User robot choice data imported successfully. Initializing R bridge... Estimated Parameters: phil: 1.9594 phi2: 0.1 tau: 22027.4658 error sd: 0.1 Initial Preferences (from ASCs): 0.0149 0.0146 0 === Trial Analysis === Trial: 1 Participant: 125802 Actual Choice: Robot 1 M matrix (alternatives × attributes): C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy 🗸 Nav, High Exposure C4 - Hard Nav, High Exposure Robot1 0.30736 0.63124 0.34013 ዾ 0.016247 Robot2 0.63633 0.35335 ⊭ 0.29973 0.016756 Robot3 0.57448 0.29476 ⊭ 0.29029 0.010571 DFT Results: E P: -6.34 18.47 -12.13 Choice probabilities: 0.000 1.000 0.000 Predicted choice: Robot 2 Actual choice: Robot 1 X Prediction differs from actual choice === Trial Analysis === Trial: 2 Participant: 141831 Actual Choice: Robot 3 M matrix (alternatives × attributes): C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy 🛂 Nav, High Exposure C4 - Hard Nav, High Exposure Robot1 0.62828 0.24666 ⊭ 0.015951 0.39756

0.40981 ⊭

0.43023 ⊭

0.767

Robot3 0.81184

0.029824

Robot2

0.38702

0.41592 0.034308

DFT Results:

E_P: -37.06 38.46 -1.41

Choice probabilities: 0.000 1.000 0.000

Predicted choice: Robot 2 Actual choice: Robot 3

X Prediction differs from actual choice

=== Trial Analysis ===

Trial: 3

Participant: 141831 Actual Choice: Robot 3

M matrix (alternatives × attributes):

C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy 🗸

Nav, High Exposure C4 - Hard Nav, High Exposure

Robot1	0.7426	0.40539 ⊭
0.36459	0.027383	
Robot2	0.81966	0.43443 Ľ
0.42032	0.035089	
Robot3	0.75922	0.45109 Ľ
0.33718	0.029045	

DFT Results:

E_P: -17.23 -12.78 30.02

Choice probabilities: 0.000 0.000 1.000

Predicted choice: Robot 3 Actual choice: Robot 3

 \checkmark Prediction matches actual choice

=== Trial Analysis ===

Trial: 4

Participant: 141831 Actual Choice: Robot 2

M matrix (alternatives × attributes):

C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy 🗸

Nav, High Exposure C4 - Hard Nav, High Exposure

		k
Robot1	0.70338	0.42149 Ľ
0.30534	0.023461	
Robot2	0.73631	0.45985 Ľ
0.30321	0.026754	
Robot3	0.67241	0.38387 Ľ
0.30891	0.020365	

DFT Results:

E P: 0.64 31.52 -32.16

Choice probabilities: 0.000 1.000 0.000

Predicted choice: Robot 2 Actual choice: Robot 2

✓ Prediction matches actual choice

=== Trial Analysis ===

Trial: 5

Participant: 125802 Actual Choice: Robot 2

M matrix (alternatives × attributes):

C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy 🗸

Nav, High Exposure C4 - Hard Nav, High Exposure

Dobo+1	0.00004	0.49389 ⊭
Robot1	0.98664	0.49389
0.54454	0.051787	
Robot2	0.93322	0.49881 Ľ
0.48085	0.046445	
Robot3	1	0.513 ⊭
0.54013	0.053123	

DFT Results:

E_P: -20.55 21.57 -1.02

Choice probabilities: 0.000 1.000 0.000

Predicted choice: Robot 2 Actual choice: Robot 2

 \checkmark Prediction matches actual choice

=== Trial Analysis ===

Trial: 6

Participant: 141831 Actual Choice: Robot 1

M matrix (alternatives × attributes):

C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy 🗸

Nav, High Exposure C4 - Hard Nav, High Exposure

		v
Robot1	0.60885	0.33068 Ľ
0.29218	0.014008	
Robot2	0.56476	0.32263 Ľ
0.25173	0.01	
Robot3	0.46877	0.18594 Ľ
0.28283	0.01	

K

DFT Results:

E P: 1.02 36.58 -37.60

Choice probabilities: 0.000 1.000 0.000

Predicted choice: Robot 2 Actual choice: Robot 1

X Prediction differs from actual choice

=== Trial Analysis ===

Trial: 7

Participant: 141831 Actual Choice: Robot 3

M matrix (alternatives × attributes):

C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy 🗸

Nav, High Exposure C4 - Hard Nav, High Exposure

Robot1	0.89792	0.51496 Ľ
0.42588	0.042915	
Robot2	0.8563	0.4713 k
0.42376	0.038753	
Robot3	0.912	0.527 Ľ
0.42933	0.044324	

DFT Results:

E P: 9.22 -21.69 12.46

Choice probabilities: 0.000 0.000 1.000

Predicted choice: Robot 3 Actual choice: Robot 3

✓ Prediction matches actual choice

=== Trial Analysis ===

Trial: 8

Participant: 141831 Actual Choice: Robot 2

M matrix (alternatives × attributes):

C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy 🗸

Nav, High Exposure C4 - Hard Nav, High Exposure

Robot1	0.75528	0.424 Ľ
0.35993	0.028651	
Robot2	0.79511	0.44213 Ľ
0.38561	0.032635	
Robot3	0.6814	0.35012 Ľ
0.35254	0.021263	

DFT Results:

E_P: 25.51 -6.52 -18.99

Choice probabilities: 1.000 0.000 0.000

Predicted choice: Robot 1 Actual choice: Robot 2

X Prediction differs from actual choice

=== Trial Analysis ===

Trial: 9

Participant: 125802 Actual Choice: Robot 2

M matrix (alternatives × attributes):

C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy 🗸

Nav, High Exposure C4 - Hard Nav, High Exposure

		
Robot1	0.66226	0.37703 ⊭
0.30458	0.019349	
Robot2	0.51638	0.25254 Ľ
0.2686	0.01	
Robot3	0.5161	0.22512 Ľ
0.29571	0.01	

DFT Results:

E_P: 21.58 19.70 -41.28

Choice probabilities: 1.000 0.000 0.000

Predicted choice: Robot 1 Actual choice: Robot 2

X Prediction differs from actual choice

=== Trial Analysis ===

Trial: 10

Participant: 125802 Actual Choice: Robot 2

M matrix (alternatives × attributes):

C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy 🗸

Nav, High Exposure C4 - Hard Nav, High Exposure

		Ľ
Robot1	0.85796	0.46159 ⊭
0.43529	0.038919	
Robot2	0.80416	0.43735 Ľ
0.40035	0.03354	
Robot3	0.89753	0.50604 k
0.43436	0.042876	

DFT Results:

E_P: -24.29 9.37 14.92

Choice probabilities: 0.000 0.000 1.000

Predicted choice: Robot 3
Actual choice: Robot 2

 $m{\chi}$ Prediction differs from actual choice >>