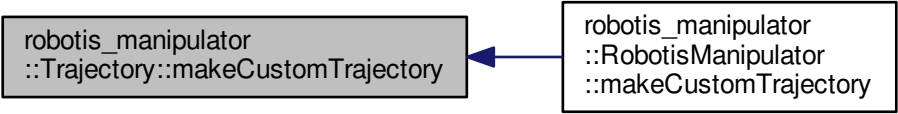


robotis_manipulator
::Trajectory::makeCustomTrajectory



```
graph LR; A["robotis_manipulator  
::RobotisManipulator  
::makeCustomTrajectory"] --> B["robotis_manipulator  
::Trajectory::makeCustomTrajectory"]
```

The diagram consists of two rectangular boxes. The box on the left is shaded gray and contains the text 'robotis_manipulator' followed by '::Trajectory::makeCustomTrajectory' on the next line. The box on the right is white with a black border and contains the text 'robotis_manipulator' followed by '::RobotisManipulator' on the next line, and '::makeCustomTrajectory' on the third line. A blue arrow points from the right box to the left box, indicating a function call or dependency.

robotis_manipulator
::RobotisManipulator
::makeCustomTrajectory