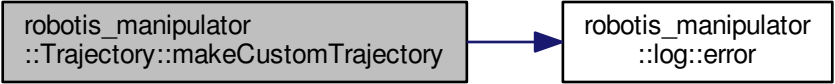


```
robotis_manipulator  
::Trajectory::makeCustomTrajectory
```



```
graph LR; A[robotis_manipulator::Trajectory::makeCustomTrajectory] --> B[robotis_manipulator::log::error]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'robotis_manipulator::Trajectory::makeCustomTrajectory'. The right box is white and contains the text 'robotis_manipulator::log::error'. A dark blue arrow points from the right side of the gray box to the left side of the white box.

```
robotis_manipulator  
::log::error
```