# Regularized estimation of LM and GLM Part 1: Ridge regression

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References:

Section 3.4 in Hastie, Tibshirani, and Friedman (2009)

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### Introduction

- In the multiple linear regression model (with n observations and p predictors, p possibly greater than n) we consider the penalized least squares coefficients estimator where the penalization is given by the L<sub>1</sub> or the L<sub>2</sub> norms of the estimator.
- This procedures leads to ridge regression ( $L_2$  penalization) and to lasso (least absolute shrinkage and selection operator) estimation ( $L_1$  penalization).
- In the pathway, we will learn:
  - Linear estimators of a regression function.
  - Effective number of parameters (or effective degrees of freedom) of a regression estimator.
  - Tuning parameters choice based on leave-one-out cross-validation,
     k-fold cross-validation or generalized cross-validation.
  - Efficient computation of leave-one-out cross-validation for linear estimators



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# Multiple linear regression model

• Consider that n pairs  $(x_i, y_i)$ , i = 1, ..., n of data,  $y_i \in \mathbb{R}$  and  $x_i \in \mathbb{R}^p$ , are observed from the multiple linear regression model

$$y_i = \beta_0 + \sum_{j=1}^p x_{ij}\beta_j + \varepsilon_i,$$

where  $\varepsilon_1, \ldots, \varepsilon_n$  are i.i.d. r.v. with zero mean and variance  $\sigma^2$ , and  $\boldsymbol{\beta} = (\beta_0, \ldots, \beta_p)^\mathsf{T} \in \mathbb{R}^{p+1}$  is a vector of unknown coefficients.

• Fitting the model consists in providing estimators for  $\beta$  and  $\sigma^2$ , jointly with information about the sampling distribution of these estimators (standard errors, hypothesis testing, among others).

# Ordinary Least Squares (OLS)

Ordinary Least Squares (OLS) estimator:

$$\hat{\boldsymbol{\beta}}_{\text{OLS}} = \arg\min_{\boldsymbol{\beta}} \sum_{i=1}^{n} \left( y_i - \beta_0 - \sum_{j=1}^{p} x_{ij} \beta_j \right)^2$$

- In matrix notation:  $\hat{\boldsymbol{\beta}}_{OLS} = (\boldsymbol{X}^{\mathsf{T}}\boldsymbol{X})^{-1}\boldsymbol{X}^{\mathsf{T}}\boldsymbol{y}$ .
- $\hat{\beta}_{OLS}$  is an unbiased estimator of  $\beta$ .

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- Gauss–Markov Theorem. For any  $\mathbf{a} \in \mathbb{R}^{p+1}$ , the OLS estimator of the linear combination  $\mathbf{a}^\mathsf{T} \boldsymbol{\beta}$ , namely  $\mathbf{a}^\mathsf{T} \hat{\boldsymbol{\beta}}_\mathsf{OLS}$ , is unbiased and it has the lowest variance among the linear unbiased estimates of  $\mathbf{a}^\mathsf{T} \boldsymbol{\beta}$ .
- In particular, following the Bayes rule, the prediction for a new observation x, is  $\hat{y} = x^T \beta$ .
- So its best unbiased estimator is  $\hat{y}_{OLS} = x^{\mathsf{T}} \hat{\beta}_{OLS}$ .

#### Multicolinearity and bad conditioned matrices

- The computation of  $\hat{\boldsymbol{\beta}}_{\text{OLS}}$  is numerically unstable when  ${\pmb X}^{\sf T}{\pmb X}$  is close to be singular.
- Condition number of a symmetric matrix  ${\bf A}$ :  $\kappa({\bf A})=\sqrt{\frac{\gamma_{\max}}{\gamma_{\min}}}$ , where  $\gamma_{\max}$  and  $\gamma_{\min}$  are, respectively, the largest and lowest eigenvalue absolute values of  ${\bf A}$ .
- **A** is not invertible if and only if  $\kappa(\mathbf{A}) = \infty$ .
- A large value of  $\kappa(\mathbf{A})$  (in practice, larger than 30), indicates that numerical problems may appear when inverting  $\mathbf{A}$ .
- In these cases we say that A is bad conditioned.
- If  $\mathbf{X}^\mathsf{T}\mathbf{X}$  is bad conditioned: unstable computation of  $\hat{\boldsymbol{\beta}}_\mathsf{oLS}$ .
- A large condition number indicates that X is close to be singular, that is, close that some columns of X can be written as linear combinations of the other.
- We talk about multicolinearity between columns of X.

# Regularized regression

- Beyond numerical problems,  $\hat{\boldsymbol{\beta}}_{\text{OLS}}$  can not be computed when the rank of  $\boldsymbol{X}$  is lower than the number of variables (p+1) (this is an extreme case of multicolinearity).
- This is the case when p+1>n (or  $p+1\gg n$ , as it can happen in applications with large scale data).
- In practical terms, what happens is that y can be written as a linear combination of the predictors using infinitely many coefficient vectors, for which the objective OLS objective function is equal to 0, its minimum. So there is no way to select the best among those coefficient vectors.
- Shrinkage (or regularized) methods: They add a penalty (depending on  $\beta$ ) to the objective function in such a way that the new optimum is attained at a unique vector  $\hat{\beta}$ .
- The unbiasedness of OLS estimation is lost, but the new estimators

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# Ridge regression

The ridge coefficients minimize a penalized sum of squares residuals:

$$\begin{split} \boldsymbol{\hat{\beta}_{\text{ridge}}} &= \arg\min_{\boldsymbol{\beta}} \mathsf{SSR}_{\mathsf{pen}}(\boldsymbol{\beta}) \\ &= \arg\min_{\boldsymbol{\beta}} \left\{ \sum_{i=1}^{n} \left( y_i - \beta_0 - \sum_{j=1}^{p} x_{ij} \beta_j \right)^2 + \lambda \sum_{j=1}^{p} \beta_j^2 \right\} \\ &= \arg\min_{\boldsymbol{\beta}} \left\{ (\boldsymbol{y} - \boldsymbol{X} \boldsymbol{\beta})^\mathsf{T} (\boldsymbol{y} - \boldsymbol{X} \boldsymbol{\beta}) + \lambda \|\boldsymbol{\beta}_{-0}\|_2^2 \right\} \end{split}$$

where  $\boldsymbol{\beta}_{-0} = (\beta_1, \dots, \beta_p)^T$ .

• Here  $\lambda \geq 0$  is a complexity parameter that controls the amount of shrinkage: the larger the value of  $\lambda$ , the greater the amount of shrinkage of  $\beta_{-0}$  toward zero.

Ridge regression is a penalized least squares problem:

$$\hat{\boldsymbol{\beta}}_{\text{ridge}} = \arg\min_{\boldsymbol{\beta}} \left\{ \sum_{i=1}^{n} \left( y_i - \beta_0 - \sum_{j=1}^{p} x_{ij} \beta_j \right)^2 + \lambda \sum_{j=1}^{p} \beta_j^2 \right\}$$

Alternative expression, constrained least squares problem:

$$\hat{eta}_{ ext{ridge}} = \arg\min_{eta} \sum_{i=1}^n \left( y_i - eta_0 - \sum_{j=1}^p x_{ij} eta_j 
ight)^2$$
 subject to  $\sum_{i=1}^p eta_j^2 \le t$ ,

for  $t \geq 0$ . There is a one-to-one decreasing correspondence between parameters  $\lambda \in [0, \infty)$  and  $t \in (0, \|\hat{\boldsymbol{\beta}}_{-0, \alpha}\|^2]$ .



- Observe that changes in scale of the explanatory variables affect the constraint effects (or, equivalently, the effects of penalization term).
- For this reason, from now on we assume that the predictor variables have zero mean and unit variance (otherwise we center and standardize them in advance):

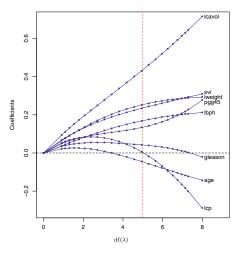
$$\sum_{i=1}^{n} x_{ij} = 0, \frac{1}{n} \sum_{i=1}^{n} x_{ij}^{2} = 1, \quad j = 1, \dots, p.$$

• Moreover, the response variable is assumed to have zero mean  $(\sum_{i=1}^{n} y_i = 0)$ , that is,  $\beta_0 = 0$ .

# Prostate cancer example. Ridge regression

- Goal: To examine the correlation between the level of log of prostate-specific antigen (lpsa) and a number of clinical measures in 97 men who were about to receive a radical prostatectomy.
- The predictor variables are
  - log cancer volume (lcavol),
  - log prostate weight (lweight),
  - age,
  - log of the amount of benign prostatic hyperplasia (lbph),
  - seminal vesicle invasion (svi),
  - log of capsular penetration (lcp),
  - Gleason score (gleason), and
  - percent of Gleason scores 4 or 5 (pgg45).





Source: Hastie, Tibshirani, and Friedman (2009)

## Explicit solution for the ridge regression

 The ridge regression estimators are the solution of the penalized least squares problem

$$\min_{\beta \in \mathbb{R}^p} \left\{ \sum_{i=1}^n \left( y_i - \sum_{j=1}^p x_{ij} \beta_j \right)^2 + \lambda \sum_{j=1}^p \beta_j^2 \right\}$$

that can be expressed as

$$\min_{oldsymbol{eta} \in \mathbb{R}^p} \varPsi(oldsymbol{eta}) = (oldsymbol{y} - oldsymbol{X}oldsymbol{eta})^\mathsf{T} (oldsymbol{y} - oldsymbol{X}oldsymbol{eta}) + \lambda oldsymbol{eta}^\mathsf{T}oldsymbol{eta},$$

that has an explicit solution, as we show now.

Taking the gradient

$$\nabla \Psi(\boldsymbol{\beta}) = -2\boldsymbol{X}^{\mathsf{T}}(\boldsymbol{y} - \boldsymbol{X}\boldsymbol{\beta}) + 2\lambda\boldsymbol{\beta},$$

and solving in  $\beta$  the equation  $\nabla \Psi(\beta) = \mathbf{0}$ , we obtain

$$\hat{oldsymbol{eta}} = \left( oldsymbol{X}^\mathsf{T} oldsymbol{X} + \lambda oldsymbol{I}_p 
ight)^{-1} oldsymbol{X}^\mathsf{T} oldsymbol{y}$$
 , which is a second sec

- Ridge regression estimator:  $\hat{\boldsymbol{\beta}}_{\text{ridge}} = \left( \boldsymbol{X}^{\mathsf{T}} \boldsymbol{X} + \lambda \boldsymbol{I}_{p} \right)^{-1} \boldsymbol{X}^{\mathsf{T}} \boldsymbol{y}.$
- ullet Therefore, for any  $x\in\mathbb{R}^p$ , the corresponding predicted value is

$$\hat{y} = oldsymbol{x}^\mathsf{T} \hat{oldsymbol{eta}}_\mathsf{ridge} = oldsymbol{x}^\mathsf{T} oldsymbol{X}^\mathsf{T} oldsymbol{X} + \lambda oldsymbol{I}_{oldsymbol{
ho}} ig)^{-1} oldsymbol{X}^\mathsf{T} oldsymbol{y}.$$

The vector of fitted values is

$$\hat{\mathbf{y}} = \mathbf{X} \left( \mathbf{X}^{\mathsf{T}} \mathbf{X} + \lambda \mathbf{I}_{p} \right)^{-1} \mathbf{X}^{\mathsf{T}} \mathbf{y} = \mathbf{H}_{\lambda} \mathbf{y}.$$

• Compare with the OLS solution:  $\hat{\boldsymbol{\beta}}_{\text{OLS}} = \left( \boldsymbol{X}^{\mathsf{T}} \boldsymbol{X} \right)^{-1} \boldsymbol{X}^{\mathsf{T}} \boldsymbol{y}.$ 

$$\hat{\mathbf{y}}_{\text{OLS}} = \mathbf{X} \left( \mathbf{X}^{\mathsf{T}} \mathbf{X} \right)^{-1} \mathbf{X}^{\mathsf{T}} \mathbf{y} = \mathbf{H} \mathbf{y},$$

where  $\mathbf{H} = \mathbf{X} \left( \mathbf{X}^{\mathsf{T}} \mathbf{X} \right)^{-1} \mathbf{X}^{\mathsf{T}}$  is called the hat matrix.

•  $\lim_{\lambda \longrightarrow 0} \hat{oldsymbol{eta}}_{ ext{ridge}} = \hat{oldsymbol{eta}}_{ ext{OLS}}$ ,  $\lim_{\lambda \longrightarrow \infty} \hat{oldsymbol{eta}}_{ ext{ridge}} = oldsymbol{0}$ .



#### **Practice:**

- Prostate data: Ridge regression estimation and coefficients path.
- Use the R script prostate.ridge.regression.R.

# Singular Value Decomposition of X

- Let  $X = UDV^T$  be the Singular Value Decomposition of X. That is:
  - U,  $n \times p$  orthonormal matrix whose columns span the X column space.
  - D, p×p diagonal matrix with elements d<sub>1</sub> ≥ ... ≥ d<sub>p</sub> ≥ 0 in the diagonal, that are called singular values of X.
  - V,  $p \times p$  orthonormal matrix whose columns span the row space of X.
- Observe that X<sup>T</sup>X = VDU<sup>T</sup>UDV<sup>T</sup> = VD<sup>2</sup>V<sup>T</sup> and it follows that the eigenvalues of X<sup>T</sup>X are the squared singular values of X:

$$\gamma_j=d_j^2,\ j=1,\ldots,p.$$



As we are assuming that the explanatory variables have zero mean, we have that  $\boldsymbol{X}^T\boldsymbol{X}$  is the sample covariance matrix. Then the columns of  $\boldsymbol{V}$  are the principal components of  $\boldsymbol{X}$ . Moreover the columns of  $\boldsymbol{UD}$  are the scores of the observed data in the principal components.

# Numerical stability of ridge regression

- $\bullet \ \hat{\boldsymbol{\beta}}_{\text{ridge}} = \left( \boldsymbol{X}^{\mathsf{T}} \boldsymbol{X} + \lambda \boldsymbol{I}_{p} \right)^{-1} \boldsymbol{X}^{\mathsf{T}} \boldsymbol{y}$
- Let us compute the condition number of  $\boldsymbol{X}^{\mathsf{T}}\boldsymbol{X} + \lambda \boldsymbol{I}_{p}$ ,

$$\mathbf{X}^{\mathsf{T}}\mathbf{X} + \lambda \mathbf{I}_{p} = \mathbf{V}\mathbf{D}^{2}\mathbf{V}^{\mathsf{T}} + \lambda \mathbf{V}\mathbf{V}^{\mathsf{T}} = \mathbf{V}\left(\mathbf{D}^{2} + \lambda \mathbf{I}_{p}\right)\mathbf{V}^{\mathsf{T}}.$$

•  $(\mathbf{D}^2 + \lambda \mathbf{I}_p)$  is a diagonal matrix whose elements in the diagonal are

$$d_j^2 + \lambda = \gamma_j + \lambda, \ j = 1, \dots, p.$$

• Therefore the condition number of  $\boldsymbol{X}^{\mathsf{T}}\boldsymbol{X} + \lambda \boldsymbol{I}_{p}$  is

$$\kappa \left( \boldsymbol{X}^{\mathsf{T}} \boldsymbol{X} + \lambda \boldsymbol{I}_{\boldsymbol{p}} \right) = \sqrt{\frac{\gamma_1 + \lambda}{\gamma_p + \lambda}}$$

lower than  $\kappa\left(\boldsymbol{X}^{\mathsf{T}}\boldsymbol{X}\right) = \sqrt{\gamma_1/\gamma_p}$  for all  $\lambda > 0$ .

• By the way,  $(\mathbf{X}^{\mathsf{T}}\mathbf{X} + \lambda \mathbf{I}_p)^{-1} = \mathbf{V} (\mathbf{D}^2 + \lambda \mathbf{I}_p)^{-1} \mathbf{V}^{\mathsf{T}}$ , and  $(\mathbf{D}^2 + \lambda \mathbf{I}_p)^{-1} = \mathsf{Diagonal}(1/(d_j^2 + \lambda), j = 1, \dots, p)$ .

# Variance of the ridge regression estimator

Remember that  $\hat{\boldsymbol{\beta}}_{\text{ridge}} = \left( \boldsymbol{X}^{\mathsf{T}} \boldsymbol{X} + \lambda \boldsymbol{I}_{p} \right)^{-1} \boldsymbol{X}^{\mathsf{T}} \boldsymbol{y}$ . Then

$$Var(\hat{\boldsymbol{\beta}}_{ridge}) = \left(\boldsymbol{X}^{\mathsf{T}}\boldsymbol{X} + \lambda \boldsymbol{I}_{\boldsymbol{\rho}}\right)^{-1} \boldsymbol{X}^{\mathsf{T}} Var(\boldsymbol{y}) \boldsymbol{X} \left(\boldsymbol{X}^{\mathsf{T}}\boldsymbol{X} + \lambda \boldsymbol{I}_{\boldsymbol{\rho}}\right)^{-1}$$
$$= \sigma^{2} \left(\boldsymbol{X}^{\mathsf{T}}\boldsymbol{X} + \lambda \boldsymbol{I}_{\boldsymbol{\rho}}\right)^{-1} \boldsymbol{X}^{\mathsf{T}} \boldsymbol{X} \left(\boldsymbol{X}^{\mathsf{T}}\boldsymbol{X} + \lambda \boldsymbol{I}_{\boldsymbol{\rho}}\right)^{-1}.$$

From the s.v.d. of  $\boldsymbol{X}$ ,  $\boldsymbol{X} = \boldsymbol{U}\boldsymbol{D}\boldsymbol{V}^{\mathsf{T}}$ , we have deduced that  $\boldsymbol{X}^{\mathsf{T}}\boldsymbol{X} = \boldsymbol{V}\boldsymbol{D}^{2}\boldsymbol{V}^{\mathsf{T}}$  and that  $\left(\boldsymbol{X}^{\mathsf{T}}\boldsymbol{X} + \lambda\boldsymbol{I}_{p}\right)^{-1} = \boldsymbol{V}\left(\boldsymbol{D}^{2} + \lambda\boldsymbol{I}_{p}\right)^{-1}\boldsymbol{V}^{\mathsf{T}}$  Therefore,

$$\begin{aligned} \mathsf{Var}(\hat{\boldsymbol{\beta}}_{\scriptscriptstyle{\mathsf{ridge}}}) &= \sigma^2 \boldsymbol{V} \left( \boldsymbol{D}^2 + \lambda \boldsymbol{I}_p \right)^{-1} \boldsymbol{D}^2 \left( \boldsymbol{D}^2 + \lambda \boldsymbol{I}_p \right)^{-1} \boldsymbol{V}^\mathsf{T} \\ &= \sigma^2 \boldsymbol{V} \; \mathsf{Diagonal} \left( d_i^2 / (d_i^2 + \lambda)^2, \, j = 1, \dots, p \right) \boldsymbol{V}^\mathsf{T}. \end{aligned}$$

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#### Linear estimators of a regression function

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# Linear estimators of a regression function

- Let  $(x_i, y_i)$ , i = 1, ..., n, be n i.i.d. observs. from the r.v. (X, Y).
- Let  $m(x) = \mathbb{E}(Y|X = x)$  be the regression function of Y over X.
- Let  $\hat{m}(x)$  an estimator (parametric, non-parametric, ...) of the regression function m(x).
- We say that  $\hat{m}(x)$  is a linear estimator when for any fix x,  $\hat{m}(x)$  is a linear function of  $y_1, \ldots, y_n$ :

$$\hat{m}(x) = \sum_{i=1}^{n} w_i(x) y_i,$$

where in fact  $w_i(x) = w_i(x; x_1, \dots, x_n)$ .

• For the *n* observed values  $x_i$  of the explanatory variable, let

$$\hat{y}_i = \hat{m}(x_i) = \sum_{j=1}^n w_j(x_i)y_j$$

be the fitted values.

• In matrix format,

$$\hat{\mathbf{y}} = \mathbf{W} \mathbf{y},$$

where the column vectors  $\boldsymbol{y}$  and  $\hat{\boldsymbol{y}}$  have elements  $y_i$  and  $\hat{y}_i$ , respectively, and the matrix  $\boldsymbol{W}$  has generic (i,j) element

$$w_{ij} = w_j(\boldsymbol{x}_i).$$

The matrix W is analogous to the hat matrix H = X(X<sup>T</sup>X)<sup>-1</sup>X<sup>T</sup> in OLS estimation of the multiple linear regression:

$$\hat{\mathbf{y}}_{\text{OLS}} = \mathbf{X}(\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{y} = \mathbf{H}\mathbf{y}.$$

Observe that ridge regression is a linear estimation method:

$$\hat{\mathbf{y}}_{\text{ridge}} = \mathbf{X} \left( \mathbf{X}^{\mathsf{T}} \mathbf{X} + \lambda \mathbf{I}_{p} \right)^{-1} \mathbf{X}^{\mathsf{T}} \mathbf{y} = \mathbf{H}_{\lambda} \mathbf{y}.$$

## Effective number of parameters for linear estimators

 Consider the multiple linear regression with p regressors (including the constant term, if it appears in the model):

$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \varepsilon,$$

**X** being a  $n \times p$  matrix,  $\beta \in \mathbb{R}^p$ .

It is known that

$$\mathsf{Trace}(\boldsymbol{H}) = \mathsf{Trace}(\boldsymbol{X}(\boldsymbol{X}^\mathsf{T}\boldsymbol{X})^{-1}\boldsymbol{X}^\mathsf{T}) = \mathsf{Trace}((\boldsymbol{X}^\mathsf{T}\boldsymbol{X})^{-1}\boldsymbol{X}^\mathsf{T}\boldsymbol{X}) = \mathsf{Trace}(\boldsymbol{I}_p) = p,$$

that is the number of parameters in the model.

• For a linear estimator with matrix  $\mathbf{W}$  ( $\hat{\mathbf{y}} = \mathbf{W}\mathbf{y}$ ) we define

$$u = \mathsf{Trace}(\boldsymbol{W}) = \sum_{i=1}^{n} w_{ii},$$

the sum of diagonal elements of W.



- $\nu = \operatorname{Trace}(\boldsymbol{W})$  is called the effective number of parameters of the linear estimator corresponding to matrix  $\boldsymbol{W}$ .
- In some books (and softwares)  $\nu$  is called effective degrees of freedom (df) of the regression estimator. This is the terminology used by Hastie, Tibshirani, and Friedman (2009) and Hastie, Tibshirani, and Wainwright (2015), and related packages.
- The interpretation of  $\nu$  as the effective number of parameters is valid for any linear estimator of the regression function (parametric, nonparametric, ...).
- Then we can compare the degree of complexity of two linear estimators of a regression function just comparing their effective numbers of parameters.
- Usually a good estimator of  $\sigma^2$ , the residual variance, is

$$\hat{\sigma}^2 = \frac{1}{n-\nu} \sum_{i=1}^n (y_i - \hat{y}_i)^2.$$



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## Effective number of parameters in ridge regression

In the case of ridge regression  $\nu = \nu(\lambda) = df(\lambda)$  has an explicit expression:

$$\begin{split} \boldsymbol{W} &= \boldsymbol{H}_{\lambda} = \boldsymbol{X} \left( \boldsymbol{X}^{\mathsf{T}} \boldsymbol{X} + \lambda \boldsymbol{I}_{p} \right)^{-1} \boldsymbol{X} = \boldsymbol{U} \boldsymbol{D} \boldsymbol{V}^{\mathsf{T}} \boldsymbol{V} \left( \boldsymbol{D}^{2} + \lambda \boldsymbol{I}_{p} \right)^{-1} \boldsymbol{V}^{\mathsf{T}} \boldsymbol{V} \boldsymbol{D} \boldsymbol{U}^{\mathsf{T}} = \\ \boldsymbol{U} \boldsymbol{D} \left( \boldsymbol{D}^{2} + \lambda \boldsymbol{I}_{p} \right)^{-1} \boldsymbol{D} \boldsymbol{U}^{\mathsf{T}} = \boldsymbol{U} \left( \mathrm{Diagonal}(d_{j}^{2}/(d_{j}^{2} + \lambda), j = 1, \dots, p \right) \boldsymbol{U}^{\mathsf{T}} \\ &\Rightarrow \nu(\lambda) = \mathrm{df}(\lambda) = \mathrm{Trace}(\boldsymbol{H}_{\lambda}) = \\ \mathrm{trace}(\boldsymbol{U} \left( \mathrm{Diagonal}(d_{j}^{2}/(d_{j}^{2} + \lambda), j = 1, \dots, p \right) \boldsymbol{U}^{\mathsf{T}} \right) = \\ \mathrm{trace}(\left( \mathrm{Diagonal}(d_{j}^{2}/(d_{j}^{2} + \lambda), j = 1, \dots, p \right) \boldsymbol{U}^{\mathsf{T}} \boldsymbol{U}) = \\ \mathrm{trace}(\left( \mathrm{Diagonal}(d_{j}^{2}/(d_{j}^{2} + \lambda), j = 1, \dots, p \right)) = \sum_{j=1}^{p} \frac{d_{j}^{2}}{d_{j}^{2} + \lambda}. \end{split}$$

$$\nu(\lambda) = \mathsf{df}(\lambda) = \sum_{j=1}^{p} \frac{d_j^2}{d_j^2 + \lambda}$$

- $\lim_{\lambda \longrightarrow \infty} df(\lambda) = 0$ ,  $\lim_{\lambda \longrightarrow 0} df(\lambda) = rank(X)$ .
- The effective number of parameters  $\nu(\lambda) = df(\lambda)$  is a decreasing function of penalizing parameter  $\lambda$ :
  - Small values of  $\lambda$  correspond to large numbers  $\nu$  of effective parameters, close to the number of linearly independent explanatory variables (usually min $\{n, p\}$ ), allowing complex and flexible estimators
  - Large values of  $\lambda$  correspond to small numbers  $\nu$  of effective parameters, that is, to regression estimators with low complexity and flexibility.

#### **Practice:**

- Prostate data: Effective number of parameters in ridge regression.
- Use the R script prostate.ridge.regression.R.

# Effective degrees of freedom for non-linear estimators

- Let  $\hat{m}(x)$  an estimator of the regression function m(x) (a random function because it is based on  $(Y_1, \ldots, Y_n)$ ). Let  $\hat{Y}_i = \hat{m}(x_i)$ .
- The effective degrees of freedom of  $\hat{m}(x)$  is defined as

$$df(\hat{m}) = \frac{1}{\sigma^2} \sum_{i=1}^n Cov(\hat{Y}_i, Y_i).$$

- Interpretation:
  - A very flexible regression estimator  $\hat{m}(x)$  will be able to interpolate the observed data, and then

$$\hat{Y}_i = Y_i$$
,  $Var(\hat{Y}_i) = Var(Y_i) = \sigma^2$ ,  $Cov(\hat{Y}_i, Y_i)/\sigma^2 = Cor(\hat{Y}_i, Y_i) = 1$ , so  $df(\hat{m}) = n$ :  $\hat{m}(x)$  has as many degrees of freedom as the number of observed data.

- The constant function equal to the sample mean of Y<sub>1</sub>,..., Y<sub>n</sub> for all x
  has 1 degree of freedom.
- A function that is constant in x has 0 degrees of freedom if this constant does not depend on the data.

#### Both definitions of df coincide in linear estimators

Assume that  $\hat{m}(x)$  is a linear estimator with matrix W . Assume also that  $\mathbb{E}(Y)=0$ . Then

$$\begin{split} \mathsf{df}(\hat{m}) &= \frac{1}{\sigma^2} \sum_{i=1}^n \mathsf{Cov}(\hat{Y}_i, Y_i) = \frac{1}{\sigma^2} \mathsf{Trace}\left(\mathsf{Cov}(\hat{\boldsymbol{Y}}, \boldsymbol{Y})\right) = \\ &\frac{1}{\sigma^2} \mathsf{Trace}\left(\mathbb{E}\left(\hat{\boldsymbol{Y}} \, \boldsymbol{Y}^\mathsf{T}\right)\right) = \frac{1}{\sigma^2} \mathsf{Trace}\left(\mathbb{E}\left(\boldsymbol{W} \, \boldsymbol{Y} \, \boldsymbol{Y}^\mathsf{T}\right)\right) = \\ &\frac{1}{\sigma^2} \mathsf{Trace}\left(\boldsymbol{W} \mathbb{E}\left(\boldsymbol{Y} \, \boldsymbol{Y}^\mathsf{T}\right)\right) = \frac{1}{\sigma^2} \mathsf{Trace}\left(\boldsymbol{W} \, \sigma^2 \boldsymbol{I}_{\boldsymbol{p}}\right) = \mathsf{Trace}(\boldsymbol{W}). \end{split}$$

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# Choosing the tuning parameter $\lambda$

- The tuning parameter  $\lambda$  can be chosen by cross-validation (CV), k-fold cross-validation (k-fold CV) or by generalized cross-validation (GCV).
- Given the expression of  $\hat{\boldsymbol{\beta}}_{\text{ridge}}$  (linear in  $\boldsymbol{y}$ ) CV and GCV are not computationally expensive.
- We will first introduce these concepts before talking about efficient computation.

 Predictive Mean Square Error (PMSE). It is the expected squared error made when predicting

$$Y = m(x) + \varepsilon$$

by  $\hat{m}(x)$ , where x is an observation of the random variable X, distributed as the observed explanatory variable, when X and  $\varepsilon$  are independent from the sample  $\mathcal{Z} = \{(X_i, Y_i) : i = 1, \dots, n\}$  used to compute  $\hat{m}$ :

$$\mathsf{PMSE}(\hat{m}) = \mathbb{E}_{\mathcal{Z}, \mathbf{X}, \varepsilon} \left[ (Y - \hat{m}(\mathbf{X}))^2 \right].$$

### Prediction error in a validation set

- When the number of available data is large (as it usually happens in data mining or in Big Data problems) the sample is randomly divided in three sets:
  - The training set: it is used to fit the model.
  - The validation set: it is used to compute feasible versions of the PMSE for model selection and/or parameter tuning.
  - The test set: it is used to evaluate the generalization (or prediction) error of the final chosen model in independent data.
- Assuming that at least a validation set has been preserved, an estimation
  of PMSE is the Predictive Mean Squared Error in the validation set:

$$\mathsf{PMSE}_{\mathsf{val}}(\hat{m}) = \frac{1}{n_V} \sum_{i=1}^{n_V} (y_i^V - \hat{m}(x_i^V))^2,$$

where  $(x_i^V, y_i^V)$ ,  $i = 1, ..., n_V$ , is the validation set and  $\hat{m}(x)$  is the estimator computed using the training set.

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### Leave-one-out cross-validation

- When the sample size does not allow us to set a validation set aside, leave-one-out cross-validation is an attractive alternative:
  - **1** Remove the observation  $(x_i, y_i)$  from the sample and fit the regression using the other (n-1) data. Let  $\hat{m}_{(i)}(x)$  be the resulting estimator.
  - 2 Now use  $\hat{m}_{(i)}(x_i)$  to predict  $y_i$ .
  - **3** Repeat the previous steps for i = 1, ..., n.
  - 4 Compute

$$PMSE_{CV}(\hat{m}) = \frac{1}{n} \sum_{i=1}^{n} (y_i - \hat{m}_{(i)}(x_i))^2.$$

In ridge regression:

$$\lambda_{CV} = \arg\min_{\lambda \geq 0} \mathsf{PMSE}_{\mathsf{CV}}(\lambda) = \frac{1}{n} \sum_{i=1}^n (y_i - x_i^\mathsf{T} \hat{\boldsymbol{\beta}}_{\mathsf{ridge},\lambda}^{(i)})^2.$$



#### **Practice:**

- Prostate data: Leave-one-out cross-validation in ridge regression.
- Use the R script prostate.ridge.regression.R.

## k-fold cross validation

- PMSE<sub>CV</sub>( $\hat{m}$ ) is an approximately unbiased estimator of PMSE( $\hat{m}$ ), but has a considerable variance.
- The variance can be reduced doing k-fold cross-validation: The sample is randomly divided in k subsets, each of them is removed by turns from the sample, the model is estimated with the other (k-1) subsamples and the removed subsample is used to compute prediction errors.
- *n*-fold cross-validation is leave-one-out cross-validation.
- k-fold cross-validation has lower variance than leave-one-out cross-validation but larger bias.
- General recommendation: Use 5-fold or 10-fold cross-validation.



# Efficient computation of PMSE<sub>CV</sub>

- Consider a linear estimator of the regression function with matrix  $\mathbf{W} = (w_{ii})_{i,j}$ :  $\hat{\mathbf{y}} = \mathbf{W} \mathbf{y}$ .
- That is

$$\hat{y}_i = \sum_{j=1}^n w_{ij} y_j, \ i = 1, \ldots, n,$$

where 
$$w_{ij}=w_j(x_i)=w_j(x_i;x_1,\ldots,x_n)$$
.

- In these cases PMSE<sub>CV</sub> can be calculated avoiding the computational cost of fitting n different regression models.
- For most linear estimators it can be proved that

$$\mathsf{PMSE}_{\mathsf{CV}} = \frac{1}{n} \sum_{i=1}^{n} \left( \frac{y_i - \hat{y}_i}{1 - w_{ii}} \right)^2.$$

### Self-stable linear estimators

(See Fan, Li, Zhang, and Zou 2020, page 48)

- Let  $\hat{m}(x)$  be a linear estimator of the regression function  $m(x) = \mathbb{E}(Y|X=x)$  fitted on the data  $(x_i, y_i)$ ,  $i=1,\ldots,n$ .
- Let  $x_0$  be a new covariate vector and  $\hat{m}(x_0)$  be its predicted value using the linear estimator.
- We augment the data set by including  $(x_0, \hat{m}(x_0))$  as a new point, and refit the linear estimator on this augmented data set:  $\hat{m}_a(x)$ .
- The linear estimator of the regression function is said to be self-stable if the fit based on the augmented data set is identical to the fit based on the original data regardless of x<sub>0</sub>.

# Self-stability and efficient computation of PMSE<sub>CV</sub>

Theorem (Theorem 2.7, Fan, Li, Zhang, and Zou 2020)

For any linear smoother  $\hat{\mathbf{Y}} = \mathbf{W} \, \mathbf{Y}$  with the self-stability property, we have

$$y_i - \hat{m}_{(i)}(\boldsymbol{x}_i) = \frac{y_i - \hat{y}_i}{1 - w_{ii}}$$

and, therefore, its leave-one-out cross validation error is

$$PMSE_{CV} = \frac{1}{n} \sum_{i=1}^{n} \left( \frac{y_i - \hat{y}_i}{1 - w_{ii}} \right)^2.$$

# Proof for the ridge regression estimation

• Let  $\hat{\beta}_{ridge,\lambda}^{(i)}$  be the estimation of  $\beta = (\beta_1, \dots, \beta_p)$  when leaving out the *i*-th observation:

$$\hat{\boldsymbol{\beta}}_{\text{ridge},\lambda}^{(i)} = \arg\min_{\boldsymbol{\beta}} \left\{ \sum_{l=1,l\neq i}^{n} \left( y_l - \sum_{j=1}^{p} x_{lj} \beta_j \right)^2 + \lambda \|\boldsymbol{\beta}\|_2^2 \right\}$$

Let us define

$$\tilde{y}_{l}^{(i)} = \begin{cases} y_{l} & \text{if} \quad l \neq i, \\ \hat{y}_{i}^{(i)} = \sum_{j=1}^{p} x_{ij} \hat{\beta}_{\text{ridge}, \lambda, j}^{(i)} & \text{if} \quad l = i. \end{cases}$$

CV and GCV

• It follows that for all  $\beta \in \mathbb{R}^p$ ,

$$\sum_{l=1}^{n} \left( \tilde{y}_{l}^{(i)} - \sum_{j=1}^{p} x_{lj} \beta_{j} \right)^{2} + \lambda \|\beta\|_{2}^{2} =$$

$$\left\{ \sum_{l=1,l\neq i}^{n} \left( y_l - \sum_{j=1}^{p} x_{lj} \beta_j \right)^2 + \lambda \|\boldsymbol{\beta}\|_2^2 \right\} + \left( \sum_{j=1}^{p} x_{ij} (\hat{\beta}_{\text{ridge},\lambda,j}^{(i)} - \beta_j) \right)^2$$

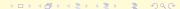
• Observe that  $\hat{\beta}_{idre}^{(i)}$  minimizes both terms in the right hand side. Then it is also

$$\hat{\boldsymbol{\beta}}_{\text{ridge},\lambda}^{(i)} = \arg\min_{\boldsymbol{\beta}} \left\{ \sum_{l=1}^{n} \left( \tilde{y}_{l}^{(i)} - \sum_{j=1}^{p} x_{lj} \beta_{j} \right)^{2} + \lambda \|\boldsymbol{\beta}\|_{2}^{2} \right\}$$

- This is the ridge regression estimator corresponding to a data set with matrix of explanatory variables X and vector of responses  $\tilde{\mathbf{v}}^{(i)} = (\tilde{\mathbf{v}}_1^{(i)}, \dots, \tilde{\mathbf{v}}_n^{(i)})^\mathsf{T}.$
- Then

$$\hat{\boldsymbol{\beta}}_{\text{ridge},\lambda}^{(i)} = (\boldsymbol{X}^{\mathsf{T}}\boldsymbol{X} + \lambda \boldsymbol{I}_{p})^{-1}\boldsymbol{X}^{\mathsf{T}}\tilde{\boldsymbol{y}}^{(i)},$$

$$\hat{\boldsymbol{y}}^{(i)} = \boldsymbol{X}\hat{\boldsymbol{\beta}}_{\text{ridge},\lambda}^{(i)} = \boldsymbol{X}(\boldsymbol{X}^{\mathsf{T}}\boldsymbol{X} + \lambda \boldsymbol{I}_{p})^{-1}\boldsymbol{X}^{\mathsf{T}}\tilde{\boldsymbol{y}}^{(i)} = \boldsymbol{H}_{\lambda}\tilde{\boldsymbol{y}}^{(i)}.$$



- Observe that the *i*-th element of  $\hat{\tilde{y}}^{(i)}$  is just  $\hat{y}_i^{(i)} = \sum_{j=1}^p x_{ij} \hat{\beta}_{\text{ridge},\lambda,j}^{(i)}$ .
- Let e<sub>i</sub> be the n-dimensional vector whose i-th element is 1 and the others are equal to 0.
- Then  $\tilde{\pmb{y}}^{(i)} = \pmb{y} (y_i \hat{y}_i^{(i)}) \pmb{e}_i$  and, consequently,

$$\hat{\tilde{\mathbf{y}}}^{(i)} = \mathbf{H}_{\lambda} \tilde{\mathbf{y}}^{(i)} = \mathbf{H}_{\lambda} \left( \mathbf{y} - (y_i - \hat{y}_i^{(i)}) \mathbf{e}_i \right) =$$

$$\mathbf{H}_{\lambda}\mathbf{y}-(y_i-\hat{y}_i^{(i)})\mathbf{H}_{\lambda}\mathbf{e}_i=\hat{\mathbf{y}}-(y_i-\hat{y}_i^{(i)})\mathbf{h}_i^{\lambda},$$

where  $\boldsymbol{h}_{i}^{\lambda}$  is the *i*-th column of  $\boldsymbol{H}_{\lambda}$ .

- Looking just at the *i*-th component,  $\hat{y}_i^{(i)} = \hat{y}_i (y_i \hat{y}_i^{(i)})h_{ii}^{\lambda}$ , where  $h_{ii}^{\lambda}$  is the element (i,i) of  $\boldsymbol{H}_{\lambda}$ , or the *i*-th element in the diagonal of  $\boldsymbol{H}_{\lambda}$ .
- Then  $y_i \hat{y}_i^{(i)} = y_i \hat{y}_i + (y_i \hat{y}_i^{(i)}) h_{ii}^{\lambda}$  and we conclude that

$$y_i - \hat{y}_i^{(i)} = \frac{y_i - \hat{y}_i}{1 - h_{ii}^{\lambda}}.$$

So the loo-CV errors  $(y_i - \hat{y}_i^{(i)})$  can be computed if we know the errors  $(y_i - \hat{y}_i)$  when fitting the ridge regression with all the data, and the diagonal of  $\mathbf{H}_{\lambda}$ , and the proof concludes.

#### **Practice:**

- Prostate data: Efficient computation of PMSE<sub>CV</sub> in ridge regression.
- Use the R script prostate.ridge.regression.R.

### Generalized cross-validation

- For linear estimators of the regression function, a modification can be done in the measure of PMSE<sub>CV</sub>.
- It is known as generalized cross-validation (GCV).
- It consists in replacing in the expression of PMSE<sub>CV</sub> the values  $w_{ii}$ , coming from the diagonal of W, by their average value:

$$PMSE_{GCV} = \frac{1}{n} \sum_{i=1}^{n} \left( \frac{y_i - \hat{y}_i}{1 - \nu/n} \right)^2,$$

 $\nu = \mathsf{Trace}(\boldsymbol{W}) = \sum_{i=1}^{n} w_{ii}$  is the effective number of parameters.

- In ridge regression,  $\lambda_{GCV} = \arg\min_{\lambda} \mathsf{PMSE}_{GCV}(\lambda)$ .
- Manipulating the expression of PMSE<sub>GCV</sub> it follows that

$$\mathsf{PMSE}_{\mathsf{GCV}} = \frac{n\hat{\sigma}_{\varepsilon}^2}{n - \nu},$$

where  $\hat{\sigma}_{\varepsilon}^2 = \frac{1}{n-\nu} \sum_{i=1}^n (y_i - \hat{y}_i)^2$  estimates the residual variance.



### **Practice:**

- Prostate data: PMSE<sub>GCV</sub> in ridge regression.
- Use the R script prostate.ridge.regression.R.

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