0.29298

Robot3

User robot choice data imported successfully. Initializing R bridge... Estimated Parameters: phi1: 2.5417 phi2: 0.1 tau: 22027.4658 error sd: 0.1 Initial Preferences (from ASCs): 0.0141 0.0131 0 === Trial Analysis === Trial: 1 Participant: 125802 Actual Choice: Robot 3 M matrix (alternatives × attributes): C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy 🗸 Nav, High Exposure C4 - Hard Nav, High Exposure Robot1 0.758 0.39006 ዾ 0.015007 0.38295 Robot2 0.75062 0.42345 ⊭ 0.34143 0.014269 Robot3 0.68271 0.33475 ⊭ 0.35544 0.01 DFT Results: E P: -12.32 -6.58 18.91 Choice probabilities: 0.000 0.000 1.000 Predicted choice: Robot 3 Actual choice: Robot 3 ✓ Prediction matches actual choice === Trial Analysis === Trial: 2 Participant: 125802 Actual Choice: Robot 1 M matrix (alternatives × attributes): C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy 🛂 Nav, High Exposure C4 - Hard Nav, High Exposure 0.6831 0.32233 ዾ Robot1 0.01 0.36828 0.62413 0.33277 ⊭ Robot2

0.01

0.29477 ⊭

0.57014

0.27159 0.01

DFT Results:

E_P: -27.51 -3.17 30.68

Choice probabilities: 0.000 0.000 1.000

Predicted choice: Robot 3
Actual choice: Robot 1

X Prediction differs from actual choice

=== Trial Analysis ===

Trial: 3

Participant: 141831 Actual Choice: Robot 3

M matrix (alternatives × attributes):

C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy 🗸

Nav, High Exposure C4 - Hard Nav, High Exposure

Robot1 0.65342 0.24903 \(\begin{align*} 0.40894 & 0.01 & 0.42192 \(\begin{align*} 0.39776 & 0.019249 & 0.44356 \(\begin{align*} 0.42839 & 0.024001 & 0.024001 & 0.024001 & 0.024001 & 0.024001 & 0.024903 \(\begin{align*} 0.24903 \times & 0.44356 \(\begin{align*} 0.42839 & 0.024001 & 0.024001 & 0.024001 & 0.024903 \times & 0.024903 \tim

DFT Results:

E_P: 11.44 -2.09 -9.35

Choice probabilities: 1.000 0.000 0.000

Predicted choice: Robot 1 Actual choice: Robot 3

X Prediction differs from actual choice

=== Trial Analysis ===

Trial: 4

Participant: 125802 Actual Choice: Robot 2

M matrix (alternatives × attributes):

C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy 🗸

Nav, High Exposure C4 - Hard Nav, High Exposure

Robot1	0.7667	0.47769 Ľ
0.30489	0.015877	
Robot2	0.76424	0.45273 Ľ
0.32714	0.01563	
Robot3	0.83484	0.4868 Ľ
0.37073	0.022691	

DFT Results:

E P: 5.67 8.29 -13.96

Choice probabilities: 0.000 1.000 0.000

Predicted choice: Robot 2 Actual choice: Robot 2

 \checkmark Prediction matches actual choice

=== Trial Analysis ===

Trial: 5

Participant: 125802 Actual Choice: Robot 2

M matrix (alternatives × attributes):

C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy 🗸

Nav, High Exposure C4 - Hard Nav, High Exposure

Robot1	0.99868	0.5267 Ľ
0.51106	0.039075	
Robot2	0.82271	0.41973 Ľ
.42445	0.021478	
Robot3	0.88322	0.45201 ⊭
0.45873	0.027529	

DFT Results:

E_P: -12.96 10.58 2.38

Choice probabilities: 0.000 1.000 0.000

Predicted choice: Robot 2 Actual choice: Robot 2

 \checkmark Prediction matches actual choice

=== Trial Analysis ===

Trial: 6

Participant: 141831 Actual Choice: Robot 2

M matrix (alternatives × attributes):

C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy 🗸

Nav, High Exposure C4 - Hard Nav, High Exposure

		∠
Robot1	1	0.56688 ⊭
0.4757	0.039514	
Robot2	0.97999	0.56048 Ľ
0.45672	0.037206	
Robot3	0.96385	0.51549 Ľ
0.48396	0.035592	

DFT Results:

E_P: -7.98 1.03 6.95

Choice probabilities: 0.000 0.000 1.000

Predicted choice: Robot 3 Actual choice: Robot 2

X Prediction differs from actual choice

=== Trial Analysis ===

Trial: 7

Participant: 141831 Actual Choice: Robot 3

M matrix (alternatives × attributes):

C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy 🗸

Nav, High Exposure C4 - Hard Nav, High Exposure

Robot1 0.8221 0.43192

0.4116 0.021417

Robot2 0.89145 0.48402

0.43578 0.028352

Robot3 0.91995 0.49952

0.45163 0.031202

DFT Results:

E P: 14.92 -3.59 -11.33

Choice probabilities: 1.000 0.000 0.000

Predicted choice: Robot 1 Actual choice: Robot 3

X Prediction differs from actual choice

=== Trial Analysis ===

Trial: 8

Participant: 125802 Actual Choice: Robot 1

M matrix (alternatives × attributes):

C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy 🗹

Nav, High Exposure C4 - Hard Nav, High Exposure

Robot1 0.83805 0.49172

0.36935 0.023012

Robot2 0.68565 0.34671

Robot3 0.72531 0.37528

0.36177 0.011738

DFT Results:

Ľ

E_P: -11.60 13.90 -2.30

Choice probabilities: 0.000 1.000 0.000

Predicted choice: Robot 2 Actual choice: Robot 1

X Prediction differs from actual choice

=== Trial Analysis ===

Trial: 9

Participant: 125802 Actual Choice: Robot 1

M matrix (alternatives × attributes):

C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy 🗸

Nav, High Exposure C4 - Hard Nav, High Exposure

Robot1	0.65311	0.35537 ⊭	
0.30227	0.01		
Robot2	0.77891	0.43516 Ľ	
0.36085	0.017098		
Robot3	0.72616	0.41203 Ľ	
0.32596	0.011823		

DFT Results:

E_P: 26.29 -17.41 -8.88

Choice probabilities: 1.000 0.000 0.000

Predicted choice: Robot 1 Actual choice: Robot 1

✓ Prediction matches actual choice

=== Trial Analysis ===

Trial: 10

Participant: 125802 Actual Choice: Robot 2

M matrix (alternatives × attributes):

C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy 🗸

Nav, High Exposure C4 - Hard Nav, High Exposure

Robot1	0.89681	0.47678 Ľ
0.44891	0.028888	
Robot2	0.8398	0.4511 Ľ
0.41189	0.023187	
Robot3	0.93874	0.52389 ⊭
0.44793	0.033081	

DFT Results:

E_P: -1.62 14.15 -12.53

Choice probabilities: 0.000 1.000 0.000

Predicted choice: Robot 2 Actual choice: Robot 2

 \checkmark Prediction matches actual choice

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