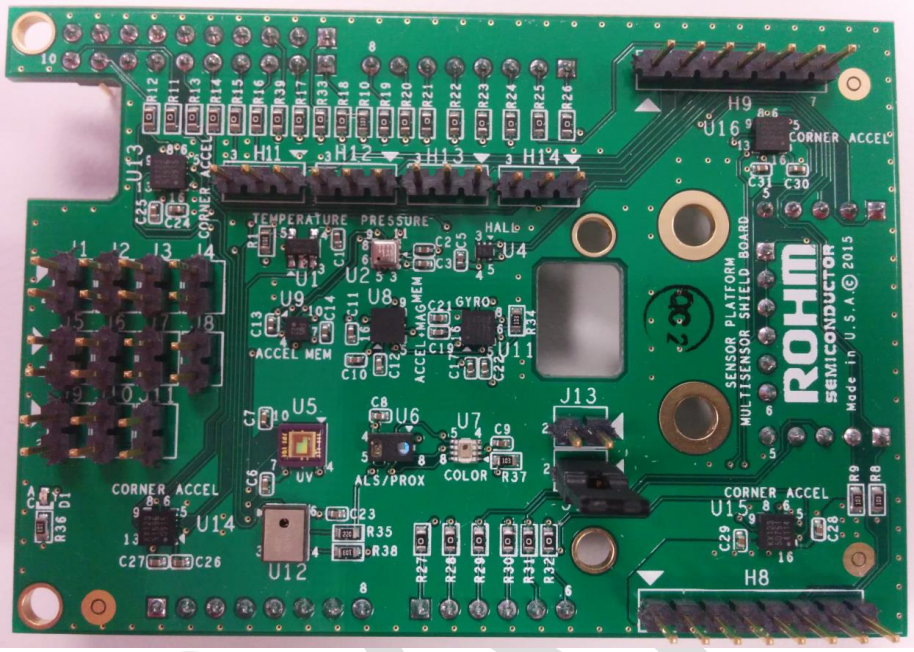
U.S. Design Center

Product Overview: SENSORSHLD0-EVK-101
ROHM Multi-Sensor Shield



Above: Top view of ROHM SENSORSHLD0-EVK-101

25 September 2015, Revision A

Introduction

The following document was written to provide a brief connection guide and general information about ROHM's SENSORSHLD0-EVK-101. Supplementary information about this board can be found at the following repository link.

ROHM's Multi-Sensor Shield GitHub Repository Page:
https://github.com/ROHMUSDC/ROHM_SensorPlatform_Multi-Sensor-Shield

ROHM's SENSORSHLD0-EVK-101 is a shield evaluation platform that connects all ROHM sensor products onto a single board. This shield uses standard Arduino shield interface pins; therefore can connect to any evaluation kit that has a shield interface header. The shield contains the following sensors:

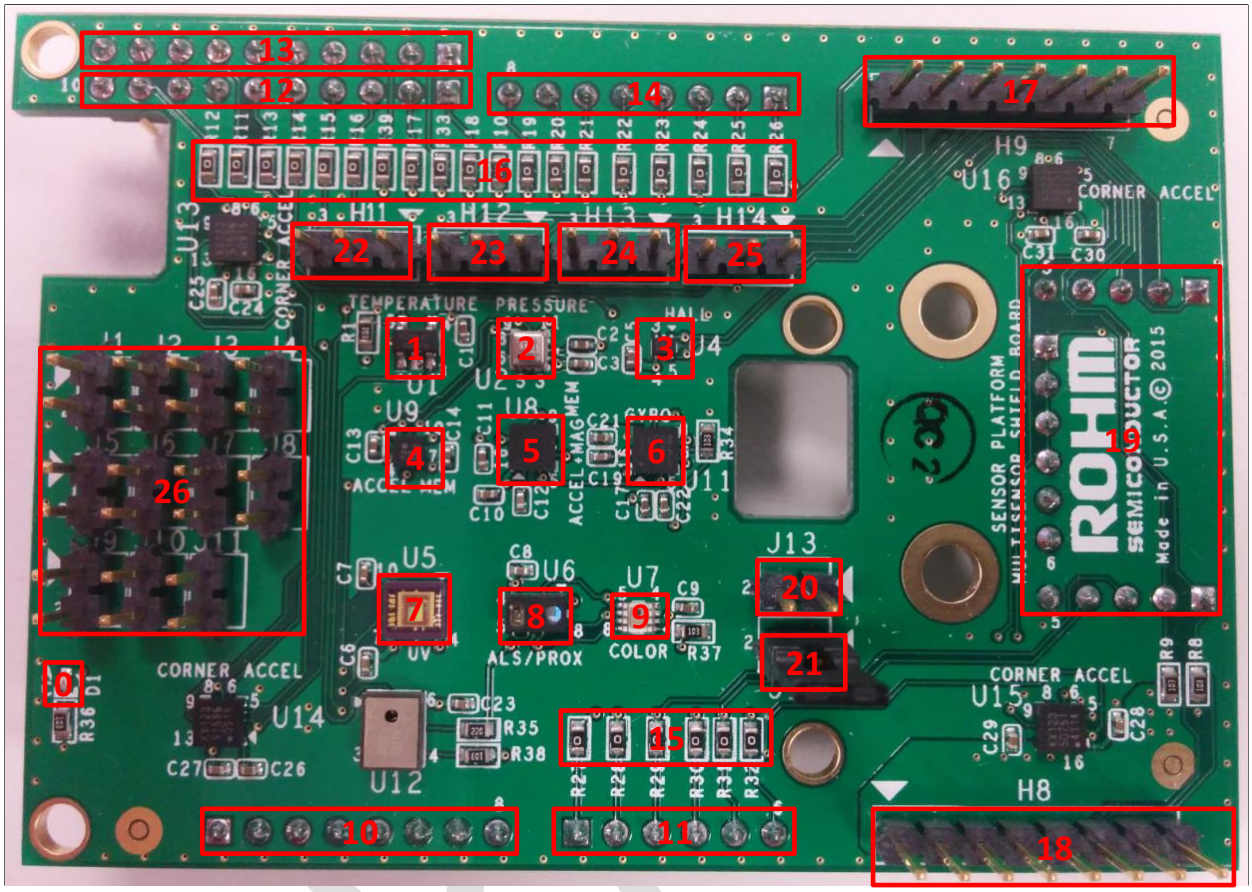
- ROHM BDE0600G – Analog Temperature Sensor
- LAPIS ML8511 – Analog UV Sensor
- ROHM BU52014HFV – Hall Switch Sensor
- KIONIX KMX62 – Digital Accelerometer and Magnetometer
- ROHM BM1383GLV – Digital Barometric Pressure Sensor
- ROHM RPR-0521 – Digital Ambient Light Sensor and Proximity Sensor
- ROHM BH1745 – Digital Color Sensor
- KIONIX KX122 – Digital Accelerometer
- KIONIX KXG03 – Digital Gyroscope Sensor

General Board Specifications

For the specifications of the individual sensors on this shield board, please refer to the associated datasheet/application note that can be found on www.rohm.com

In general, this shield board will be powered by the V3.3 pin (Pin 4 of Header H4) on the shield board. Please only connect a maximum of 3.3V to this pin as it is tied to the VDD of the full system and some of the sensors onboard cannot tolerate voltages greater than 3.3V.

Hardware Explanation Section

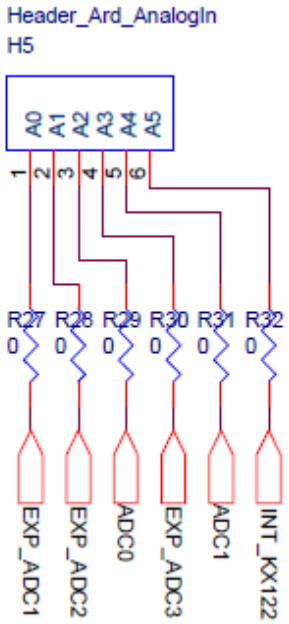


0. POWER ON LED: When the shield have 3.3V connected to the VCC Net, this LED will turn on
1. BDE0600G Temperature Sensor
2. BM1383GLV Pressure Sensor
3. BU52014HFV Hall Effect Switch Sensor
4. KX122 Accelerometer
5. KMX62 Accelerometer and Magnetometer Combo Sensor
6. KXG03 Gyroscope and Accelerometer Combo Sensor
7. ML8511 UV Sensor
8. RPR-0521 Combo Ambient Light Sensor and Proximity Sensor
9. BH1745 RGB Color Sensor
10. H4 – Standard Arduino Power Header
    a. On the shield board, this header is only connected to pins 4, 7 and 8. See section below for an explanation of the shield connector's pin out
11. H5 – Standard Arduino AnalogIn Header
    a. See section below for an explanation of the shield connector's pinout
12. H7 – Standard Arduino Digital Header 1

a. See section below for an explanation of the shield connector's pinout

13. H10 - Auxiliary header for Microphone interface
14. H6 – Standard Arduino Digital Header 2
    a. See section below for an explanation of the shield connector's pinout
15. 0 Ohm Jumper Line for pins connected to H5

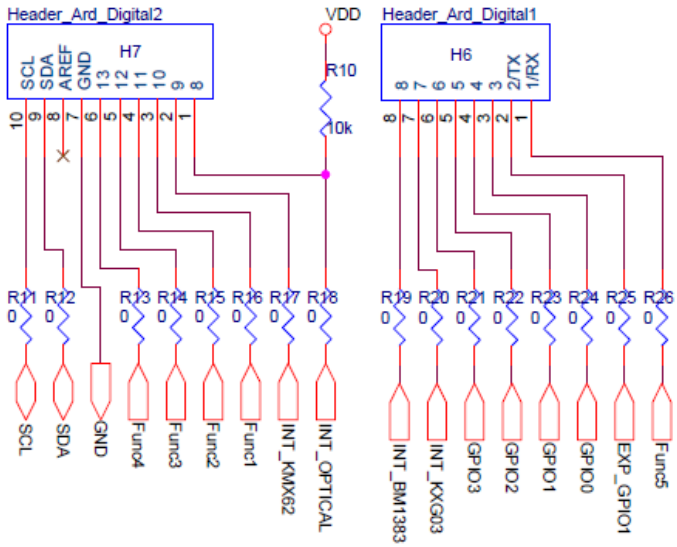
a.



b. The purpose of these headers are to depopulate pin connections on the shield if the user decides to use a pass through path or needs to adjust pin functionality depending on the needed pin configuration

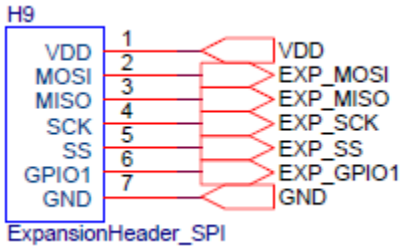
16. 0 Ohm Jumper Line for pins connected to H6 and H7

a.



b. The purpose of these headers are to depopulate pin connections on the shield if the user decides to use a pass through path or needs to adjust pin functionality depending on the needed pin configuration

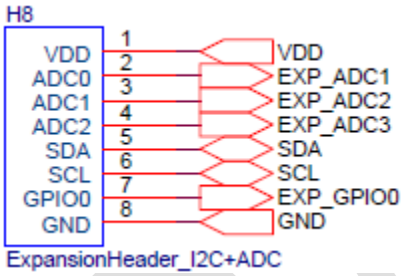
17. H9 – Expansion Header for SPI devices



a.

b. This header is an expansion header to connect any additional SPI based sensors that you may want to use

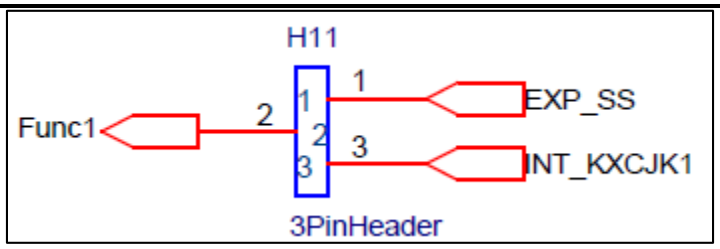
18. H8 – Expansion Header for I2C devices



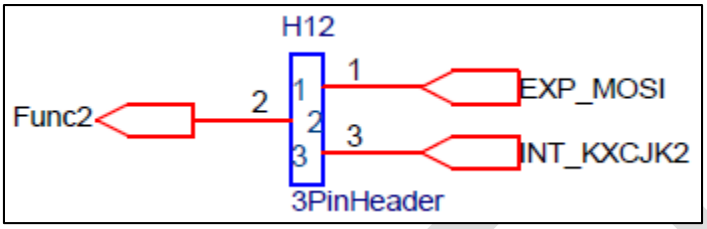
a.

b. This header is an expansion header to connect any additional I^2C based sensors that you may want to use

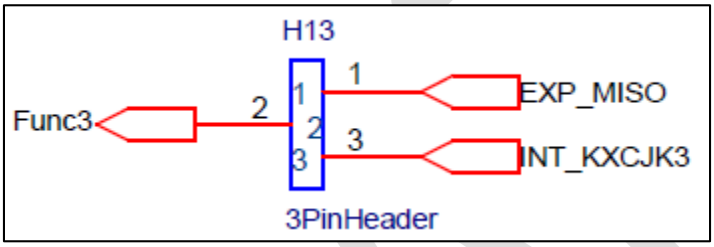
19. Interface to the ROHM Sensor Platform Kit
    a. This is the interface onto the base board provided in ROHM's sensor platform kit
    b. Please see the following repository for this Sensor Kit for additional Information
        i. https://github.com/ROHMUSDC/ROHMSensorPlatformEVK
20. J13 – Jumper Setting for KXG03 Gyroscope Sensor
    a. When Jumper is not used, the ADDR pin on the Gyro will be tied low, making the I2C address 0x4E
    b. When Jumper is used, the ADDR pin on the Gyro will be tied high, making the I2C address 0x4F
21. J12 – Jumper Setting for the BH1745 Color Sensor
    a. When Jumper is not used, the ADDR pin on the color sensor will be tied low, making the I2C address 0x38
    b. When Jumper is used, the ADDR pin on the color sensor will be tied high, making the I2C address 0x39
22. H11 – Function 1 Pin assignment

a. 

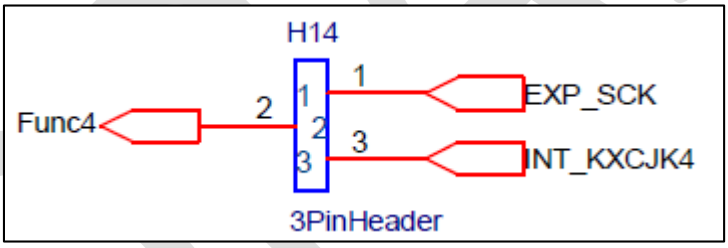
23. H12 – Function 2 Pin assignment

a. 

24. H13 – Function 3 Pin assignment

a. 

25. H14 – Function 4 Pin assignment

a. 

26. Do Not Use
    a. This was initially added to be used with the older sensor platform kit; however, this was deemed unnecessary for future revisions. This will be removed/revised for future revisions of this board.

General Board Software Explanation

Software explanations will differ, depending on the application processor you plan to use. Therefore, please see this shield's repository for platform guides for using this shield:

https://github.com/ROHMUSDC/ROHM_SensorPlatform_Multi-Sensor-Shield

…/ROHM_SensorPlatform_Multi-Sensor-Shield/Platform Code/