

User robot choice data imported successfully.

Initializing R bridge...

Estimated Parameters:

phi1: 1.7857

phi2: 0.1

tau: 22027.4658

error_sd: 0.1

Initial Preferences (from ASCs):

0.0147 0.0144 0

=== Trial Analysis ===

Trial: 1

Participant: 141831

Actual Choice: Robot 3

M matrix (alternatives × attributes):

C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy
Nav, High Exposure C4 - Hard Nav, High Exposure

Robot1	0.76903		0.47714 ✓
0.3688		0.076903	
Robot2	0.68421		0.45711 ✓
0.29552		0.068421	
Robot3	0.75055		0.44632 ✓
0.37929		0.075055	

DFT Results:

E_P: 6.16 18.26 -24.41

Choice probabilities: 0.000 1.000 0.000

Predicted choice: Robot 2

Actual choice: Robot 3

X Prediction differs from actual choice

=== Trial Analysis ===

Trial: 2

Participant: 125802

Actual Choice: Robot 1

M matrix (alternatives × attributes):

C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy
Nav, High Exposure C4 - Hard Nav, High Exposure

Robot1	0.69073		0.39646 ✓
0.36334		0.069073	
Robot2	0.69587		0.40983 ✓
0.35563		0.069587	
Robot3	0.63335		0.35061 ✓

0.34608

0.063335

DFT Results:

E_P: -6.48 18.43 -11.96

Choice probabilities: 0.000 1.000 0.000

Predicted choice: Robot 2

Actual choice: Robot 1

✗ Prediction differs from actual choice

=== Trial Analysis ===

Trial: 3

Participant: 125802

Actual Choice: Robot 3

M matrix (alternatives × attributes):

	C1 - Easy Nav, Low Exposure	C2 - Hard Nav, Low Exposure	C3 - Easy
Nav, High Exposure	C4 - Hard Nav, High Exposure		✗

Robot1	0.64473	0.31791 ✗
0.39129	0.064473	
Robot2	0.70235	0.35085 ✗
0.42174	0.070235	
Robot3	0.72785	0.37943 ✗
0.42121	0.072785	

DFT Results:

E_P: 6.48 -15.89 9.40

Choice probabilities: 0.000 0.000 1.000

Predicted choice: Robot 3

Actual choice: Robot 3

✓ Prediction matches actual choice

=== Trial Analysis ===

Trial: 4

Participant: 125802

Actual Choice: Robot 3

M matrix (alternatives × attributes):

	C1 - Easy Nav, Low Exposure	C2 - Hard Nav, Low Exposure	C3 - Easy
Nav, High Exposure	C4 - Hard Nav, High Exposure		✗

Robot1	0.78749	0.43651 ✗
0.42973	0.078749	
Robot2	0.78045	0.46837 ✗
0.39013	0.078045	
Robot3	0.71568	0.38375 ✗
0.40349	0.071568	

DFT Results:

E_P: -19.22 46.29 -27.07

Choice probabilities: 0.000 1.000 0.000

Predicted choice: Robot 2

Actual choice: Robot 3

X Prediction differs from actual choice

=== Trial Analysis ===

Trial: 5

Participant: 125802

Actual Choice: Robot 2

M matrix (alternatives × attributes):

C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy Nav, High Exposure C4 - Hard Nav, High Exposure

Robot1	0.96259	0.5409
0.51795	0.096259	
Robot2	0.90815	0.5323
0.46666	0.090815	
Robot3	1	0.58221
0.51779	0.1	

DFT Results:

E_P: -27.69 19.52 8.18

Choice probabilities: 0.000 1.000 0.000

Predicted choice: Robot 2

Actual choice: Robot 2

✓ Prediction matches actual choice

=== Trial Analysis ===

Trial: 6

Participant: 125802

Actual Choice: Robot 1

M matrix (alternatives × attributes):

C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy Nav, High Exposure C4 - Hard Nav, High Exposure

Robot1	0.71364	0.35506
0.42995	0.071364	
Robot2	0.89824	0.53025
0.45781	0.089824	
Robot3	0.88604	0.50277
0.47187	0.088604	

DFT Results:

E_P: -16.65 31.38 -14.73

Choice probabilities: 0.000 1.000 0.000

Predicted choice: Robot 2

Actual choice: Robot 1

X Prediction differs from actual choice

=== Trial Analysis ===

Trial: 7

Participant: 125802

Actual Choice: Robot 1

M matrix (alternatives × attributes):

	C1 - Easy Nav, Low Exposure	C2 - Hard Nav, Low Exposure	C3 - Easy
Nav, High Exposure	C4 - Hard Nav, High Exposure		

Robot1	0.73163		0.3408 ✓
0.464	0.073163		
Robot2	0.87344		0.47121 ✓
0.48957	0.087344		
Robot3	0.86047		0.45145 ✓
0.49507	0.086047		

DFT Results:

E_P: -16.44 20.88 -4.44

Choice probabilities: 0.000 1.000 0.000

Predicted choice: Robot 2

Actual choice: Robot 1

X Prediction differs from actual choice

=== Trial Analysis ===

Trial: 8

Participant: 141831

Actual Choice: Robot 3

M matrix (alternatives × attributes):

	C1 - Easy Nav, Low Exposure	C2 - Hard Nav, Low Exposure	C3 - Easy
Nav, High Exposure	C4 - Hard Nav, High Exposure		

Robot1	0.80329		0.46243 ✓
0.42118	0.080329		
Robot2	0.88118		0.49179 ✓
0.47752	0.088118		
Robot3	0.8201		0.50863 ✓
0.39348	0.08201		

DFT Results:

E_P: -16.90 -14.32 31.23
 Choice probabilities: 0.000 0.000 1.000
 Predicted choice: Robot 3
 Actual choice: Robot 3

✓ Prediction matches actual choice

=== Trial Analysis ===

Trial: 9

Participant: 125802

Actual Choice: Robot 3

M matrix (alternatives × attributes):

C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy Nav, High Exposure C4 - Hard Nav, High Exposure

Robot1	0.75297		0.4466 ✓
0.38167		0.075297	
Robot2	0.69057		0.42302 ✓
0.33661		0.069057	
Robot3	0.7024		0.44856 ✓
0.32408		0.07024	

DFT Results:

E_P: -21.94 -5.19 27.12
 Choice probabilities: 0.000 0.000 1.000
 Predicted choice: Robot 3
 Actual choice: Robot 3

✓ Prediction matches actual choice

=== Trial Analysis ===

Trial: 10

Participant: 141831

Actual Choice: Robot 3

M matrix (alternatives × attributes):

C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy Nav, High Exposure C4 - Hard Nav, High Exposure

Robot1	0.9603		0.57318 ✓
0.48314		0.09603	
Robot2	0.91823		0.52906 ✓
0.48099		0.091823	
Robot3	0.97453		0.58536 ✓
0.48663		0.097453	

DFT Results:

E_P: 9.24 -21.67 12.43

```
Choice probabilities: 0.000  0.000  1.000
Predicted choice: Robot 3
Actual choice: Robot 3
```

```
✓ Prediction matches actual choice
```

```
Saving results to CSV...
```

```
Error using table
```

```
All table variables must have the same number of rows.
```

```
Error in main_BoundingOverwatch (line 302)
```

```
output_table = table(E_P, V_P, P_tau(end,:),)', ...
```

```
>>
```