Mass properties of selected components Coordinate system: Arm2 Coordinate

The center of mass and the moments of inertia are output in the coordinate system of δpAssembly \* Includes the mass properties of one or more hidden components/bodies.

Mass = 3.9997 kilograms

Volume = 0.0013 cubic meters

Surface area = 0.3339 square meters

Center of mass: ( meters )

X = 0.0363Y = -0.0017Z = -0.0524

Principal axes of inertia and principal moments of inertia: ( kilograms \* square meters ) Taken at the center of mass.

Ix = (0.9310, 0.0016, -0.3651)Px = 0.0057Py = 0.1706ly = (-0.3651, -0.0007, -0.9310)Pz = 0.1745Iz = (-0.0017, 1.0000, 0.0000)

Moments of inertia: ( kilograms \* square meters )

Taken at the center of mass and aligned with the output coordinate system.

Lxx = 0.0276Lxy = 0.0003Lxz = -0.0561Lyx = 0.0003Lyy = 0.1745Lyz = -0.0001Lzy = -0.0001Lzx = -0.0561Lzz = 0.1486

Moments of inertia: ( kilograms \* square meters )

Taken at the output coordinate system.

Ixx = 0.0386Ixy = 0.0000Ixz = -0.0637lyx = 0.0000lyy = 0.1908lyz = 0.0003Izx = -0.0637Izy = 0.0003Izz = 0.1539