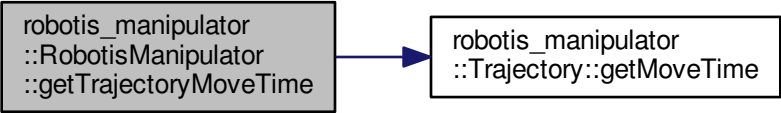


robotis\_manipulator  
::RobotisManipulator  
::getTrajectoryMoveTime



```
graph LR; A["robotis_manipulator  
::RobotisManipulator  
::getTrajectoryMoveTime"] --> B["robotis_manipulator  
::Trajectory::getMoveTime"]
```

A diagram illustrating a function call. On the left, a gray rectangular box contains the text 'robotis\_manipulator', '::RobotisManipulator', and '::getTrajectoryMoveTime'. A blue arrow points from the right side of this box to the right side of a white rectangular box on the right. The white box contains the text 'robotis\_manipulator', '::Trajectory::', and 'getMoveTime'.

robotis\_manipulator  
::Trajectory::getMoveTime