

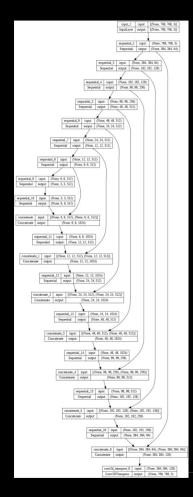
Pix2Pix for Monocular Depth Estimation

### Background

It's a GAN

- Jittered input images
- Often effective with small datasets

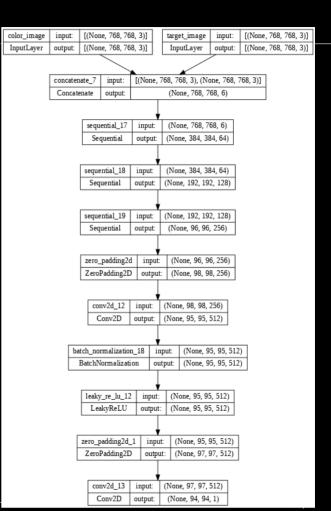
### <u>Layers</u>



#### That's a lot of layers!

- Downsampling
- Upsampling
- Skip-Connections

The values deviate from the paper's C64-C128-C256-C512 due to the image size



### **Checkpoints**

```
ModelCheckpoint class

keras.callbacks.ModelCheckpoint(
    filepath,
    monitor="val_loss",
    verbose=0,
    save_best_only=False,
    save_weights_only=False,
    mode="auto",
    save_freq="epoch",
    initial_value_threshold=None,
)
Callback to save the Keras model or model weights at some frequency.
```

tf.train.Checkpoint [] 
{}

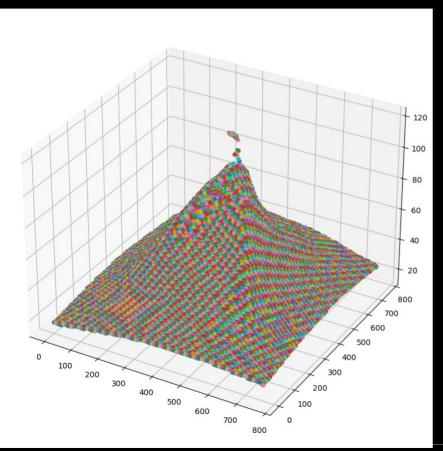
View source on GitHub

Manages saving/restoring trackable values to disk.

No more lost epochs!

# Rendering a Point Cloud

Just needs a few rotations...



```
print(darray.shape)
darray = pd.DataFrame(darray)
fig = plt.figure(figsize=(15, 10))
ax = plt.axes(projection="3d")
#Doing 768^2 operations on CPU is awful, let's do 48^2 instead
for x in range(0,768,6):
    for y in range(0,768,6):
      ax.scatter(x, y, darray[x][y])
print("Done")
```

#slicing the 3-tuple into a 2D array

darray = darray[:,:,0]

### Portable Colab Instances

```
1 from google.colab import drive
2 drive.mount('/content/drive')
```

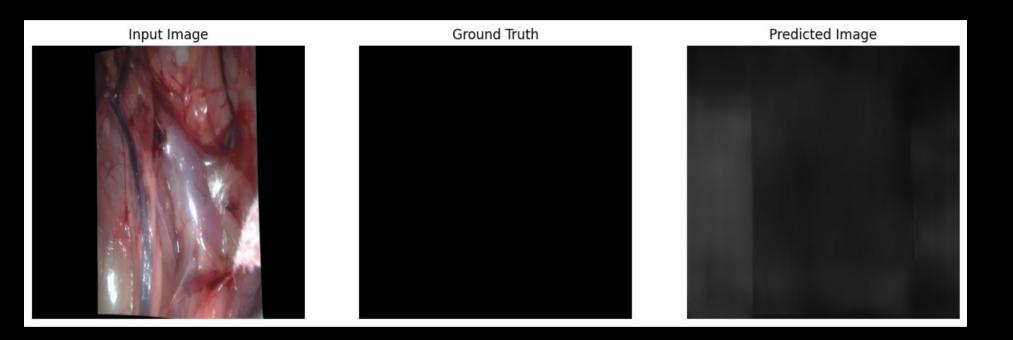
```
1 PATH = '/content/drive/MyDrive/Pix2Pix/Comb Data/'
 2 sample image = tf.io.read file(PATH +'0.png')
 3 sample image = tf.io.decode png(sample image)
 4 print(sample image.shape)
(768, 1536, 4)
 1 plt.figure()
 2 plt.axis('off')
 3 plt.imshow(sample image)
<matplotlib.image.AxesImage at 0x7b93c768f190>
```

Downloading my self hosted checkpoint and dataset

```
1 !wget http://daniel.win/CSCI_4800/pix2pixDWcomp.tar
2 !tar -xvzf pix2pixDWcomp.tar
```

```
Comb_Data/22.png
Comb_Data/31.png
Comb_Data/59.png
Comb_Data/61.png
```

#### Oh.



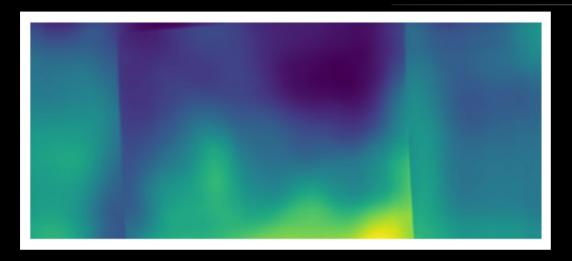
# **PyTorch**

It seems like all the cool new depth estimation models use PyTorch.

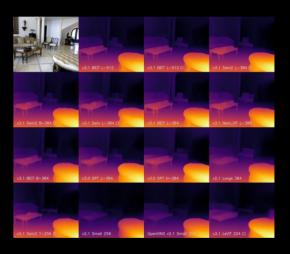
- MiDaS (2019)
- ZoeDepth (2023)
- UniDepth (2024)

Some of these models offer metric depth estimation

# MiDaS?





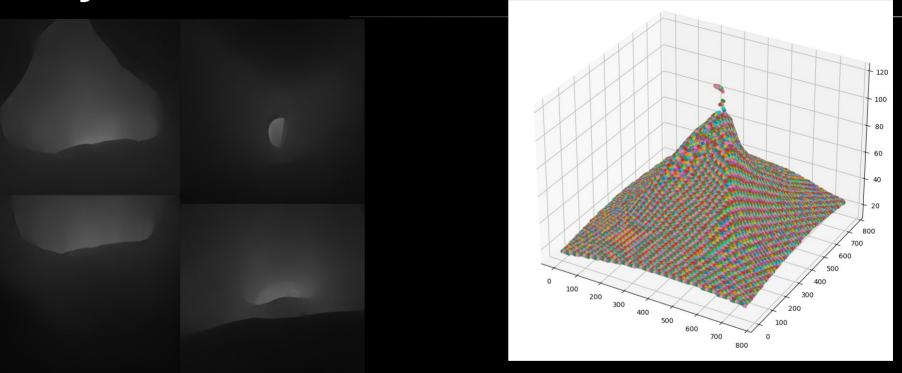


### The data must be cleaned

Might be the hardest part of Phase II

- Dimensions
- Planar Distortion
- Not Phong shaded
   It's not gonna be pretty.

# Thank you!



Feel free to check out my Pix2Pix .ipynb at: http://daniel.win/pix2pix.ipynb