```
User robot choice data imported successfully.
Initializing R bridge...
Estimated Parameters:
phi1: 0
phi2: 0.1799
tau: 22027.4658
error sd: 1
Initial Preferences (from ASCs):
   0.1118 -1.1965 0
Warning: Matrix is close to singular or badly scaled. Results may be inaccurate. RCOND = \checkmark
7.714168e-17.
> In calculateDFTdynamics (line 70)
In main BoundingOverwatch (line 164)
=== Trial Analysis ===
Trial: 1
Participant: 214504
Actual Choice: Robot 2
M matrix (alternatives × attributes):
             C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy ✓
Nav, High Exposure C4 - Hard Nav, High Exposure
                                                     0.00724 🗹
   Robot1
                      0.01181
0.00575
                               0.00118
                                                     0.00357 ∠
   Robot2
                      0.00589
0.00291
                               0.00059
              0.00944
                                                     0.00623 🗹
   Robot3
0.00416
                               0.00094
DFT Results:
E P: -3.37 3.69 -0.32
Choice probabilities: 0.001 0.981 0.018
Predicted choice: Robot 2
Actual choice: Robot 2
✓ Prediction matches actual choice
Warning: Matrix is close to singular or badly scaled. Results may be inaccurate. RCOND = ✓
7.714168e-17.
> In calculateDFTdynamics (line 70)
In main BoundingOverwatch (line 164)
=== Trial Analysis ===
Trial: 2
Participant: 214504
Actual Choice: Robot 1
M matrix (alternatives × attributes):
          C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy ✓
Nav, High Exposure C4 - Hard Nav, High Exposure
```

		∠
Robot1	0.0082	0.00519 <b></b>
0.00383	0.00082	
Robot2	0.00947	0.00601 <b>Ľ</b>
0.0044	0.00095	/
Robot3	0.00782	0.00526 🗹
0.00334	0.00078	
DFT Results:		
E_P: 0.88 -2.22		
	ies: 0.381 0.017 0.602	
Predicted choice:		
Actual choice: Ro	bot 1	
Warning: Matrix i 7.714168e-17. > In calculateDFT	Fers from actual choice s close to singular or badly sed dynamics (line 70) everwatch (line 164)	caled. Results may be inaccurate. RCOND = $\checkmark$
C1	bot 3 tives × attributes):	- Hard Nav, Low Exposure C3 - Easy✔ ure
Robot1	0.02779	0.01602 <b></b>
0.01455	0.00278	
Robot2	0.02613	0.01548 🗹
0.01326	0.00261	
Robot3	0.02291	0.01338 ⊭
0.01181	0.00229	
DFT Results: E_P: -2.69 -1.77 Choice probabilit Predicted choice: Actual choice: Ro	ies: 0.001 0.002 0.997 Robot 3	
	ches actual choice s close to singular or badly so	caled. Results may be inaccurate. RCOND = 🗷

Warning: Matrix is close to singular or badly scaled. Results may be inaccurate. RCOND =  $\checkmark$  7.714168e-17.

> In calculateDFTdynamics (line 70)
In main\_BoundingOverwatch (line 164)

Predicted choice: Robot 3
Actual choice: Robot 3

=== Trial Analysis === Trial: 4 Participant: 214504 Actual Choice: Robot 1 M matrix (alternatives × attributes): C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy ✓ Nav, High Exposure C4 - Hard Nav, High Exposure Robot1 0.00805 0.0045 🗹 0.00436 0.00081 Robot2 0.00969 🗹 0.01617 0.00809 0.00162 Robot3 0.0117 0.0077 ∠ 0.00517 0.00117 DFT Results: E P: 6.09 -6.72 0.63 Choice probabilities: 0.996 0.000 0.004 Predicted choice: Robot 1 Actual choice: Robot 1 ✓ Prediction matches actual choice Warning: Matrix is close to singular or badly scaled. Results may be inaccurate. RCOND = ✓ 7.714168e-17. > In calculateDFTdynamics (line 70) In main BoundingOverwatch (line 164) === Trial Analysis === Trial: 5 Participant: 214504 Actual Choice: Robot 3 M matrix (alternatives × attributes): C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy ✔ Nav, High Exposure C4 - Hard Nav, High Exposure Robot1 0.01181 0.00773 **∠** 0.00525 0.00118 Robot2 0.00463 🗹 0.00802 0.0042 0.0008 Robot3 0.00544 🗹 0.00883 0.00428 0.00088 DFT Results: E P: -2.84 1.37 1.47 Choice probabilities: 0.007 0.472 0.521

```
✓ Prediction matches actual choice
Warning: Matrix is close to singular or badly scaled. Results may be inaccurate. RCOND = \checkmark
7.714168e-17.
> In calculateDFTdynamics (line 70)
In main BoundingOverwatch (line 164)
=== Trial Analysis ===
Trial: 6
Participant: 181700
Actual Choice: Robot 3
M matrix (alternatives × attributes):
           C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy ✓
Nav, High Exposure C4 - Hard Nav, High Exposure
   Robot1 0.01272
                                                0.00704 🗹
0.00695
                      0.00127
   Robot2 0.01643
                                             0.00918 ≰
0.0089
                     0.00164
   Robot3 0.01124
                                                 0.00623 ∠
                           0.00112
0.00613
DFT Results:
E P: 1.40 -5.12 3.72
Choice probabilities: 0.090 0.000 0.910
Predicted choice: Robot 3
Actual choice: Robot 3
✓ Prediction matches actual choice
Warning: Matrix is close to singular or badly scaled. Results may be inaccurate. RCOND = ✓
7.714168e-17.
> In calculateDFTdynamics (line 70)
In main BoundingOverwatch (line 164)
=== Trial Analysis ===
Trial: 7
Participant: 181700
Actual Choice: Robot 2
M matrix (alternatives × attributes):
         C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy ✓
Nav, High Exposure C4 - Hard Nav, High Exposure
  Robot1
                    0.02763
                                                 0.01521 🗹
0.01518
                      0.00276
   Robot2
                     0.01524
                                                 0.00822 🗹
0.00854
                           0.00152
   Robot3
                    0.0223
                                                 0.01303 🗹
```

```
0.0115
                              0.00223
DFT Results:
E P: -7.70 8.34 -0.64
Choice probabilities: 0.000 1.000 0.000
Predicted choice: Robot 2
Actual choice: Robot 2
✓ Prediction matches actual choice
Warning: Matrix is close to singular or badly scaled. Results may be inaccurate. RCOND = \checkmark
7.714168e-17.
> In calculateDFTdynamics (line 70)
In main BoundingOverwatch (line 164)
=== Trial Analysis ===
Trial: 8
Participant: 181700
Actual Choice: Robot 1
M matrix (alternatives × attributes):
             C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy ✓
Nav, High Exposure C4 - Hard Nav, High Exposure
   Robot1 0.01689
                                                      0.0102 🗹
0.00838
                               0.00169
                                                      0.01025 🗹
   Robot2
                       0.01739
0.00888
                            0.00174
   Robot3
                                                      0.01408 🗹
                       0.02256
0.01074
                               0.00226
DFT Results:
E P: 3.59 1.63 -5.22
Choice probabilities: 0.876 0.124 0.000
Predicted choice: Robot 1
Actual choice: Robot 1
✓ Prediction matches actual choice
Warning: Matrix is close to singular or badly scaled. Results may be inaccurate. RCOND = \checkmark
7.714168e-17.
> In calculateDFTdynamics (line 70)
In main BoundingOverwatch (line 164)
=== Trial Analysis ===
Trial: 9
Participant: 214504
Actual Choice: Robot 1
M matrix (alternatives × attributes):
             C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy 🗸
Nav, High Exposure C4 - Hard Nav, High Exposure
```

X Prediction differs from actual choice

>>

Robot1 0.0119 0.00741 🗹 0.00568 0.00119 Robot2 0.0042 🗹 0.00712 0.00363 0.00071 Robot3 0.00884 0.00525 🗹 0.00448 0.00088 DFT Results: E P: -3.28 2.22 1.06 Choice probabilities: 0.003 0.760 0.237 Predicted choice: Robot 2 Actual choice: Robot 1 X Prediction differs from actual choice Warning: Matrix is close to singular or badly scaled. Results may be inaccurate. RCOND = ✓ 7.714168e-17. > In calculateDFTdynamics (line 70) In main BoundingOverwatch (line 164) === Trial Analysis === Trial: 10 Participant: 214504 Actual Choice: Robot 3 M matrix (alternatives × attributes): C1 - Easy Nav, Low Exposure C2 - Hard Nav, Low Exposure C3 - Easy✔ Nav, High Exposure C4 - Hard Nav, High Exposure Robot1 0.00806 0.00523 **L** 0.00363 0.00081 Robot2 0.00562 0.0037 🗹 0.00249 0.00056 0.01058 Robot3 0.00618 🗹 0.00546 0.00106 DFT Results: E P: 0.61 2.73 -3.33 Choice probabilities: 0.107 0.891 0.002 Predicted choice: Robot 2 Actual choice: Robot 3