

Mass properties of selected components
Coordinate system:Arm1Coordinate

The center of mass and the moments of inertia are output in the coordinate system of TopAssembly

* Includes the mass properties of one or more hidden components/bodies.

Mass = 3.9997 kilograms

Volume = 0.0013 cubic meters

Surface area = 0.3339 square meters

Center of mass: (meters)

X = 0.3113

Y = -0.0017

Z = -0.2004

Principal axes of inertia and principal moments of inertia: (kilograms * square meters)

Taken at the center of mass.

Ix = (0.9310, 0.0016, -0.3651)

Px = 0.0057

Iy = (-0.3651, -0.0007, -0.9310)

Py = 0.1706

Iz = (-0.0017, 1.0000, 0.0000)

Pz = 0.1745

Moments of inertia: (kilograms * square meters)

Taken at the center of mass and aligned with the output coordinate system.

Lxx = 0.0276

Lxy = 0.0003

Lxz = -0.0561

Lyx = 0.0003

Lyx = 0.1745

Lyx = -0.0001

Lzx = -0.0561

Lzy = -0.0001

Lzz = 0.1486

Moments of inertia: (kilograms * square meters)

Taken at the output coordinate system.

Ixx = 0.1883

Ixy = -0.0019

Ixz = -0.3056

Iyx = -0.0019

Iyy = 0.7227

Iyz = 0.0013

Izx = -0.3056

Izy = 0.0013

Izz = 0.5362