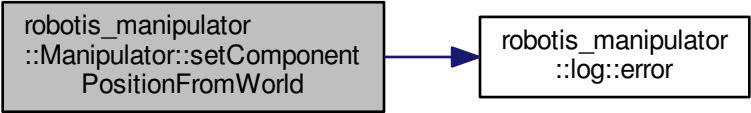


robotis_manipulator
::Manipulator::setComponent
PositionFromWorld



```
graph LR; A["robotis_manipulator  
::Manipulator::setComponent  
PositionFromWorld"] --> B["robotis_manipulator  
::log::error"]
```

robotis_manipulator
::log::error