command line, then the `TERM` (terminate) signal is sent by default. The `kill` command is most often used to send the following signals:

Table 10-4: Common Signals

Number	Name	Meaning
1	HUP	Hangup. This is a vestige of the good old days when terminals were attached to remote computers with phone lines and modems. The signal is used to indicate to programs that the controlling terminal has “hung up.” The effect of this signal can be demonstrated by closing a terminal session. The foreground program running on the terminal will be sent the signal and will terminate. This signal is also used by many daemon programs to cause a reinitialization. This means that when a daemon is sent this signal, it will restart and reread its configuration file. The Apache web server is an example of a daemon that uses the `HUP` signal in this way.
2	INT	Interrupt. This performs the same function as a `Ctrl-c` sent from the terminal. It will usually terminate a program.
9	KILL	Kill. This signal is special. Whereas programs may choose to handle signals sent to them in different ways, including ignoring them all together, the `KILL` signal is never actually sent to

		the target program. Rather, the kernel immediately terminates the process. When a process is terminated in this manner, it is given no opportunity to "clean up" after itself or save its work. For this reason, the KILL signal should be used only as a last resort when other termination signals fail.
15	TERM	Terminate. This is the default signal sent by the kill command. If a program is still "alive" enough to receive signals, it will terminate.
18	CONT	Continue. This will restore a process after a STOP or TSTP signal. This signal is sent by the bg and fg commands.
19	STOP	Stop. This signal causes a process to pause without terminating. Like the KILL signal, it is not sent to the target process, and thus it cannot be ignored.
20	TSTP	Terminal stop. This is the signal sent by the terminal when Ctrl-z is pressed. Unlike the STOP signal, the TSTP signal is received by the program, but the program may choose to ignore it.

Let's try out the kill command:

```
[me@linuxbox ~]$ xlogo &
[1] 13546
[me@linuxbox ~]$ kill -1 13546
[1]+  Hangup                  xlogo
```

In this example, we start the xlogo program in the background and then send it a HUP signal with kill. The xlogo program terminates, and the shell indicates that the background process has received a hangup signal. We may need to press the Enter key a couple of times before the message appears. Note that signals may be specified either by number or by name, including the name prefixed with the letters SIG.

```
[me@linuxbox ~]$ xlogo &
```

```
[1] 13601
[me@linuxbox ~]$ kill -INT 13601
[1]+  Interrupt               xlogo
[me@linuxbox ~]$ xlogo &
[1] 13608
[me@linuxbox ~]$ kill -SIGINT 13608
[1]+  Interrupt               xlogo
```

Repeat the example above and try the other signals. Remember, we can also use jobspecs in place of PIDs.

Processes, like files, have owners, and you must be the owner of a process (or the superuser) to send it signals with `kill`.

In addition to the list of signals above, which are most often used with `kill`, there are other signals frequently used by the system as listed in Table 10-5.

Table 10-5: Other Common Signals

Number	Name	Meaning
3	QUIT	Quit.
11	SEGV	Segmentation violation. This signal is sent if a program makes illegal use of memory, that is, if it tried to write somewhere it was not allowed to write.
28	WINCH	Window change. This is the signal sent by the system when a window changes size. Some programs , such as `top` and `less` will respond to this signal by redrawing themselves to fit the new window dimensions.

For the curious, a complete list of signals can be displayed with the following command:

```
[me@linuxbox ~]$ kill -l
```

Sending Signals to Multiple Processes with `killall`

It's also possible to send signals to multiple processes matching a specified program or username by using the `killall` command. Here is the syntax:

```
killall [-u user] [-signal] name...
```

To demonstrate, we will start a couple of instances of the `xlogo` program and then terminate them.

```
[me@linuxbox ~]$ xlogo &
[1] 18801
[me@linuxbox ~]$ xlogo &
[2] 18802
[me@linuxbox ~]$ killall xlogo
[1]-  Terminated              xlogo
[2]+  Terminated              xlogo
```

Remember, as with `kill`, we must have superuser privileges to send signals to processes that do not belong to us.

Shutting Down the System

The process of shutting down the system involves the orderly termination of all the processes on the system, as well as performing some vital housekeeping chores (such as syncing all of the mounted file systems) before the system powers off. There are four commands that can perform this function. They are `halt`, `poweroff`, `reboot`, and `shutdown`. The first three are pretty self-explanatory and are generally used without any command line options. Here's an example:

```
[me@linuxbox ~]$ sudo reboot
```

The `shutdown` command is a bit more interesting. With it, we can specify which of the actions to perform (halt, power down, or reboot) and provide a time delay to the shutdown event. Most often it is used like this to halt the system:

```
[me@linuxbox ~]$ sudo shutdown -h now
```

or like this to reboot the system:

```
[me@linuxbox ~]$ sudo shutdown -r now
```

The delay can be specified in a variety of ways. See the `shutdown` man page for details. Once the `shutdown` command is executed, a message is "broadcast" to all logged-in users warning them of the impending event.

More Process-Related Commands

Since monitoring processes is an important system administration task, there are a lot of commands for it. Table 10-6 lists some to play with:

Table 10-6: Other Process Related Commands

Command	Description
`pstree`	Outputs a process list arranged in a tree-like pattern showing the parent-child relationships between processes.
`vmstat`	Outputs a snapshot of system resource usage including, memory, swap, and disk I/O. To see a continuous display, follow the command with a time delay (in seconds) for updates. Here's an example: `vmstat 5`. Terminate the output with `Ctrl-c`.
`xload`	A graphical program that draws a graph showing system load over time.
`tload`	Similar to the `xload` program but draws the graph in the terminal. Terminate the output with `Ctrl-c`.

Summing Up

Most modern systems feature a mechanism for managing multiple processes. Linux provides a rich set of tools for this purpose. Given that Linux is the world's most deployed server operating system, this makes a lot of sense. However, unlike some other systems, Linux relies primarily on command line tools for process management. Though there are graphical process tools for Linux, the command line tools are greatly preferred because of their speed and light footprint. While the GUI tools may look pretty, they often create a lot of system load themselves, which somewhat defeats the purpose.