view_frames Result Recorded at time: 1507738828.526 footprint Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1507738828.526 sec old) Buffer length: 0.000 sec ax12a_1 Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1507738828.504 (0.022 sec old) Buffer length: 4.900 sec cradle_base Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1507738828.526 sec old) Most recent transform: 0.000 (1507738828.526 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec rh_side rectangular_side_part Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10.204 Hz Average rate: 10000.000 Hz Most recent transform: 1507738828.504 (0.022 sec old) Most recent transform: 0.000 (1507738828.526 sec old) Most recent transform: 0.000 (1507738828.526 sec old) Buffer length: 4.900 sec Buffer length: 0.000 sec Buffer length: 0.000 sec $ax12a_3$ ax12a_2 straight_lever_2 Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Average rate: 10.204 Hz Most recent transform: 1507738828.504 (0.022 sec old) Most recent transform: 1507738828.504 (0.022 sec old) Buffer length: 4.900 sec Buffer length: 4.900 sec servo_mounting_arm central_lever Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Average rate: 10.204 Hz Most recent transform: 1507738828.504 (0.022 sec old) Most recent transform: 1507738828.504 (0.022 sec old) Buffer length: 4.900 sec Buffer length: 4.900 sec straight_lever triangular_piece Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1507738828.504 (0.022 sec old) Buffer length: 4.900 sec forearm_lever