Mass properties of selected components Coordinate system:Arm2 Coordinate

The center of mass and the moments of inertia are output in the coordinate system of δpAssembly \* Includes the mass properties of one or more hidden components/bodies.

Mass = 2.512492 kilograms

Volume = 0.000740 cubic meters

Surface area = 0.206451 square meters

Center of mass: ( meters )

X = -0.001429

Y = -0.132910

Z = 0.161234

Principal axes of inertia and principal moments of inertia: ( kilograms \* square meters )

Taken at the center of mass.

Ix = (0.002825, -0.330797, 0.943698) Px = 0.003027 Iy = (0.000658, -0.943701, -0.330800) Py = 0.032070Iz = (0.999996, 0.001556, -0.002448) Pz = 0.033982

Moments of inertia: ( kilograms \* square meters )

Taken at the center of mass and aligned with the output coordinate system.

Lxx = 0.033982 Lxy = -0.000030 Lxz = 0.000082 Lyx = -0.000030 Lyy = 0.028892 Lyz = -0.009066 Lzz = 0.006206

Moments of inertia: ( kilograms \* square meters )

Taken at the output coordinate system.

|xx = 0.143681| |xy = 0.000447| |xz = -0.000497| |yx = 0.000447| |yy = 0.094212| |yz = -0.062908| |zx = -0.000497| |zy = -0.062908| |zz = 0.050594|