Nemanja Rakićević





Research interests

- Uncertainty-based efficient exploration methods

- Deep reinforcement learning, generative models, probabilistic graphical models

Education

2016 – now	PhD Candidate Robot Intelligence Lab, Imperial College London
2011 – 2013	European Master On Advanced Robotics (EMARO), double degree program. Thesis development: Keio University, Japan 2nd year: Ecole Centrale de Nantes, grade average A 1st year: University of Genova, grade average A
2007 – 2011	Mechatronics, Robotics and Automatization, Faculty of Technical Sciences, University of Novi Sad. 240 ECTS, grade average 10 [100/100]

Employment and academic activities

2019-07	Attended: Machine Learning Summer School, London, UK		
2018-09 – 2019-01	Research Intern: DeepMind, London, UK		
2017-(06 – 08)	Data Scientist: Human (previously CitySail), London, UK Developing and implementing models for real-time human personality estimation.		
2015-01 – 2016-05	Research Assistant: iBug group, Imperial College London, UK Sequential probabilistic models for emotion recognition based on facial expressions and audio data. Multimodal Neural Conditional Random Fields for Behaviour Analysis.		
2015 –	Graduate Teaching Assistant: Imperial College London, UK Machine Learning (prof Maja Pantic), Computing II, Robotics (Dr Petar Kormushev) Data Structures and Algorithms (Dr Heikki Peura)		
2013-12 – 2014-07	Research Engineer: RIS group, LAAS-CNRS, Toulouse, France. Rover locomotion diagnostics based on proprioceptive sensor feeds.		
2013-07	MSc thesis testing sessions: Japanese Aerospace Exploration Agency's (JAXA) Institute of Space and Astronautical Science on the "Cuatro" rover test bed		
2011	Team leader: National robotics competition (EUROBOT)		
2010-(09 – 10)	Intern: "Mihajlo Pupin" Institute, Belgrade, Serbia Robotic gripper and small rover movement programming. [Supervisor: Professor Aleksandar Rodić]		

Publications

RP Saputra, **N Rakicevic**, P Kormushev. "Sim-to-Real Learning for Casualty Detection from Ground Projected Point Cloud Data", IROS, 2019

N Rakicevic, P Kormushev. "Active Learning via Informed Search in Movement Parameter Space for Efficient Robot Task Learning and Transfer", AURO, 2019

N Rakicevic, P Kormushev. "Efficient Robot Task Learning and Transfer via Informed Search in Movement Parameter Space", AIRW (NIPS), 2017

N Rakicevic, O Rudovic, S Petridis, M Pantic. "Multi-Modal Neural Conditional Ordinal Random Fields for Dynamic Agreement Level Classification", ICPR, 2016

N Rakicevic, O Rudovic, S Petridis, M Pantic. "Neural Conditional Ordinal Random Fields for Agreement Level Estimation", WASA, 2015.

Courses and projects

IVISC:		
M1	Control of Multivariable Systems, Real-Time Systems, Neural Networks,	
	Computer Vision, Mechanical Design Methods, Optimization Techniques,	
	Embedded Systems, Artificial Intelligence (Machine Learning), Mobile Robot	

Embedded Systems, Artificial Intelligence (Machine Learning), Mobile Robotics; Group project - building an underwater robot to compete at the NURC SAUC-E

2012 (mechanical, control and electronics design) [Supervisor: Professor Giuseppe Casalino]

M2 Vision Based Control, Advanced Modeling of Robots, Identification and Control of

Robots, Humanoid and Walking Robots, Capture and Simulation of Human

Motion;

Keio Aerospace Propulsion, Mixed Reality, Space Systems Engineering;

Thesis Topic - "Guidance, Navigation and Control for Planetary Rover" [Supervisors: Professors Masaki Takahashi, Philippe Martinet and Giuseppe

Casalino]

BSc: Electronics (analog, digital), Industrial Robotics, PLC Programming, Mechanics,

Automated Control Systems, Microprocessor Electronics, Optimization Methods, Machine Mechanics (mechanisms), Components of Technological Systems

(pneumatics and hydraulics);

Group project - building a mobile robot to compete at the EUROBOT 2011 competition (group leader; electronics design, movement programming) **Thesis topic** - "Realization of the Robot Sensor System and Motion Control for

the EUROBOT 2011 Competition, within the Team MAXIMILIAN"

[Supervisor: Professor Branislav Borovac]

Awards and recognitions

2016 – 2020	Imperial College London President's PhD Scholarship	
2011 – 2013	Erasmus Mundus scholarship laureate for the EMARO MSc programme	
2010/2011	Declared best student in generation 2010/11, University of Novi Sad	
2010 – 2013	"Dositeja" scholarship laureate, Ministry of Youth and Sport, Republic of Serbia	
2009/2010	University of Novi Sad scholarship laureate	
2008 – 2012	Annual award to exceptional students for their achievements during studies, Ministry of Education, Republic of Serbia	

Skills

Computer skills	[active]	Python, Tensorflow, MuJoCo, PyBullet, LaTeX, Git
	[passive]	MATLAB, C/C++, Solid Edge, Pro/ENGINEER

Languages Serbian, English, Italian, Spanish, French

Hobbies Capoeira Club "Capoeira Associação Sérvia" (since 2005), Surfing, Drawing