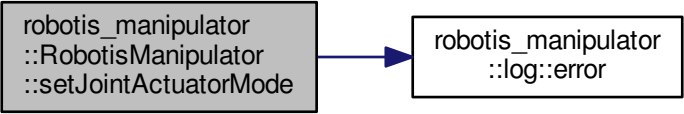


robotis_manipulator
::RobotisManipulator
::setJointActuatorMode



```
graph LR; A["robotis_manipulator  
::RobotisManipulator  
::setJointActuatorMode"] --> B["robotis_manipulator  
::log::error"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box has a light gray background and a black border, containing the text 'robotis_manipulator', '::RobotisManipulator', and '::setJointActuatorMode' stacked vertically. The right box has a white background and a black border, containing the text 'robotis_manipulator' and '::log::error' stacked vertically. A blue arrow points from the right side of the left box to the left side of the right box.

robotis_manipulator
::log::error