

BufferThread:threading.Thread

- buffer_lock:threading.Lock
 - model:ROSMModel
 - timer:rospy.Timer
 - buffer:list
 - rated_buffer:list<RatedStatistics>
 - running: bool
 - monitoring_proxy: rospy.ServiceProxy
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- + __init__(model: ROSModel)
 - + start()
 - + update_model()
 - + add_buffer_item(object)
 - + add_buffer_item(RatedStatistics)