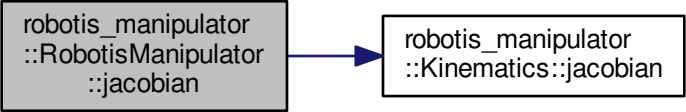


robotis_manipulator
::RobotisManipulator
::jacobian



```
graph LR; A["robotis_manipulator  
::RobotisManipulator  
::jacobian"] --> B["robotis_manipulator  
::Kinematics::jacobian"]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box has a light gray background and contains the text 'robotis_manipulator', '::RobotisManipulator', and '::jacobian' stacked vertically. The right box has a white background and contains the text 'robotis_manipulator', '::Kinematics::jacobian' stacked vertically.

robotis_manipulator
::Kinematics::jacobian