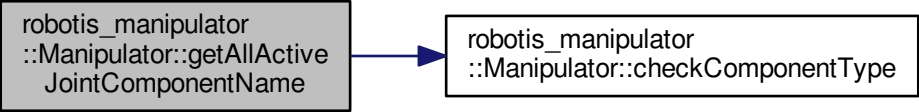


robotis_manipulator
::Manipulator::getAllActive
JointComponentName



```
graph LR; A["robotis_manipulator::Manipulator::getAllActiveJointComponentName"] --> B["robotis_manipulator::Manipulator::checkComponentType"]
```

robotis_manipulator
::Manipulator::checkComponentType