«Singleton» ROSModel

- monitoring_proxy: rospy.ServiceProxy
- model_lock:threading.Lock
- log:list<list<string»
- root_item: AbstractItem
- item_delegate:SizeDelegate
- log_model:QStandardItemModel

+ __init__(data:list,)
+ <u>get_instance(): ROSModel</u>
+ get_log():list<list<strings»
+ data(index:QModelIndex, role:int):QVariant
+ flags(index:QModelIndex):ItemFlags
+ headerData(section:int, orientation:Orientation, role:int):QVariant
+ index(row:int, column:int, parent:QModelIndex):QModelIndex
+ parent(index:QModelIndex):QModelIndex
+ rowCount(parent:QModelIndex):int
+ columnCount(parent:QModelIndex):int
+ update_model(data:list)
+ transform_data(data:AbstractItem)
+ transform_data(data:msgs.statistics)
+ transform_data(data:msgs.HostStatistics)
+ transform_data(data:msgs.RatedStatistics)
+ transform_data(data:msgs.StatisticHistory)
+ trigger_node_action(node:string, action:RemoteAction)
+ add_log_item(list<string>)