



* Sampling Theorem

Nyquist: $f_s \geq 2f_m$ → max-frequency of signal

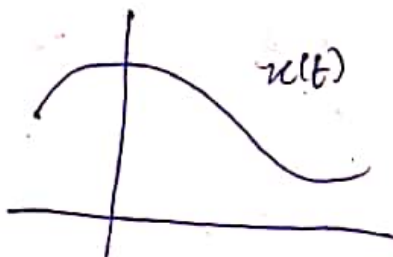
Signal → 

Impulse train → 

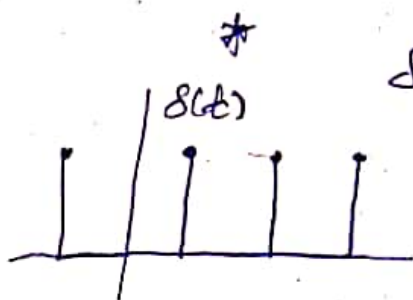
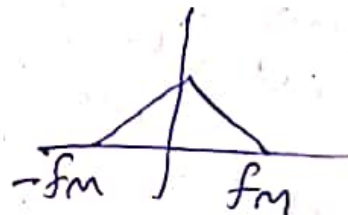
$$f_s = \frac{1}{T_s}$$

low-pass sampling theorem: (0 to f_m)

band pass
↳ f_m to f_{max}
↓
can do much lesser than $2f_m$



at least ⇒



⇓



$$s'(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT)$$

$$s'(t) = \sum_{n=-\infty}^{\infty} c_k e^{jk\omega_0 t}$$

$$\omega_0 = \frac{2\pi}{T}$$

$$s'(t) = a_0 + \sum_{n=1}^{\infty} (a_n \cos(n\omega_0 t) + b_n \sin(n\omega_0 t))$$

$$c_k = \frac{1}{T} \int_{-T/2}^{T/2} s'(t) \cdot e^{-jk\omega_0 t} dt$$

$$c_k = 1/T$$

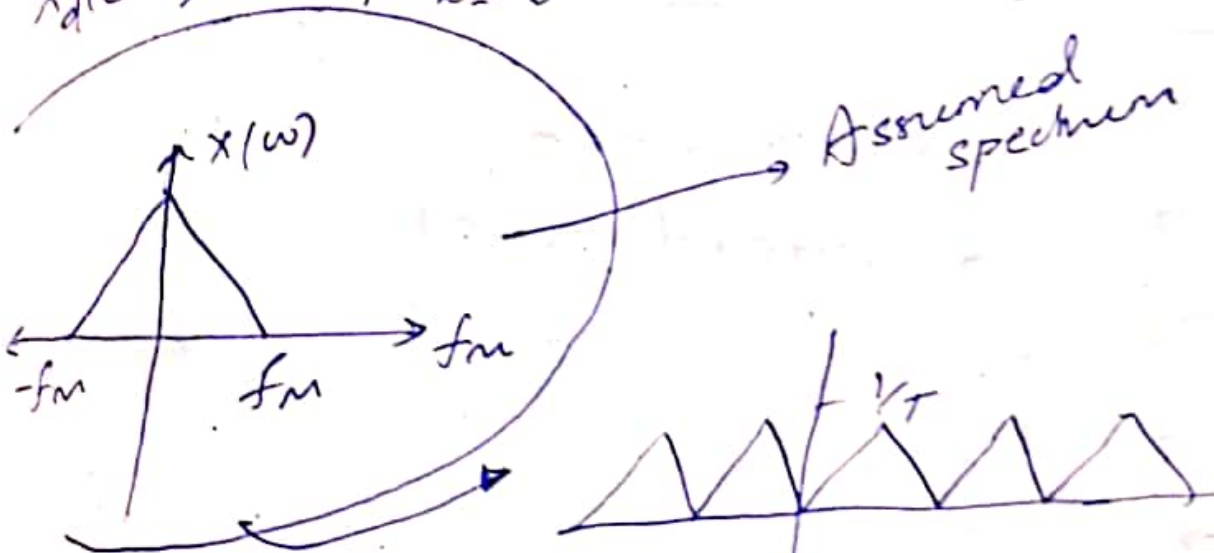
$$s'(t) = \sum_{n=-\infty}^{\infty} \frac{1}{T} \cdot e^{jk\omega_0 t}$$

$$x_d(n) = x(t) \cdot \delta'(t)$$

$$= x(t) \cdot \sum_{n=-\infty}^{\infty} \frac{1}{T} \cdot e^{jk\omega_0 t}$$

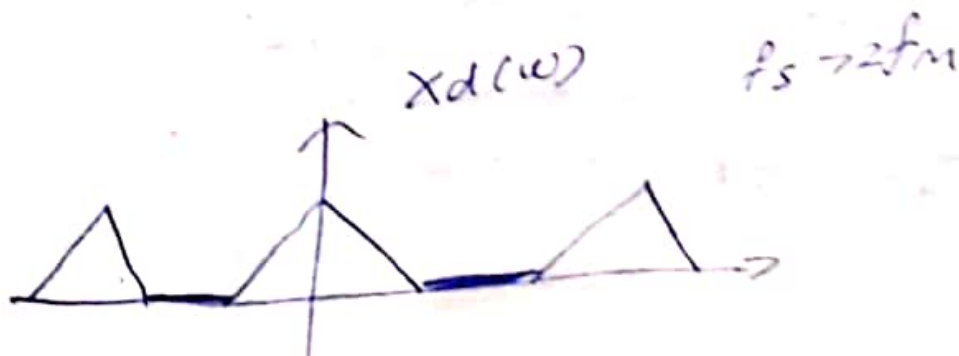
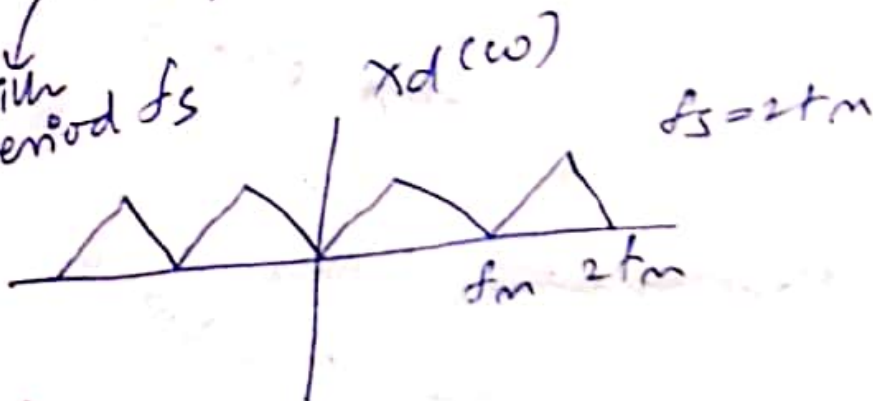
$$X_d(e^{j\omega}) = \frac{1}{T} \left[\mathcal{F} \left\{ x(t) \sum_{k=-\infty}^{\infty} e^{jk\omega_0 t} \right\} \right]$$

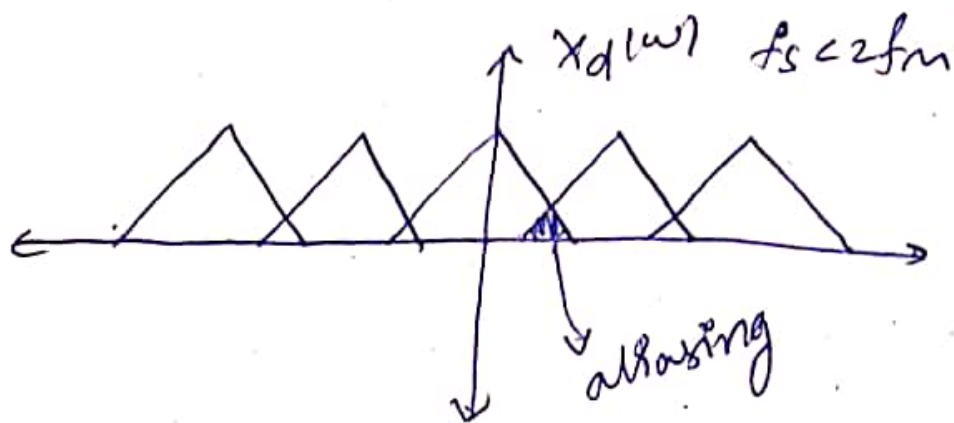
$$X_d(e^{j\omega}) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X(e^{j(\omega - k\omega_0)})$$



Discrete signal became periodic version of continuous signal but by a factor of $1/T$

with period f_s





$0 \rightarrow 0.3125 \Rightarrow 000$
 $5/8 \rightarrow 0.3125 + d \Rightarrow 001$

$0-5V$
 \downarrow
 3-bits

$5/4$

$15/8$

$5/2$

$25/8$

$30/8$

$35/8$

5

step-size: $\frac{V_{\max} - V_{\min}}{2^N}$

max-quantization error: $\frac{V_{\max} - V_{\min}}{2^N + 1}$

$3.25 \xrightarrow{0.3125} \text{error}$
 $\quad \quad \quad \text{encoding}$

$3.2 \quad \underline{101} \quad 0.2375$

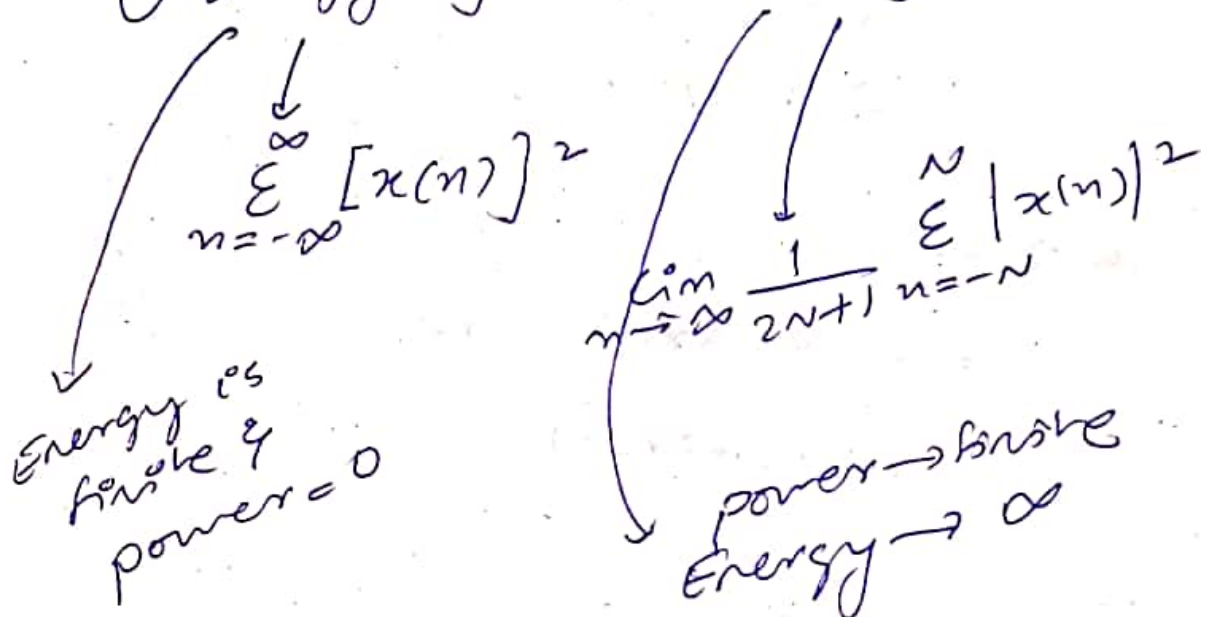
$\Rightarrow \text{Music} - 128 \text{ kbps} - f_s \times N$

* Different kinds of signals & system

- i) \downarrow periodic/apperiodic
- ii) CT/DT
- iii) even & odd

iv) 1D, 2D, 3D

v) Energy signal / Power signal



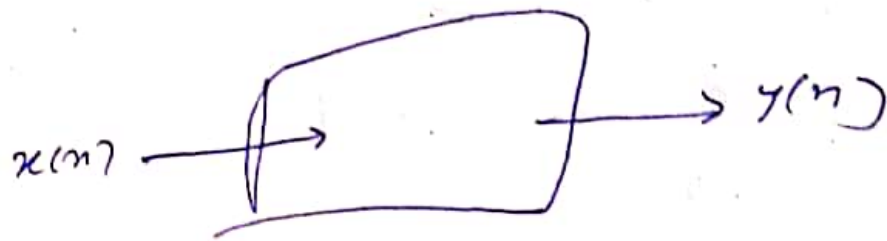
vi) Deterministic / Random

$x(t)$

* Discrete-time systems

$x(n)$ \downarrow discrete
 $x(t)$ \downarrow continuous
 $= \{1, 2, 3, 4\}$
 \uparrow
 $= x(0) \cdot \delta(n) + x(1) \cdot \delta(n-1) + x(2) \cdot \delta(n-2) + \dots$

$$y(n) = x(n) + x(n-1) + y(n-2) \cdot 2 + y(n-1)$$



- 1) Delay
- 2) Adder
- 3) Multiplier

* Linear

$$a_1 x_1(t) + b x_2(t) \rightarrow a_1 y_1(t) + b y_2(t)$$

$$y(n) = x(n-1)$$

* Time invariance

$$x(n) \rightarrow y(n)$$

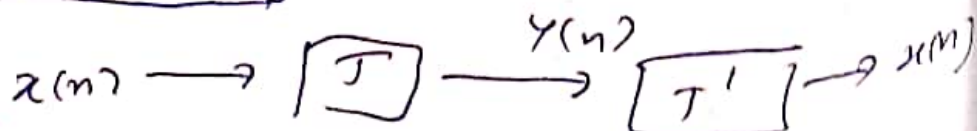
$$x(n-d) \rightarrow y(n-d)$$

* Stable systems

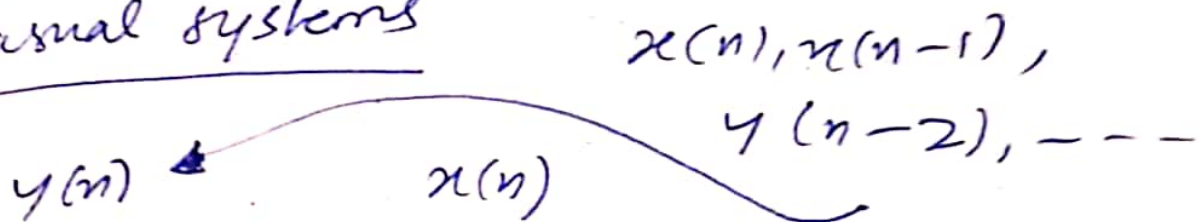
$$x(n) \leq |M_x|$$

$$y(n) \leq |M_y|$$

* Invertibility



* Casual systems



output depends on present
inputs, past inputs,
past outputs

* Memory \rightarrow memoryless

* $\frac{\text{Max} - \text{Min}}{2^{N+1}}$ \rightarrow quantisation error

Bit-rate $\rightarrow f_s \times N$

* Signals

- Discrete / Digital Analysis
- periodic / aperiodic
- odd, even
- Energy $\Rightarrow E \rightarrow \text{finite}, P = 0$
- Power $\Rightarrow E \rightarrow \infty, P = \text{finite}$
- 1D, 2D, 3D

* System

\rightarrow Linear-system $\begin{cases} \text{homogeneity} \\ \text{superposition} \end{cases}$

$$a x_1(n) + b x_2(n)$$

$$\rightarrow a y_1(n) + b y_2(n)$$

\rightarrow Time-invariant, Time-variant

$$\rightarrow x(n) \rightarrow y(n)$$

$$x(n-k) \rightarrow y(n-k)$$

* \rightarrow Memoryless, Memory

\downarrow
depends
only
on $x(n)$

\rightarrow Causal system \rightarrow practical

\rightarrow stability \rightarrow Bounded

casual
linear
Time-inv
Stable

LTI

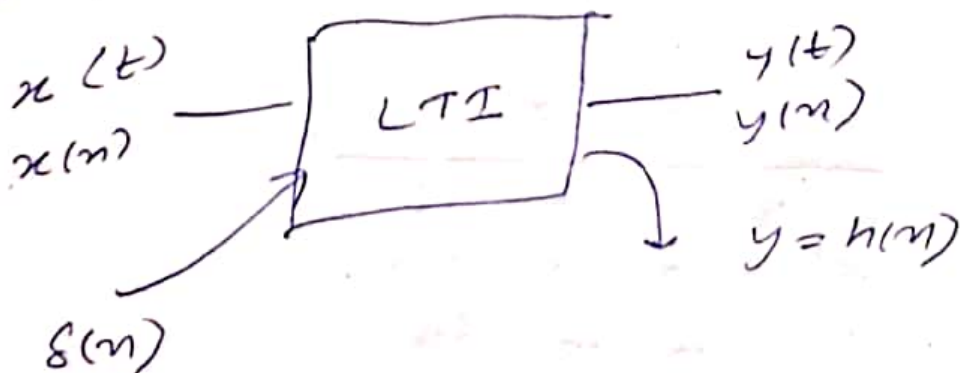
→ convolution

$$x_1(n) * x_2(n)$$

$$= \sum_{m=-\infty}^{\infty} x_1(m) \cdot x_2(n-m)$$

$$x_1(t) * x_2(t) = \int_{-\infty}^{\infty} x_1(\tau) \cdot x_2(t-\tau) d\tau$$

→



$$y(n) = x(n) * h(n)$$

$$\rightarrow x(0) = \{ \dots, x(-2), x(-1), x(0), \dots \}$$

$$x(n) = \dots + x(-2) \cdot \delta(n+2) + x(-1) \cdot \delta(n+1) + x(0) \cdot \delta(0) + \dots + x(1) \cdot \delta(n-1) + \dots + x(2) \cdot \delta(n-2) + \dots$$

$$\begin{aligned}
 y(n) &= \dots + x(-2) \cdot h(n+2) + \dots \\
 &\quad + \dots + x(1) \cdot h(n-1) \\
 &= \sum_{m=-\infty}^{\infty} x(m) \cdot h(n-m)
 \end{aligned}$$

$$\begin{aligned}
 \Rightarrow y(n) &= x(n) + x(n-1) \\
 h(n) &= \delta(n) + \delta(n-1) \quad \left. \begin{array}{l} \text{impulse} \\ \text{response} \end{array} \right\}
 \end{aligned}$$

* Linear convolution

$$x(n) = \{1, 2, 3, 4\}, \quad h(n) = \{4, 5, 6\}$$

$$y(n) = x(n) * h(n) = \{4, 13, 28, 43, 38, 24\}$$

	1	2	3	4
4	4	8	12	16
5	5	10	15	20
6	6	12	18	24

$$\|y(n)\| = \|x(n)\| + \|h(n)\| - 1$$

* Circular convolution

$$\Rightarrow x(t) * h(t) \rightarrow x(\omega) \cdot h(\omega)$$

$$\begin{aligned}
 \text{DFT} \{x(n) * h(n)\} &\rightarrow X_1(k) \cdot X_2(k) \\
 \downarrow N = \text{size}
 \end{aligned}$$

$$\rightarrow \begin{Bmatrix} 1, 2, 3, 4 \\ 4, 5, 6 \end{Bmatrix} \rightarrow \begin{Bmatrix} 1, 2, 3, 4 \\ 4, 5, 6, 0 \end{Bmatrix}$$

$$y(n)_N = \sum_N x(m) \cdot h(n-m)_N$$

$$\{1, 2, 3, 4\}, \{4, 5, 6\}$$

$$\begin{bmatrix} 1 & 4 & 3 & 2 \\ 2 & 1 & 4 & 3 \\ 3 & 2 & 1 & 4 \\ 4 & 3 & 2 & 1 \end{bmatrix} \cdot \begin{bmatrix} 4 \\ 5 \\ 6 \\ 0 \end{bmatrix} = \begin{bmatrix} 4 & 2 \\ 3 & 7 \\ 2 & 8 \\ 4 & 3 \end{bmatrix}$$

→ Circular convolution
↳ Linear convolution

$$\begin{bmatrix} 4 \\ 3 \end{bmatrix}$$

$$\begin{Bmatrix} 1, 2, 3, 4, 0, 0 \\ 4, 5, 6, 0, 0, 0 \end{Bmatrix}$$