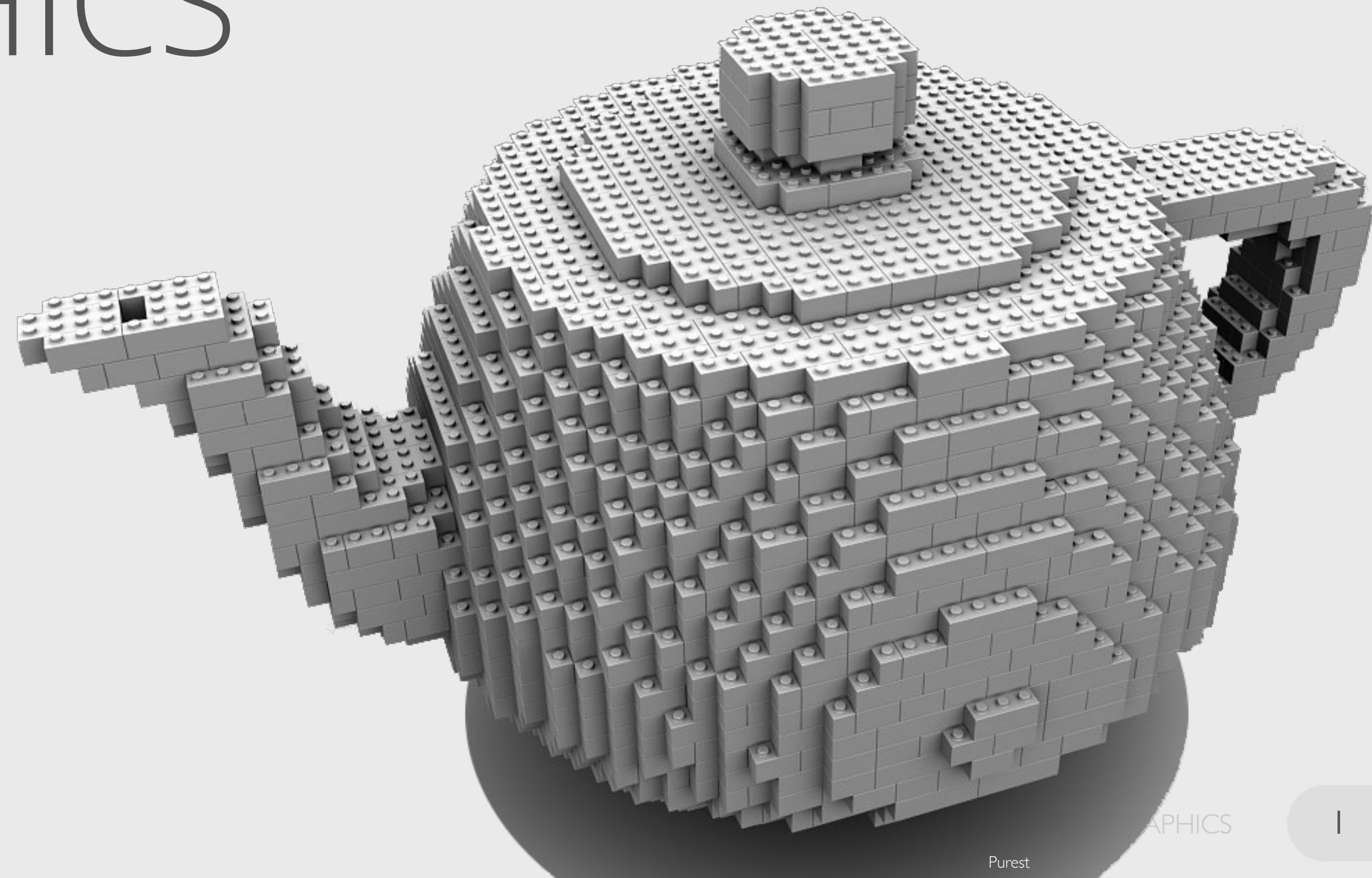


MULTIMEDIA & COMPUTER GRAPHICS

Dr. Arturo Jafet Rodríguez Muñoz

Ing. Bernardo Moya de la Mora

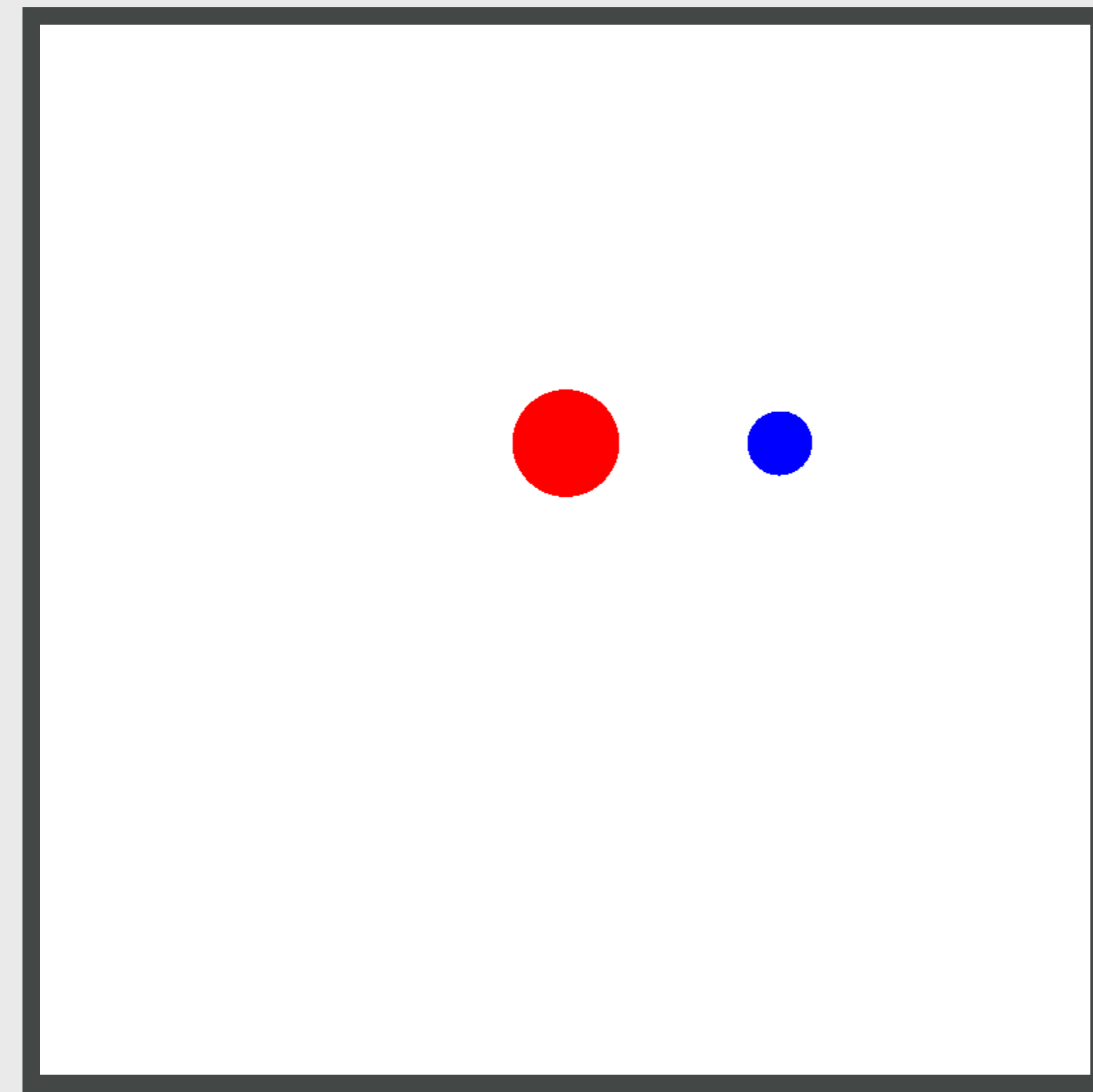
RAY TRACING



RAYTRACER v0.1

Objective:

Render flat spheres

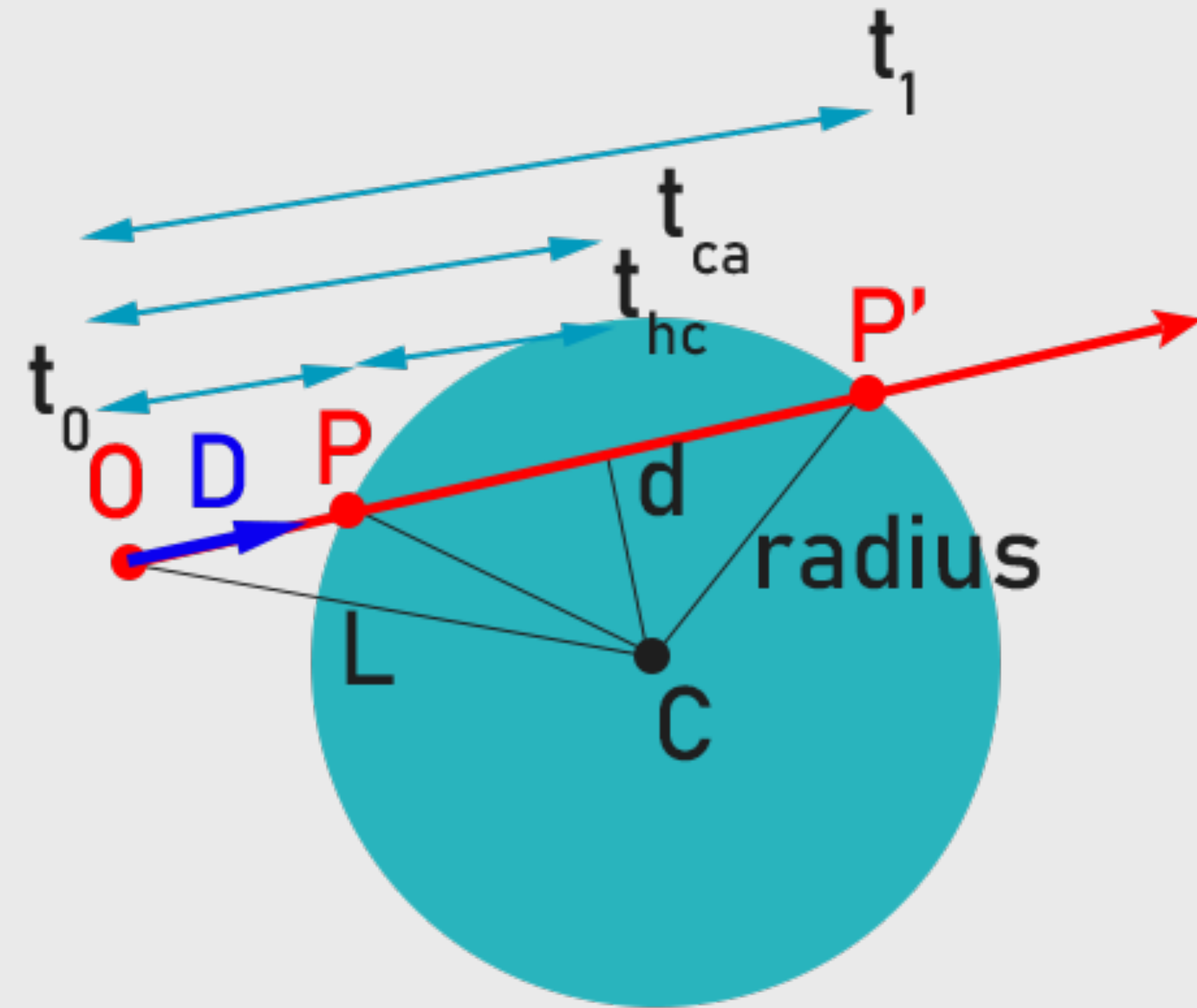


RAYTRACER v0.1

Intersection ray – sphere

Analytic solution

Geometric solution



ANALYTIC SOLUTION

Ray equation

$$O + tD = \text{Point}$$

Origin of the ray

Direction of the ray

Distance

Sphere equation

$$x^2 + y^2 + z^2 = R^2$$

Point in position x, y, z

Radius



ANALYTIC SOLUTION

$$[1] O + tD \quad [2] x^2 + y^2 + z^2 = R^2$$

$$P^2 - R^2 = 0$$

$$|O + tD|^2 - R^2 = 0 \quad [3] O^2 + (tD)^2 + 2OtD - R^2 = O^2 + t^2D^2 + 2OtD - R^2 = 0$$

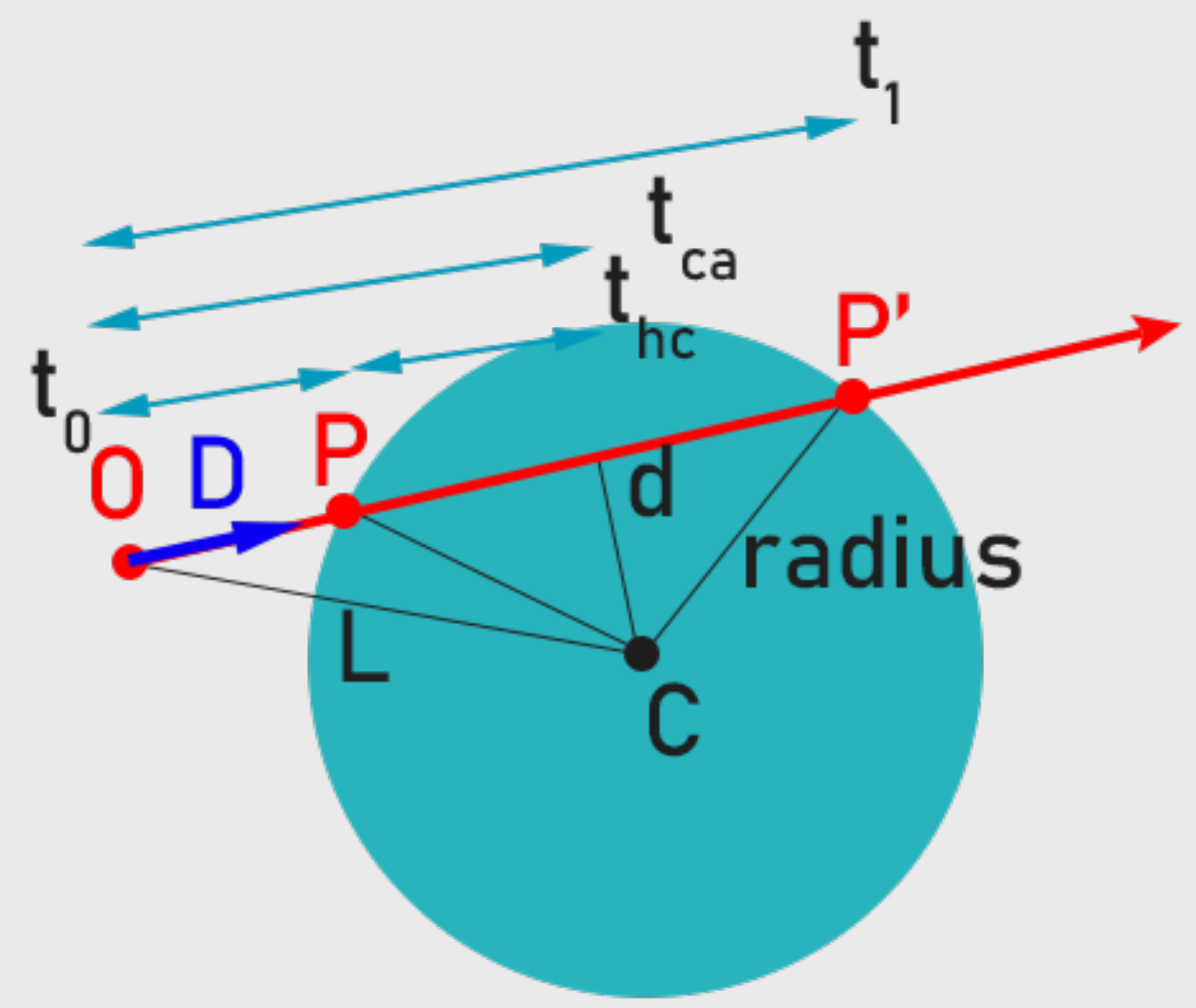
Which follow the form of $f(x) = ax^2 + bx + c$

$$a = D^2 \quad b = 2OD \quad c = O^2 - R^2 \quad \text{which is solved by } x = (-b \pm \sqrt{b^2 - 4ac}) / 2a$$



$$\Delta = b^2 - 4ac \quad \text{if } (\Delta > 0): 2 \text{ points} \quad \text{if } (\Delta == 0): 1 \text{ point} \quad \text{if } (\Delta < 0): \text{no points}$$

GEOMETRIC SOLUTION



GEOMETRIC SOLUTION

Equation

$$O + t_0 D = \text{Point}_0$$

$$O + t_1 D = \text{Point}_1$$

Origin of the ray

Direction of the ray

Distance

Center of the Sphere

$$L = C - O$$

$$t_{ca} = L \cdot D$$

if($t_{ca} < 0$) no collision

$$d^2 + t_{ca}^2 = L^2$$

$$d = \sqrt{L^2 - t_{ca}^2} = \sqrt{L \cdot L - t_{ca} \cdot t_{ca}}$$

if($d < 0$) no collision



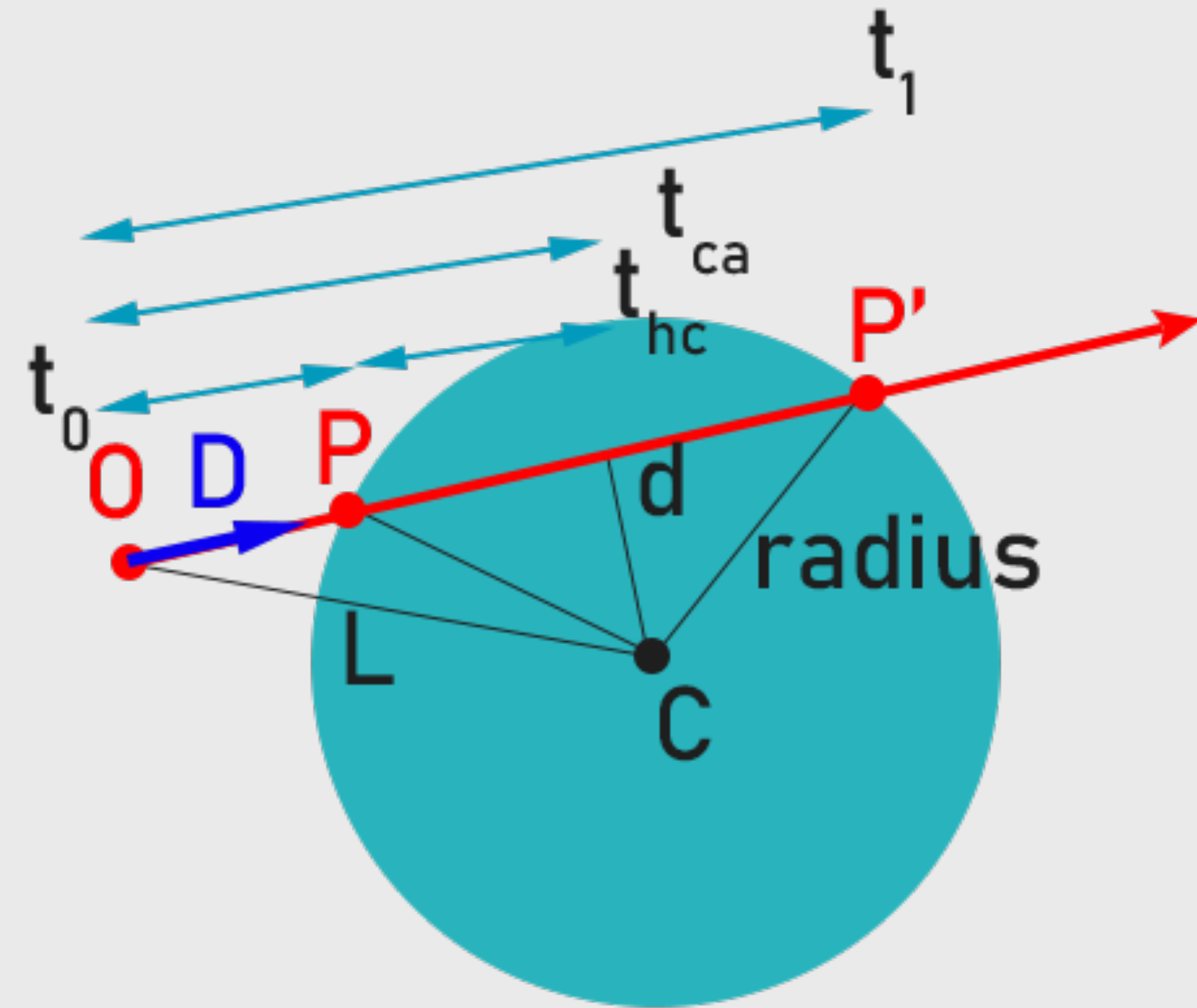
GEOMETRIC SOLUTION

$$d^2 + t_{hc}^2 = \text{radius}^2$$

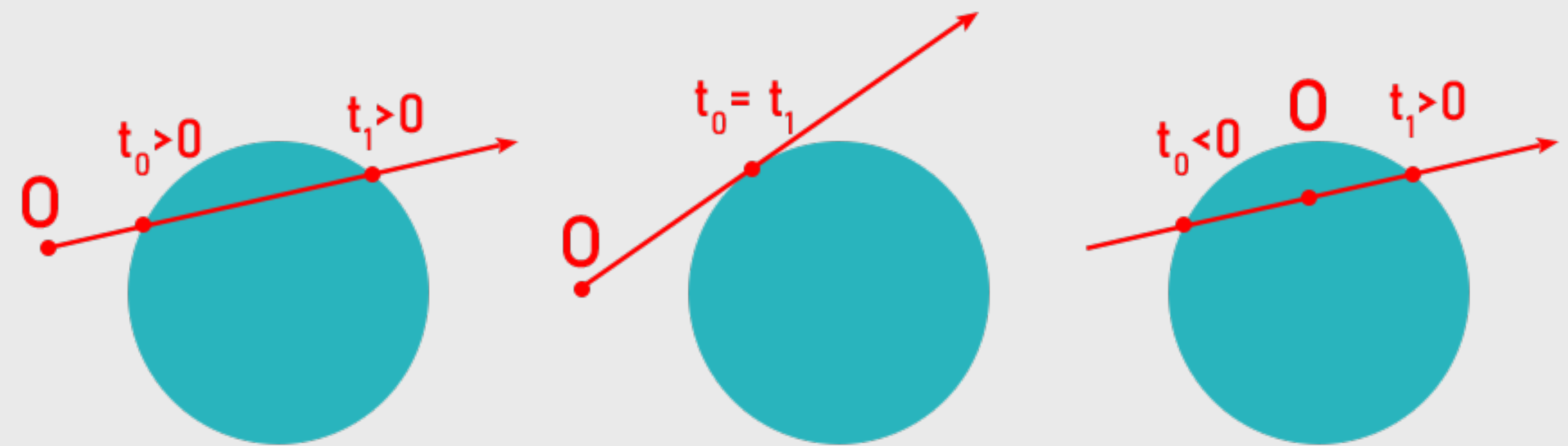
$$t_{hc} = \sqrt{\text{radius}^2 - d^2}$$

$$t_0 = t_{ca} - t_{hc}$$

$$t_1 = t_{ca} + t_{hc}$$

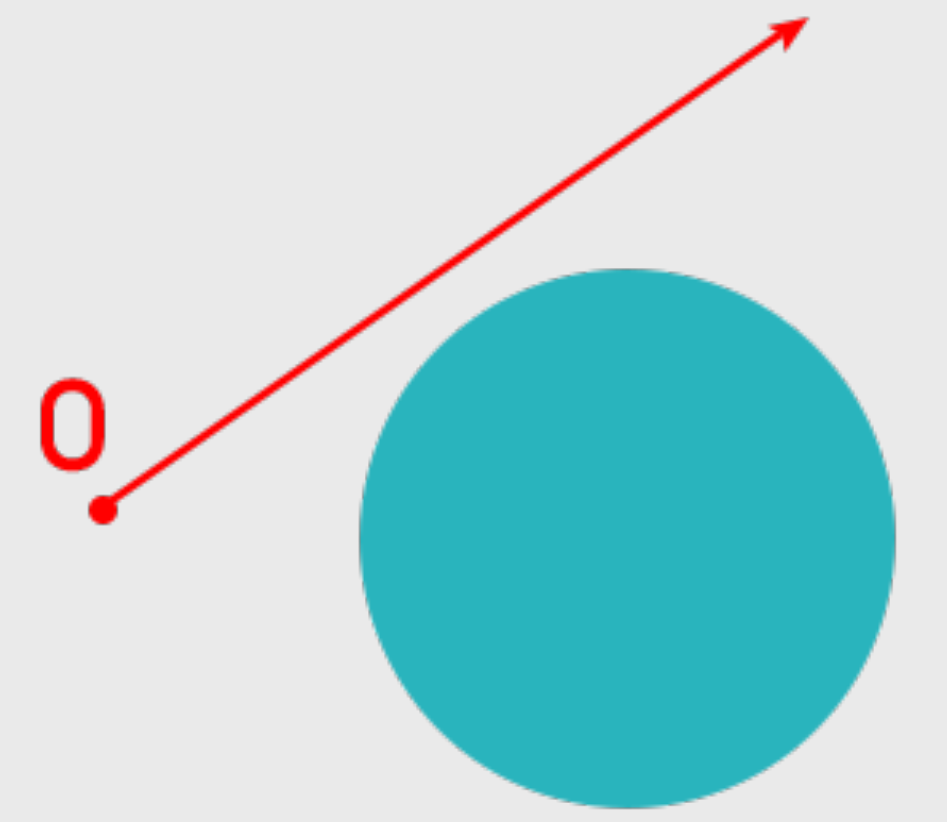


SOLUTION

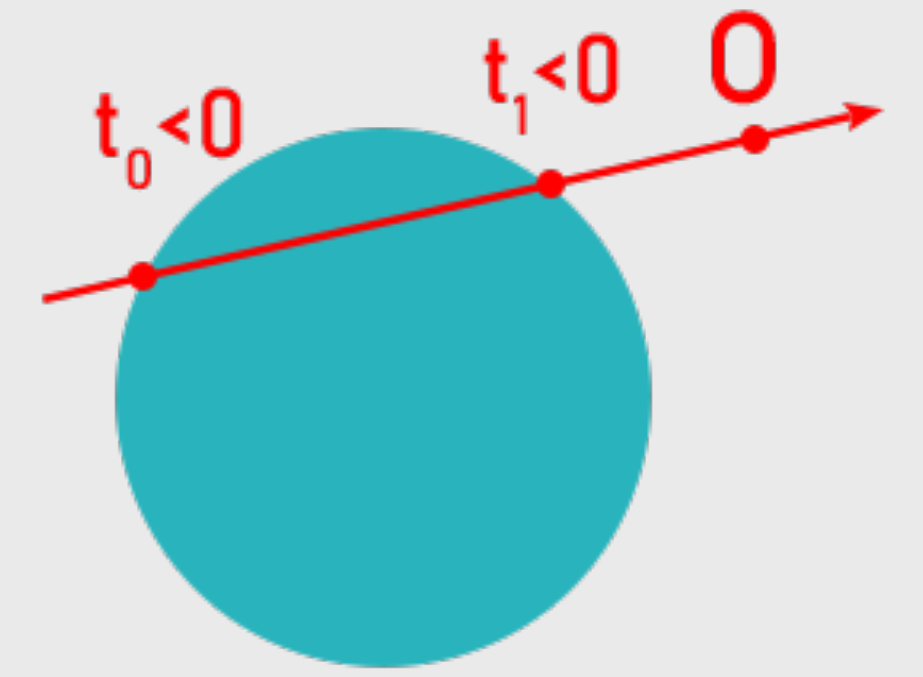


Collision in front is positive t

Collision behind is negative t



No intersection



RAYTRACER v0.1

Classes required:

Vector3D

Intersection

Ray

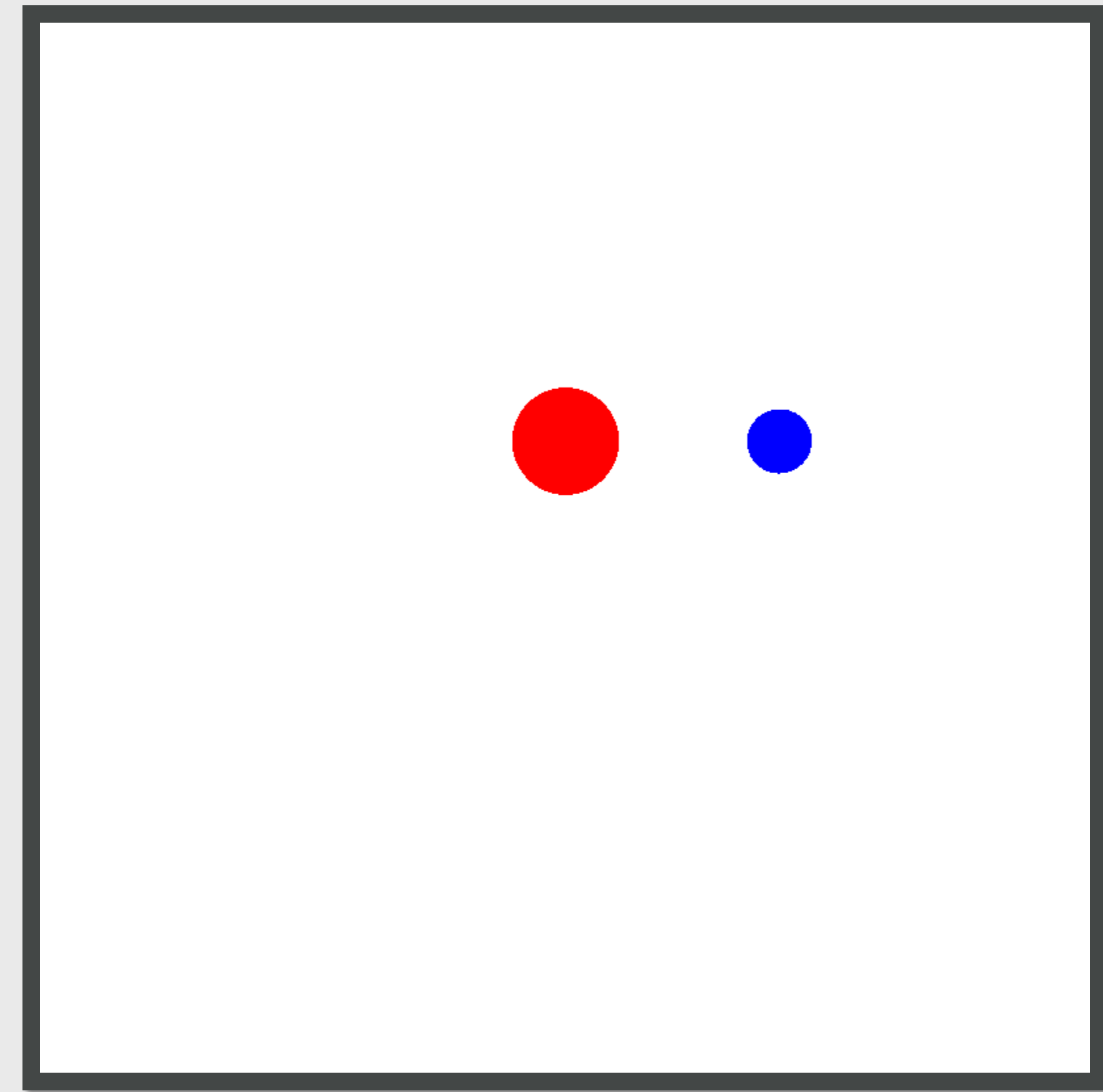
Object3D

Camera

Sphere

Scene

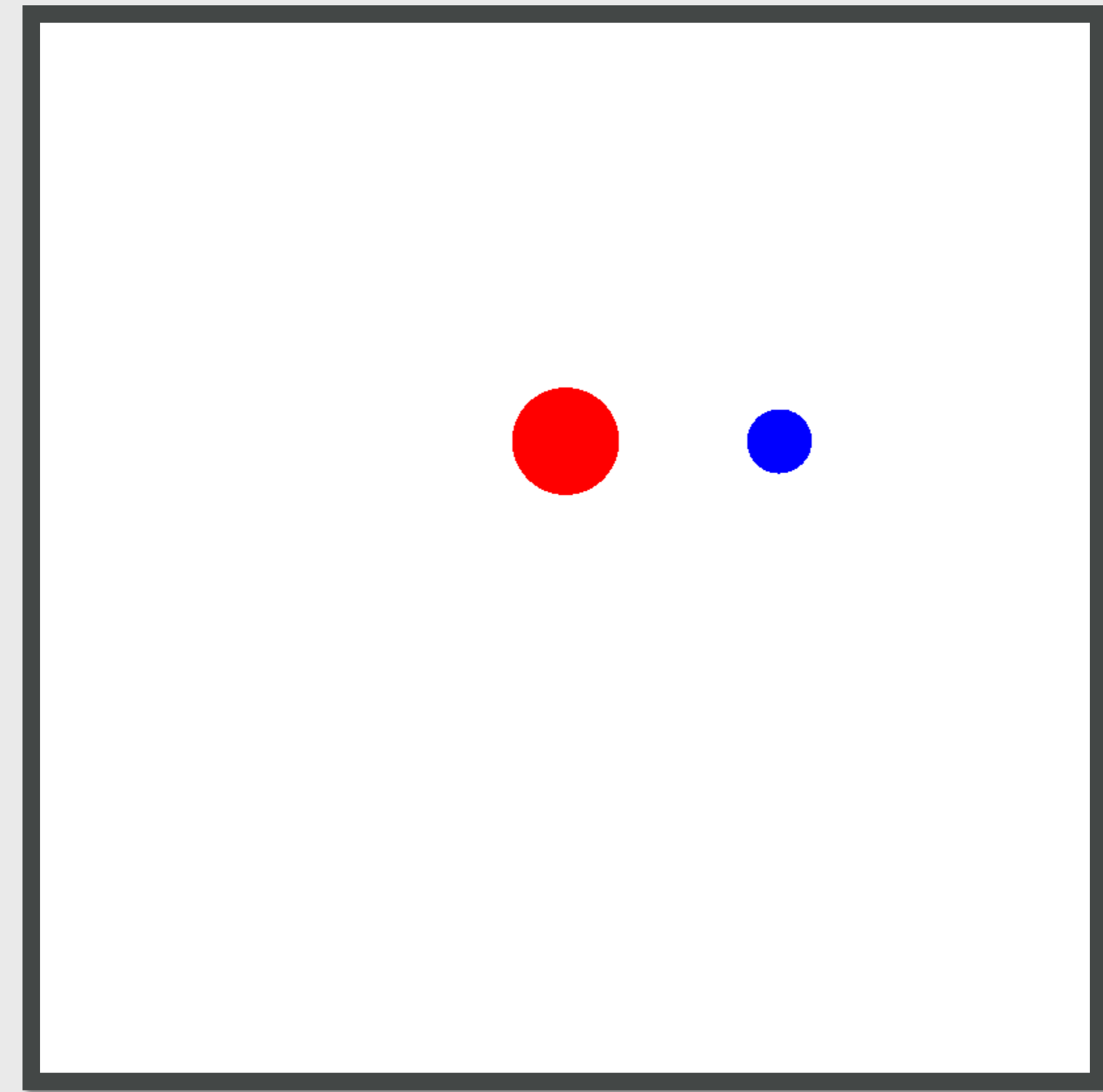
Raytracer



HW

Objective:

Render flat spheres



REFLECTION

