1. Difference Between 2 and d.

2 is used when there are other variables in the final solution.

Eig.

Cut f= xy

cut g=x

Note: You can have more than I variable in the function and still use d.

Chain Rule

at w=f(x,y,z,t)

Cut x = x(t)

(it y = y(t) (it z = z(t)

$$\frac{d\omega}{dt} = \left(\frac{\partial x}{\partial w} \cdot \frac{dx}{dt}\right) + \left(\frac{\partial y}{\partial w} \cdot \frac{dy}{dt}\right) + \left(\frac{\partial z}{\partial w} \cdot \frac{dz}{dt}\right) + \left(\frac{\partial z}{\partial w}\right)$$

Fig. Let $z=v^2\sin(w)+2t$ Let $v=\sin(t)$ Let $v=t^3$

Find dz

Solution:

 $\frac{dz}{dt} = \frac{\partial z}{\partial v} \cdot \frac{dv}{dt} + \frac{\partial z}{\partial v} \cdot \frac{dv}{dt} + \frac{\partial z}{\partial t}$

= (2 usinv)(cost) + (u2 cosv)(3t2) + 2

= (2)(sint)(sint3)(cost)+ (sin2+)(cost3)(3+1)+2

See how we started with 3 variables but still used a because the final answer only has I variable.

3. Jacobian Matrix:

1	2fi 2xi	9£1	ite .	_ Each row has the same function.
	2fz	əfz) ofz	
	IXE		- DXn	
	2fn	2fn.	2fn	
	1xe	242	9×n	
	•			

Each col has the Same Variable. 4. Tangent/Velocity Vectors:

(it c be a path defined by c(t) = (x(t), y(t), z(t)) and let c be differentiable.

The tangent vector of c at t is defined by

c'(t) = lim c(tth)-c(t), where h = At

= (x'(t), y'(t), z'(t)).

Proof:

 $C^{2}(t) = \lim_{h \to 0} \frac{c(t+h) - c(t)}{h}$ $= \lim_{h \to 0} \frac{(x(t+h), y(t+h), z(t+h)) - (x(t), y(t), z(t))}{h}$ $= \lim_{h \to 0} \frac{(x(t+h) - x(t), y(t+h) - y(t), z(t+h) - z(t))}{h}$ $= \lim_{h \to 0} \frac{(x(t+h) - x(t))}{h}, \lim_{h \to 0} \frac{(y(t+h) - y(t), lim)}{h}$

= (x'(+), y'(+), z'(+)),

Fig. Compute the tangent vector to the path of $c(t) = (t, t^2, e^t)$ at t = 0.

Soln: C'(t)=(1, 2t, et)

Plugging in t, we get (1,0,1), which
is the tangent vector.

5. Tangent Live:

The tangent line to c at point a= (x(to), y(to), z(to)) is defined to be the line through "a" with a direction of c'(to).

Formula:

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x(t_0) \\ y(t_0) \\ x(t_0) \end{pmatrix} + \begin{pmatrix} x'(t_0) \\ z'(t_0) \\ x'(t_0) \end{pmatrix} (t-t_0)$$

OR

Fig. A path in R³ goes through the point (3,6,5) at t=0 with a tangent vector i-j. Find the eqn of the tangent line.

Soln:

t=0 means that to=0.

$$\vec{x}$$
 = (3,6,5) + t(1,-1,0)
= (3+t,6-t,5)

OR

$$\begin{pmatrix} \times \\ y \\ z \end{pmatrix} = \begin{pmatrix} 3 \\ 6 \\ 5 \end{pmatrix} + t \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}$$



Eig. Find the velocity vector of the path c(t) = (cost, sint, t). Then, find the tangent line of the curve at (\$\frac{1}{27}\$, \$\frac{1}{27}\$).

Soln:

('(+)= (-sint, cost, 1)

Note: Check that the value of to fits with the other egns.

In our case, sin (7) = 5 cos(7) = 5

:. The tangent live is

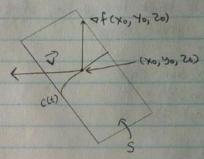
6. The gradient is normal to level surfaces:

Cut f: R3-3R have cont partial derivatives and let (x0, Y0, Z0) lie on the level surface S defined by f(x,y,z)=k, k is a constant. Then, \(\nabla f(x0, Y0, Z0)\) is normal (orthogonal) to S.

S= {(x, y, z) | f(x, y, z) = k}

Another way to think about this is:

If \vec{y} is a tangent vector at t=0 of a path c(t) in S with $c(0) = (x_0, y_0, z_0)$, then $\nabla f(x_0, y_0, z_0) \cdot \vec{V} = 0$.



Proof:

(it ((1) = (x(1), y(1), z(1)) be any differentible path that passes Xo at t=to on S. V= ('(to)

:. f(x(to), y(to), z(to)) = k, ker

$$\frac{df}{dt_0} = \left(\frac{\partial f}{\partial x}\right) \left(\frac{dx}{dt_0}\right) + \left(\frac{\partial f}{\partial t}\right) \left(\frac{dy}{dt_0}\right) + \left(\frac{\partial f}{\partial z}\right) \left(\frac{dz}{dt_0}\right)$$

$$\frac{df}{dto} = \frac{dk}{dto}$$

= 0 (k is a constant and the derivative of constants = 0.)

7. Tangent Planes:

Cut S be the surface containing (x, y, z) s.t. f(x, y, z) = k, k is a constant. The tangent plane of S at a point (xo, yo, zo) of S is defined by the eqn:

 $\nabla f(x_0, Y_0, z_0) \cdot (x - x_0, y - y_0, z - z_0) = 0$ if $\nabla f(x_0, Y_0, z_0) \neq 0$ Proof:

cut c(t) = (x(t), y(t), z(t)) be any differentialle path that passes through (xo, Yo, Zo) at t= to on S.

(x-xo, y-yo, z-zo) = (c'(to))(t-to)
This is the tangent line of c(t) at t=to.

√f(x(to), y(to), z(to)). (c'(to))(t-to) = 0(t-to) =0

Fig. Find the eqn of the place tangent to the surface defined by 3xy + z² at (1,1,1).

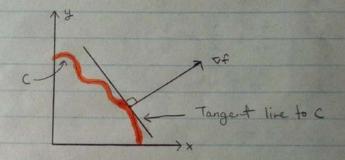
Solution:

 $f(x,y,z) = 3xy + z^2$ $\nabla f(x,y,z) = [3y, 3x, 2z]$ At the point (1,1,1), $\nabla f = [3,3,2]$.

 $(3,3,2) \cdot (x-1, y-1, z-1) = 0$ 3(x-1) + 3(y-1) + 2(z-1) = 03x + 3y + 2z = 8 What we've just learned is also applicable for a function $f: R^2 \rightarrow R$. However, this time,

(it $f: R^2 \rightarrow R$. (it C be a level curve containing (x,y) s.t. f(x,y) = k, k is a constant. Then, $\nabla F(x_0,y_0)$ is perpendicular to C for any point (x_0,y_0) on C.

∇f(xo, yo). (x-xo, y-yo)=0 if ∇f(xo, yo) =0



we will be using level curves.

Eig. Find the points on the surface defined by $x^2+2y^2+3z^2=1$ where the tangent plane is parallel to the plane defined by 3x-y+3z=1.

Soln: $f(x,y,z) = x^2 + zy^2 + 3z^2$ $\nabla f = [2x, 4y, 6z]$ [2x, 4y, 6z] || [3,-1,3] This means that there exists a k such that

$$2x = 3k \rightarrow x = \frac{3}{2}k$$

 $4y = -k \rightarrow y = -\frac{1}{4}k$
 $6z = 3k \rightarrow z = \frac{1}{2}k$

Furthermore, we know that X2+2y2+322=1.

$$\frac{(\frac{3}{2}k)^{2} + 2(-\frac{1}{4}k)^{2} + 3(\frac{1}{2}k)^{2} = 1}{9k^{2} + \frac{2k^{2}}{16} + \frac{3k^{2}}{4} = 1}$$

$$\frac{9k^{2}}{4} + \frac{2k^{2}}{8} + \frac{3k^{2}}{4} = 1$$

$$k^{2} \left(\frac{9}{4} + \frac{1}{8} + \frac{3}{4}\right) = 1$$

$$k^{2} \left(\frac{18+1+6}{8}\right) = 1$$

$$k^{2} = \frac{8}{25}$$

$$k = \pm \frac{252}{5}$$

Solving for x, y, and Z, we get

1.
$$x = \frac{352}{5}$$
, $y = -\frac{52}{10}$, $z = \frac{52}{5}$

2.
$$x = -\frac{352}{5}$$
, $y = \frac{52}{10}$, $z = -\frac{52}{5}$

The two points are 1.
$$\left(\frac{3\sqrt{2}}{5}, \frac{-\sqrt{2}}{10}, \frac{\sqrt{2}}{5}\right)$$

$$2. \left(-\frac{3\sqrt{2}}{5}, \frac{\sqrt{2}}{10}, -\frac{\sqrt{2}}{5}\right)$$

8. Linear Approximation:

Cut $f: \mathbb{R}^2 \to \mathbb{R}$ be differentiable at (x_0, y_0) .

The linear approx of f at (x_0, y_0) is defined by $L(x,y) = f(x_0, y_0) + \left[\frac{\partial f}{\partial x} (x_0, y_0) \right] (x-x_0) + \left[\frac{\partial f}{\partial y} (x_0, y_0) \right] (y-y_0)$

Fig. Find the linear approx to the function $f(x,y) = \sin(xy)$ at (1, 3).

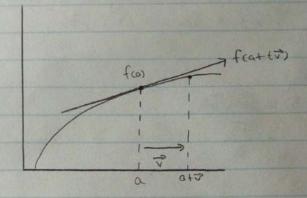
Soln: $f(1, \frac{\pi}{3}) = \sin(\frac{\pi}{3})$ $= \frac{\sqrt{3}}{2}$

 $L(x) = f(1, \frac{\pi}{3}) + \frac{\partial f}{\partial x}(1, \frac{\pi}{3})(x-1) + \frac{\partial f}{\partial y}(1, \frac{\pi}{3})(x-1)$ $= \frac{\sqrt{3}}{2} + (\frac{\pi}{3})(\sin(\frac{\pi}{3}))(x-1) + (1)(\sin(\frac{\pi}{3}))(y-1)$ $= \frac{\sqrt{3}}{2} + \frac{\pi}{6}(x-1) + \frac{1}{2}(y-1)$

9. Directional Derivatives with Linear Approx:

Consider a path along direction of that passes through point a. The rate of change of f in the direction of is given by Dor(fcor).

0



We can approx featt). L(a+tv) = fca) + Dv(fca).11v11 = fca) + Vf.v

Dr (fca) = Dr. Tis NOT a unit vector

DV (fcai) = Vf.V, if V is a unit vector

If f is differentiable then all directional derivatives exist. (It $\overrightarrow{V} = [V_1, V_2, V_3]$ be an unit vector. Then, the directional derivative of f at (X_3, Y_3, Z) in the direction \overrightarrow{V} is given by

$$D \stackrel{>}{\Rightarrow} (f(x,y,z)) = \nabla f(x,y,z) \cdot \nabla^2$$

$$= \frac{\partial f}{\partial x} (x,y,z) \cdot V_1 + \frac{\partial f}{\partial y} (x,y,z) \cdot V_2 + \frac{\partial f}{\partial x} (x,y,z) \cdot V_3$$

10. Examples From Tutorial:

1. Partial Derivatives:

(it
$$f(x,y) = \frac{\cos(xy^2)}{x}$$

$$\frac{\partial f}{\partial x} = \frac{(y^2)(-\sin(xy^2))(x) - \cos(xy^2)}{x^2}$$

$$\frac{\partial f}{\partial y} = \frac{(2xy)(-\sin(xy^2))}{x}$$
$$= -2y(\sin(xy^2))$$

2. Jacobian Matrix:

9×1	Ofi Dxz	2f1	- Jacobian Motrix
9×1			
3fk 3xi	• • •	. ∂fk ∂xn	

$$f_1 = x^2 + x \sin(y)$$

$$f_2 = x^3 e^{xy}$$

$$f_3 = 3^{xy}$$

$$\begin{bmatrix}
2\sin(y) & x\cos(y) \\
e^{xy}(3x^2+yx^3) & x^4e^{xy} \\
(y)(\ln 3)(3^{xy}) & (x)(\ln 3)(3^{xy})
\end{bmatrix}$$

Cut f: R" ->R

$$Df(\omega) = \left[\frac{\partial f}{\partial x_1}(\omega), \frac{\partial f}{\partial x_2}(\omega), \dots \frac{\partial f}{\partial x_n}(\omega) \right]$$

This is called the gradient of f, denoted by of.

3. Chain Rule:

D(fog) con = Df(g(an). Dg(a)

This is the formula for the chain rule, However, there are 2 special cases of the chain rule,

Case 1:

Suppose we have f(x,y,z), x(t), y(t) and z(t).

$$\frac{df}{dt} = \frac{\partial f}{\partial x} \cdot \frac{dx}{dt} + \frac{\partial f}{\partial y} \cdot \frac{dy}{dt} + \frac{\partial f}{\partial z} \cdot \frac{dz}{dt}$$

Case 2:

Suppose we have z=f(x,y), x=g(s,t), y=h(s,t).

$$\frac{\partial z}{\partial s} = \frac{\partial z}{\partial x} \cdot \frac{\partial x}{\partial s} + \frac{\partial z}{\partial y} \cdot \frac{\partial y}{\partial s}$$

$$\frac{\partial z}{\partial t} = \frac{\partial z}{\partial x} \cdot \frac{\partial x}{\partial t} + \frac{\partial z}{\partial y} \cdot \frac{\partial y}{\partial t}$$

E,g. Let
$$z = e^{2x} \cdot \sin(3x)$$

Let $x = \frac{1}{5^2 + t^2}$
Let $y = \frac{1}{5^2 + t^2}$

Find $\frac{\partial z}{\partial s}$ and $\frac{\partial z}{\partial t}$

Solution:

$$\frac{\partial z}{\partial s} = \frac{\partial z}{\partial x} \cdot \frac{\partial x}{\partial s} + \frac{\partial z}{\partial y} \cdot \frac{\partial y}{\partial s}$$

=
$$(2)(e^{2x})(\sin(3x)(t) + (3)(e^{2x})(\cos(3x))(\frac{25}{2\sqrt{5^2+t^2}})$$

=
$$(2t)(e^{2(st-t^2)})(sin(3(\sqrt{s^2+t^2})) + (3)(e^{2(st-t^2)})$$

 $(cos(3(\sqrt{s^2+t^2})))$
 $(\frac{S}{\sqrt{s^2+t^2}})$

$$\frac{\partial z}{\partial t} = \frac{\partial z}{\partial x} \cdot \frac{\partial x}{\partial t} + \frac{\partial z}{\partial y} \cdot \frac{\partial y}{\partial t}$$

=
$$(2)(e^{2x})(\sin(3y))(5-2t) + (3)(e^{2x})(\cos(3y))(2t)$$

=
$$(2)(e^{2(st-t^2)})(\sin(3\sqrt{s^2+t^2}))(s-2t) + (3)(e^{2(st-t^2)})$$

 $(\cos(3\sqrt{s^2+t^2}))$
 $(\frac{t}{\sqrt{s^2+t^2}})$