## MATBGI Week 2 Notes

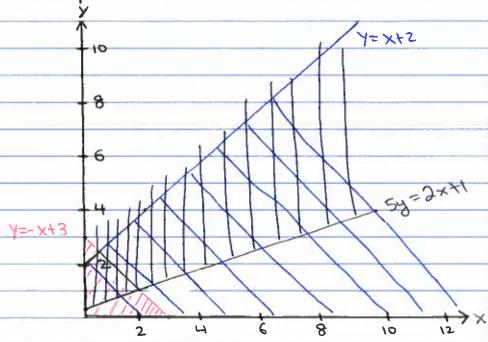
- 1. Linear Programming Theorem:
  - Let f be a linear function. Let

    U be a non-empty region in R<sup>2</sup>

    St. U is defined by linear
    inequalities and it includes its
    boundaries.
    - a) If U is bounded, then f has a max and a min on U and these values occur at corner points of U.
    - b) If U is unbounded and if f has a max or min, then this occurs at a corner point of U.
- 2. Graphic Soln of LP Problems:
  - Find the max and min of f(xy) = 3x+2y subject to the constraints:
    - 1. Y = X+3
    - 2. Y = -x+3
    - 3. 5Y≥2x+1
    - 4. X20, Y20

Soln

1. Graph the lines, Since x≥0 and y≥0, we just need the first quadrant.



2. Find the region that satisfies the first 3 constraints. I've shaded the region that satisfies each constraint and the region that has all 3 colours is the region that satisfies all 3 constraints. I've also highlighted the border in green.

3. Once you have the region, determine if its bounded or unbounded. In this case, it's bounded, so the max and min must be one of the 4 corner points, each.

4. Find all the corner points and plug them into the eqn to see which is the max and which is the min.

We can find 2 corner points by looking at the graph: (0, 2) and  $(0, \frac{1}{2})$ . We need to solve for the remaining ones.

1. 
$$-x+3 = x+2$$
  
 $2x = 1$   
 $x = \frac{1}{2}$  Corner Point:  
 $y = x+2$   $\left(\frac{1}{2}, \frac{5}{2}\right)$   
 $= \frac{1}{2}+2$   
 $= \frac{5}{2}$ 

2. 
$$-X+3 = \frac{1}{5}(2x+1)$$
  
 $-5x+15 = 2x+1$   
 $-7x = -14$  Corner Point:  
 $x = 2$  (2,1)  
 $Y = -X+3$   
 $= -2+3$   
 $= 1$ 

Now that we have all the corner points, we will plug them into fixy)= 3x+2y to find the max and min point.

$$f(0, 1/5) = 3(0) + 2(1/5)$$
=  $\frac{2}{5}$ 

$$f(\frac{1}{2}, \frac{5}{2}) = 3(\frac{1}{2}) + 2(\frac{5}{2})$$

$$= \frac{3}{2} + 5$$

$$= \frac{13}{2}$$

$$f(2,1) = 3(2) + 2(1)$$
  
= 6+2  
= 8

: f(xy)= 3xtdy subject to the constraints

Y \( \text{X} \tag{2} \)

Y \( \text{X} \tag{3} \times \tag{5} \)

Y \( \text{Z} \)

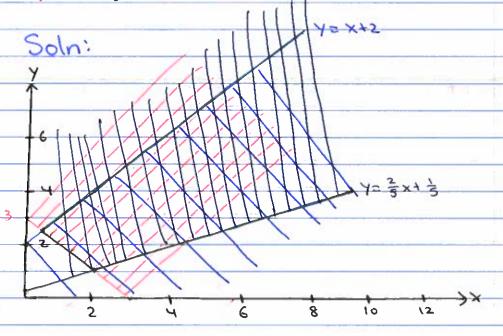
Y \( \text

b) Find the min and max of f(x,y) = 3x+2y subject to
1. Y \( \times \) x+2

2. Y = X+2

3.  $y = \frac{2}{5}x + \frac{1}{5}$ 

4. X20, Y20



Note that this region is unbounded. If the coefficients of the obj func are all positive, then an unbounded feasible region will have a min but no max. This is because the isoprofit lines increases in value and since the region is unbounded, there's no limit on how big it can get.

Isoprofit lines are parallel straight lines that represent constant values of the obj func.

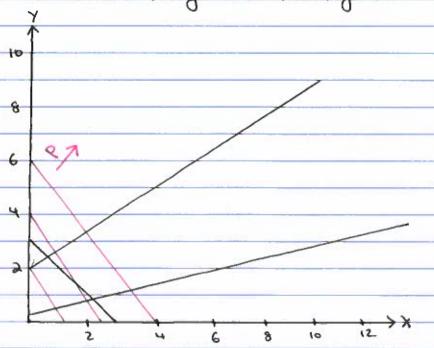
To get the isoprofit lines, let p= 3x+2y, and then isolate y.

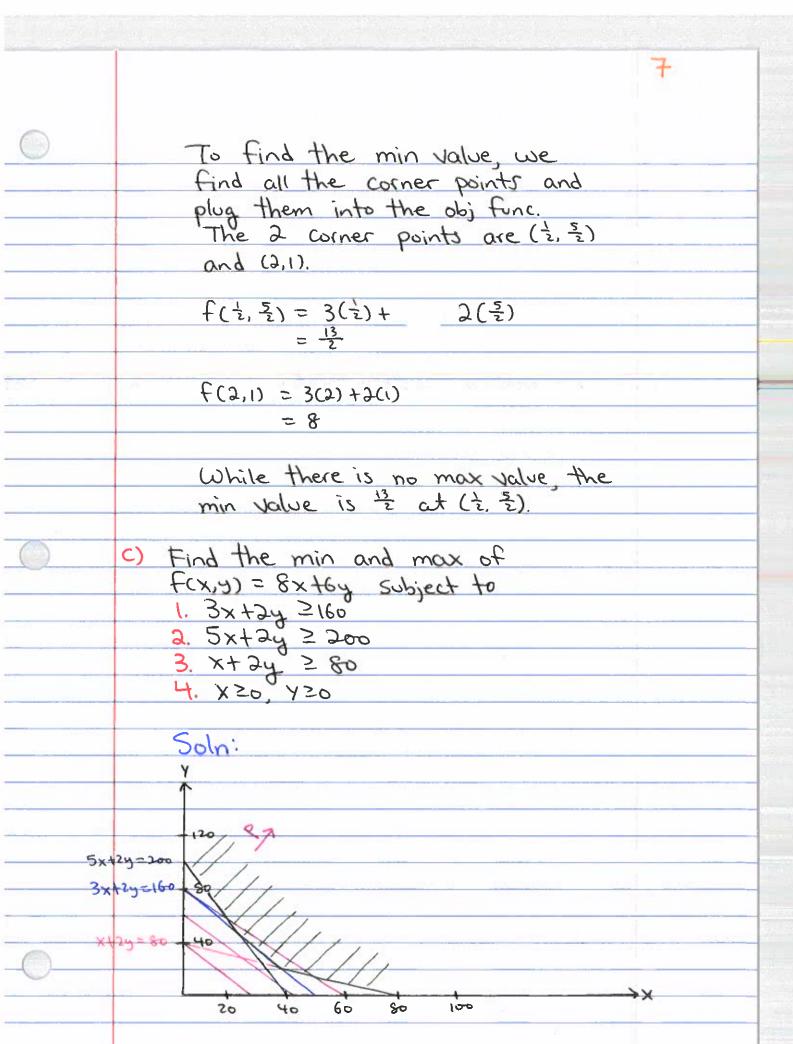
 $P = 3 \times + 2y$  2y = -3x + P y = -3x + P 2

If P=2, Y=-3x2 If P=10, Y=-3x+5

If P=20, Y=-3x+10

Note: You must show a few isoprofit lines as well as the direction they are moving to.





Once again, the feasible region is unbounded. Since the coefficients of the obj func are all positive, there is no max and only a min.

Isoprofit lines:  $P = 8 \times 16 \text{ y}$   $6 \text{ y} = -8 \times 19$   $9 = -4 \times 19$  $9 = -4 \times 19$ 

P=0 -> Y= -4x

 $P=6 \longrightarrow Y=-4x$ 

 $P = 60 \longrightarrow Y = -4x + 10$ 

To find the min value, find all corner points and plug them into the obj func.

Corner points: (0,100), (20,50), (40,20), (80,0).

f(0,100) = 8(0) +6(100) = 600

f(20, 50) = 8(20) + 6(50) = 460

The corner pts are: (0,6),  $(0,\frac{11}{3})$  and (2,3).

f(0,6) = 54  $f(0,\frac{4}{3}) = 33$ f(2,3) = 33

Any pt on the line  $y=-\frac{1}{3}x+\frac{1}{3}$ btwo the pts (0,  $\frac{1}{3}$ ) and (2,3) gets the optimal soln.

Thm:

If (X1, Y1) and (X2, Y2) are 2 Corner pts at which the obj func is optimum, then the obj func will also be optimum at all pts (Xy) where X=(1-t)X1 t t X2 Y=(1-t)Y1 t t Y2 O L t L 1

... The optimal soln is f(x,y)=33 at all points on the line  $y=-\frac{1}{3}x+\frac{1}{3}$  bluen the points (0,  $\frac{1}{3}$ ) and (2,3).

- 3. Geometry of LP Problems:
  - a) Geometry of a constraint of a LP Problem:
    - air XI + air X2 + III + ain Xn & bi or a Tx & bi where a T = [air, air, III, air]
    - The set of pts x= (x1, x2, 111, xn)
      in R<sup>n</sup> that satisfy this
      constraint is called a
      closed half-space.
    - The set of points x=(xi, xz,..., xn)
      in Rn that satisfy a x = bi is
      called a hyperplane. A hyperplane
      is a boundary of a closed halfspace,
    - The set of feasible solns to a LP problem is the intersection of all the closed half-spaces determined by the constraints.
  - b) Geometry of the obj func:
    - An obj func is Z= CTX.
    - Let k be a constant. CTX=k is a hyperplane.

- Geometrically, the optimal
  Soln is the hyperplane that
  intersects the set of
  feasible solns and for which
  Ic is a max or min.
- c) Geometry of the set of feasible solns:
  - Let X<sub>1</sub> and X<sub>2</sub> be feasible solns.
     The line segment connecting X<sub>1</sub> and X<sub>2</sub> is ξx ∈ R<sup>n</sup> | X = λx<sub>1</sub> + (1-λ) X<sub>2</sub>, 0 ≤ λ | 3.
  - If atx & bi is a constant of
    the problem and atx & & bi and
    atx & & bi, for any interior pt
    of the line segment, then
    x = \( \frac{1}{2} \times 1 \), to I \( \frac{1}{2} \) \( \frac{1}{2}

Proof:  $a^{T}x = \lambda a^{T}x_{1} + (1-\lambda)a^{T}x_{2}, \lambda^{2}0$   $(1-\lambda)^{2}0$   $\leq \lambda b_{1} + (1-\lambda)b_{1}$  $= b_{1}$  - If CTX, & CTX2, then CTX, & CTX & CTX2.

Proof:

 $C^{T}X = \lambda C^{T}X_{1} + (1-\lambda) C^{T}X_{2}$   $\geq \lambda C^{T}X_{1} + (1-\lambda) C^{T}X_{1}$   $= C^{T}X_{1}$ 

 $C^{T}X = \Lambda C^{T}X_{1} + (1-\Lambda)C^{T}X_{2}$   $= \Lambda C^{T}X_{2} + (1-\Lambda)C^{T}X_{2}$  $= C^{T}X_{2}$ 

- An interior point is a feasible soln but not an optimal soln.
- A subset k of R<sup>n</sup> is convex if
  for any X<sub>1</sub>, X<sub>2</sub> Ek, X= λX<sub>1</sub> +

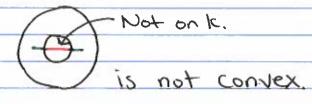
  (1-λ)X<sub>2</sub> Ek,

  I.e. k is convex if for any X<sub>1</sub>,

  X<sub>2</sub> Ek, the line segment

  btwo X<sub>1</sub> and X<sub>2</sub> is included in k.

Eig.



is convex.

- Determine whether or not the below sets are convex:
  - a) A hyperplane a, x, + ... + anxn = b Yes, it is convex. Proof:  $a^{T} x = b$

YY, Yz Ex, aTY, = b and aTYz=b Y= 77, + (1-2) Y2, 05251  $\alpha^T Y = \lambda \alpha^T Y_1 + (1-\lambda) \alpha^T Y_2$ 

= 2P+ (1-2)P

.. Y is on the hyperplane.

b) A closed half-space aixit ... t anxn &b. Yes, it is convex. Proof: aTX Eb YY, YZEX, aTY, Eb, aTYZEb

Y= xx, + (1-x) Y2, 0 = x = 1 aty = 2 aty, + (1-2) aty2 ₹ 7P+ (1-X)P

.. Y is on the hyperplane.

C) { ||x|| > | |xer } and { ||x|| = | |xer } No, it is not convex, In R2, 11×11≥1 has a hole. In R2, 11x11=1 is just a boundary.

- Thm: The intersection of a finite collection of convex sets is convex.

Proof: Let  $k_1$ ,  $k_2$ , ...,  $k_n$  be convex sets. Let  $k = \bigcap k_i$  and k is non-empty. Assume that  $X, Y \in k$ . Since  $k = \bigcap k_i$ ,  $X, Y \in k_i$ . Since  $k = \bigcap k_i$ ,  $X, Y \in k_i$ . Since  $k = \bigcap k_i$ ,  $X, Y \in k_i$ . Since  $k = \bigcap k_i$ ,  $X, Y \in k_i$ . Since  $k = \bigcap k_i$ ,  $X, Y \in k_i$ . Then, this means that  $X \times (I - X) \times$ 

4. Extreme Point Thm:

- A point XER" is a convex combination of the points XI, X2,..., Xr in R" if for some real numbers CI, C2,..., Cr which satisfy \(\xi\_1 \cdot Ci=1\) and Ci≥o for i in 1,2,...,r, we have X = \(\xi\_1 \cdot Ci \times i)

I.e. A convex combination is a linear combination of points where all the welficients are non-negative and sum to 1.

- A convex set is bounded if it can be enclosed in a rectangle {xer" | ai & xi & bi} in R". Otherwise, it's unbounded.

- Thm: The set of all convex combinations of a finite set of points in Rn is a convex set. Proof: Let 5 be a set of finite points. S= {Xili=1,2, ..., r3 ER" Let k= {x1x=Cix,+,,+crxr, Ci20, ¿ Ci=1, 1=1,2, ... < } YY, Yz EK, Y= aix, t... + arxr, a; 20, £ 01=1 12 = bix, t ... + brxr, bi 20 & bi=1 Let Y= 2 /1 + (1-2) /2, 0 = 2 51 = > [a,x,+,..+a,x,]+(1-2)[b,x, t... + brxr7 =  $(\lambda a + (1-\lambda)b) \times + + (\lambda a + (1-\lambda)b) \times +$ As 7, 1-2, ai, bi 20, 20; t(1-2) bi 20 7ai + (1-2) bi  $= \sum_{i} \lambda \alpha_{i} + \sum_{i} (1-\lambda)b_{i}$ =  $\lambda \sum_{\alpha} a_i + (1-\lambda) \sum_{\alpha} b_i$  $= \lambda + (1-\lambda)$ : Y is a convex comb of X, ..., Xr. .: k is a convex set