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Peoblem-1
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Assumptions +

-> Fixed increment  $\eta(i) = \eta = constant 70$ 

-> Sequential gradient discent -> Data points are linearly separable

-> Use reflected data points znan, n=1,2...N

We can set n=1 without loss of generality, Let 2, 2, = 2 72, , 770

Then drop primes.

Algorithm:  $S \bowtie (0) \rightarrow \text{arbitrary}$   $\bowtie (i+1) \rightarrow \bowtie (i) + z_i \bowtie (i) \forall z_i \bowtie i \leq b \end{bmatrix}$ 

in which Zizi =0,1,2... are the cyclically order

let of training data points.

let z'z' be the mis classified points at each iteration

Algorithm: S N(0) = arbitrary

(N(i+1) = N(i) + z z'

where with it z'z' & b Vi.

Note that if  $\hat{\mathbb{Q}}$  is a solution, then  $a\hat{\mathbb{Q}}$ , and is also

wtznzn >b Hn awiznzn >b Un, ifa>1 Enci) = || \( \omega(i) - \alpha \omega(i) \) | \( \omega(i) - \alpha \omega(i) \) | \( \omega(i) - \alpha \omega(i) + \alpha \omega(i) + \alpha \omega(i) \) | \( \omega(i+1) - \alpha \omega(i) \) | \( \omega(i) - \alpha \omega(i) - \alpha \omega(i) \) | \( \omega(i) - \alpha \omega(i) \) | \( \omega(i) - \alpha \omega(i) \) | \( \omega(i) -

c = min { w zj zj 3 >b.

Let a = 1 + c (azi)

 $\begin{array}{rcl}
 & \Delta & \text{even} & 2b - 2(\lambda^2 + c) + \lambda^2 \\
 & = 2b - 2\lambda^2 - 2c + \lambda^2 \\
 & = 2(b - c) - \lambda^2
\end{array}$ 

If  $b-c\approx -\Delta$  where  $\Delta$  is small then Degror =  $-2\Delta - \frac{1}{4^2}$  which is minimum amount of decrease in error.

For iteration io, 200 (io) 2 (2D+2) then, En (io) 20 which is not reached with the condition

: Convergence is reached at (io-1) iteration

Robbins 2.

$$g_{1}(x)^{2} - x_{1}^{2} - x_{3}^{2} - x_{4}^{2} - x_{5}^{2}$$
 $g_{1}(x)^{2} \times x_{1}^{2} + x_{3}^{2} + x_{4}^{2} + x_{5}^{2}$ 
 $g_{2}(x)^{2} \times x_{1}^{2} + x_{3}^{2} + x_{4}^{2} + x_{5}^{2}$ 
 $g_{3}(x)^{2} = 0$ 
 $g_{3}(x)^{2} = 0$ 

Solution of  $g_{3}(x)^{2} = 0$ 
 $g_{3}(x)$ 

uplied wights
$$w_{(1+2)}^{(1+2)} = w_{(1)}^{(1)}(1) + \eta_{(1)} \times 4$$

$$= \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 1 \\ -1 \\ 0 \\ -1 \end{bmatrix}$$

$$w_{(1)}^{(1)} = \begin{bmatrix} 0 \\ -1 \\ 0 \\ -1 \end{bmatrix} - \begin{bmatrix} 1 \\ -1 \\ 0 \\ -1 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ -2 \\ -1 \end{bmatrix}$$

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$$w_{(2)}^{(1)} = \begin{bmatrix} 0 \\ -1 \\ 0 \\ -1 \end{bmatrix} - \begin{bmatrix} 1 \\ -1 \\ 0 \\ -1 \end{bmatrix} - \begin{bmatrix} 1 \\ -1 \\ 0 \\ -1 \end{bmatrix} - \begin{bmatrix} -1 \\ 0 \\ 0 \\ -1 \end{bmatrix} - \begin{bmatrix} -1 \\ 0 \\ 0 \\ 0 \end{bmatrix} - \begin{bmatrix} -1 \\ 0 \end{bmatrix} - \begin{bmatrix} -1 \\ 0 \end{bmatrix} -$$

$$g_{3}(x^{4}) = g_{3}(x^{4}) = g_{3$$

Problem 26)

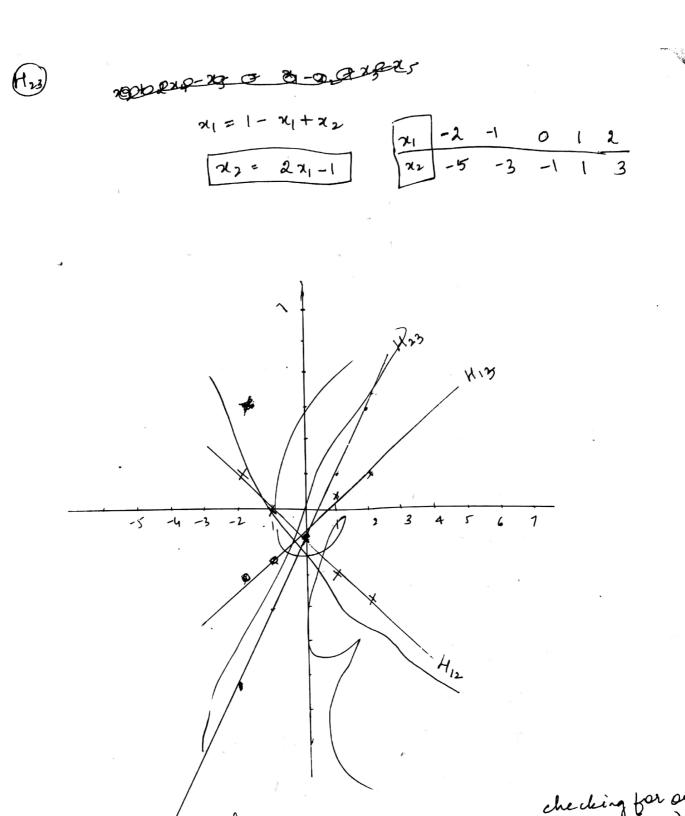
$$-2x^{2} = 1 - x_{1} + \frac{1}{2}x^{2} + 1$$

$$-2x^{2} = 9 - x_{1}$$

$$-2x^{2} = \frac{9}{2} - \frac{2}{1}$$

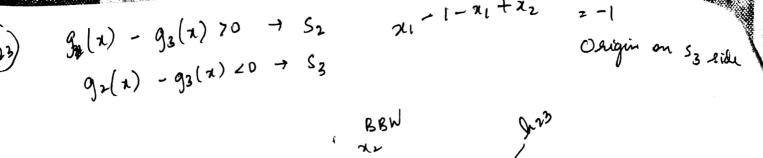
$$-2x^{2} = \frac{1}{2}x_{1} - \frac{1}{1}$$

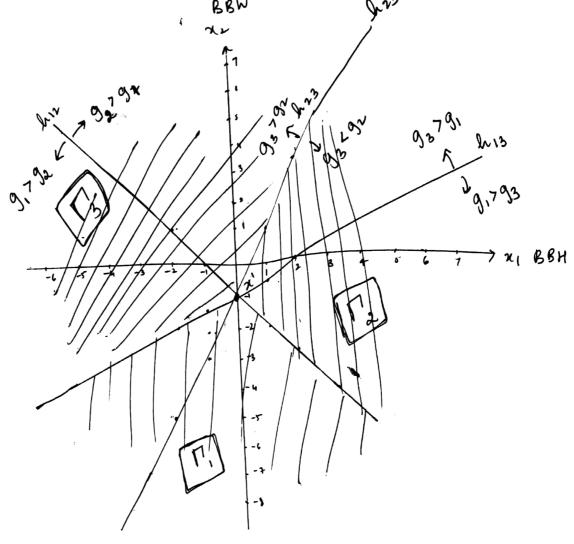
$$-2x^{2} = \frac{1}{2}x_{1} - \frac{1}{1}$$



Decision rule for no and x2;

checking for origin





(3) 
$$J(w) = \frac{1}{N} \left[ \frac{x}{x} \frac{w}{w} - \frac{b}{b} \right]_{2}^{2} + \lambda \left[ \frac{w}{w} \right]_{2}^{2}$$

$$J(w) = \frac{1}{N} \left[ \frac{w}{x} \frac{x}{x} \frac{w}{w} - \frac{b}{y} \right] + \lambda \left[ \frac{w}{w} \frac{w}{w} \right]$$

$$= \frac{1}{N} \left[ \frac{w}{x} \frac{x}{x} \frac{w}{w} - \frac{w}{x} \frac{x}{x} \frac{w}{w} - \frac{b}{x} \frac{x}{x} \frac{w}{w} + \frac{b}{y} \frac{b}{y} \right] + \lambda \left[ \frac{w}{w} \frac{w}{w} \right]$$

$$= \frac{1}{N} \left[ \frac{w}{x} \frac{x}{x} \frac{w}{w} - \frac{a}{x} \frac{x}{y} \frac{x}{b} \right] + 2\lambda \frac{w}{w}$$

$$= \frac{1}{N} \left[ \frac{2x}{x} \frac{x}{x} \frac{w}{w} - \frac{a}{x} \frac{x}{y} \frac{b}{y} \right] + 2\lambda \frac{w}{w}$$

$$= \frac{1}{N} \left[ \frac{2x}{x} \frac{x}{x} \frac{w}{w} - \frac{a}{x} \frac{x}{y} \frac{b}{y} \right] + 2\lambda \frac{w}{w}$$

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$$= \frac{1}{N} \left[ \frac{2x}{x} \frac{x}{x} \frac{w}{w} - \frac{a}{x} \frac{x}{y} \frac{b}{y} \frac{b}{$$

Comparing this to the psedoinverse result, we have an entar NX term added to the personal (2000)

$$J_{n}(\underline{w}) : ||\underline{w}_{n}^{T} \underline{w}^{T} - b_{n}||_{2}^{2}$$

$$= (\underline{w}_{n}^{T} \underline{x}_{n} - b_{n})^{T} (\underline{w}_{n}^{T} \underline{x}_{n} - b_{n})$$

$$= \underline{x}_{n}^{T} \underline{w} \underline{w}_{n}^{T} \underline{x}_{n} - \underline{w}_{n}^{T} \underline{x}_{n} \underline{b}_{n} - \underline{b}_{n}^{T} \underline{w}_{n}^{T} \underline{x}_{n} + \underline{b}_{n}^{T} \underline{b}_{n}^{T}$$

$$J_{n}(\underline{w}) := \underline{x}_{n}^{T} \underline{w} \underline{w}_{n}^{T} \underline{x}_{n} \underline{w}_{n}^{T} - \underline{x}_{n}^{T} \underline{w}_{n}^{T} \underline{w}_{n}^{T}$$

Differences -

1. withouthap learning algorithm was done for C=2, here it is home fore C72

2. Widraw-haff was done considering the reflected are considered. There it is the adread data points that