

robotis\_manipulator  
::JointActuator

+ enabled\_state\_

+ JointActuator()  
+ ~JointActuator()  
+ init()  
+ setMode()  
+ getId()  
+ enable()  
+ disable()  
+ sendJointActuatorValue()  
+ receiveJointActuatorValue()  
+ findId()  
+ getEnabledState()