

MATB44 Week 3 Notes

1. Existence and Uniqueness Theorem:

- Note: We won't be tested on this.

- Let $y' = f(t, y)$ where $f = t^2 + y^2$

Lets take some arbitrary values for t and y and find f .

E.g.

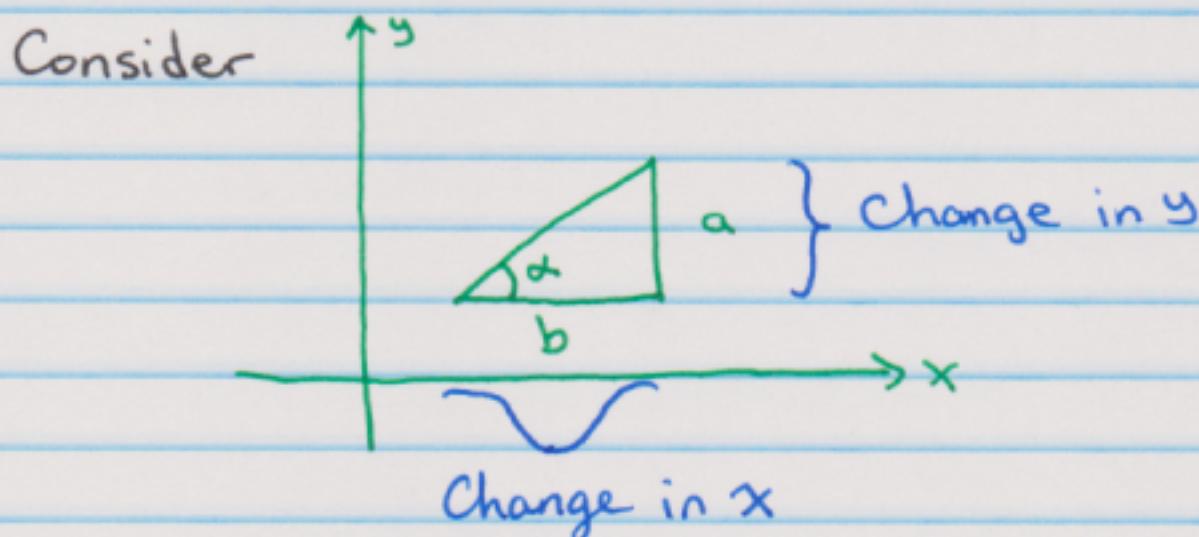
$$f(1, 1) = 2$$

$$= \tan \alpha_{(1, 1)}$$

$$f(1, 2) = 5$$

$$= \tan \alpha_{(1, 2)}$$

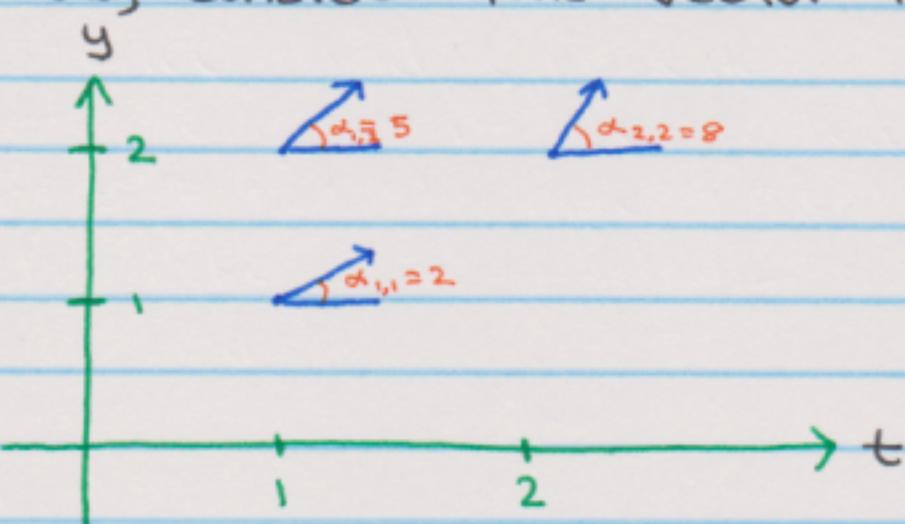
Recall: The derivative of a function is the slope of that function. Once we start talking about slopes, we start talking about tangent. This is because
Slope = Change in Y and $\tan \alpha = \frac{\text{Change in } Y}{\text{Change in } x}$



$$\tan \alpha = \frac{a}{b}$$

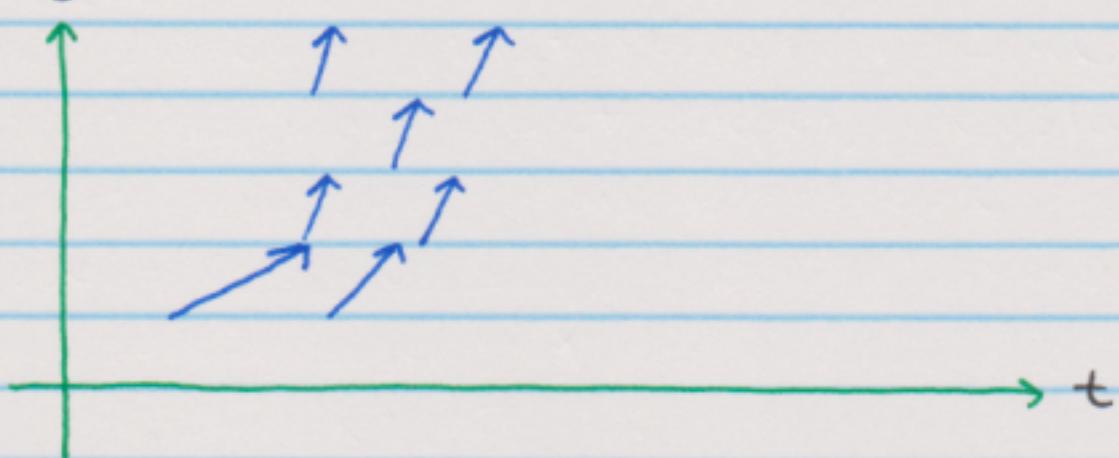
$$= \frac{\text{Change in } Y}{\text{Change in } x}$$

Now, consider this vector field



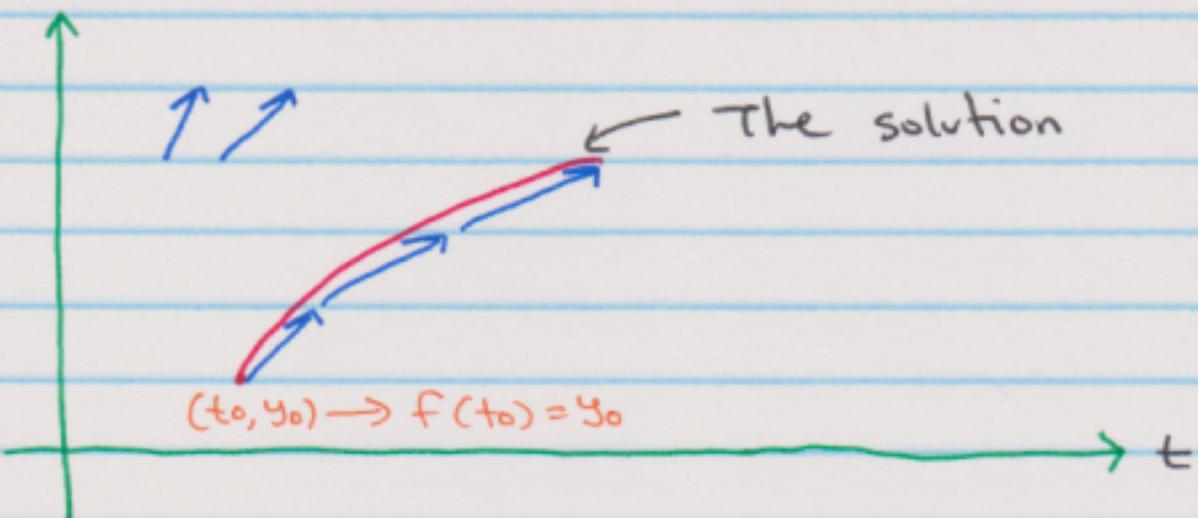
In a vector field, at each point, there is a unit vector attached to it.

E.g.



The solution is given based on the vector field.

E.g.

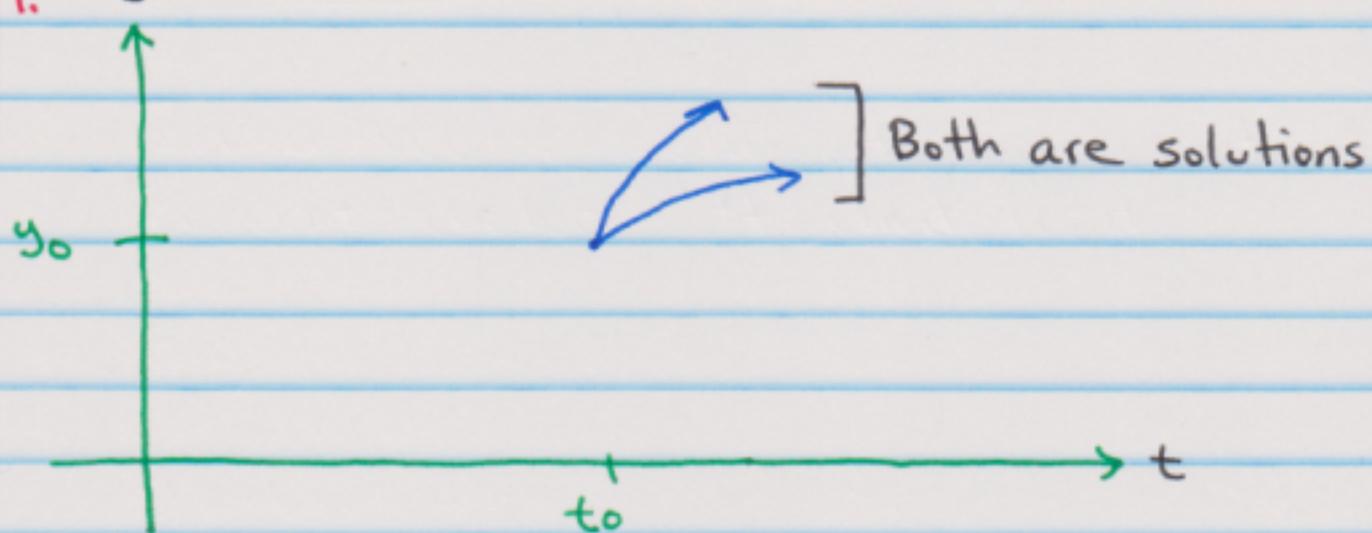


- Existence and Uniqueness Theorem:

Given an eqn $y' = f(t, y)$ with the initial condition $y(t_0) = y_0$, we can find an unique soln defined for some interval $t_0 < t < t_1$.

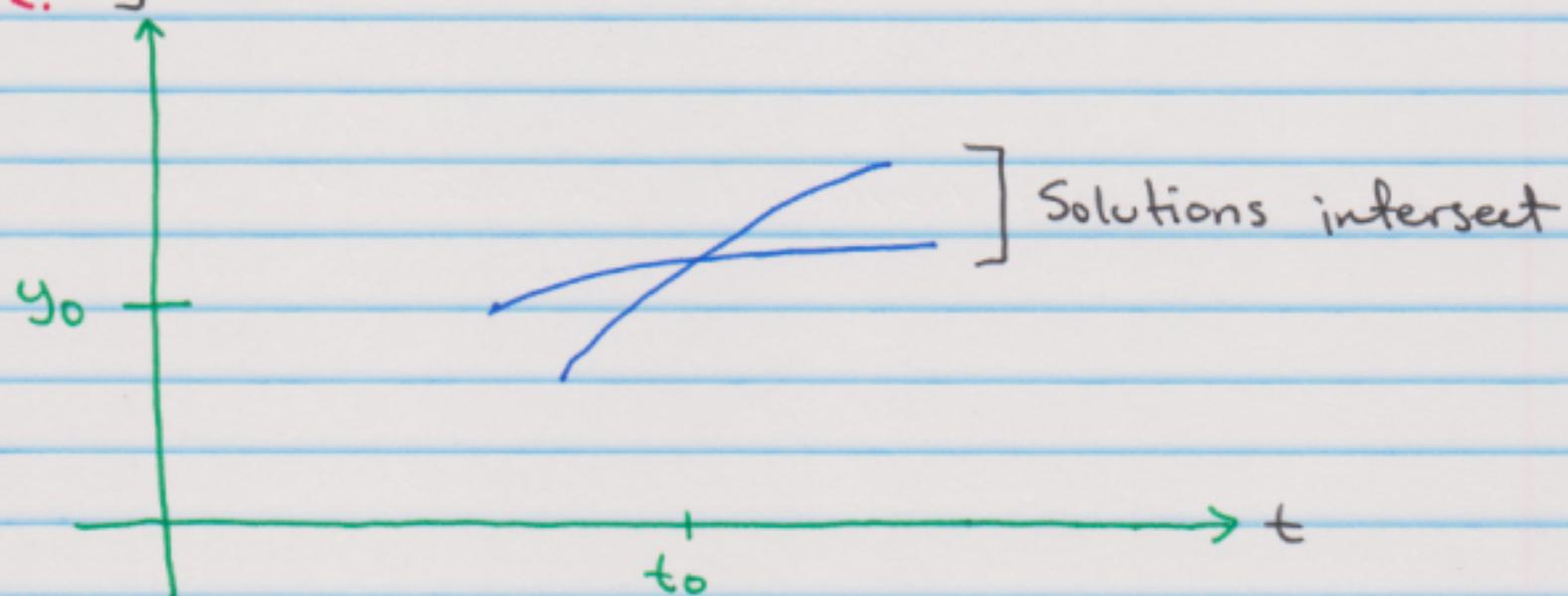
I.e. The following two things never happen.

1. y



Both are solutions

2. y



Solutions intersect

This can't happen because the solns are parallel. Furthermore, if they did intersect, that means that there would be 2 slopes at one point.

Consider the question $y' = y^2$, $y(0) = 1$

$$\frac{dy}{dt} = y^2$$

$$\frac{1}{y^2} dy = 1 dt$$

$$\int \frac{1}{y^2} dy = \int 1 dt$$

$$-\frac{1}{y} = t + c$$

$$y = \frac{-1}{t+c}$$

Plug in 0 for t and 1 for y .

$$1 = \frac{-1}{0+c}$$

$$c = -1$$

$$y = \frac{-1}{t-1}$$

$$= \frac{1}{1-t}$$

Now, we know $t_0 = 0$, but how far can it go?

$t_0 = 0 \rightarrow$ up to $t = 1$. At $t = 1$ there's a problem.

The denominator is 0. The soln escapes to infinity. Hence, the soln is only good for $0 \leq t < 1$. After $t = 1$, the soln changes.

Hence, solns are defined for some interval $t_0 < t < t_1$.

2. Homogeneous Equations With Constant Coefficients:

a) Introduction:

- Many second order differential equations have the form $\frac{d^2y}{dt^2} = f(t, y, \frac{dy}{dt})$.

We say that the above eqn is **linear** if f has the form $f(t, y, \frac{dy}{dt}) = g(t) - p(t)\frac{dy}{dt} - q(t)y$.

In this case, we can rewrite the first eqn as $y'' + p(t)y' + q(t)y = g(t)$.

We may also see the eqn in this form

$$P(t)y'' + Q(t)y' + R(t)y = G(t).$$

If $P(t) \neq 0$, then we can get $y'' + p(t)y' + q(t)y = g(t)$ from $P(t)y'' + Q(t)y' + R(t)y = G(t)$ by dividing the latter eqn by $P(t)$.

i.e.

$$p(t) = \frac{Q(t)}{P(t)}, \quad q(t) = \frac{R(t)}{P(t)}, \quad g(t) = \frac{G(t)}{P(t)}$$

If the eqn is not of the form

$y'' + p(t)y' + q(t)y = g(t)$ or $P(t)y'' + Q(t)y' + R(t)y = G(t)$ then it is **non-linear**.

- A second order linear differential eqn is **homogeneous** if $g(t)$ or $G(t)$ or RHS is 0. Otherwise, the eqn is **non homogeneous**.

b) Solving Homogeneous Eqns with Constant Coefficients

Rule 1: Homogeneous eqns always have a soln of this form $y = e^{rt}$ where r is an unknown constant and t is an unknown function.

Rule 2: We can combine the solns to get a new soln.

c) Solving Homogeneous Eqns with Constant Coefficients and 2 Real Distinct Roots
 E.g. 1 Solve $y'' - y = 0$, $y(0) = 2$ and $y'(0) = -1$

Soln:

$$y = e^{rt}$$

$$y' = re^{rt}$$

$$y'' = r^2 e^{rt}$$

} Applying rule 1

$$r^2 e^{rt} - e^{rt} = 0$$

$$e^{rt}(r^2 - 1) = 0$$

$$r^2 - 1 = 0$$

$$r^2 = 1$$

$$r = \pm 1$$

$$y_1 = e^t, y_2 = e^{-t}$$

$$y = C_1 e^t + C_2 e^{-t} \leftarrow \text{Applying rule 2}$$

Note: C_1 and C_2 are arbitrary constants.

There are 2 constants because it's a 2nd order diff eqn.

7

Now, we'll solve for C_1 and C_2 .

$$y(0) = 2 \rightarrow 2 = C_1 e^0 + C_2 e^{-0} \\ = C_1 + C_2$$

$$y'(0) = -1 \rightarrow y' = (C_1 e^t + C_2 e^{-t})' \\ = C_1 e^t - C_2 e^{-t} \\ -1 = C_1 e^0 - C_2 e^{-0} \\ = C_1 - C_2$$

$$2 = C_1 + C_2$$

$$-1 = C_1 - C_2$$

$$C_1 = \frac{1}{2}, C_2 = \frac{3}{2}$$

$$\therefore y = \frac{e^t}{2} + \frac{3e^{-t}}{2}$$

- From example 1, we can come to this conclusion:
 $ay'' + by' + cy = 0 \rightarrow (ar^2 + br + c)e^{rt} = 0$
 Since $e^{rt} \neq 0$,
 $ar^2 + br + c = 0$.

Note: $ar^2 + br + c = 0$ is called the characteristic equation.

Assuming that $r_1 \neq r_2$, $y_1 = e^{r_1 t}$ and $y_2 = e^{r_2 t}$
 and $y = C_1 \cdot e^{r_1 t} + C_2 \cdot e^{r_2 t}$.

E.g. 2 Solve $y'' + 5y' + 6y = 0$

Soln:

$$\begin{aligned} r^2 + 5r + 6 &= 0 \\ r &= \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} \\ &= \frac{-5 \pm \sqrt{25 - 24}}{2} \\ &= \frac{-5 \pm 1}{2} \\ &= -2 \text{ or } -3 \end{aligned}$$

Aside: Consider $b^2 - 4ac$.

It has 3 possible values:

a) > 0 , b) $= 0$, c) < 0 .

For this section, $b^2 - 4ac > 0$.

This means that there will be 2 distinct, real roots.

$$y_1 = e^{-2t}, y_2 = e^{-3t}$$

$$y = C_1 e^{-2t} + C_2 e^{-3t} \leftarrow \text{General Solution}$$

E.g. 3 Solve $y'' + 5y' + 6y = 0$, $y(0) = 2$, $y'(0) = 3$

Soln:

We know from above that $y = C_1 e^{-2t} + C_2 e^{-3t}$

$$y(0) = 2 \rightarrow 2 = C_1 + C_2$$

$$y'(0) = 3 \rightarrow y' = -2C_1 e^{-2t} - 3C_2 e^{-3t}$$

$$3 = -2C_1 - 3C_2$$

$$C_1 + C_2 = 2$$

$$-2C_1 - 3C_2 = 3$$

$$C_1 = 9 \text{ and } C_2 = -7$$

$$y = 9e^{-2t} - 7e^{-3t}$$

E.g. 4 Solve $4y'' - 8y' + 3y = 0$, $y(0) = 2$,
 $y'(0) = \frac{1}{2}$

Soln:

$$4r^2 - 8r + 3 = 0$$

$$\begin{aligned} r &= \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} \\ &= \frac{8 \pm \sqrt{64 - 48}}{8} \\ &= \frac{8 \pm \sqrt{16}}{8} \\ &= \frac{8 \pm 4}{8} \\ &= \frac{3}{2} \text{ or } \frac{1}{2} \end{aligned}$$

$$\begin{aligned} y_1 &= e^{\frac{1}{2}t}, \quad y_2 = e^{\frac{3}{2}t} \\ y &= C_1 \cdot e^{\frac{t}{2}} + C_2 \cdot e^{\frac{3t}{2}} \end{aligned}$$

$$y(0) = 2 \rightarrow 2 = C_1 + C_2$$

$$\begin{aligned} y'(0) = \frac{1}{2} \rightarrow y' &= \frac{C_1}{2} \cdot e^{\frac{t}{2}} + \frac{3C_2}{2} \cdot e^{\frac{3t}{2}} \\ \frac{1}{2} &= \frac{C_1}{2} + \frac{3C_2}{2} \\ 1 &= C_1 + 3C_2 \end{aligned}$$

$$\left. \begin{array}{l} C_1 + C_2 = 2 \\ C_1 + 3C_2 = 1 \end{array} \right\} \quad \begin{array}{l} C_1 = \frac{5}{2} \\ C_2 = -\frac{1}{2} \end{array}$$

$$y = \frac{5}{2} e^{\frac{t}{2}} - \frac{1}{2} e^{\frac{3t}{2}}$$

E.g. 5 Solve $y'' + 2y' - 3y = 0$

Soln:

$$\begin{aligned} r^2 + 2r - 3 &= 0 \\ r &= \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} \\ &= \frac{-2 \pm \sqrt{4 - (-12)}}{2} \\ &= \frac{-2 \pm 4}{2} \\ &= 1 \text{ or } -3 \end{aligned}$$

$$\begin{aligned} y_1 &= e^t, \quad y_2 = e^{-3t} \\ y &= C_1 \cdot e^t + C_2 \cdot e^{-3t} \end{aligned}$$

E.g. 6 Solve $y'' + 3y' + 2y = 0$

Soln:

$$\begin{aligned} r^2 + 3r + 2 &= 0 \\ (r+2)(r+1) &= 0 \\ r &= -2 \text{ or } -1 \\ y_1 &= e^{-2t}, \quad y_2 = e^{-t} \\ y &= C_1 \cdot e^{-2t} + C_2 \cdot e^{-t} \end{aligned}$$

E.g. 7 Solve $y'' + 3y' - 10y = 0, \quad y(0) = 4, \quad y'(0) = -2$

Soln:

$$\begin{aligned} r^2 + 3r - 10 &= 0 \quad \Rightarrow \quad y_1 = e^{2t}, \quad y_2 = e^{-5t} \\ (r-2)(r+5) &= 0 \\ r &= 2 \text{ or } -5 \end{aligned}$$

$$y(0) = 4 \rightarrow 4 = C_1 + C_2$$

$$y'(0) = -2 \rightarrow y' = 2C_1 \cdot e^{2t} - 5C_2 \cdot e^{-5t}$$

$$-2 = 2C_1 - 5C_2$$

$$\begin{aligned} C_1 + C_2 &= 4 \\ 2C_1 - 5C_2 &= -2 \end{aligned} \quad \left\} \quad \begin{aligned} C_1 &= \frac{18}{7}, \\ C_2 &= \frac{10}{7} \end{aligned}$$

$$y = \frac{18}{7} \cdot e^{2t} + \frac{10}{7} \cdot e^{-5t}$$

d) Solving Homogeneous Eqns with Constant Coefficients and Complex Roots

- So far, we have been dealing with eqns s.t. $b^2 - 4ac > 0$. Now, we will look at what happens if $b^2 - 4ac < 0$.

- If $b^2 - 4ac < 0$, then

$r_1 = \lambda + i\mu$, $r_2 = \lambda - i\mu$ where λ and μ are real numbers.

$$\text{Furthermore, } y_1 = e^{r_1 t} = e^{(\lambda + i\mu)t} \quad y_2 = e^{r_2 t} = e^{(\lambda - i\mu)t}$$

i.e. If $\lambda = -1$, $\mu = 2$ and $t = 3$, then

$$y_1 = e^{(-1+2i)(3)} = e^{-3+6i}, \quad y_2 = e^{(-1-2i)(3)} = e^{-3-6i}$$

- Euler's Formula: $e^{it} = \cos(t) + i\sin(t)$

Note: If t is replaced with $-t$, we get

$$e^{-it} = \cos(t) - i\sin(t).$$

Note: If t is replaced with μt , we get

$$e^{i\mu t} = \cos(\mu t) - i\sin(\mu t).$$

- With Euler's Formula in mind,

$$\begin{aligned} e^{(\lambda+iu)t} &= e^{\lambda t + iut} \\ &= e^{\lambda t} (e^{iut}) \\ &= e^{\lambda t} (\cos(ut) + i\sin(ut)) \\ &= e^{\lambda t} \cos(ut) + ie^{\lambda t} \sin(ut) \end{aligned}$$

AND

$$\begin{aligned} e^{(\lambda-iu)t} &= e^{\lambda t - iut} \\ &= e^{\lambda t} (e^{-iut}) \\ &= e^{\lambda t} (\cos(ut) - i\sin(ut)) \\ &= e^{\lambda t} \cos(ut) - ie^{\lambda t} \sin(ut) \end{aligned}$$

Recall that $y_1 = e^{(\lambda+iu)t}$ and $y_2 = e^{(\lambda-iu)t}$.
Hence, $y_1 = e^{\lambda t} \cos(ut) + ie^{\lambda t} \sin(ut)$ and
 $y_2 = e^{\lambda t} \cos(ut) - ie^{\lambda t} \sin(ut)$.

Thm 1. Consider $y'' + p(t)y' + q(t)y = 0$.
If $y = u(t) + iv(t)$ is a complex-valued soln,
then both u and v are also solutions.

$$\begin{aligned} y_1 &= e^{\lambda t} \cos(ut) + ie^{\lambda t} \sin(ut) \\ y_2 &= e^{\lambda t} \cos(ut) - ie^{\lambda t} \sin(ut) \end{aligned}$$

Let $a(t) = e^{\lambda t} (\cos(ut))$
 $b(t) = e^{\lambda t} (\sin(ut))$

} By Thm 1.

$$\begin{aligned} y &= C_1(a(t)) + C_2(b(t)) \\ &= C_1(e^{\lambda t} (\cos(ut))) + C_2(e^{\lambda t} (\sin(ut))) \end{aligned}$$

Fig. 8 Solve $y'' + y' + 9.25y = 0$, $y(0) = 2$, $y'(0) = 8$

Soln:

$$r^2 + r + 9.25 = 0$$

$$4r^2 + 4r + 37 = 0$$

$$r = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$= \frac{-4 \pm \sqrt{16 - 592}}{8}$$

$$= \frac{-4 \pm \sqrt{-576}}{8}$$

$$= \frac{-4 \pm 24i}{8}$$

$$= -\frac{1}{2} \pm 3i$$

$$r_1 = -\frac{1}{2} + 3i, \quad r_2 = -\frac{1}{2} - 3i$$

$$\lambda = -\frac{1}{2}, \quad u = 3$$

$$\begin{aligned} y_1 &= e^{\lambda t} (\cos(ut) + i \sin(ut)) \\ &= e^{-t/2} (\cos(3t) + i \sin(3t)) \end{aligned} \quad \begin{aligned} y_2 &= e^{\lambda t} (\cos(ut) - i \sin(ut)) \\ &= e^{-t/2} (\cos(3t) - i \sin(3t)) \end{aligned}$$

14

$$a(t) = e^{-\frac{t}{2}} (\cos(3t)), \quad b(t) = e^{-\frac{t}{2}} (\sin(3t))$$

$$\begin{aligned} y &= C_1(a(t)) + C_2(b(t)) \\ &= C_1(e^{-\frac{t}{2}} (\cos(3t))) + C_2(e^{-\frac{t}{2}} (\sin(3t))) \end{aligned}$$

$$\begin{aligned} y(0) &= 2 \rightarrow 2 = C_1(e^0 (\cos(0))) + C_2(e^0 (\sin(0))) \\ &= C_1 \end{aligned}$$

$$\begin{aligned} y'(0) &= 8 \rightarrow y' = (C_1(e^{-\frac{t}{2}} (\cos(3t)) + C_2(e^{-\frac{t}{2}} (\sin(3t)))))' \\ &= \frac{-C_1(e^{-\frac{t}{2}})(6\sin(3t) + \cos(3t))}{2} \\ &\quad - \frac{C_2(e^{-\frac{t}{2}})(\sin(3t) - 6\cos(3t))}{2} \end{aligned}$$

$$8 = (-C_1(1) - [C_2(-6)])(\frac{1}{2})$$

$$\begin{aligned} 16 &= -C_1 + 6C_2 \\ &= -2 + 6C_2 \end{aligned}$$

$$18 = 6C_2$$

$$C_2 = 3 \quad C_1 = 2, C_2 = 3$$

$$\begin{aligned} y &= 2e^{-\frac{t}{2}} \cos(3t) + 3e^{-\frac{t}{2}} \sin(3t) \\ &= e^{-\frac{t}{2}} (2\cos(3t) + 3\sin(3t)) \end{aligned}$$

E.g. 9 Solve $16y'' - 8y' + 145y = 0$, $y(0) = -2$, $y'(0) = 1$

Soln :

$$16r^2 - 8r + 145 = 0$$

$$r = \frac{1}{4} \pm 3i$$

$$\lambda = \frac{1}{4}, \mu = 3$$

$$y_1 = e^{\lambda t} (\cos(ut) + i \sin(ut))$$

$$= e^{\frac{t}{4}} (\cos(3t) + i \sin(3t))$$

$$y_2 = e^{\lambda t} (\cos(ut) - i \sin(ut))$$

$$= e^{\frac{t}{4}} (\cos(3t) - i \sin(3t))$$

$$a(t) = e^{\lambda t} (\cos(ut))$$

$$b(t) = e^{\lambda t} (\sin(ut))$$

$$= e^{\frac{t}{4}} (\cos(3t))$$

$$= e^{\frac{t}{4}} (\sin(3t))$$

$$y = C_1 a(t) + C_2 b(t)$$

$$= C_1 (e^{\frac{t}{4}}) (\cos(3t)) + C_2 (e^{\frac{t}{4}}) (\sin(3t))$$

$$y(0) = -2 \rightarrow -2 = C_1$$

$$y'(0) = 1 \rightarrow 1 = \frac{-C_1(-1)}{4} + \frac{C_2(12)}{4}$$

$$1 = C_1 + 12C_2$$

$$6 = 12C_2$$

$$C_2 = \frac{1}{2}$$

$$y = -2(e^{\frac{t}{4}}) (\cos(3t)) + \frac{1}{2}(e^{\frac{t}{4}}) (\sin(3t))$$

E.g. 10 Solve $y'' + 9y = 0$

Soln:

$$r^2 + 9r = 0$$

$$r = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$= \frac{0 \pm \sqrt{-36}}{2}$$

$$= \frac{\pm 6i}{2}$$

$$= \pm 3i \rightarrow r_1 = 3i, r_2 = -3i$$

$$\lambda = 0 \text{ and } u = 3$$

$$a(t) = e^{\lambda t} (\cos(ut)) \quad b(t) = e^{\lambda t} (\sin(ut)) \\ = \cos(3t) \quad \quad \quad = \sin(3t)$$

$$y = c_1 a(t) + c_2 b(t) \\ = c_1 \cdot \cos(3t) + c_2 \cdot \sin(3t)$$

E.g. 11 Solve $y'' - 2y' + 2y = 0$

Soln:

$$r^2 - 2r + 2 = 0$$

$$r = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$= \frac{2 \pm \sqrt{4 - 8}}{2}$$

$$= \frac{2 \pm 2i}{2}$$

$$= 1+i \text{ or } 1-i$$

$$\lambda = 1, u = 1$$

$$\begin{aligned} a(t) &= e^{\lambda t} (\cos(ut)) \\ &= e^t (\cos(t)) \end{aligned} \quad \begin{aligned} b(t) &= e^{\lambda t} (\sin(ut)) \\ &= e^t (\sin(t)) \end{aligned}$$

$$\begin{aligned} y &= C_1 a(t) + C_2 b(t) \\ &= C_1 (e^t) (\cos(t)) + C_2 (e^t) (\sin(t)) \end{aligned}$$

E.g. 12 Solve $y'' - 2y' + 6y = 0$

Soln:

$$\begin{aligned} r^2 - 2r + 6 &= 0 \\ r &= \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} \\ &= \frac{2 \pm \sqrt{4 - 24}}{2} \\ &= \frac{2 \pm 2\sqrt{5}i}{2} \\ &= 1 \pm \sqrt{5}i \end{aligned}$$

$$\lambda = 1, u = \sqrt{5}$$

$$\begin{aligned} a(t) &= e^{\lambda t} (\cos(ut)) \\ &= e^t (\cos(\sqrt{5}t)) \end{aligned} \quad \begin{aligned} b(t) &= e^{\lambda t} (\sin(ut)) \\ &= e^t (\sin(\sqrt{5}t)) \end{aligned}$$

$$\begin{aligned} y &= C_1 a(t) + C_2 b(t) \\ &= C_1 (e^t) (\cos(\sqrt{5}t)) + C_2 (e^t) (\sin(\sqrt{5}t)) \end{aligned}$$

e) Solving Homogeneous Eqns With Constant Coefficients and 1 Real Distinct Root

- We will now look at the case when $b^2 - 4ac = 0$.

$$\text{If } b^2 - 4ac = 0, \text{ then } r = \frac{-b \pm 0}{2a} = \frac{-b}{2a}$$

Hence, if $b^2 - 4ac = 0$, there is 1 distinct real root.

However, this poses a problem. We need both y_1 and y_2 , and right now, we just have y_1 .

- To find y_2 , we will use the Wronksian.

- The Wronksian is also important for seeing if a particular soln is also a general soln. We will look at this first.

Consider the following:

$$p(t)y'' + q(t)y' + r(t)y = 0 \text{ and } y(t_0) = y_0 \text{ and } y'(t_0) = y'_0$$

Suppose that y_1 and y_2 are solutions to this eqn.

We know that $y = c_1 y_1 + c_2 y_2$ is also a soln. What we want to know is if this will be a general soln. In order for this to be a general soln, it must satisfy the initial conditions.

$$y_0 = C_1 y_1(t_0) + C_2 y_2(t_0)$$

$$y'_0 = C_1 y'_1(t_0) + C_2 y'_2(t_0)$$

We can use Cramer's Rule to find C_1 and C_2 .

$$C_1 = \frac{\begin{vmatrix} y_0 & y_2(t_0) \\ y'_0 & y'_2(t_0) \end{vmatrix}}{\begin{vmatrix} y_1(t_0) & y_2(t_0) \\ y'_1(t_0) & y'_2(t_0) \end{vmatrix}} \quad C_2 = \frac{\begin{vmatrix} y_1(t_0) & y_0 \\ y'_1(t_0) & y'_0 \end{vmatrix}}{\begin{vmatrix} y_1(t_0) & y_2(t_0) \\ y'_1(t_0) & y'_2(t_0) \end{vmatrix}}$$

The denominator is the Wronksian.

I.e. If y_1 and y_2 are 2 solns of a linear homogeneous eqn, then

$$W(t) = \begin{vmatrix} y_1 & y_2 \\ y'_1 & y'_2 \end{vmatrix}$$

$$= y_1 y'_2 - y_2 y'_1$$

Notice that the only thing preventing us from finding C_1 and C_2 is if $w(t) = 0$. If $w(t) \neq 0$ and y_1 and y_2 are solns, then the 2 solns are called a **Fundamental Set of solns** and $y = C_1 y_1 + C_2 y_2$ is a general soln.

Note: The Wronksian Dichotomy for Two Solns states that for 2 solns, $w(t) = 0$ for all t or $w(t) \neq 0$ for all t .

- Now, we will see how the Wronksian is used to find y_2 .

$$\begin{aligned} w &= y_1 y_2' - y_1' y_2 \\ w' &= (y_1 y_2' - y_1' y_2)' \\ &= \cancel{y_1' y_2'} + y_1 y_2'' - y_1'' y_2 - \cancel{y_1' y_2'} \\ &= y_1 y_2'' - y_1'' y_2 \end{aligned}$$

Note that

- $y_1'' + p(t)y_1' + q(t)y_1 = 0 \rightarrow y_1'' = -p(t)y_1' - q(t)y_1$
- $y_2'' + p(t)y_2' + q(t)y_2 = 0 \rightarrow y_2'' = -p(t)y_2' - q(t)y_2$

$$\begin{aligned} w' &= y_1 (-p(t)y_2' - q(t)y_2) - y_2 (-p(t)y_1' - q(t)y_1) \\ &= -y_1 p(t)y_2' - y_1 q(t)y_2 + y_2 p(t)y_1' + y_2 q(t)y_1 \\ &= -y_1 p(t)y_2' + y_2 p(t)y_1' \\ &= p(t)(-y_1 y_2' + y_2 y_1') \\ &= -p(t)(y_1 y_2' - y_2 y_1') \\ &= -p(t) \cdot w \end{aligned}$$

$$\frac{dw}{dt} = -p(t)w$$

$$\frac{1}{w} dw = -p(t) dt \leftarrow \text{Separable Eqn}$$

$$\int \frac{1}{w} dw = \int -p(t) dt$$

$$\ln|w| = \int -p(t) dt + C$$

$$w = e^{\int -p(t) dt + C}$$

$$\omega = e^c \cdot e^{sp}$$

$$= c' \cdot e^{sp} \leftarrow \text{Abel's Formula}$$

Note: Abel's formula proves the dichotomy.
 Either $c=0$ and $\omega=0$ everywhere or
 $c \neq 0$ and $\omega \neq 0$ everywhere.

Note: It is very important for this calculation that there is no coefficient in front of y'' .

E.g. 13 Solve $y'' + 2y' + y = 0$

Soln:

$$r^2 + 2r + 1 = 0$$

$$(r+1)^2 = 0$$

$$r = -1$$

$$y_1 = e^{-t}$$

$$\begin{aligned}\omega &= c' e^{-\int p dt} \\ &= c' e^{-\int 2 dt} \\ &= c' e^{2t + C_1}\end{aligned}$$

$$\text{Let } c' = 1$$

$$\omega = e^{-2t} \cdot e^{C_1}$$

Let e^{C_1} be C_1 .

$$\omega = C_1 \cdot e^{2t}$$

$$\text{Let } C_1 = 1.$$

$$\omega = e^{2t}$$

$$\text{Also, } \omega = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$$

$$= y_1 y_2' - y_2 y_1'$$

$$= e^{-t} y_2' - (e^{-t})' y_2$$

$$(e^{-t}) y_2' - (e^{-t})' y_2 = e^{-2t}$$

$$(e^{-t}) y_2' + (e^{-t}) y_2 = e^{-2t}$$

$$(e^{-t})(y_2' + y_2) = e^{-2t}$$

$$y_2' + y_2 = e^{-t} \leftarrow \text{Linear Differential Eqn}$$

$$y_2 = te^{-t}$$

Note: If we have $y'' + by' + cy = 0$ and $r_1 = r_2$, then $y_1 = e^{r_1 t}$ and $y_2 = te^{r_1 t}$. This is called the Repeated Root's Rule.

E.g. 14 Solve $y'' - 4y' + 4y = 0$

Soln

$$r^2 - 4r + 4 = 0$$

$$(r-2)^2 = 0$$

$$r = 2$$

$$y_1 = e^{2t}$$

$$y_2 = te^{2t}$$

$$y = c_1 e^{2t} + c_2 te^{2t}$$

E.g. 15 Solve $y'' + 14y' + 49y = 0$

Soln:

$$r^2 + 14r + 49 = 0$$

$$(r+7)^2 = 0 \rightarrow r = -7$$

$$y_1 = e^{-7t}$$

$$y_2 = te^{-7t}$$

$$y = c_1 e^{-7t} + c_2 te^{-7t}$$

E.g. 16 Let $f(t) = e^{2t}$, $g(t)$ be an unknown function and $w(f, g) = 3e^{4t}$. Find $g(t)$.

Soln:

$$w = \begin{vmatrix} f & g \\ f' & g' \end{vmatrix} \\ = 3e^{4t}$$

$$\begin{aligned} f \cdot g' - f' \cdot g &= 3e^{4t} \\ e^{2t} \cdot g' - 2e^{2t} \cdot g &= 3e^{4t} \\ e^{2t}(g' - 2g) &= 3e^{4t} \\ g' - 2g &= 3e^{2t} \quad \leftarrow \text{Linear First Order} \\ g &= 3te^{2t} + ce^{2t} \end{aligned}$$

↑ Note: Here, we keep the c.
We don't let it be 0 or 1.

E.g. 17 Solve $y'' - 8y' + 17y = 0$

Soln:

$$\begin{aligned} r^2 - 8r + 17 &= 0 \\ r &= \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} \\ &= \frac{8 \pm \sqrt{64 - 68}}{2} \\ &= \frac{8 \pm 2i}{2} \\ &= 4 \pm i \end{aligned}$$

$$r_1 = 4+i, r_2 = 4-i$$

$$\lambda = 4, u = 1$$

$$\begin{aligned} a(t) &= e^{\lambda t} (\cos(ut)) & b(t) &= e^{\lambda t} (\sin(ut)) \\ &= e^{4t} (\cos t) & &= e^{4t} (\sin t) \end{aligned}$$

$$y = C_1 a(t) + C_2 b(t) = C_1 e^{4t} (\cos t) + C_2 e^{4t} (\sin t)$$