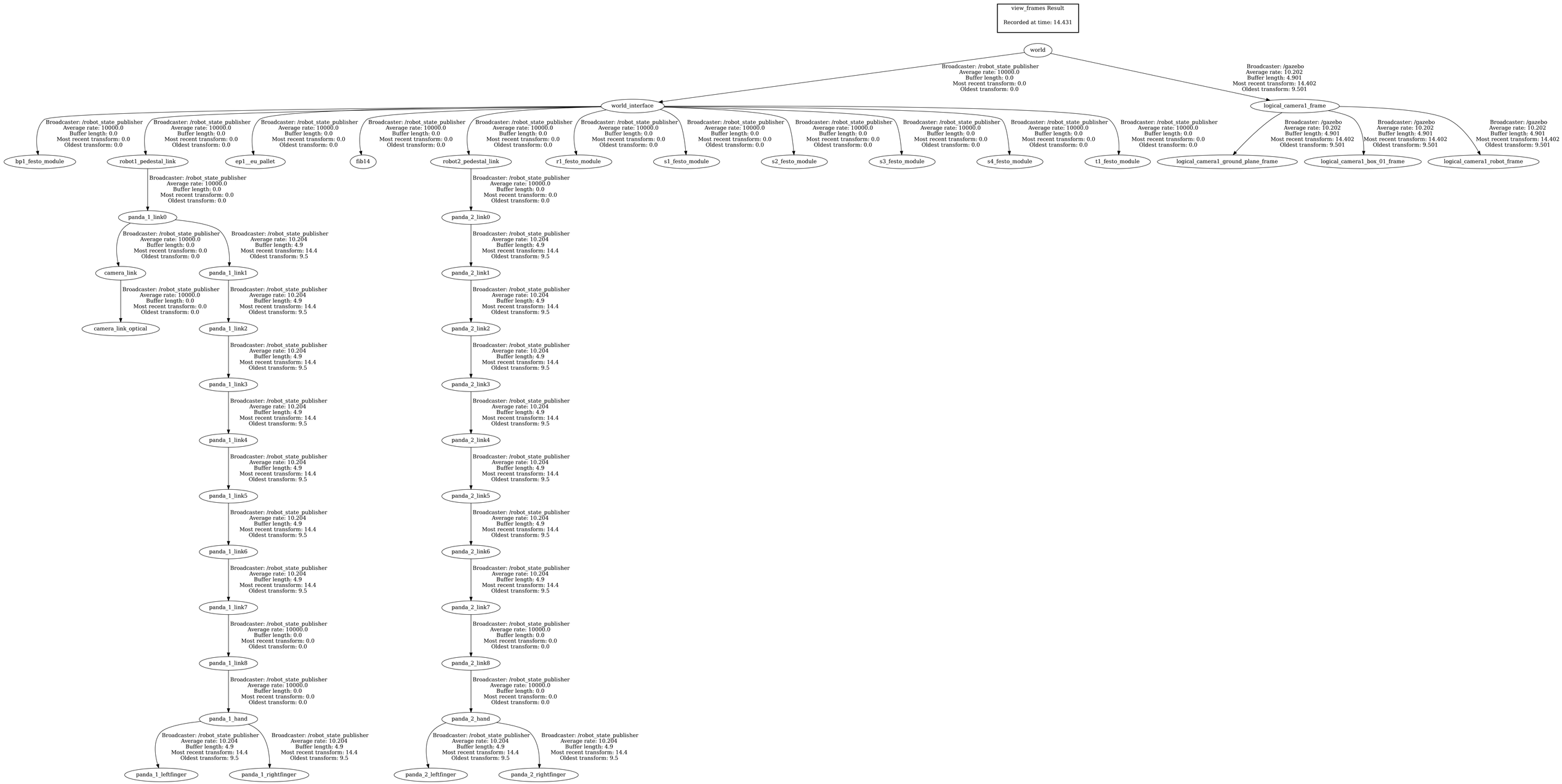
view_frames Result
Recorded at time: 14.431
world
Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
Broadcaster: /gazebo
Average rate: 10.202
Buffer length: 4.901
Most recent transform: 14.402
Oldest transform: 9.501
world_interface
logical_camera1_frame
bp1_festo_module
robot1_pedestal_link
ep1__eu_pallet
fib14
robot2_pedestal_link
r1_festo_module
s1_festo_module
s2_festo_module
s3_festo_module
s4_festo_module
t1_festo_module
logical_camera1_ground_plane_frame
logical_camera1_box_01_frame
logical_camera1_robot_frame
panda_1_link0
camera_link
camera_link_optical
panda_1_link1
panda_1_link2
panda_1_link3
panda_1_link4
panda_1_link5
panda_1_link6
panda_1_link7
panda_1_link8
panda_1_hand
panda_1_leftfinger
panda_1_rightfinger
panda_2_link0
panda_2_link1
panda_2_link2
panda_2_link3
panda_2_link4
panda_2_link5
panda_2_link6
panda_2_link7
panda_2_link8
panda_2_hand
panda_2_leftfinger
panda_2_rightfinger