

## MATB44 Week 4 Notes

### 1. Review of Week 3 Material

#### a) Homogeneous Eqns With Constant Coefficients

- Rule 1:  $y = e^{rt}$
- Rule 2: We can combine 2 solns to get a new soln.

#### b) Homogeneous Eqns With Constant Coefficients and 2 Real Distinct Roots

- Suppose  $ay'' + by' + cy = 0$ .

From rule 1, we know that  $y = e^{rt}$ .

$$y' = re^{rt}$$

$$y'' = r^2 e^{rt}$$

$$ar^2(e^{rt}) + br(e^{rt}) + c(e^{rt}) = 0$$

$$(e^{rt})(ar^2 + br + c) = 0$$

Since  $e^{rt} \neq 0$ , we can divide both sides by it.

$$ar^2 + br + c = 0 \quad \leftarrow \text{Called characteristic equation}$$

$$r = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$r_1 = \frac{-b + \sqrt{b^2 - 4ac}}{2a}, \quad r_2 = \frac{-b - \sqrt{b^2 - 4ac}}{2a}$$

$$y_1 = e^{r_1 t}, \quad y_2 = e^{r_2 t}$$

From rule 2, we know that we can combine 2 solns to get a new one.

$$y = C_1 y_1 + C_2 y_2$$



### c) Wronksian

- Useful for finding the second soln in homogeneous eqns with constant coefficients and repeated roots as well as determining if a pair of solns is a fundamental set of soln.

- Consider  $p(t)y'' + q(t)y' + r(t)y = 0$  and  $y(t_0) = y_0$  and  $y'(t_0) = y'_0$ . Suppose  $y_1$  and  $y_2$  are solns. Then,  $y = C_1 y_1 + C_2 y_2$  is also a soln. We want to know if  $y = C_1 y_1 + C_2 y_2$  is also a general soln. In order to be a general soln, it must satisfy the initial conditions.

$$y_0 = C_1 y_1(t_0) + C_2 y_2(t_0)$$

$$y'_0 = C_1 y'_1(t_0) + C_2 y'_2(t_0)$$

We can use Cramer's rule to find  $C_1$  and  $C_2$ .

$$C_1 = \frac{\begin{vmatrix} y_0 & y_2(t_0) \\ y'_0 & y'_2(t_0) \end{vmatrix}}{\begin{vmatrix} y_1(t_0) & y_2(t_0) \\ y'_1(t_0) & y'_2(t_0) \end{vmatrix}} \quad C_2 = \frac{\begin{vmatrix} y_1(t_0) & y_0 \\ y'_1(t_0) & y'_0 \end{vmatrix}}{\begin{vmatrix} y_1(t_0) & y_2(t_0) \\ y'_1(t_0) & y'_2(t_0) \end{vmatrix}}$$

The denominator is the **Wronksian**.

I.e. If  $y_1$  and  $y_2$  are 2 solns to a linear homogeneous eqn with constant coefficients, then

$$W = \begin{vmatrix} y_1 & y_2 \\ y'_1 & y'_2 \end{vmatrix} \\ = y_1 y'_2 - y'_1 y_2$$



Notice that the only thing preventing us from finding  $C_1$  and  $C_2$  is if  $\omega = 0$ .

If  $\omega \neq 0$  and  $y_1$  and  $y_2$  are solns, then  $y_1$  and  $y_2$  are a **fundamental set/pair of solns** and  $y = C_1 y_1 + C_2 y_2$  is a general soln.

I.e. Take  $y = C_1 y_1 + C_2 y_2$  and the initial conditions  $y(t_0) = y_0$  and  $y'(t_0) = y'_0$ .

$$\left. \begin{aligned} C_1 y_1(t_0) + C_2 y_2(t_0) &= y_0 \\ C_1 y'_1(t_0) + C_2 y'_2(t_0) &= y'_0 \end{aligned} \right\} \text{ This system has a soln for any RHS iff } \omega \neq 0.$$

**Note:** Recall from linear algebra that a matrix is linearly independent iff the determinant of the matrix  $\neq 0$ . Hence, if  $\omega \neq 0$ ,  $y_1$  and  $y_2$  are linearly independent. otherwise, they are linearly dependent.

**Note:** If  $\omega = \begin{vmatrix} y_1 & y_2 \\ y'_1 & y'_2 \end{vmatrix} \neq 0$ , then  $y_1$  and  $y_2$  are a fundamental pair of solns.

**E.g. 1** Let  $f(t) = e^{2t}$ ,  $\omega = \begin{vmatrix} f & g \\ f' & g' \end{vmatrix} = 3e^{4t}$ .

Solve for  $g(t)$ .

Soln:

$$\omega = \begin{vmatrix} f & g \\ f' & g' \end{vmatrix}$$

$$fg' - f'g = 3e^{4t}$$

$$e^{2t}g' - 2e^{2t}g = 3e^{4t}$$



$$e^{2t}(g' - 2g) = 3e^{4t}$$

$$g' - 2g = 3e^{2t} \leftarrow \text{Linear first order}$$

$$g = 3te^{2t} + \underline{c}e^{2t}$$

We keep the  $c$ .

- We can solve  $w$  without solving the eqn.

$$w = y_1 y_2' - y_1' y_2$$

$$\frac{dw}{dt} = y_1' y_2' + y_1 y_2'' - y_1'' y_2 - y_1' y_2'$$

$$= y_1 y_2'' - y_1'' y_2$$

Recall that

$$y_1'' + p(t)y_1' + q(t)y_1 = 0 \rightarrow y_1'' = -p(t)y_1' - q(t)y_1$$

$$y_2'' + p(t)y_2' + q(t)y_2 = 0 \rightarrow y_2'' = -p(t)y_2' - q(t)y_2$$

$$\frac{dw}{dt} = y_1(-p(t)y_2' - q(t)y_2) - y_2(-p(t)y_1' - q(t)y_1)$$

$$= -p(t)y_1 y_2' - q(t)y_1 y_2 + p(t)y_1' y_2 + q(t)y_1 y_2$$

$$= -p(t)(y_1 y_2' - y_1' y_2)$$

$$= -p(t)(y_1 y_2' - y_1' y_2)$$

$$= -p(t)w$$

$$\frac{1}{w} dw = -p(t) dt$$

$$\int \frac{1}{w} dw = \int -p(t) dt$$

$$\ln(w) + c = \int -p(t) dt$$

$$\ln(w) = \int -p(t) dt + c$$

$$w = e^{-\int p(t) dt + c}$$

$$= e^{-\int p(t) dt} \cdot e^c$$

$$= c' e^{-\int p(t) dt}$$

$\leftarrow$  Abel's Formula



- The Wronskian Dichotomy for 2 Solns states that for 2 solns,  $w=0$  for all  $t$  or  $w \neq 0$  for all  $t$ .

Abel's formula proves the dichotomy. Either  $c'=0$  and  $w=0$  everywhere or  $c' \neq 0$  and  $w \neq 0$  everywhere.

E.g. 2 Let  $x^2 y'' - x(x+2)y' + (x+2)y = 0$

a) Verify  $y_1 = x$  and  $y_2 = xe^x$

Soln:

Simply plug  $y_1$  and  $y_2$  into the eqn above and see if  $LHS = RHS$ .

$y_1$ :

$$LHS = -x(x+2) + (x+2)x$$

$$= 0$$

$$RHS = 0$$

$$LHS = RHS$$

$y_2$ :

$$LHS = x^2(xe^x)'' - x(x+2)(xe^x)' + (x+2)(xe^x)$$

$$= x^2(x+2)e^x - x(x+2)(x+1)e^x + (x+2)(x)(e^x)$$

$$= e^x(x^3 + 2x^2 - x^3 - 3x^2 - 2x + x^2 + 2x)$$

$$= e^x(0)$$

$$= 0$$

$$RHS = 0$$

$$LHS = RHS$$



b) Do  $y_1$  and  $y_2$  make a fundamental pair of solns?

Soln:

$$\begin{aligned}
 W &= \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} \\
 &= \begin{vmatrix} x & xe^x \\ 1 & e^x + xe^x \end{vmatrix} \\
 &= x(e^x + xe^x) - xe^x \\
 &= xe^x + x^2e^x - xe^x \\
 &= x^2e^x
 \end{aligned}$$

$$W \neq 0 \text{ Iff } x \neq 0$$

**Note:** We can't use Abel's formula here. All it says is that  $W=0$  iff  $c'=0$ , which doesn't give us enough information.

**E.g. 3** Suppose we have  $y_1 = e^{-t}$  and  $y_2 = 2e^{-t}$ . Prove that they are not a fundamental pair of solns.

Solns:

$$\begin{aligned}
 W &= \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} \\
 &= \begin{vmatrix} e^{-t} & 2e^{-t} \\ -e^{-t} & -2e^{-t} \end{vmatrix} \\
 &= (e^{-t})(-2e^{-t}) - (2e^{-t})(-e^{-t}) \\
 &= 0
 \end{aligned}$$



**E.g. 4** Let  $y_1 = t$  and  $y_2 = \sin t$ . Are  $y_1$  and  $y_2$  solns?  
a fundamental pair of

Soln:

$$\begin{aligned} W &= \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} \\ &= \begin{vmatrix} t & \sin t \\ 1 & \cos t \end{vmatrix} \\ &= t \cos t - \sin t \end{aligned}$$

If  $t=0$ ,  $W=0$ .

Furthermore,  $W(\frac{\pi}{2}) = -1 < 0$   
 $W(2\pi) = 2\pi > 0$  } Contradiction

Abel's formula either gives all positives or all negatives.

Hence,  $y_1$  and  $y_2$  cannot be a fundamental pair of solns.

d) Homogeneous Eqns with Constant Coefficients and Repeated Roots

- Here  $r_1 = r_2$ . However, this poses a problem. We need  $y_1$  and  $y_2$ , and right now, we just have  $y_1$ .

- **E.g. 5** Solve  $y'' + 2y' + y = 0$

Soln:

$$r^2 + 2r + 1 = 0$$

$$(r+1)^2 = 0$$

$$r = -1$$

$$y_1 = e^{-t}$$



To find  $y_2$ , we'll use the Wronskian.

$$\begin{aligned}
 W &= \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} \\
 &= y_1 y_2' - y_1' y_2 \\
 &= (e^{-t}) y_2' - (-e^{-t}) y_2 \\
 &= (e^{-t}) y_2' + (e^{-t}) y_2 \\
 &= (e^{-t})(y_2' + y_2)
 \end{aligned}$$

$$\begin{aligned}
 \text{Also, } W &= C' \cdot e^{-\int p \, dt} \\
 &= C' \cdot e^{-\int 2 \, dt} \\
 &= C' \cdot e^{-2t + C_1} \\
 &= e^{-2t}
 \end{aligned}$$

$$(e^{-t})(y_2' + y_2) = e^{-2t}$$

$$y_2' + y_2 = e^{-t} \leftarrow \text{Linear Differential eqn}$$

$$y_2 = te^{-t}$$

**Note:** If we have  $y'' + by' + cy = 0$  and  $r_1 = r_2$  then  $y_1 = e^{r_1 t}$  and  $y_2 = te^{r_1 t}$ .

This is called the **Repeated Roots Rule**.

e) Homogeneous Eqns With Constant Coefficients and Complex Roots

-  $Z$  is a complex number if it can be written in the form:  $Z = a + ib$ .

$a$  and  $b$  are real numbers.

$$i = \sqrt{-1} \Leftrightarrow i^2 = -1$$

$a$  is the **real part**.

$b$  is the **imaginary part**. (Does not include  $i$ ).

$i$  is the **imaginary unit**.

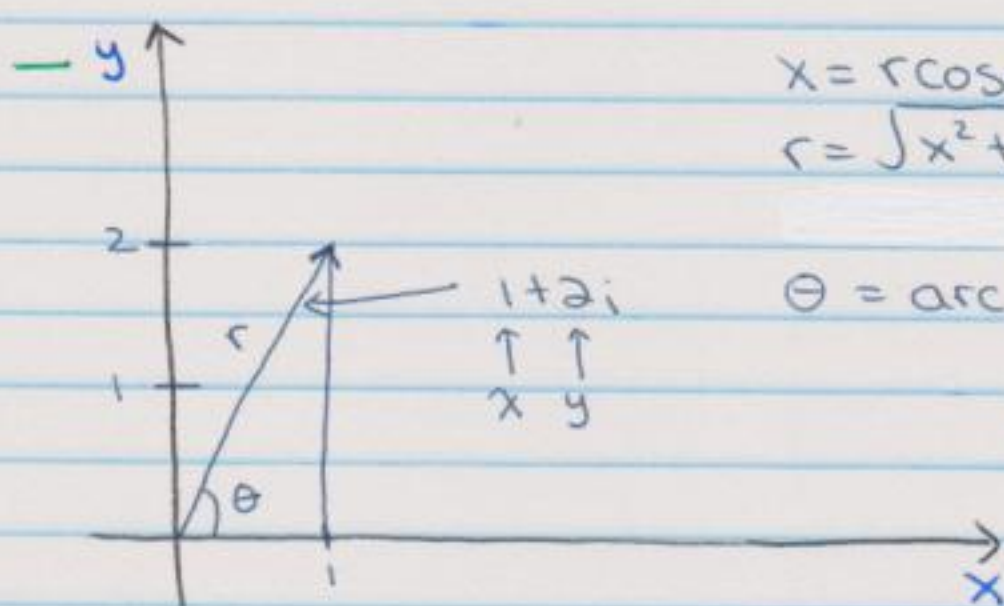


$$(a+ib) + (c+id) = (a+c) + i(b+d)$$

**E.g. 6**  $(1+2i) + (3+4i) = 4+6i$

$$\begin{aligned}(a+ib) \times (c+id) &= ac + iad + ibc + i^2 bd \\ &= ac + i(ad+bc) - bd \\ &= (ac-bd) + i(ad+bc)\end{aligned}$$

**E.g. 7**  $(1+2i) \times (3+4i)$   
 $= 3+4i+6i+8i^2$   
 $= -5+10i$



$$x = r \cos \theta, \quad y = r \sin \theta$$

$$r = \sqrt{x^2 + y^2}$$

$$\theta = \arctan\left(\frac{y}{x}\right)$$

$y$  is the imaginary part.  
 $x$  is the real part.

$$Z = x + iy$$

$$= r \cos \theta + i r \sin \theta$$

$$= r(\cos \theta + i \sin \theta) \leftarrow \text{Polar form of Complex Numbers}$$

— Euler's Formula:  $e^{i\theta} = \cos \theta + i \sin \theta$

Consider

$$e^{i\alpha} = \cos \alpha + i \sin \alpha$$

$$e^{i\beta} = \cos \beta + i \sin \beta$$



$$\begin{aligned}
 e^{i\alpha} \times e^{i\beta} &= (\cos\alpha + i\sin\alpha) \times (\cos\beta + i\sin\beta) \\
 &= \cos\alpha\cos\beta + i\cos\alpha\sin\beta + i\sin\alpha\cos\beta + i^2\sin\alpha\sin\beta \\
 &= (\cos\alpha\cos\beta - \sin\alpha\sin\beta) + i(\cos\alpha\sin\beta + \sin\alpha\cos\beta) \\
 &= \cos(\alpha+\beta) + i\sin(\alpha+\beta) \\
 &= e^{i(\alpha+\beta)}
 \end{aligned}$$

Hence,  $e^{a+ib} = e^a \cdot e^{ib}$

If  $R_1 \neq R_2$  and  $R_1, R_2 \in \mathbb{C}$ ,  $R_1, R_2 = \lambda \pm i\mu$ ,  
 $y_1 = e^{\lambda t} \cos(\mu t)$ ,  $y_2 = e^{\lambda t} \sin(\mu t)$ .

**E.g. 8** Solve  $y'' + y' + 9.25y = 0$

**Soln:**

$$r^2 + r + 9.25 = 0$$

$$r = \frac{-1}{2} \pm 3i$$

Recall that  $y = e^{rt}$

$$\begin{aligned}
 y &= e^{rt} \\
 &= e^{(-\frac{1}{2} + 3i)t} \\
 &= e^{-\frac{t}{2} + (3t)i} \\
 &= e^{-t/2} \cdot e^{(3t)i} \\
 &= e^{-t/2} (\cos(3t) + i\sin(3t)) \text{ By Euler's Formula} \\
 &= \underline{e^{-t/2} \cos(3t)} + i \underline{e^{-t/2} \sin(3t)}
 \end{aligned}$$

Solns

**Note:** We're only taking the real parts.



$$e^{-\frac{t}{2}} \cos(3t) = e^{\lambda} \cos(ut)$$
$$e^{-\frac{t}{2}} \sin(3t) = e^{\lambda} \sin(ut)$$

**Note:** We don't need to consider  $r = \frac{-1}{2} - 3i$  because it gives us redundant solns.

$$r_2 = \frac{-1}{2} - 3i$$

$$y = e^{-\frac{t}{2}} ((\cos(-3t)) + (i \sin(-3t)))$$
$$= e^{-\frac{t}{2}} (\cos(-3t)) + i e^{-\frac{t}{2}} (\sin(-3t))$$

However, because  $\cos$  is an even function,  $\cos(-3t) = \cos(3t)$ .

Furthermore, because  $\sin$  is an odd function,  $\sin(-3t) = -\sin(3t)$ .

Hence, we get no new solns.



## 2 Reduction of Order

- Now we will focus on homogeneous eqns with non-constant coefficients.

- Rule 1:  $y_1(t) = \frac{1}{t}$

- Rule 2:  $y_2(t) = v(t) y_1(t)$  where  $v(t)$  is an unknown function.

- E.g. 9 Solve  $2t^2 y'' + 3ty' - y = 0$

Soln:

$$y_1(t) = \frac{1}{t}$$

$$y_2(t) = v(t) y_1(t)$$

$$y_2' = (v y_1)' \\ = v' y_1 + v y_1'$$

$$y_2'' = (v' y_1 + v y_1')' \\ = v'' y_1 + v' y_1' + v' y_1' + v y_1'' \\ = v'' y_1 + 2v' y_1' + v y_1''$$

Now, put  $y_2$ ,  $y_2'$  and  $y_2''$  back into the original eqn.

$$2t^2(v'' y_1 + 2v' y_1' + v y_1'') + 3t(v' y_1 + v y_1') - v y_1 = 0$$

Now, expand the above eqn.

$$2t^2 v'' y_1 + 4t^2 v' y_1' + 2t^2 v y_1'' + 3t v' y_1 + 3t v y_1' - v y_1 = 0$$



Now, collect all the terms that has  $v$  in it.  
We do not collect the terms with  $v'$  or  $v''$ .

$$(2t^2 v y_1'' + 3t v y_1' - v y_1) + (2t^2 v'' y_1 + 4t^2 v' y_1' + 3t v' y_1) = 0$$

All the terms with a  $v$ .

$$v(2t^2 y_1'' + 3t y_1' - y_1) + (2t^2 v'' y_1 + 4t^2 v' y_1' + 3t v' y_1) = 0$$

Notice that this is our original eqn but with  $y_1$  instead of  $y$ . Since we know that  $y_1$  is a soln, then this equals 0.

**Note:** If you did your calculations correctly, at some point all the terms with  $v$  will go away.  $v$  must go.

Now, we're left with  
 $2t^2 v'' y_1 + 4t^2 v' y_1' + 3t v' y_1 = 0$  } No term with  $v$ .

Now, let  $w = v'$  and  $w' = v''$ .

So, we have:  $2t^2 w' y_1 + 4t^2 w y_1' + 3t w y_1 = 0$

Plug in  $y_1 = \frac{1}{t} \rightarrow \frac{2t^2 w'}{t} + \frac{4t^2 w}{-t^2} + \frac{3t w}{t} = 0$

$$2t w' - 4w + 3w = 0$$

$$2t w' - w = 0$$

$$2t \frac{dw}{dt} = w$$

$$2t dw = w dt$$

$$\frac{1}{w} dw = \frac{1}{2t} dt \leftarrow \text{Separable Eqs}$$



$$\int \frac{1}{w} dw = \int \frac{1}{2t} dt$$

$$\ln |w| + C_1 = \frac{\ln |t|}{2} + C_2$$

$$\begin{aligned} \ln |w| &= \frac{\ln |t|}{2} + \underbrace{C_2 - C_1}_C \\ &= \frac{\ln |t|}{2} + C \end{aligned}$$

$$e^{\ln |w|} = e^{\frac{\ln |t|}{2} + C}$$

$$\begin{aligned} w &= e^C \cdot e^{\frac{\ln |t|}{2}} \\ &= C' \cdot (e^{\ln |t|})^{1/2} \\ &= C' \cdot t^{1/2} \end{aligned}$$

**Note:** If we just want  $y_2$ , we can let  $C' = 1$ .

$$w = t^{1/2}$$

Now, we will solve for  $v$ .

$$v' = w$$

$$v = \int w dt$$

$$= \int t^{1/2} dt \rightarrow \int x^n dx = \frac{x^{n+1}}{n+1}$$

$$= \frac{2}{3} t^{3/2}$$

$$y_2 = v y_1$$

$$= \left( \frac{2}{3} t^{3/2} \right) \left( \frac{1}{t} \right)$$

$$= \frac{2}{3} t^{1/2}$$



**Note:** Letting  $y_2 = v y_1$  is called **D'Alembert's step**. When you do it,  $y_1$  and  $y_2$  always make a fundamental pair of solns.

**Note:** If the question also asks to verify that  $y_1$  and  $y_2$  are a fundamental pair of solns, show that  $W \neq 0$ .

I.e. In our example  $y_1 = \frac{1}{t}$ ,  $y_2 = \frac{2}{3} t^{1/2}$

$$\begin{aligned} W &= \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} \\ &= \begin{vmatrix} \frac{1}{t} & \frac{2}{3} t^{1/2} \\ -\frac{1}{t^2} & \frac{1}{3} t^{-1/2} \end{vmatrix} \\ &= \left(\frac{1}{t}\right)\left(\frac{1}{3} t^{-1/2}\right) - \left(-\frac{1}{t^2}\right)\left(\frac{2}{3} t^{1/2}\right) \\ &= \frac{1}{3t^{3/2}} + \frac{2}{3t^{3/2}} \\ &= \frac{1}{t^{3/2}} \\ &\neq 0 \end{aligned}$$

**Note:** The steps I did to find  $y_2$  were used that  $v$  has to go. On assignments/quizzes/tests, you don't have to show all those steps. Here are the steps you should do on tests/quizzes/assignments.

$$2t^2 (v''(\frac{1}{t}) + 2v'(\frac{1}{t})' + v(\frac{1}{t})'') + 3t(v'(\frac{1}{t}) + v(\frac{1}{t})') - v(\frac{1}{t}) = 0$$



Ignore all terms with a  $v$ .

**Note:** If you expand and simplify, you'll find that the terms with  $v$  cancel out.

$$\frac{2t^2 v''}{t} + \frac{4t^2 v'}{-t^2} + \frac{3tv'}{t} = 0$$

$$2tv'' - 4v' + 3v' = 0$$

$$2tv'' - v' = 0$$

Let  $w = v'$  and  $w' = v''$ .

$$2t \frac{dw}{dt} = w$$

$$\frac{1}{w} dw = \frac{1}{2t} dt$$

$$\int \frac{1}{w} dw = \int \frac{1}{2t} dt$$

$$\ln|w| + C_1 = \frac{\ln|t|}{2} + C_2$$

$$\ln|w| = \frac{\ln|t|}{2} + c$$

$$w = c' \cdot t^{1/2} \\ = t^{1/2}$$

$$v' = w$$

$$v = \int w dt$$

$$= \int t^{1/2} dt$$

$$= \frac{2}{3} t^{3/2}$$

$$y_2 = \frac{2t^{3/2}}{3}, y_1$$

$$= \frac{2}{3} t^{3/2} \cdot \frac{1}{t}$$

$$= \frac{2}{3} t^{1/2}$$



**Note:** Another way to solve for  $y_2$  is to use Abel's formula. Here, it is crucial that the coefficient of  $y''$  is 1.

$$2t^2 y'' + 3ty' - y = 0$$

$$y'' + \frac{3y'}{2t} - \frac{y}{2t^2} = 0$$

Now, apply Abel's formula.

$$w_1 = C' e^{-\int p(t) dt}$$

$$= C' e^{-\int \frac{3}{2t} dt}$$

$$= C' e^{-\frac{3}{2} \int \frac{1}{t} dt}$$

$$= C' e^{-\frac{3}{2} \ln|t| + C_1}$$

$$= C' \cdot C_1 \cdot t^{-3/2}$$

$$= \frac{C}{t^{3/2}} \leftarrow \text{Take } C=1$$

$$= \frac{1}{t^{3/2}}$$

Another way to compute  $w_1$ .

$$w_2 = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$$

$$= y_1 y_2' - y_1' y_2$$

$$= \frac{y_2'}{t} + \frac{y_2}{t^2}$$



$$\omega_1 = \omega_2$$

$$\frac{1}{t^{3/2}} = \frac{y_2'}{t} + \frac{y_2}{t^2}$$

$$y_2' + \frac{y_2}{t} = \frac{1}{t^{1/2}} \leftarrow \text{Linear Diff Eqn First order}$$

$$\mu(y_2') + \frac{\mu y_2}{t} = \frac{\mu}{t^{1/2}}$$

$$\text{LHS} = (\mu y_2)'$$

$$\cancel{\mu(y_2')} + \frac{\mu y_2}{t} = (\mu y_2)'$$

$$= \mu' y_2 + \cancel{\mu y_2'}$$

$$\frac{\mu y_2}{t} = \mu' y_2$$

$$\frac{1}{t} = \frac{\mu'}{\mu}$$

$$= (\ln(\mu))'$$

$$\int \frac{1}{t} dt = \ln(\mu)$$

$$\ln|t| + C = \ln(\mu)$$

$$\mu = t$$

$$(\mu y_2)' = \frac{\mu}{t^{1/2}}$$

$$(\mu y_2)' = \frac{t}{t^{1/2}}$$

$$= t^{1/2}$$

$$t y_2 = \int t^{1/2} dt$$

$$= \frac{2}{3} t^{3/2} + C$$

$$y_2 = \frac{2}{3} t^{1/2} + \frac{C}{t} \rightarrow y_2 = \frac{2}{3} t^{1/2}$$

Let this be 0.