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Product Overview: SENSORSHLD1-EVK-101
ROHM Multi-Sensor Shield
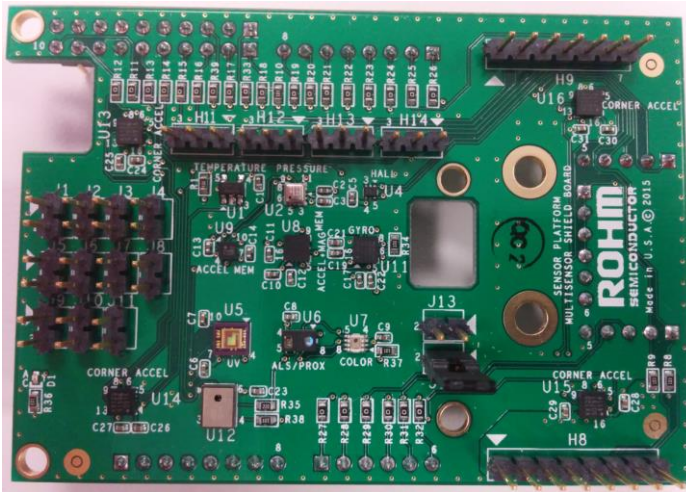
Above: Top view of ROHM SENSORSHLD0-EVK-101

25 September 2015, Revision A

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Introduction

The following document was written to provide a brief connection guide and general information about ROHM's SENSORSHLD1-EVK-101. Supplementary information including application examples and HW design files for this board can be found at the following repository link.

ROHM's Multi-Sensor Shield GitHub Repository Page:
https://github.com/ROHMUSDC/ROHM_SensorPlatform_Multi-Sensor-Shield

ROHM's SENSORSHLD1-EVK-101 is a shield evaluation platform that connects all ROHM sensor products onto a single board. This shield uses standard Arduino shield interface pins; therefore can connect to any evaluation kit that has a shield interface header. The shield contains the following sensors:

- Core Sensors:
    - ROHM BDE0600G – Analog Temperature Sensor
    - ROHM BM1383AGLV – Digital Barometric Pressure Sensor
    - ROHM BU52014HFV – Hall Switch Sensor (Omnipolar with Polarity Discrimination)
    - ROHM BM1422GMV – Magnetometer Sensor
    - KIONIX KX122 – Digital Accelerometer
    - KIONIX KMX62 – Digital Magnetometer and Accelerometer
    - KIONIX KXG03 – Digital Gyroscope and Accelerometer
    - LAPIS ML8511A – Analog UV Sensor
    - ROHM RPR-0521 – Digital Ambient Light Sensor and Proximity Sensor
    - ROHM BH1745 – Digital Color Sensor

- Special Functions:
    - KNOWLES SPM0423HD4H-WB – Digital Microphone
        - Primarily for use with NXP MCU Lineup
    - KIONIX KX123-1039, KX124-1050 – Accelerometer
        - For four corner Accelerometer algorithm development
        - Difference between 1039 and 1050 is the I2C register address scheme to control all 4 accelerometers using a single I2C master

NOTE: As of 3-3-2016, ROHM is currently working on making revisions to the SENSORSHLD0-EVK-101 to SENSORSHLD1-EVK-101. This documentation DOES NOT provide all details about that board yet, but is a placeholder DS for that product once ready. If you have any immediate concerns about this topic, please feel free to let us know at engineering@rohmsemiconductor.com

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Key Differences between SHLD0 and SHLD1

- Removed Erroneous Jumpers
- Removed J5 to J11 and adjusted routing for J1 to J4
- Added ROHM BM1422GMV Magnetometer, 1.8V level shifter, and 1.8V LDO (for Magnetometer usage)
- Changed pressure sensor from BM1383GLV to BM1383AGLV. (No HW change, but new PN has new FW I2C register mapping)
- PN Change from ML8511 to ML8511A (only chip labelling change)
- KIONIX Corner Accelerometer: one PN, KX123-1050, has been adjusted to the KX124-1050

General Board Specifications

For the specifications of the individual sensors on this shield board, please refer to the associated datasheet/application note that can be found on www.rohm.com

In general, this shield board will be powered by the V3.3 pin (Pin 4 of Header H4) on the shield board. Please only connect a maximum of 3.3V to this pin as it is tied to the VDD of the full system and some of the sensors onboard cannot tolerate voltages greater than 3.3V.

Commented [KB2]: These are planned differences… still open to any suggestions on how to make this shield a great evaluation board

Hardware Explanation Section
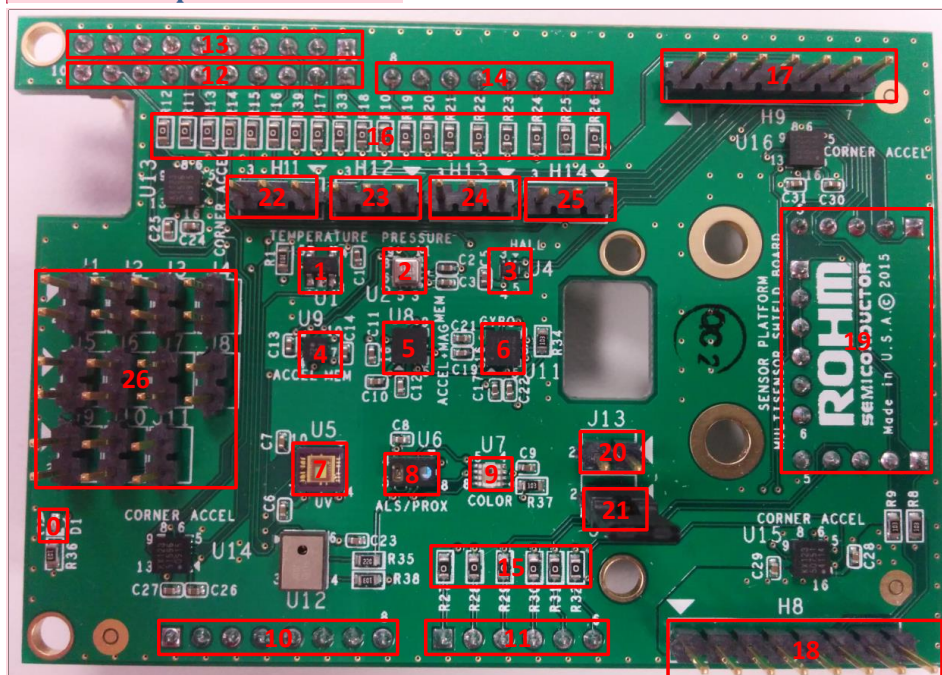
0. POWER ON LED: When the shield have 3.3V connected to the VCC Net, this LED will turn on
1. BDE0600G Temperature Sensor
2. BM1383GLV Pressure Sensor
3. BU52014HFV Hall Effect Switch Sensor
4. KX122 Accelerometer
5. KMX62 Accelerometer and Magnetometer Combo Sensor
6. KXG03 Gyroscope and Accelerometer Combo Sensor
7. ML8511 UV Sensor
8. RPR-0521 Combo Ambient Light Sensor and Proximity Sensor
9. BH1745 RGB Color Sensor
10. H4 – Standard Arduino Power Header
    a. On the shield board, this header is only connected to pins 4, 7 and 8. See section below for an explanation of the shield connector's pin out
11. H5 – Standard Arduino AnalogIn Header
    a. See section below for an explanation of the shield connector's pinout
12. H7 – Standard Arduino Digital Header 1

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      a. See section below for an explanation of the shield connector's pinout
13. H10 - Auxiliary header for Microphone interface
14. H6 – Standard Arduino Digital Header 2
      a. See section below for an explanation of the shield connector's pinout
15. 0 Ohm Jumper Line for pins connected to H5
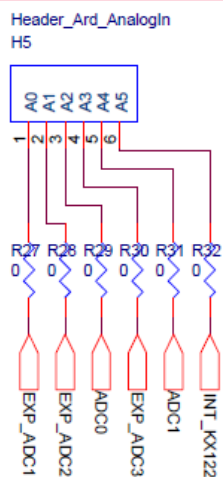
    a.
    b. The purpose of these headers are to depopulate pin connections on the shield if the user decides to use a pass through path or needs to adjust pin functionality depending on the needed pin configuration
16. 0 Ohm Jumper Line for pins connected to H6 and H7
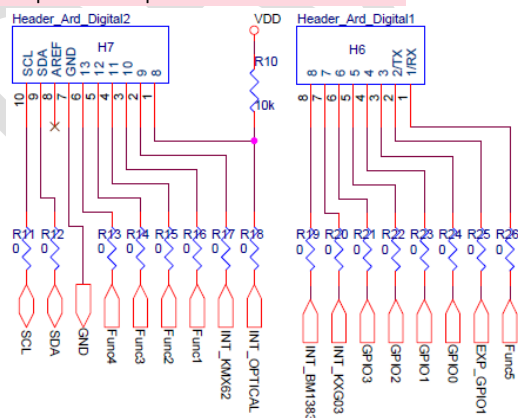

    a.

b. The purpose of these headers are to depopulate pin connections on the shield if the user decides to use a pass through path or needs to adjust pin functionality depending on the needed pin configuration

17. H9 – Expansion Header for SPI devices
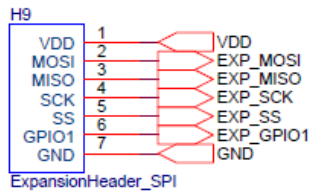
a.
b. This header is an expansion header to connect any additional SPI based sensors that you may want to use

18. H8 – Expansion Header for I2C devices
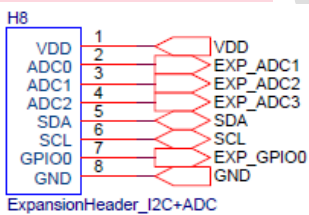
a.
b. This header is an expansion header to connect any additional I^{2}C based sensors that you may want to use

19. Interface to the ROHM Sensor Platform Kit
   a. This is the interface onto the base board provided in ROHM's sensor platform kit
   b. Please see the following repository for this Sensor Kit for additional Information
   i. https://github.com/ROHMUSDC/ROHMSensorPlatformEVK

20. J13 – Jumper Setting for KXG03 Gyroscope Sensor
   a. When Jumper is not used, the ADDR pin on the Gyro will be tied low, making the I2C address 0x4E
   b. When Jumper is used, the ADDR pin on the Gyro will be tied high, making the I2C address 0x4F
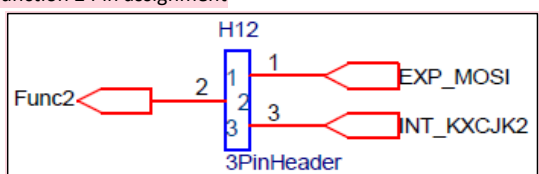
21. J12 – Jumper Setting for the BH1745 Color Sensor
   a. When Jumper is not used, the ADDR pin on the color sensor will be tied low, making the I2C address 0x38
   b. When Jumper is used, the ADDR pin on the color sensor will be tied high, making the I2C address 0x39

22. H11 – Function 1 Pin assignment

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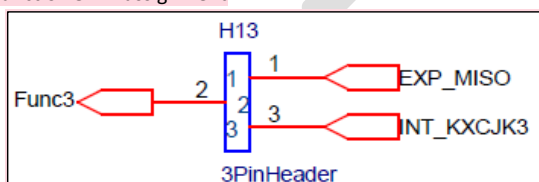SEMICONDUCTOR

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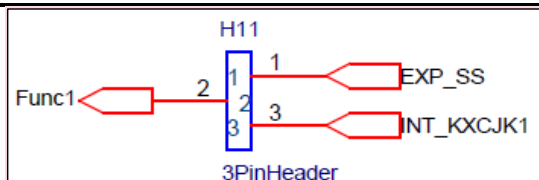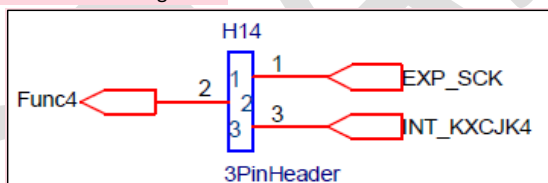

a.

23. H12 – Function 2 Pin assignment

a.

24. H13 – Function 3 Pin assignment

a.

25. H14 – Function 4 Pin assignment

a.

26. Do Not Use

    a. This was initially added to be used with the older sensor platform kit; however, this was deemed unnecessary for future revisions. This will be removed/revised for future revisions of this board.

General Board Software Explanation

Software explanations will differ, depending on the application processor you plan to use. Therefore, please see this shield's repository for platform guides for using this shield:

https://github.com/ROHMUSDC/ROHM_SensorPlatform_Multi-Sensor-Shield

…/ROHM_SensorPlatform_Multi-Sensor-Shield/Platform Code/

> **Commented [KB3]:** ALL of this will change, but we won't be able to change until we spin the new board… need picture reference of new board, etc….