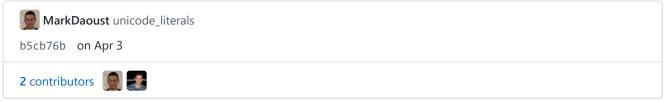
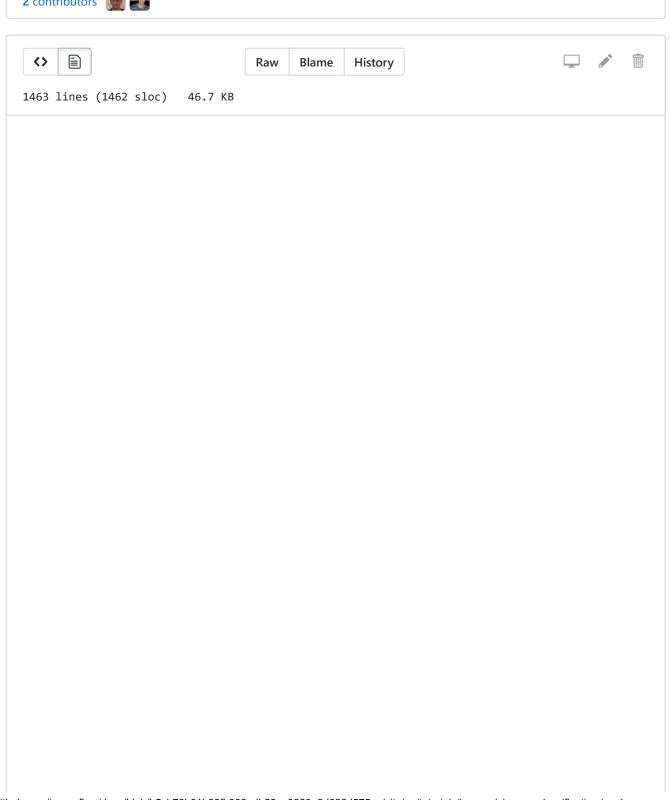
Tree: b5cb76b01b ▼ Find file Copy path

### docs / site / en / tutorials / images / \_image\_classification.ipynb





#### Copyright 2018 The TensorFlow Authors.

```
In [0]:
        #@title Licensed under the Apache License, Version 2.0 (the "License");
        # you may not use this file except in compliance with the License.
        # You may obtain a copy of the License at
        # https://www.apache.org/licenses/LICENSE-2.0
        # Unless required by applicable law or agreed to in writing, software
        # distributed under the License is distributed on an "AS IS" BASIS,
        # WITHOUT WARRANTIES OR CONDITIONS OF ANY KIND, either express or impli
        # See the License for the specific language governing permissions and
        # limitations under the License.
```

# Image Classification using tf.keras



View on TensorFlow.org

(https://www.tensorflow.org/images/image\_classification.ipynb) (https://colab.research.google.com/githu

Run in Google Colab

In this tutorial, we will discuss how to classify cats vs dogs from images. We'll build an image classifier using tf.keras.Sequential model and load data using tf.keras.preprocessing.image.ImageDataGenerator.

## Specific concepts that will be covered:

In the process, we will build practical experience and develop intuition around the following concepts

- · Building data input pipelines using the tf.keras.preprocessing.image.ImageDataGeneratorclass — How can we efficiently work with data on disk to interface with our model?
- Overfitting what is it, how to identify it, and how can we prevent it?
- Data Augmentation and Dropout Key techniques to fight overfitting in computer vision tasks that we will incorporate into our data pipeline and image classifier model.

## We will follow the general machine learning workflow:

- 1. Examine and understand data
- 2. Build an input pipeline
- 3. Build our model
- 4. Train our model
- 5. Test our model
- 6. Improve our model/Repeat the process

**Audience:** This post is geared towards beginners with some Keras API and ML background. To get the most out of this post, you should have some basic ML background and know what CNNs are.

## Importing packages

Let's start by importing required packages. **os** package is used to read files and directory structure, **numpy** is used to convert python list to numpy array and to perform required matrix operations and **matplotlib.pyplot** is used to plot the graph and display images in our training and validation data.

```
In [0]: from __future__ import absolute_import, division, print_function, unico
    de_literals
    import os
    import numpy as np
    import matplotlib.pyplot as plt
```

The data we are using is initially available as ".zip" archive file. We are using **zipfile** to extract its contents.

```
In [0]: import zipfile
```

Let's import **Tensorflow as tf** and from **tf.keras**, we need to import different methods to construct our model. Uses of all these methods will be explained as we progress with the tutorial.

## **Data Loading**

In order to build our image classifier, we can begin by downloading the dataset. The dataset we are using is a filtered version of <u>Dogs vs Cats (https://www.kaggle.com/c/dogs-vs-cats/data)</u> dataset from Kaggle. We first need to download the archive version of the dataset and after the download we are storing it to "/tmp/" directory.

After downloading the dataset, we need to extract its contents.

```
In [0]: local_zip = '/tmp/cats_and_dogs_filtered.zip' # local path of downloade
    d .zip file
    zip_ref = zipfile.ZipFile(local_zip, 'r')
```

```
zip_ref.extractall('/tmp') # contents are extracted to '/tmp' folder
zip_ref.close()
```

The dataset we have downloaded has following directory structure.

After extracting its contents, we need to assign variables with the proper file path for training and validation set.

```
In [0]: base_dir = '/tmp/cats_and_dogs_filtered'
train_dir = os.path.join(base_dir, 'train')
validation_dir = os.path.join(base_dir, 'validation')
```

### Understanding our data

Let's look at how many cats and dogs images we have in our training and validation directory

```
In [0]: num_cats_tr = len(os.listdir(train_cats_dir))
    num_dogs_tr = len(os.listdir(train_dogs_dir))

num_cats_val = len(os.listdir(validation_cats_dir))
    num_dogs_val = len(os.listdir(validation_dogs_dir))

total_train = num_cats_tr + num_dogs_tr
    total_val = num_cats_val + num_dogs_val
```

```
In [0]: print('total training cat images:', num_cats_tr)
    print('total training dog images:', num_dogs_tr)

    print('total validation cat images:', num_cats_val)
    print('total validation dog images:', num_dogs_val)
    print('' ")
```

```
print( -- )
print("Total training images:", total_train)
print("Total validation images:", total_val)
```

# **Setting Model Parameters**

For convenience, let us set up variables that will be later used while pre-processing our dataset and training our network.

```
In [0]: batch_size = 100
    epochs = 15
    IMG_SHAPE = 150 # Our training data consists of images with width of 15
    0 pixels and height of 150 pixels
```

## **Data Preparation**

Images should be formatted into appropriately pre-processed floating point tensors before being fed into the network. The steps involving preparing these images are:

- 1. Read images from the disk
- Decode contents of these images and convert it into proper grid format as per their RGB content
- 3. Convert them into floating point tensors
- 4. Rescale the tensors from values between 0 and 255 to values between 0 and 1, as neural networks prefer to deal with small input values.

Fortunately, all these tasks can be done using a single class provided in **tf.keras** preprocessing module, called **ImageDataGenerator**. Not only it can read images from the disks and preprocess images into proper tensors, but it will also set up generators that will turn these images into batches of tensors, which will be very helpful while training our network as we need to pass our input to the network in the form of batches.

We can easily set up this using a couple of lines of code.

After defining our generators for training and validation images, **flow\_from\_directory** method will load images from the disk and will apply rescaling and will resize them into required dimensions using single line of code.

```
practice to shuffle the training data

shuffle=True,
target_size=(IMG_S

HAPE,IMG_SHAPE), #(150,150)

class_mode='binar
y')
```

### Visualizing Training images

We can visualize our training images by using following lines of code which will first extract a batch of images from training generator, which is 32 images in our case and then we will plot 5 of them using **matplotlib** 

```
In [0]: sample_training_images, _ = next(train_data_gen)
```

**next** function returns a batch from the dataset. The return value of **next** function is in form of (x\_train, y\_train) where x\_train is training features and y\_train, its labels. We are discarding the labels in above situation because we only want to visualize our training images.

```
In [0]: # This function will plot images in the form of a grid with 1 row and 5
    columns where images are placed in each column.

def plotImages(images_arr):
    fig, axes = plt.subplots(1, 5, figsize=(20,20))
    axes = axes.flatten()
    for img, ax in zip( images_arr, axes):
        ax.imshow(img)
    plt.tight_layout()
    plt.show()
```

```
In [0]: plotImages(sample_training_images[:5])
```

## **Model Creation**

The model consists of 3 convolution blocks with max pool layer in each of them. We have a fully connected layer with 512 units on top of it, which is activated by **relu** activation function. Model will output class probabilities based on binary classification which is done by **sigmoid** activation function.

```
In [0]: model = Sequential()
model.add(Conv2D(16, 3, padding='same', activation='relu', input_shape=
```

```
(IMG_SHAPE,IMG_SHAPE, 3,)))
model.add(MaxPooling2D(pool_size=(2, 2)))
model.add(Conv2D(32, 3, padding='same', activation='relu'))
model.add(MaxPooling2D(pool_size=(2, 2)))

model.add(Conv2D(64, 3, padding='same', activation='relu'))
model.add(MaxPooling2D(pool_size=(2, 2)))

model.add(Flatten())
model.add(Dense(512, activation='relu'))
model.add(Dense(1, activation='sigmoid'))
```

### Compiling the model

We will use **ADAM** optimizer as our choice of optimizer for this task and **binary cross entropy** function as a loss function. We would also like to look at training and validation accuracy on each epoch as we train our network, for that we are passing it in the metrics argument.

### **Model Summary**

Let's look at all the layers of our network using **summary** method.

```
In [0]: model.summary()
```

#### Train the model

Its time we train our network. We will use **fit\_generator** function to train our network instead of **fit** function, as we are using **ImageDataGenerator** class to generate batches of training and validation data for our network.

## Visualizing results of the training

Let us now visualize the results we get after training our network.

```
https://github.com/tensorflow/docs/blob/b5cb76b01b96fb936edb29ac0323a2d630d575ac/site/en/tutorials/images/ image classification.ipynb
```

```
In |v|: |acc = nistory.nistory| acc |
        val_acc = history.history['val_acc']
        loss = history.history['loss']
        val_loss = history.history['val_loss']
        epochs range = range(epochs)
        plt.figure(figsize=(8, 8))
        plt.subplot(1, 2, 1)
        plt.plot(epochs_range, acc, label='Training Accuracy')
        plt.plot(epochs_range, val_acc, label='Validation Accuracy')
        plt.legend(loc='lower right')
        plt.title('Training and Validation Accuracy')
        plt.subplot(1, 2, 2)
        plt.plot(epochs range, loss, label='Training Loss')
        plt.plot(epochs_range, val_loss, label='Validation Loss')
        plt.legend(loc='upper right')
        plt.title('Training and Validation Loss')
        plt.show()
```

As we can see from the plots, training accuracy and validation accuracy are off by large margin and our model has achieved only around **70%** accuracy on the validation set, let us analyse what went wrong there and try to increase overall performance of the model.

# **Overfitting**

If we look at the plots above, we can see that training accuracy is increasing linearly over time, whereas validation accuracy stalls around 70% after some time in our training process. Moreover, the difference in accuracy between training and validation accuracy is noticeably large. This is a sign of overfitting.

When we have small number of training examples, our model sometimes learns from noises or unwanted details from our training examples to an extent that it negatively impacts the performance of the model on new examples. This phenomenon is known as overfitting. It simply means that our model will have a hard time generalizing well on a new dataset.

There are multiple ways to fight overfitting in our training process. Two of them is **Data Augmentation** and adding **Dropout** to our model. Let's start with Data Augmentation and see how it will help us to fight overfitting in our model.

To begin, we can clear our previous session and start with a new one.

```
In [0]: # Clear resources
    tf.keras.backend.clear_session()
    epochs = 80
```

# **Data Augmentation**

Overtitting generally occurs when we have small number of training examples. One way to fix this problem is to augment our dataset so that it has sufficient number of training examples. Data augmentation takes the approach of generating more training data from existing training samples, by augmenting the samples via a number of random transformations that yield believable-looking images. The goal is that at training time, your model will never see the exact same picture twice. This helps expose the model to more aspects of the data and generalize better.

In **tf.keras** we can implement this using the same **ImageDataGenerator** class we used before. We can simply pass different transformations we would want to our dataset as a form of arguments and it will take care of applying it to the dataset during our training process.

## Augmenting and visualizing data

We can begin by applying random horizontal flip augmentation to our dataset and see how individual images will look like after the transformation.

### **Applying Horizontal Flip**

We can simply pass **horizontal\_flip** as an argument to our ImageDataGenerator class and set it to **True** to apply this augmentation.

Let's take 1 sample image from our training examples and repeat it 5 times so that the augmentation can be applied to the same image 5 times over randomly, to see the augmentation in action.

## Randomly rotating the image

Let's take a look at different augmentation called rotation and apply 45 degrees of rotation randomly to our training examples.

### **Applying Zoom**

Let's apply Zoom augmentation to our dataset to zoom images up to 50% randomly.

## Putting it all together

We can apply all the augmentations we saw above and even more with just one line of code. We can simply pass the augmentations as arguments with proper values and that would be all.

Here, we have applied rescale, rotation of 45 degrees, width shift, height shift, horizontal flip and zoom augmentation to our training images.

```
In [0]: train_data_gen = image_gen_train.flow_from_directory(
```

```
batch_size=batch_size,
directory=train_dir,
shuffle=True,
target_size=(IMG_SHAPE,

IMG_SHAPE),

class_mode='binary'
)
```

Let's visualize how a single image would look like 5 different times, when we pass these augmentations randomly to our dataset.

```
In [0]: augmented_images = [train_data_gen[0][0][0] for i in range(5)]
plotImages(augmented_images)
```

### **Creating Validation Data generator**

Generally, we only apply data augmentation to our training examples. So, in this case we are only rescaling our validation images and converting them into batches using ImageDataGenerator.

# **Dropout**

Another technique we can use to reduce overfitting is to introduce something called **Dropout** to our network. If you are not familiar with the term **regularization**, it simply means forcing the weights in your network to take only small values, which makes the distribution of weight values more regular and the network can reduce overfitting on small training examples. Dropout is one of the regularization technique we will be using in this tutorial.

When we apply Dropout to a layer it will randomly drop out (set to zero) number of output units from the applied layer during the training process. Dropout takes fraction number as its input value, in the form such as 0.1, 0.2, 0.4 etc. which simply means dropping out 10%, 20% or 40% of the output units randomly from the applied layer.

When we apply 0.1 value as a Dropout value to a certain layer, it will kill 10% of its output units randomly in each training epoch.

Let's create a network architecture with this new Dropout feature and apply it to different Convolutions and Fully Connected layers.

# Creating a new network with Dropouts

Here, we have applied Dropouts to first and last max pool layers and to a fully connected layer which has 512 output units. 30% of the first and last max pool layer and 10% of fully connected layer output units will be set to zero randomly during each epoch while training.