

EE559-MPR

Homework-4-written Report

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1)

a) w.k.t $g(x) = w_0 + \underline{w}^T x$

The decision surface is a hyperplane, if $g(x)$ is linear.
If x_1 and x_2 are on H , then,

Taking, $g(x_1) - g(x_2) = 0$
 $w^T x_1 + w_0 - (w^T x_2 + w_0) = 0$
 $w^T x_1 - w^T x_2 = 0$
 $w^T (x_1 - x_2) = 0$

The dot product is 0
 $\therefore w$ is normal to any vector lying in the hyperplane

b) $d_H = \frac{w^T x + w_0}{\|w\|}$

let $x = x_1 + a\underline{w}$

$$\begin{aligned} d_H &= \frac{\underline{w}^T (x_1 + a\underline{w}) + w_0}{\|w\|} \\ &= \frac{\underline{w}^T x_1 + \underline{w}^T a\underline{w} + w_0}{\|w\|} \\ &= \frac{(\underline{w}^T x_1 + w_0) + \underline{w}^T a\underline{w}}{\|w\|} \end{aligned}$$

$$\begin{aligned}
 &= \frac{\underline{w}^T \underline{w} a}{\|\underline{w}\|} \\
 &= \frac{\|\underline{w}\|^2 a}{\|\underline{w}\|} \\
 &= \|\underline{w}\| a \\
 &\quad \downarrow \\
 &\text{constant}
 \end{aligned}$$

$\therefore \underline{w}$ points to the +ve side of H if $a > 0$

c) w.k.t $d_H = \frac{g(x)}{\|\underline{w}\|} \rightarrow$ distance b/w a point $x^{(t)}$ and a hyperplane

$$= \frac{\underline{w}^T \underline{x} + w_0}{\|\underline{w}\|}$$

In augmented space $\underline{x}^{(+)} = \begin{bmatrix} \underline{w}^T \underline{x} + w_0 \\ \underline{w}^T \underline{x} + w_0 \end{bmatrix}$

$$d_H = \frac{g(x^{(+)})}{\|\underline{w}\|}$$

w_0 is included in \underline{w} ,
 $\underline{w}^{(+)} = \begin{bmatrix} w_0 \\ \underline{w}_1 \end{bmatrix}$

$$\underline{x}^{(+)} = \begin{bmatrix} 1 \\ \underline{x} \end{bmatrix}$$

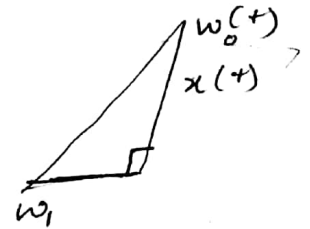
d) weight space at arbitrary point $\underline{w}^{(t)}$
 in a hyperplane $g(x^{(+)}) = \underline{w}^{(+)\top} \underline{x}^{(+)} = 0$

for, $\underline{x}^{(+)} \perp H$
 $\underline{w}_1^{(+)}$ and $\underline{w}_2^{(+)}$ lie on the hyperplane $g(x^{(+)}) = 0$
 $\underline{w}_1^{(+)\top} \underline{x}^{(+)} = 0$
 $\underline{w}_2^{(+)\top} \underline{x}^{(+)} = 0$ — (2)

$$\underline{w}_1^{(+)\top} x^{(+)} - \underline{w}_2^{(+)\top} x^{(+)} = 0$$

$$(\underline{w}_1^{(+)} - \underline{w}_2^{(+)}) x^{(+)} = 0$$

$$\Rightarrow x^{(+)} \perp H$$



r is the projection of $\underline{w}^{(+)} - \underline{w}_1^{(+)}$ onto $x^{(+)}$

$$r = \frac{(\underline{w}^{(+)} - \underline{w}_1^{(+)}) \cdot \underline{x}^{(+)}}{\| \underline{x}^{(+)} \|}$$

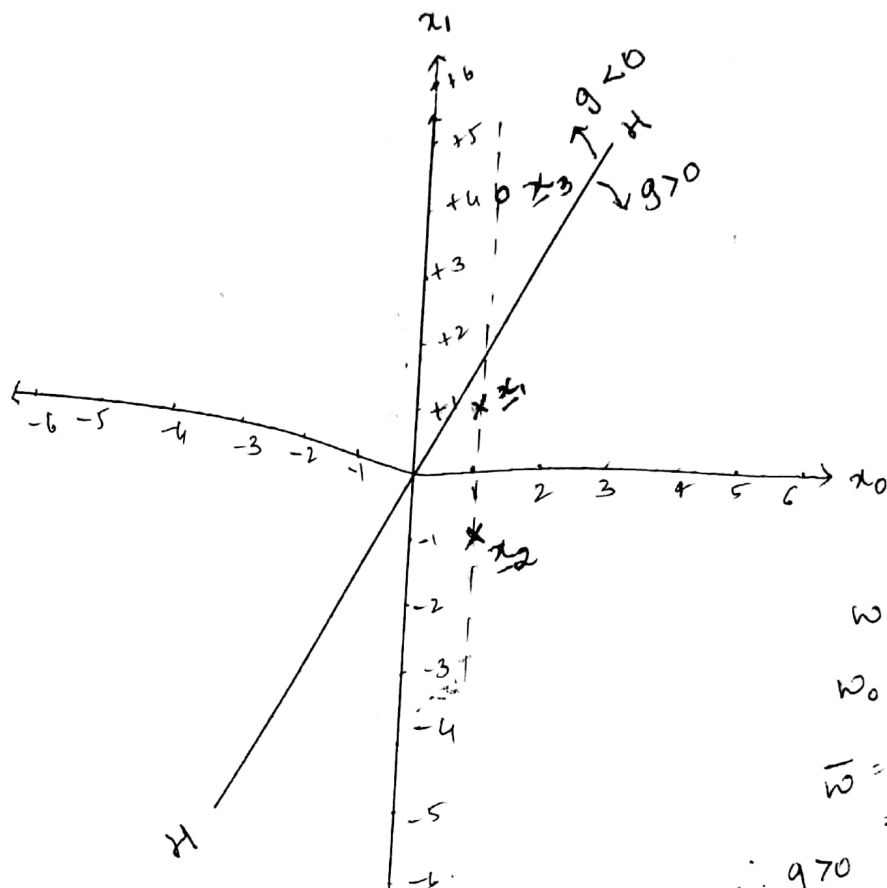
$$= \frac{(\underline{w}^{(+)} - \underline{w}_1^{(+)})^\top \underline{x}^{(+)}}{\| \underline{x}^{(+)} \|}$$

$$= \frac{\underline{w}^{(+)\top} x^{(+)} - \underline{w}_1^{(+)\top} x^{(+)}}{\| \underline{x}^{(+)} \|}$$

$$= \frac{\underline{w}^{(+)\top} x^{(+)}}{\| \underline{w}^{(+)} \|}$$

when $r > 0$, it lies on the positive side of hyperplane
also depends on which class $x^{(+)}$ is in.

2)
a)



$\times S_1$
 $\circ S_2$

$$\mu = [0, 4]$$

$$w_1 = \mu_1 - \mu_2 = 4$$

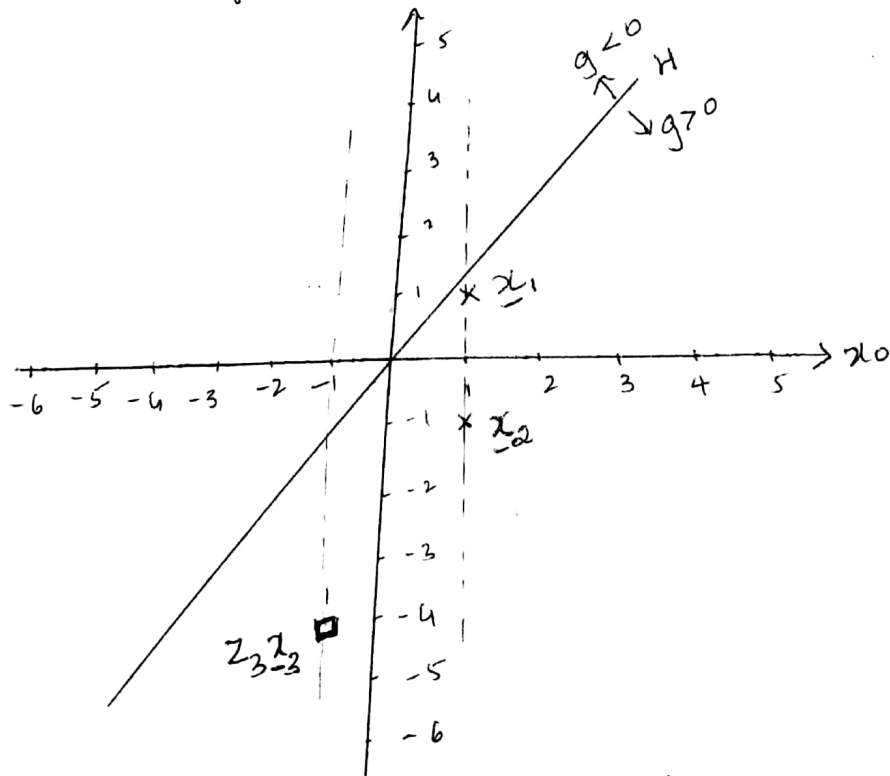
$$w_0 = \frac{1}{2} [0 - 4 \times 4] = -\frac{1}{2}$$

$$\bar{w} = [w_0, w_1]^T$$

$$= [-\frac{1}{2}, 4]^T$$

$\therefore g > 0$ is in the direction of \bar{w} & \perp to H

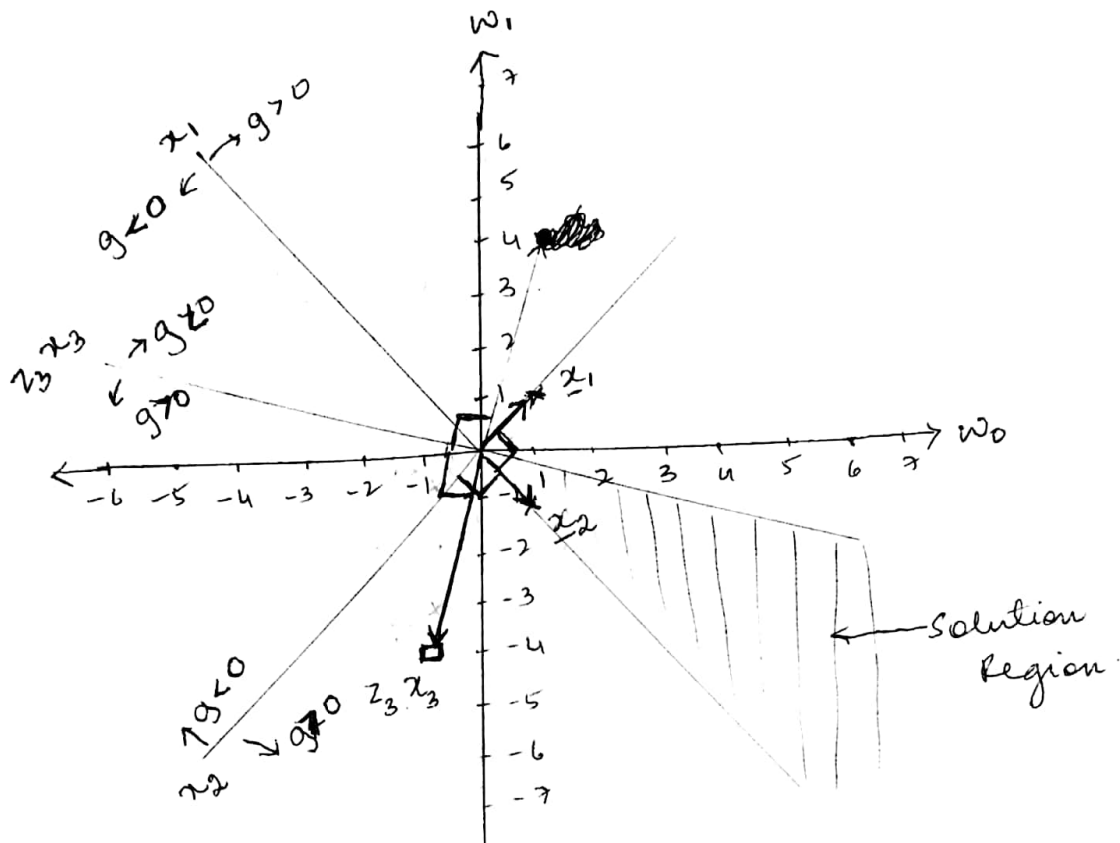
b) Since $Z_n^{(K)} = \begin{cases} +1 & \text{for } S_1 \\ -1 & \text{for } S_2 \end{cases}$, only $x_3 = (1, 4)$ gets reflected



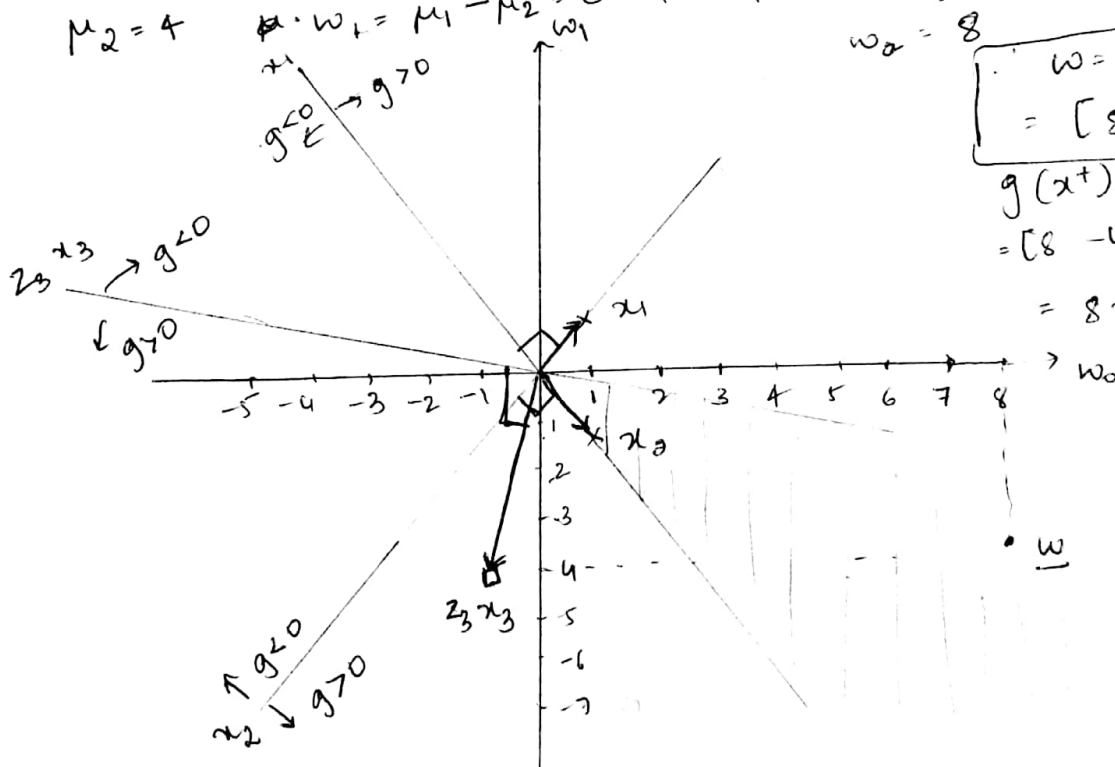
$\times S_1$
 $\circ S_2$
 $\square S_2$,
reflected

H ~~classifies~~ classifies the reflected datapoints correctly since it lies on $g > 0$

c)



d) $\mu_1 = 0$ $\mu_2 = 4$ $w_1 = \mu_1 - \mu_2 = 0 - 4 = -4$ $w_0 = -\frac{1}{2} [0 - 4 \times 4]$
 $w_0 = 8$



$$w = [w_0 \ w_1]^T$$

$$= [8 \ -4]^T$$

$$g(x^+) = w^T x^+$$

$$= [8 \ -4] \begin{bmatrix} x_0 \\ x_1 \end{bmatrix}$$

$$= 8x_0 - 4x_1$$

Yes, the weight vector w of the weight space lies in the solution region

② (a)

Given $\rightarrow p(\underline{x})$ is a scalar function of \underline{x}
 $f(p)$ is a scalar function of p

$$\therefore \nabla f[p(\underline{x})] = \begin{bmatrix} \frac{\partial f[p(\underline{x})]}{\partial p} \\ \vdots \\ \frac{\partial f[p(\underline{x})]}{\partial p} \end{bmatrix}$$

Taking for the i^{th} component,

$$\Rightarrow \frac{\partial f}{\partial p} [p(\underline{x})]$$

Applying chain rule,

$$\frac{\partial}{\partial p} f(p) \cdot D[p(\underline{x})]$$

$$\left[\frac{\partial}{\partial p} f(p) \right] \cdot \nabla p(\underline{x})$$

$$\left[\frac{\partial}{\partial p} f(p) \right] D[p(\underline{x})]$$

$$\frac{\partial}{\partial p} f(p) \cdot \nabla p(\underline{x})$$

$$\therefore \boxed{\nabla f(p(\underline{x})) = \frac{\partial}{\partial p} f(p) \cdot \nabla p(\underline{x})} \text{ Proved}$$

b)

relation given,

$$\frac{\partial}{\partial \underline{x}} [\underline{x}^T M \underline{x}] = (M + M^T) \underline{x}$$

~~to prove~~

Using this

$$\underline{x}^T M \underline{x} = \underline{x}^T \underline{x}$$

when,

$$M = \begin{bmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{bmatrix}_{d \times d}$$

$$\frac{\partial}{\partial \underline{x}} [\underline{x}^T M \underline{x}] = \frac{\partial}{\partial \underline{x}} [\underline{x}^T \underline{x}] = \left[\begin{bmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{bmatrix}_{d \times d} + \begin{bmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{bmatrix}_{d \times d} \right] \underline{x}$$

$$= [2I_{d \times d}] \underline{x}$$

$$= \begin{bmatrix} 2 & & 0 \\ & \ddots & \\ 0 & & 2 \end{bmatrix} \underline{x}$$

$$\boxed{\nabla_{\underline{x}} (\underline{x}^T \underline{x}) = 2 \underline{x}}$$

$$c) \nabla_{\underline{x}} (\underline{x}^T \underline{x})$$

$$\underline{x} = (x_1, \dots, x_d)$$

$$= \nabla_{\underline{x}} \sum_{i=1}^d x_i^2$$

$$= \frac{\partial}{\partial \underline{x}} \sum_{i=1}^d x_i^2$$

$$= \sum_{i=1}^d \frac{\partial}{\partial x_i} x_i^2$$

$$= \sum_{i=1}^d 2x_i = 2(x_1, x_2, \dots, x_n) = 2\underline{x} //$$

d)

w.k.t

$$a) \nabla_{\underline{x}} f[p(\underline{x})] = \left[\frac{\partial}{\partial p} f(p) \right] \nabla_{\underline{x}} p(\underline{x}) //$$

$$b) \nabla_{\underline{x}} (\underline{x}^T \underline{x}) = 2\underline{x}$$

$$\therefore \nabla_{\underline{x}} \left[(\underline{x}^T \underline{x})^3 \right] \Rightarrow$$

$$p = \underline{x}^T \underline{x} \\ f(p) = (\underline{x}^T \underline{x})^3$$

$$\therefore \frac{\partial}{\partial \underline{x}} (\underline{x}^T \underline{x})^3 \cdot \nabla_{\underline{x}} (\underline{x}^T \underline{x})$$

$$= 3 (\underline{x}^T \underline{x})^2 \cdot \frac{\partial}{\partial \underline{x}} \underline{x}^T \underline{x} \\ \downarrow \\ 2\underline{x}$$

$$= 3 (\underline{x}^T \underline{x})^2 \times 2\underline{x}$$

$$= 6 \underline{x} (\underline{x}^T \underline{x})^2$$

$$= 6 \underline{x} \left[\sum_{i=1}^n x_i^2 \right]$$

$$= 6 \underline{x} c //$$

4)

a)

$$\nabla_{\underline{w}} \|\underline{w}\|_2$$

$$\|\underline{w}\|_2 = \sqrt{\underline{w}^T \underline{w}}$$

$$p(\underline{w}) = \underline{w}^T \underline{w}$$

$$f(p) = \sqrt{\underline{w}^T \underline{w}}$$

$$\nabla_{\underline{w}} \|\underline{w}\|_2 = \nabla_{\underline{w}} f[p(\underline{w})] = \left[\frac{d}{dp} f(p) \right] \nabla_{\underline{w}} p(\underline{w})$$

$$= \frac{d}{dp} [\sqrt{\underline{w}^T \underline{w}}] \cdot \nabla_{\underline{w}} [\underline{w}^T \underline{w}]$$

$$= \frac{1}{2} (\underline{w}^T \underline{w})^{-1/2} \cdot 2\underline{w}$$

$$= \underline{w} (\underline{w}^T \underline{w})^{-1/2}$$

$$\boxed{\nabla_{\underline{w}} \|\underline{w}\|_2 = \frac{\underline{w}}{\|\underline{w}\|_2}}$$

b)

$$\nabla_{\underline{w}} \|M\underline{w} - \underline{b}\|_2$$

$$\|M\underline{w} - \underline{b}\|_2 = \sqrt{(M\underline{w} - \underline{b})^T (M\underline{w} - \underline{b})}$$

$$= \sqrt{\underline{w}^T M^T M \underline{w} - \underline{b}^T M \underline{w} - \underline{w}^T M^T \underline{b} + \underline{b}^T \underline{b}}$$

$$= \sqrt{\underline{b}^T \underline{b} - 2(M^T \underline{b})^T \underline{w} + \underline{w}^T M^T M \underline{w}}$$

b)

$$\nabla_{\underline{w}} \| \underline{M}\underline{w} - \underline{b} \|_2$$

$$\| \underline{M}\underline{w} - \underline{b} \|_2 = \sqrt{(\underline{M}\underline{w} - \underline{b})^T (\underline{M}\underline{w} - \underline{b})}$$

$$\text{Let } p = (\underline{M}\underline{w} - \underline{b})^T (\underline{M}\underline{w} - \underline{b}) = \underline{x}^T \underline{x}$$

$$f(p(\underline{w})) = \sqrt{p}^{1/2}$$

$$\nabla_{\underline{w}} \| \underline{M}\underline{w} - \underline{b} \|_2 = \left[\frac{d}{dp} f(p) \right] \cdot \nabla_{\underline{w}} p(\underline{w})$$

$$= \frac{d}{dp} [\sqrt{x^T x}] \cdot \nabla_{\underline{w}} [\underline{x}^T \underline{x}] \frac{d}{d\underline{w}} (\underline{M}\underline{w} - \underline{b})$$

$$= \frac{1}{2} (x^T x)^{-1/2} \cdot 2 \underline{x} (\underline{M})$$

$$= \underline{x} (x^T x)^{-1/2} (\underline{M})$$

$$= \frac{(\underline{M}\underline{w} - \underline{b})}{\sqrt{(\underline{M}\underline{w} - \underline{b})^T (\underline{M}\underline{w} - \underline{b})}} \cdot \underline{M}$$

$$\left[\nabla_{\underline{w}} \| \underline{M}\underline{w} - \underline{b} \|_2 = \frac{(\underline{M}\underline{w} - \underline{b})}{\| \underline{M}\underline{w} - \underline{b} \|_2} \underline{M} \right]$$

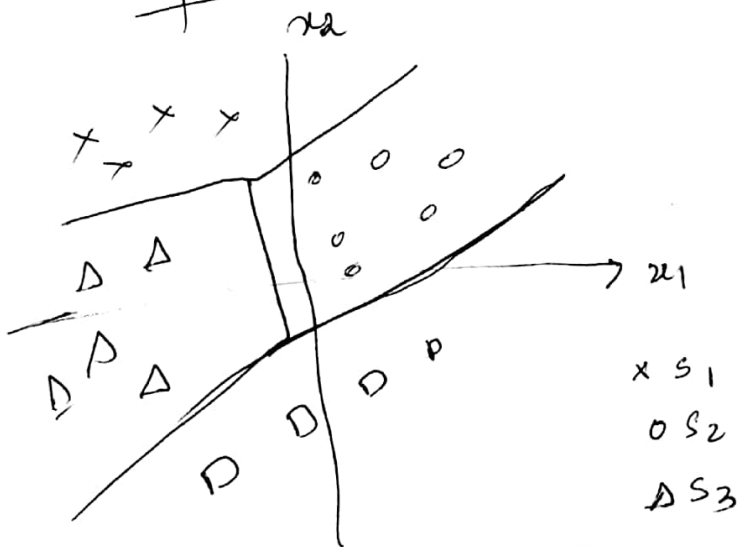
5) Extra Credit problem.

For $C72$

Totally linearly separable implies that all datapoints $x_m^{(i)}$ of class S_i can be separated from all datapoints of all other classes by a linear boundary and this holds $\forall i, i=1, 2, \dots, C$. Then the data are totally linearly separable.

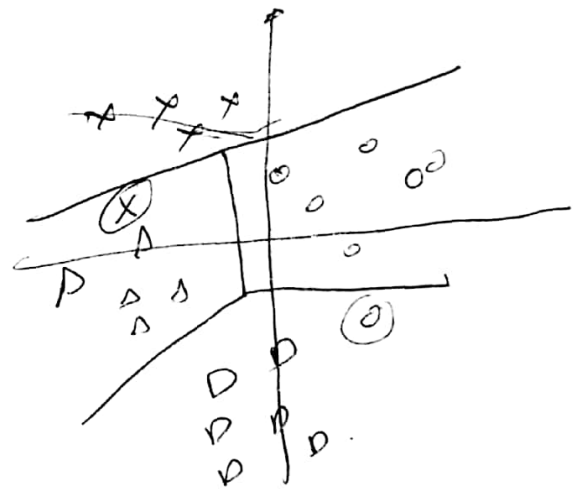
But linear separability implies that if all $g(x)$'s are linear functions, then the data points are linearly separable.

Totally linear separability



Requires that all $g(x)$'s are linear and all points are classified right

Linear separability



linear separability requires just linear functions to classify